#### Decision Trees II

#### Introduction

#### Extending Decision Trees

- Conditional Inference Trees (Hothorn et al. 2006)
  - Addresses selection bias for variables with many potential split points
  - Separates variable and split point decision
  - Variable selection and stopping criterion based on statistical test
- Model-based Recursive Partitioning (Zeileis et al. 2008)
  - Connects recursive partitioning with fitting parametric (regression) models
  - Approach to fitting "homogeneous" models in tree nodes

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- Specify a parametric model in advance
  - Constant leaves:  $y \sim \mathcal{N}(\theta, \sigma^2)$
  - OLS regression:  $y|x \sim \mathcal{N}(x'\theta, \sigma^2)$
  - logit, survival, ...
- Three types of variables
  - Response variable y
  - Predictor variables  $x_1, \ldots, x_p$
  - Partitioning variables  $z_1, \ldots, z_j$
- $\rightarrow$  Use the partitioning variables  $z_1, \dots, z_j$  to partition the n observations into distinct groups with separate models

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  - Predictor variables  $x_1, \ldots, x_p$
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#### $\textbf{Algorithm 1:} \ \mathsf{Recursive} \ \mathsf{partitioning} \ \mathsf{with} \ \mathsf{GLMs}$

```
Parameter : p-value threshold Initialization: Fit initial model using all observations

1 Perform M-fluctuation tests for each partitioning variable (H_0: stability of \hat{\beta});

2 if minimum p-value exceeds threshold then

3 | end partitioning (global H_0 not rejected);

4 else

5 | choose partitioning variable associated with the smallest p-value;

6 | find the optimal split point;

7 | split node into two subnodes at this split point;

8 | for each node of the current tree do

9 | continue partitioning process;

10 | end
```

11 end

#### M-fluctuation tests

Starting point: Objective function of OLS or ML

$$\hat{\theta} = \underset{\theta}{\operatorname{argmin}} \sum_{i=1}^{n} \Psi(y_i, x_i, \theta)$$

Solved via score function

$$\frac{\partial \Psi(y_i, x_i, \theta)}{\partial \theta}$$

Partial derivations (e.g.,  $y = \beta_0 + \beta_1 x + \epsilon$ )

$$\frac{d\Psi(y_i, x_i, \beta_0, \beta_1)}{d\beta_0} = \epsilon_i$$
 and  $\frac{d\Psi(y_i, x_i, \beta_0, \beta_1)}{d\beta_1} = x_i \epsilon$ 

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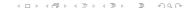
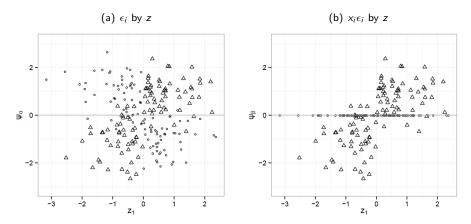


Figure: Structural change illustration with  $x_i$ {treatment ( $\Delta$ ), control ( $\circ$ )}

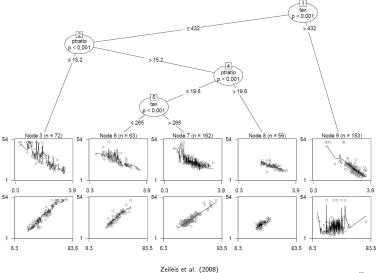


Seibold et al. (2016)

#### Controlling tree complexity

- Test-based stopping
  - $\alpha$  (alpha, default = 0.05)
- Tree-based stopping
  - Observations per node (minsize)
  - Tree depth (maxdepth)
- Post-pruning
  - Prune nodes by checking AIC or BIC improvements

Figure: Linear-regression-based tree with partial scatterplots



#### Summary

- Recursive partitioning approach can be complemented with permutation and M-fluctuation tests
- Adjusts and (heavily) extends CART idea
- Model-based Recursive Partitioning
  - 1 Tree-based approach to explore interactions
  - ② Can be used to detect model misspecification (Kopf et al. 2010)
  - 3 Extensions for various types of models available (e.g. Strobl et al. 2015)

#### Software Resources

#### Resources for R

- A Laboratory for Recursive Partytioning: party
  - Includes ctree (Conditional Inference Trees) and mob (Model-based Recursive Partitioning)
- A Toolkit for Recursive Partytioning: partykit
  - Includes a re-implementation of ctree and new interfaces for mob (lmtree, glmtree)

#### References

- Hothorn, T., Hornik, K., Zeileis, A. (2006). Unbiased Recursive Partitioning: A Conditional Inference Framework. *Journal of Computational and Graphical Statistics* 15(3), 651–674.
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