

Determinants

For a triangle with vertices $(x_1, y_1), (x_2, y_2), (x_3, y_3)$, Area is given by $\Delta = \frac{1}{2} \begin{vmatrix} x_1 & y_1 & 1 \\ x_2 & y_2 & 1 \\ x_3 & y_3 & 1 \end{vmatrix}$

If $\Delta = 0$, the points are collinear.

Properties of determinants:

1. If all elements of a row or column are zero, value of the determinant is zero.
2. If any two rows or columns of a determinant are identical, result is zero.
3. $|A| = |A'|$, where A' is the transpose of A .
4. If any row or column of a determinant is multiplied by a non-zero constant k , the result is k times.
5. By interchanging two rows or columns of a determinant, the resulting determinant is the negative of the original determinant.

$$6. \begin{vmatrix} a_1 + x_1 & b_1 & c_1 \\ a_2 + x_2 & b_2 & c_2 \\ a_3 + x_3 & b_3 & c_3 \end{vmatrix} = \begin{vmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{vmatrix} + \begin{vmatrix} x_1 & b_1 & c_1 \\ x_2 & b_2 & c_2 \\ x_3 & b_3 & c_3 \end{vmatrix}$$

$$7. |AB| = |A||B|$$

8. If a row or column is multiplied by a non-zero constant k and added to/subtracted from another row or column, the result does not change.

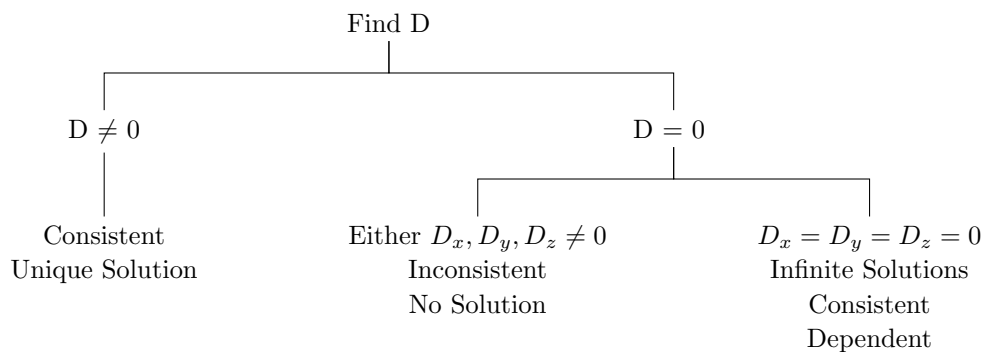
Cramer's Rule:

To solve a system of linear, non-homogenous equations using determinants.

$$\begin{aligned} a_1x + b_1y + c_1z &= d_1 \\ a_2x + b_2y + c_2z &= d_2 \\ a_3x + b_3y + c_3z &= d_3 \end{aligned}$$

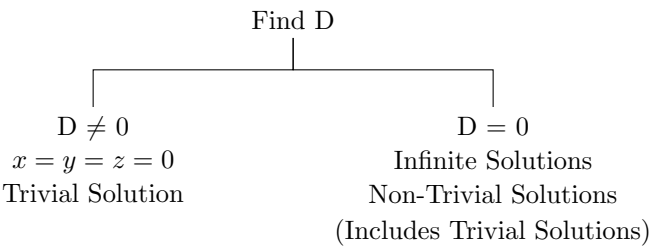
$$D = \begin{vmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{vmatrix}, D_x = \begin{vmatrix} d_1 & b_1 & c_1 \\ d_2 & b_2 & c_2 \\ d_3 & b_3 & c_3 \end{vmatrix}, D_y = \begin{vmatrix} a_1 & d_1 & c_1 \\ a_2 & d_2 & c_2 \\ a_3 & d_3 & c_3 \end{vmatrix}, D_z = \begin{vmatrix} a_1 & b_1 & d_1 \\ a_2 & b_2 & d_2 \\ a_3 & b_3 & d_3 \end{vmatrix}$$

$$x = \frac{D_x}{D}, y = \frac{D_y}{D}, z = \frac{D_z}{D}$$



Homogeneous Equations

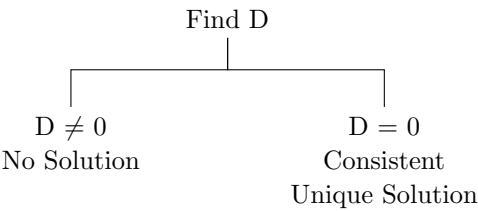
Equations in which the constant term is always 0. These are always consistent and $D_x = D_y = D_z = 0$.



Concurrency Of Lines:

For equations of the form $ax + by + c = 0$,

$$D = \begin{vmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{vmatrix}$$



Matrices

Transpose of a Matrix:

1. $(A')' = A$
2. $(A + B)' = A' + B'$
3. $(AB)' = B' A'$
4. $(kA)' = kA'$

Symmetric Matrix: $A = A'$

Skew-Symmetric Matrix: $-A = A'$

For square matrices, $A + A' = \text{Symmetric}$ and $A - A' = \text{Skew-Symmetric}$

$$A = \frac{A + A'}{2} + \frac{A - A'}{2}$$

Singular Matrix: $|A| = 0$

Adjoint of a Matrix:

An adjoint matrix is the tranpose of the cofactor matrix.

For 2×2 matrix, $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \rightarrow \text{adj } A = \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$

Exchange the elements of the principal diagonal and change the sign of the rest.

$$\text{adj}(AB) = (\text{adj } B)(\text{adj } A)$$

Inverse of a Matrix:

A and B are the inverse of each other if $AB = I$

$$\frac{\text{adj } A}{|A|} = A^{-1}$$

$$(AB)^{-1} = B^{-1} A^{-1}$$

$$(A')^{-1} = (A^{-1})'$$

Martin’s Rule:

To solve linear simultaneous equations using matrices.

$a_1x + b_1y = c_1$

$a_2x + b_2y = c_2$

$\begin{bmatrix} a_1 & b_1 \\ a_2 & b_2 \end{bmatrix}$

$\begin{bmatrix} x \\ y \end{bmatrix}$

$=$

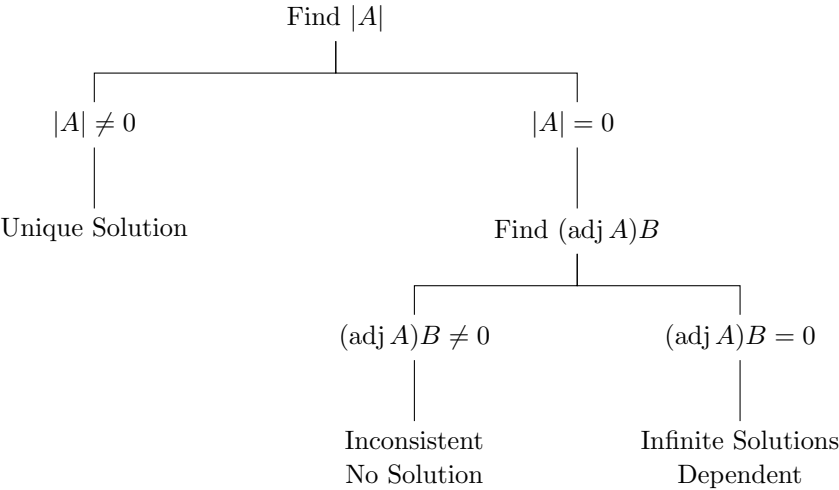
$\begin{bmatrix} c_1 \\ c_2 \end{bmatrix}$

A

X

B





$AX = B \rightarrow X = A^{-1}B = \frac{(\text{adj } A)B}{|A|}$



Conics



Parabola

A parabola is the locus of a point which moves so that its distance from a fixed point (Focus) is equal to its distance from a fixed straight line (Directrix). $e = 1$

Graph				
Type	Right	Left	Upwards	Downwards
Equation	$y^2 = 4ax$	$y^2 = -4ax$	$x^2 = 4ay$	$x^2 = -4ay$
Axis	$y = 0$	$y = 0$	$x = 0$	$x = 0$
Directrix	$x = -a$	$x = a$	$y = -a$	$y = a$
Vertex	$(0, 0)$			
Focus	$(a, 0)$	$(-a, 0)$	$(0, a)$	$(0, -a)$
Tangent at Vertex	$x = 0$		$y = 0$	
Length of Latus Rectum	$4a$			
Equation of LR	$x = a$	$x = -a$	$y = a$	$y = -a$

Ellipse



An ellipse is the locus of a point which moves so that its distance from a fixed point (Focus) bears a constant ratio (eccentricity 'e'), which is less than unity, to its distance from a fixed line (Directrix).

Graph		
Type	Horizontal	Vertical
Equation	$\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$	$\frac{y^2}{a^2} + \frac{x^2}{b^2} = 1$
Center	$(0, 0)$	
Foci	$(\pm ae, 0)$	$(0, \pm ae)$
Major Vertices	$(\pm a, 0)$	$(0, \pm a)$
Minor Vertices	$(0, \pm b)$	$(\pm b, 0)$
Length of Major Axis	$2a$	
Length of Minor Axis	$2b$	
Equations of Directrices	$x = \pm \frac{a}{e}$	$y = \pm \frac{a}{e}$
Length of Latus Rectum	$\frac{2b^2}{a}$	

$$b^2 = a^2(1 - e^2)$$

Hyperbola

A hyperbola is the locus of a point which moves so that its distance from a fixed point (Focus) bears the a constant ratio (eccentricity ‘e’), which is greater than unity, to its distance from a fixed line (Directrix).

Graph		
Type	Horizontal	Vertical
Equation	$\frac{x^2}{a^2} - \frac{y^2}{b^2} = 1$	$\frac{y^2}{a^2} - \frac{x^2}{b^2} = 1$
Center	(0, 0)	
Foci	(±ae, 0)	(0, ±ae)
Vertices	(±a, 0)	(0, ±a)
Length of Transverse Axis	2a	
Length of Conjugate Axis	2b	
Equations of Directrices	$x = \pm \frac{a}{e}$	$y = \pm \frac{a}{e}$
Equation of Transverse Axis	y = 0	x = 0
Equation of Conjugate Axis	x = 0	y = 0
Length of Latus Rectum	$\frac{2b^2}{a}$	
Focal Radii	ex ± a	ey ± a

b² = a²(e² - 1)

Tangency

Line	Curve	Condition	Tangent	Point Of Contact
y = mx + c	y² = 4ax	c = $\frac{a}{m}$	y = mx + $\frac{a}{m}$	$\left(\frac{a}{m^2}, \frac{2a}{m}\right)$
y = mx + c	y² = -4ax	c = $\frac{-a}{m}$	y = mx - $\frac{a}{m}$	$\left(\frac{-a}{m^2}, \frac{-2a}{m}\right)$
y = mx + c	$\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$	c² = a²m² + b²	y = mx ± √(a²m² + b²)	$\left(\frac{\pm a^2m}{\sqrt{a^2m^2 + b^2}}, \frac{\mp b^2}{\sqrt{a^2m^2 + b^2}}\right)$
y = mx + c	$\frac{x^2}{a^2} - \frac{y^2}{b^2} = 1$	c² = a²m² - b²	y = mx ± √(a²m² - b²)	$\left(\frac{\pm a^2m}{\sqrt{a^2m^2 - b^2}}, \frac{\pm b^2}{\sqrt{a^2m^2 - b^2}}\right)$

Inverse Trigonometric Functions

Function	Domain	Principal Values
$y = \sin^{-1} x$	$-1 \leq x \leq 1$	$\left[-\frac{\pi}{2}, \frac{\pi}{2}\right]$
$y = \cos^{-1} x$	$-1 \leq x \leq 1$	$[0, \pi]$
$y = \tan^{-1} x$	All real numbers	$\left(-\frac{\pi}{2}, \frac{\pi}{2}\right)$
$y = \cot^{-1} x$	All real numbers	$(0, \pi)$
$y = \sec^{-1} x$	$x \geq 1$ or $x \leq -1$	$(0, \pi], y \neq \frac{\pi}{2}$
$y = \csc^{-1} x$	$x \geq 1$ or $x \leq -1$	$\left[-\frac{\pi}{2}, \frac{\pi}{2}\right], y \neq 0$

$$\begin{aligned} \sin^{-1} x &= \cos^{-1} \sqrt{1-x^2} = \tan^{-1} \left(\frac{x}{\sqrt{1-x^2}} \right) \\ &= \sec^{-1} \left(\frac{1}{\sqrt{1-x^2}} \right) = \cot^{-1} \left(\frac{\sqrt{1-x^2}}{x} \right) = \csc^{-1} \frac{1}{x} \\ \cos^{-1} x &= \sin^{-1} \sqrt{1-x^2} = \tan^{-1} \left(\frac{\sqrt{1-x^2}}{x} \right) \\ &= \csc^{-1} \left(\frac{1}{\sqrt{1-x^2}} \right) = \cot^{-1} \left(\frac{x}{\sqrt{1-x^2}} \right) = \sec^{-1} \frac{1}{x} \\ \tan^{-1} x &= \sin^{-1} \left(\frac{x}{\sqrt{1+x^2}} \right) = \cos^{-1} \left(\frac{1}{\sqrt{1+x^2}} \right) \\ &= \csc^{-1} \left(\frac{\sqrt{1+x^2}}{x} \right) = \sec^{-1} \sqrt{1+x^2} = \cot^{-1} \frac{1}{x} \end{aligned}$$

$$\begin{aligned} \tan^{-1} x + \tan^{-1} y &= \tan^{-1} \left(\frac{x+y}{1-xy} \right), \quad xy < 1 \\ \tan^{-1} x - \tan^{-1} y &= \tan^{-1} \left(\frac{x-y}{1+xy} \right), \quad xy > -1 \\ 2 \tan^{-1} x &= \tan^{-1} \frac{2x}{1-x^2} = \sin^{-1} \frac{2x}{1+x^2} = \cos^{-1} \frac{1-x^2}{1+x^2} \\ 2 \sin^{-1} x &= \sin^{-1} (2x\sqrt{1-x^2}) \\ 2 \cos^{-1} x &= \cos^{-1} (2x^2-1) \\ 3 \sin^{-1} x &= \sin^{-1} (3x-4x^3) \\ 3 \cos^{-1} x &= \cos^{-1} (4x^3-3x) \\ 3 \tan^{-1} x &= \tan^{-1} \frac{3x-x^3}{1-3x^2} \end{aligned}$$

$$\begin{aligned} \sin^{-1} x + \sin^{-1} y &= \sin^{-1} (x\sqrt{1-y^2} + y\sqrt{1-x^2}) \\ \sin^{-1} x - \sin^{-1} y &= \sin^{-1} (x\sqrt{1-y^2} - y\sqrt{1-x^2}) \\ \cos^{-1} x + \cos^{-1} y &= \cos^{-1} (xy - \sqrt{1-x^2} \cdot \sqrt{1-y^2}) \\ \cos^{-1} x - \cos^{-1} y &= \cos^{-1} (xy + \sqrt{1-x^2} \cdot \sqrt{1-y^2}) \end{aligned}$$

Differentiation

Basic:

$$\frac{d}{dx}(c) = 0$$

$$\frac{d}{dx}\left(\frac{1}{x}\right) = -\frac{1}{x^2}$$

$$\frac{d}{dx}(x^n) = nx^{n-1}$$

$$\frac{d}{dx}(\sqrt{x}) = \frac{1}{2\sqrt{x}}$$

$$\frac{d}{dx}(ax+b)^n = na(ax+b)^{n-1}$$

$$\frac{d}{dx}(\sqrt{ax+b}) = \frac{a}{x\sqrt{ax+b}}$$

$$\frac{d}{dx}(x) = 1$$

Trigonometric:

$$\frac{d}{dx}(\sin x) = \cos x$$

$$\frac{d}{dx}(\tan x) = \sec^2 x$$

$$\frac{d}{dx}(\sec x) = \sec x \tan x$$

$$\frac{d}{dx}(\cos x) = -\sin x$$

$$\frac{d}{dx}(\cot x) = -\csc^2 x$$

$$\frac{d}{dx}(\csc x) = -\csc x \cot x$$

Logarithmic and Exponential:

$$\frac{d}{dx}(\log_a x) = \frac{1}{x \log_e a}$$

$$\frac{d}{dx}(e^x) = e^x$$

$$\frac{d}{dx}(\log_e x) = \frac{1}{x}$$

$$\frac{d}{dx}(a^x) = a^x \log_e a$$

Inverse Trigonometric:

$$\frac{d}{dx}(\sin^{-1} x) = \frac{1}{\sqrt{1-x^2}}$$

$$\frac{d}{dx}(\tan^{-1} x) = \frac{1}{1+x^2}$$

$$\frac{d}{dx}(\sec^{-1} x) = \frac{1}{|x|\sqrt{x^2-1}}$$

$$\frac{d}{dx}(\cos^{-1} x) = \frac{-1}{\sqrt{1-x^2}}$$

$$\frac{d}{dx}(\cot^{-1} x) = \frac{-1}{1+x^2}$$

$$\frac{d}{dx}(\csc^{-1} x) = \frac{-1}{|x|\sqrt{x^2-1}}$$

Integration

Fundamental Formulae

Basic:

$$\int x^n dx = \frac{x^{n+1}}{n+1} + C, n \neq -1$$

$$\int (ax+b)^n dx = \frac{(ax+b)^{n+1}}{a(n+1)} + C, n \neq -1$$

$$\int \frac{1}{x} dx = \log |x| + C$$

$$\int \frac{1}{ax+b} dx = \frac{\log |ax+b|}{a} + C$$

$$\int e^x dx = e^x + C$$

$$\int a^x dx = \frac{a^x}{\log a} + C$$

Special Forms:

$$\int [f(x)]^n f'(x) dx = \frac{[f(x)]^{n+1}}{n+1} + C, n \neq -1$$

$$\int \frac{f'(x)}{f(x)} dx = \log |f(x)| + C$$

$$\int \frac{f'(x)}{\sqrt{f(x)}} dx = 2\sqrt{f(x)} + C$$

Trigonometry:

$$\int \sin x dx = -\cos x + C$$

$$\int \cos x dx = \sin x + C$$

$$\int \sec^2 x dx = \tan x + C$$

$$\int \csc^2 x dx = -\cot x + C$$

$$\int \sec x \tan x dx = \sec x + C$$

$$\int \sec x dx = \log |\sec x + \tan x| + C = \log \left| \tan \left(\frac{\pi}{4} + \frac{x}{2} \right) \right| + C$$

$$\int \csc x \cot x dx = -\csc x + C$$

$$\int \tan x dx = -\log |\cos x| + C = \log |\sec x| + C$$

$$\int \cot x dx = \log |\sin x| + C$$

$$\int \csc x dx = \log |\csc x - \cot x| + C = \log \left| \tan \frac{x}{2} \right| + C$$

Integration By Parts:

$$\int u \cdot v dx = u \int v dx - \int \frac{d}{dx} u \int v dx$$

To decide first function use: **L**ogarithmic, **I**nverse Trig, **A**lgebraic, **T**rigo, **E**xponential

For integrals of the form $\int e^{ax} \cos bx$ or $\int e^{ax} \sin bx$:

Integrate by parts taking e^{ax} as the first function, and integrate by parts again, substituting the original integral as I and then simplifying.

$$\int e^x \cdot [f(x) + f'(x)] = e^x f(x) dx$$

Special Integrals:

$$\int \frac{1}{x^2 + a^2} dx = \frac{1}{a} \tan^{-1} \frac{x}{a} + C$$

$$\int \frac{1}{x^2 - a^2} dx = \frac{1}{2a} \log \left| \frac{x-a}{x+a} \right| + C$$

$$\int \frac{1}{a^2 - x^2} dx = \frac{1}{2a} \log \left| \frac{a+x}{a-x} \right| + C$$

For integrals of the form $\int \frac{x^2 + 1}{x^4 + kx^2 + 1} dx$ or $\int \frac{x^2 - 1}{x^4 + kx^2 + 1} dx$,

Divide the numerator and denominator by x^2 and put $\left(x - \frac{1}{x}\right) = t$ and $\left(x + \frac{1}{x}\right) = t$ respectively.

For integrals of the form $\int \frac{1}{ax^2 + bx + c} dx$

5. Make coefficient of x^2 unity

6. Complete the square by Adding and Subtracting the square of half the coefficient of x ($b^2/4$)

7. Use standard form for denominator as $(x + \alpha)^2 \pm \beta^2$

For integrals of the form $\int \frac{px + q}{ax^2 + bx + c} dx$,

1. Put $px + q$ as $\frac{d}{dx} (\text{Denominator}) \cdot k_1 \pm k_2$ where k_1 and k_2 are constants.

2. Split numerator taking individual denominators and evaluate

Irrational Forms:

$$\int \frac{1}{\sqrt{a^2 - x^2}} dx = \sin^{-1} \frac{x}{a} + C$$

$$\int \frac{1}{\sqrt{x^2 + a^2}} dx = \log \left| x + \sqrt{x^2 + a^2} \right| + C$$

$$\int \frac{1}{\sqrt{x^2 - a^2}} dx = \log \left| x + \sqrt{x^2 - a^2} \right| + C$$

For integrals of the form $\int \frac{1}{\sqrt{ax^2 + bx + c}} dx$,

1. Make coefficient of x^2 unity

2. Complete the square by Adding and Subtracting the square of half the coefficient of x ($b^2/4$)

3. Use standard form for denominator as $\sqrt{(x + \alpha)^2 \pm \beta^2}$

For integrals of the form $\int \frac{px + q}{\sqrt{ax^2 + bx + c}} dx$,

1. Put $px + q$ as $\frac{d}{dx} (\text{Denominator}) \cdot k_1 \pm k_2$ where k_1 and k_2 are constants.

2. Split numerator taking individual denominators and evaluate

For integrals of the form $\int \frac{1}{a + b \cos x} dx$, $\int \frac{1}{a + b \sin x} dx$, $\int \frac{1}{a \cos x + b \sin x} dx$

1. Put $\sin x = \frac{2 \tan(x/2)}{1 + \tan^2(x/2)}$, $\cos x = \frac{1 - \tan^2(x/2)}{1 + \tan^2(x/2)}$

2. Replace $1 + \tan^2(x/2)$ in numerator with $\sec^2(x/2)$

3. Put $\tan(x/2) = t$ so that $\frac{1}{2} \sec^2(x/2) dx = dt$

4. Evaluate using standard integrals

More Irrational Integrals:

$$\int \sqrt{a^2 - x^2} dx = \frac{x}{2} \cdot \sqrt{a^2 - x^2} + \frac{a^2}{2} \sin^{-1} \left(\frac{x}{a} \right) + C$$

$$\int \sqrt{x^2 + a^2} dx = \frac{x}{2} \cdot \sqrt{x^2 + a^2} + \frac{a^2}{2} \log \left| x + \sqrt{x^2 + a^2} \right| + C$$

$$\int \sqrt{x^2 - a^2} dx = \frac{x}{2} \cdot \sqrt{x^2 - a^2} - \frac{a^2}{2} \log \left| x + \sqrt{x^2 - a^2} \right| + C$$

Correlation and Regression

Karl Pearson's Co-efficient of Correlation:

Covariance:

$$Cov(x, y) = \frac{1}{n} \sum (x - \bar{x})(y - \bar{y}) = \frac{\sum d_x d_y}{n}$$

Correlation Co-efficient:

$$\rho(x, y) \text{ or } r = \frac{Cov(x, y)}{\sigma_x \sigma_y} = \frac{Cov(x, y)}{\sqrt{\sigma_x^2 \sigma_y^2}}$$
$$\rho(x, y) \text{ or } r = \frac{\sum d_x d_y}{n \cdot \sigma_x \sigma_y} = \frac{\sum d_x d_y}{\sqrt{(\sum d_x^2)(\sum d_y^2)}}$$