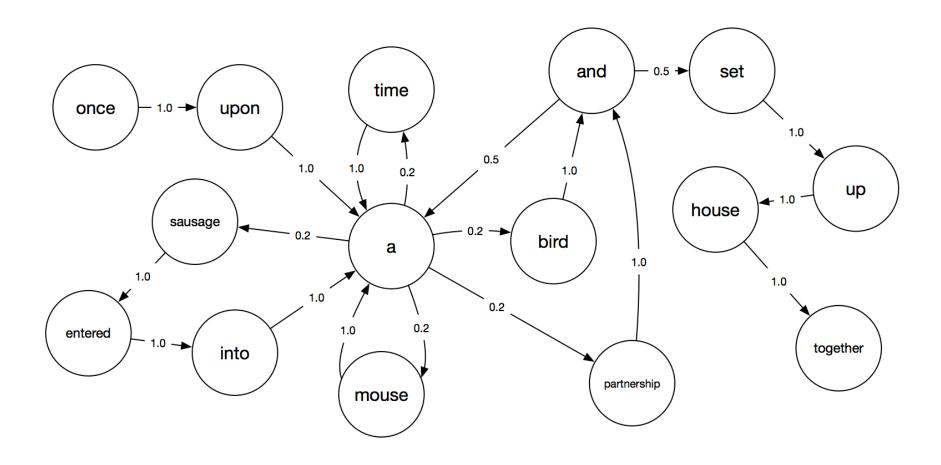
Topic 12 Text Generation

Text generation

- Markov Chains
- RNNs and LSTMs
- Seq-2-Seq

Markov Models for Text Generation

• One of the earliest algorithms used for text generation



A Markov chain

wordi -> word y Pij

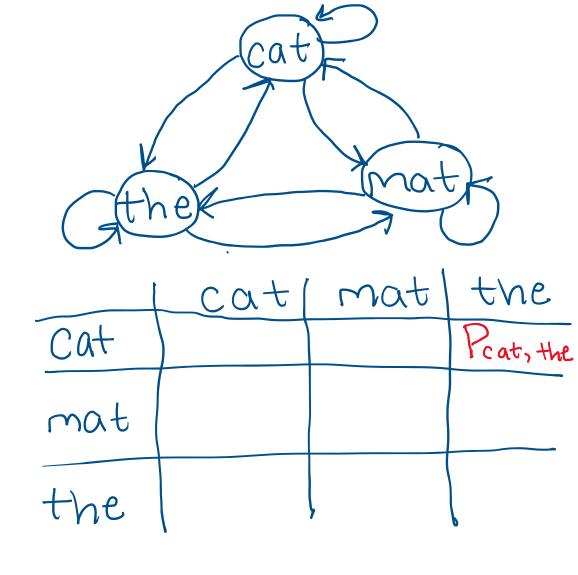
- Typically consists of two entities
 - transition matrix
 - initial state
- Simulate a random walk through the possible states starting from a state of our choice
- Follow the transition probabilities

MC = 3 States, transitions}

Mords

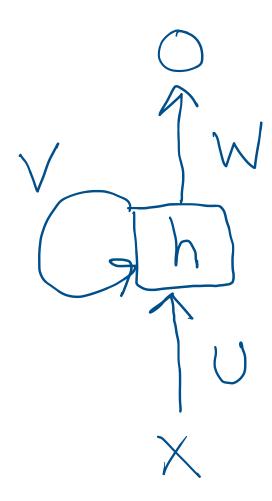
A Markov chain

- Typically consists of two entities
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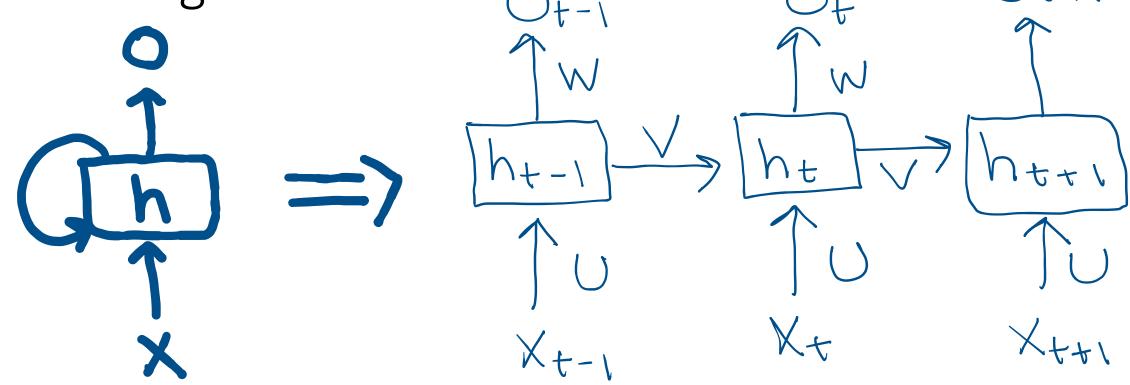


Recurrent Neural Networks

- Input (x): the current input at time t
- Hidden state (h): the network's internal memory, which is updated at each time step t
- Output (o): the output at time t, which depends on the current input and the previous hidden state

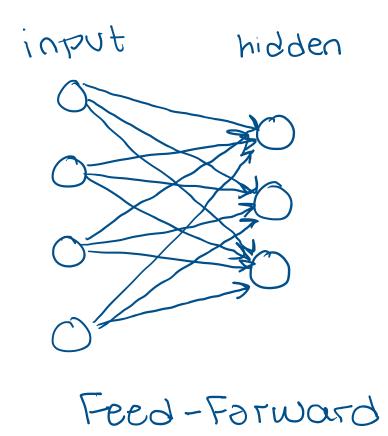


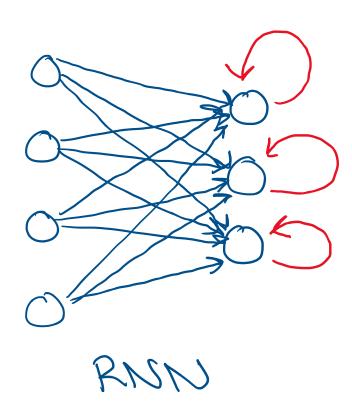
Unfolding an RNN



An unrolled recurrent neural network

RNN vs Fully Connected Feed Forward Network





Training an RNN

- 1.Initialize the hidden state to zero.
- 2. For each time step t:
 - 1. Compute the input to the hidden layer, $h_t = \sigma_1(Ux_t + Vh_t + b_1)$
 - 2. Compute the input to the output layer, $o_t = \sigma_2(Wh_t + b_2)$
- The final output of the network is the output at the last time step, o(N), where N is the length of the input sequence.

Backpropagation (Review)

- Backpropagation training algorithm modifies the weights of a neural network in order to minimize the error of the network outputs compared to some expected output
 - 1. Compare the predicted outputs to the expected outputs and calculate the error.
 - 2. Calculate the derivatives of the error with respect to the network weights.
 - 3. Adjust the weights to minimize the error.
 - 4. Repeat.

What about sequence data that may be temporally ordered?

Unfold the network over time and propagate the errors backwards

- 1. Present a sequence of timesteps of input and output pairs to the network.
- 2. Unroll the network then calculate and accumulate errors across each timestep.
- 3. Roll-up the network and update weights.
- 4. Repeat.

$$h_{t} = \sigma_{1} \left(U_{X_{t}} + V_{h_{t}} + b_{1} \right) \quad \text{hidden states}$$

$$O_{t} = \sigma_{2} \left(W_{h_{t}} + b_{2} \right) \quad \text{output distribution}$$

$$SOFTMAX$$

$$E_{t} = (g_{t} - O_{t})^{2}$$
error
$$ground$$

$$truth$$
what was
$$output at$$

$$time t$$

$$E_{t} = (g_{t} - O_{t})^{2}$$

$$E_{3} = (g_{3} - O_{3})^{2}$$
Adjusting W:
$$\frac{\partial E_{3}}{\partial W} = \frac{\partial E_{3}}{\partial O_{3}} \cdot \frac{\partial O_{3}}{\partial W}$$

$$h_{1} \rightarrow h_{2} \rightarrow h_{3}$$

$$E_{t} = (g_{t} - O_{t})^{2}$$

$$E_{3} = (g_{3} - O_{3})^{2}$$
Adjusting $V:$

$$\frac{\partial E_{3}}{\partial V} = \sum_{i=1}^{N} \frac{\partial E_{N}}{\partial O_{N}} \cdot \frac{\partial O_{N}}{\partial h_{i}} \cdot \frac{\partial h_{i}}{\partial V} + h_{2} \xrightarrow{\lambda} h_{3}$$
have to consider previous time steps.

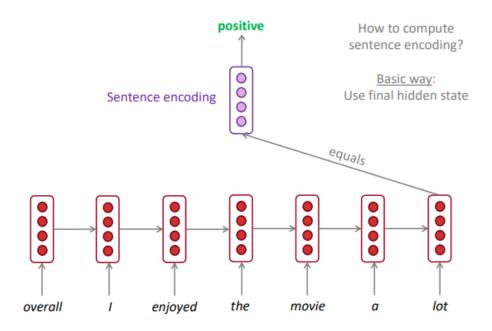
$$E_{t} = (g_{t} - O_{t})^{2}$$

$$E_{3} = (g_{3} - O_{3})^{2}$$
Adjusting $U:$

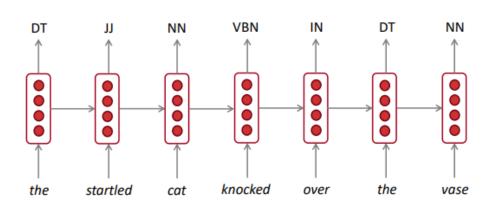
$$\frac{\partial E_{3}}{\partial U} = \sum_{i=1}^{N} \frac{\partial E_{N}}{\partial O_{N}} \frac{\partial O_{N}}{\partial h_{i}} \frac{\partial h_{i}}{\partial U} + h_{i} \xrightarrow{\lambda_{0}} h_{3}$$

$$\frac{\partial E_{3}}{\partial U} = \sum_{i=1}^{N} \frac{\partial E_{N}}{\partial O_{N}} \frac{\partial O_{N}}{\partial h_{i}} \frac{\partial h_{i}}{\partial U} + h_{i} \xrightarrow{\lambda_{0}} h_{3}$$

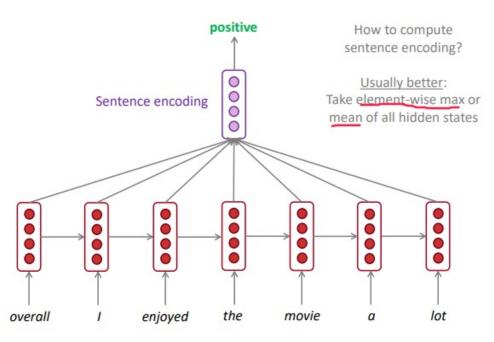
have to consider previous time steps.



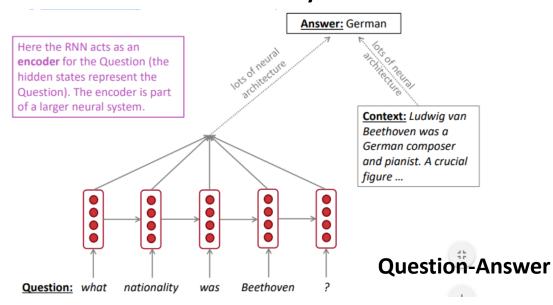
Sentiment Analysis



POS Tagging



Sentiment Analysis



Drawbacks of RNNs

- RNNs consist of sequential steps
 - If input sequences are comprised of thousands of timesteps, then this will be the number of derivatives required for a single update weight update

Errors accumulate over time:

The values in the calculations in these backpropagation steps are large (> 1)

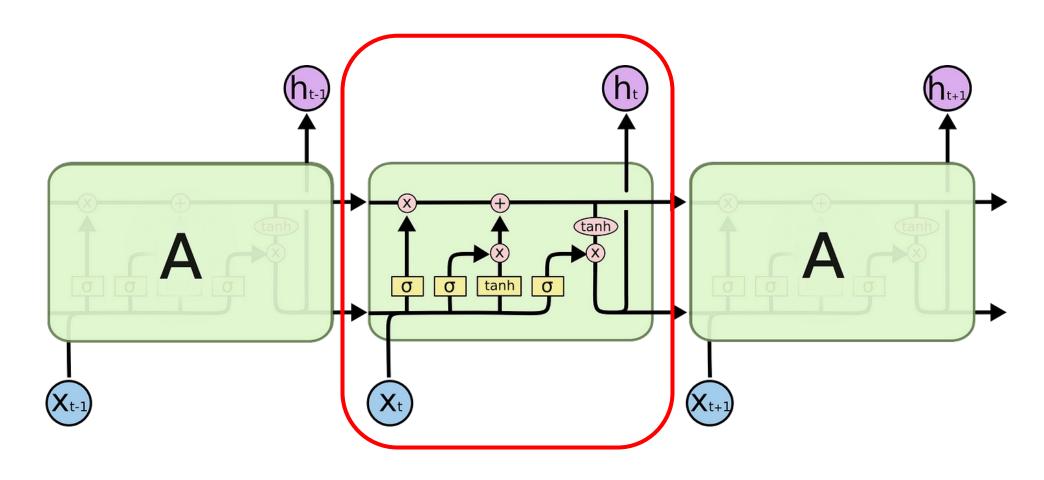
Exploding Gradients

The values in the calculations in these backpropagation steps are small (< 1)

Vanishing Gradients

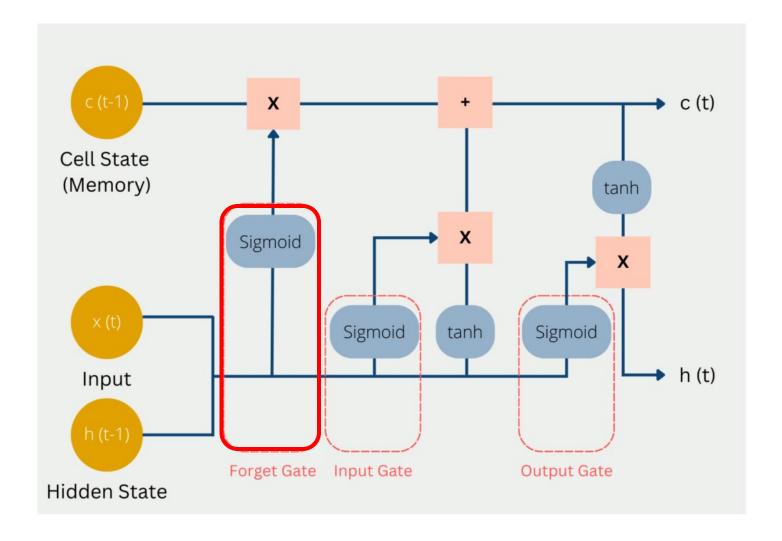
Methods to solve these issues

- Exploding Gradients
 - Truncated backpropagation through time
 - Gradient clipping
- Vanishing Gradients
 - Early stopping
 - Weight initialization
 - Use LSTMs or GRUs



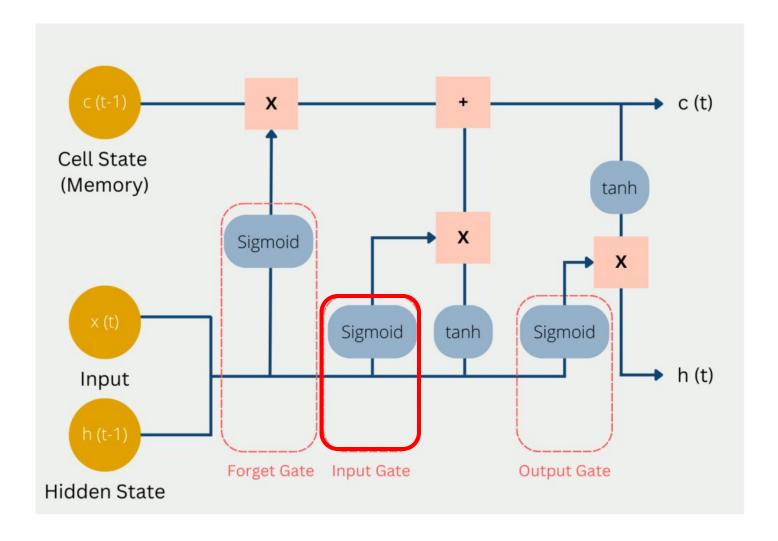
 Forget gate: controls which information from the previous cell state should be discarded

$$f_t = \sigma(W_f [x_t, h_{t-1}] + b_f)$$



Input gate: controls
 which information from
 the current input and
 previous hidden state
 should be stored in the
 cell state

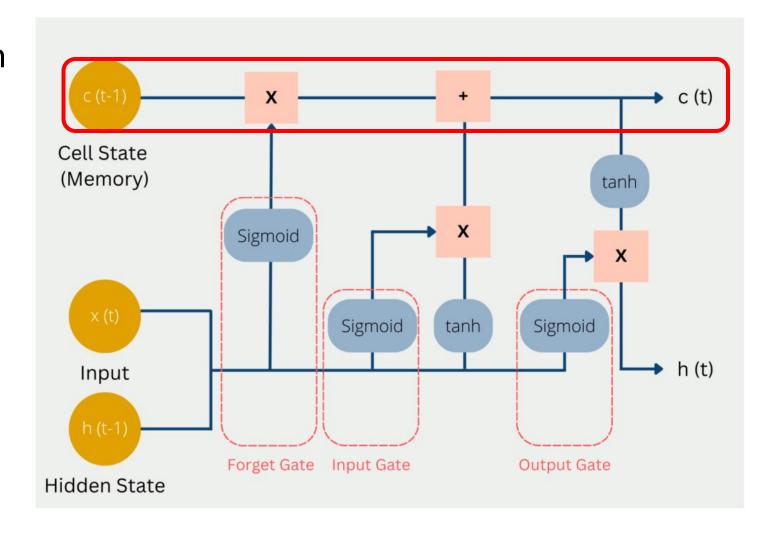
$$i_t = \sigma(W_i[x_t, h_{t-1}] + b_i)$$



 Cell state: the long-term memory of the LSTM

$$C'_{t} = tahn(W_{c} * [h_{t-1}, x_{t}] + b_{c}$$

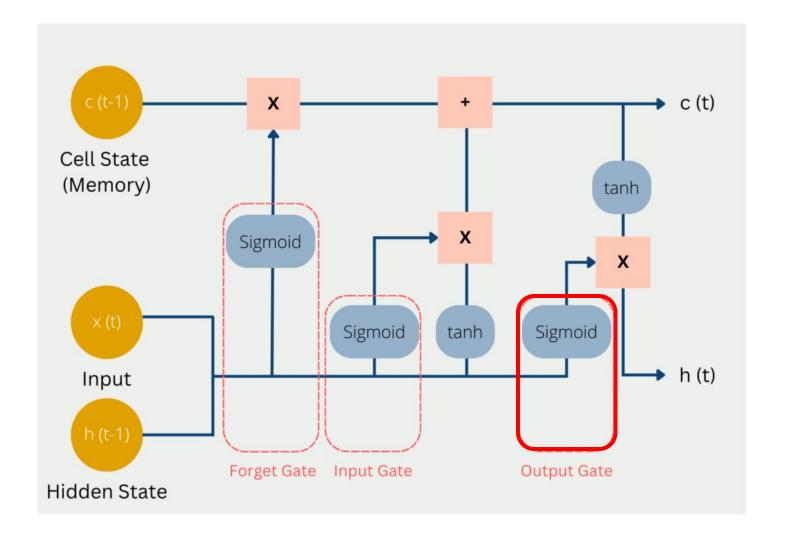
$$C_t = f_t * C_{t-1} + i_t * C'_t$$



 Output gate: controls which information from the current input and previous hidden state should be outputted from the cell state

$$o(t) = \sigma(W(o) * [h(t-1), x(t)] + b(o))$$

 $h(t) = o(t) * tanh(C(t))$

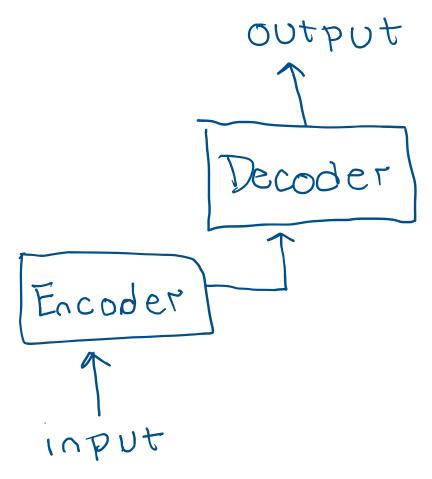


LSTMs vs vanilla RNNs

- Ability to handle long(er)-term dependencies by maintaining a cell state
- Ability to selectively remember or forget information through the gates
- Ability to output information based on the current input and previous hidden state

Sequence to Sequence Models

- The architecture of a Seq-2-Seq model consists of two main components: an encoder and a decoder
- Encoder: recurrent neural network (RNN) such as LSTM or GRU, which produces a fixed-length vector representation of the input sequence
- **Decoder:** recurrent neural network (RNN) such as LSTM or GRU, which uses the vector representation produced by the encoder to generate the output sequence one element at a time



Later: Transformers for text generation

- These seq-2-seq models are typically used for chatbots
 - For now, we will use a pre-trained models

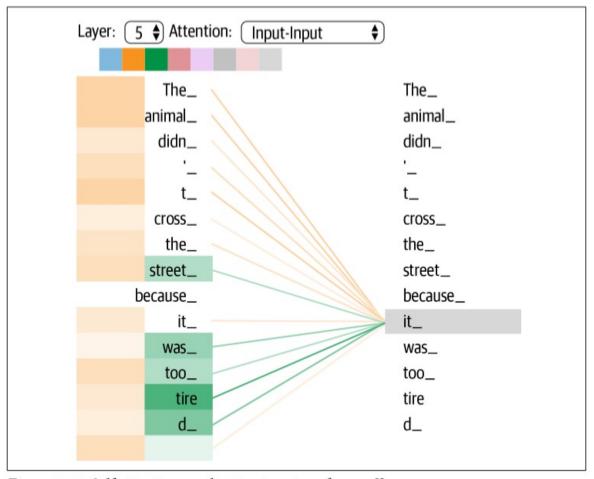


Figure 1-17. Self-attention mechanism in a transformer []

Next time

- Building a chatbot
 - Rule-based
 - Open-ended