## ${\bf RobotFramework\_Test suites}$

v. 0.2.2

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## Introduction

## 1.1 RobotFramework AIO testsuites management documentation

## This is the documentation for robotframework-testsuitesmanagement library

The RobotFramework\_Testsuites package works together with JsonPreprocessor Python package to provide the enhanced features such as json configuration files, 4 different levels of configuation, global parameters, schema validation, etc

This testsuites management package will support testing for many variants of product on the same Robot project by switching between different configuration files via variant name.

## Description

## 2.1 Getting Started

### 2.1.1 How to install

Firstly, clone RobotFramework\_Testsuites repository to your machine

Go to **robotframework-testsuitesmanagement**, using the 2 common commands below to build or install this package:

```
setup.py build will build the package underneath 'build/' setup.py install will install the package
```

After the build processes are completed, the package is located in **build**/, and the documents are located in **doc**/\_build/.

We can use --help to discover the options for build command, ex:

```
setup.py build
                    will build the package underneath 'build/'
setup.py install
                    will install the package
Global options:
--verbose (-v)
                   run verbosely (default)
--quiet (-q)
                    run quietly (turns verbosity off)
--dry-run (-n)
                    don't actually do anything
--help (-h)
                   show detailed help message
--no-user-cfg
                   ignore pydistutils.cfg in your home directory
--command-packages list of packages that provide distutils commands
Information display options (just display information, ignore any commands)
--help-commands
                  list all available commands
--name
                    print package name
--version (-V)
                   print package version
--fullname
                   print <package name>-<version>
--author
                   print the author's name
--author-email
                   print the author's email address
--maintainer
                   print the maintainer's name
--maintainer-email print the maintainer's email address
                   print the maintainer's name if known, else the author's
--contact
                    print the maintainer's email address if known, else the
--contact-email
--url
                    print the URL for this package
--license
                    print the license of the package
```

```
--licence
                    alias for --license
--description
                    print the package description
--long-description print the long package description
--platforms
                    print the list of platforms
--classifiers
                    print the list of classifiers
--keywords
                    print the list of keywords
--provides
                    print the list of packages/modules provided
--requires
                    print the list of packages/modules required
--obsoletes
                    print the list of packages/modules made obsolete
usage: setup.py [global_opts] cmd1 [cmd1_opts] [cmd2 [cmd2_opts] ...]
or: setup.py --help [cmd1 cmd2 ...]
or: setup.py --help-commands
or: setup.py cmd --help
```

## 2.2 Features

## 2.2.1 Using configuration files in Json format

Nowadays, Json is the leading of structuring data for exchange not only for web applications but also for other software applications. Json format is used to represent data, and become the universal standard of data exchange, that the reason we decided using Json format as configuration file for RobotFramework AIO.

Together with JsonPreprocessor package, RobotFramework\_Testsuites supports configuring RobotFramework AIO automation test project with json files which allow user adds the comments, imports params from other json files. Adding comments and importing json files are enhanced features which are developed and documented in JsonPreprocessor python package.

## 2.2.2 Define 4 levels of configuration

RobotFramework\_Testsuites management defines 4 different configuration levels, from level 1 to level 4 level 1 is highest priority, and level 4 is lowest priority:

## Level 1: Loads configuration file via input parameter of robot command

This is highest priority of loading configuration method, that means, configuration level 2 or 3 will be ignored even it is set.

This level 1 configuration is designed to force RobotFramework AIO executing with the configuration file for some purpose:

- In case the use wants to execute the robot run with specific configuration file for the particular purposes.
- User re-produces and verifies an issue or a corner case with new configuration file and doesn't want to modify the current configuration file.

User can address the json configuration file when executing robot testsuite with input parameter --variable config\_file: "<path\_to\_json\_file>"

robot --variable config\_file:"<path\_to\_json\_file>" <path\_to\_testsuite>

#### Level 2: Loads Json configuration according to variant name

This level 2 is designed for the scenario that user creates the automation testing project which running for many different variants. When trigger robot run, it will load the appropriate json configuration file.

To set RobotFrameowork AIO run with level 2, first user has to create a json file which contains different variants point to different configuration files.

For example, we create the variants\_cfg.json with content below:

```
"default": {
    "name": "<default_cfg_file>",
    "path": "<path>"
  },
  "variant_0": {
    "name": "<file_name_variant_0>",
    "path": "<path>"
  },
  "variant_1": {
    "name": "<file_name_variant_1>",
    "path": "<path>"
  },
  "variant_2": {
    "name": "<file_name_variant_2>",
    "path": "<path>"
}
```

Then the path of variants\_cfg.json file has to add as input parameter of testsuites.testsuite\_setup in Suite Setup of a testsuite.

In case of user wants to set configuration level 2 for entire RobotFrameowork test project instead of indiviual robot testsuite file, \_\_init\_\_.robot file has to be created at the highest folder of RobotFrameowork test project, and the path of variants\_cfg.json file has to be added as input parameter of testsuites.testsuite\_setup in Suite Setup of the \_\_init\_\_.robot file.

```
*** Settings ***
Library RobotFramework_Testsuites WITH NAME testsuites
Suite Setup testsuites.testsuite_setup <Path_to_the_file_variants_cfg.json>
```

### Level 3: Find the "config/" folder in current testsuite directory

Configuration level 3 is triggered only in case of level 1 and level 2 were not set.

The configuration level 3 will check in config/ folder in current testsuite directory the existence of json file which has the same name with testsuite file (ex: abc.rotbot & ./config/abc.json), then it will load this configuration file. In case there is no json file has the same name with robot testsuite file, it will check the existence of ./config/robot\_config.json then load this ./config/robot\_config.json file as configuration file.

### Level 4: Lowest priority level, it reads default configuration file

In case testsuites management library detects that configuration level 1, level 2, and level 3 are not set, the robot execution will use the configuration level 4 by default.

The default configuration file (robot\_config.json) in installation directory:

\RobotFramework\_Testsuites\Config\robot\_config.json

## 2.2.3 Access dictionary object of configuration by traditional way or using "."

User can access dictionary object which is defined in configuration file in robot test script by called \${dict}[abc][def] or \${dict.abc.def}

**Note:** In case a parameter name contains a ".", then it is not possible to use dotdict but the traditional way \${dict}[abc][def] is still working.

## CConfig.py

## 3.1 Class: dotdict

Imported by:

from RobotFramework\_Testsuites.Config.CConfig import dotdict

Subclass: dotdict

Subclass of dict, with "dot" (attribute) access to keys.

## 3.2 Class: CConfig

Imported by:

from RobotFramework\_Testsuites.Config.CConfig import CConfig

## Class: CConfig

Defines the properties of configuration and holds the identified config files.

The loading configuration method is divided into 4 levels, level1 is highest priority, Level4 is lowest priority.

Level1: Handed over by command line argument.

Level2: Read from content of json config file

```
"default": {
    "name": "robot_config.json",
    "path": ".../config/"
},
    "variant_0": {
        "name": "robot_config.json",
        "path": ".../config/"
},
    "variant_1": {
        "name": "robot_config_variant_1.json",
        "path": ".../config/"
},
    ...
}
```

 $\label{lem:according} According to the {\tt ConfigName}, Testsuites-Management package will choose the corresponding config file.$ 

".../config/" indicats the relative path to json config file, Testsuites-Management will recursively find the config folder.

Level3: Read in testsuite folder /config/robot\_config.json

 $\textbf{Level4:} \ Read\ from\ RobotFramework\ AIO\ install\ folder\ / RobotFramework/defaultconfig/robot\_config. \texttt{json}$ 

## 3.2.1 Method: loadCfg

### Method: loadCfg

This loadCfg method uses to load configuration's parameters from json files.

## **Arguments:**

• No input parameter is required

### Returns:

• No return variable

## 3.2.2 Method: updateCfg

### Method: updateCfg

This updateCfg method updates preprocessor, global or local params base on RobotFramework AIO local config or any json config file according to purpose of specific testsuite.

## **Arguments:**

• sUpdateCfgFile

/ Condition: required / Type: string

The path of json file which wants to update configuration parameters.

## Returns:

• No return variable

## 3.2.3 Method: verifyRbfwVersion

## Method: verifyRbfwVersion

This verifyRbfwVersion validates the current RobotFramework AIO version with maximum and minimum version (if provided in the configuration file).

In case the current version is not between min and max version, then the execution of testsuite is terminated with "unknown" state

## **Arguments:**

• No input parameter is required

#### Returns:

• No return variable

## 3.2.4 Method: bValidateMinVersion

### Method: bValidateMinVersion

This bValidateMinVersion validates the current version with required minimum version.

## Arguments:

• tCurrentVersion

```
/ Condition: required / Type: tuple
Current RobotFramework AIO version.
```

• tMinVersion

```
/ Condition: required / Type: tuple
The minimum version of RobotFramework AIO.
```

### Returns:

• True or False

## 3.2.5 Method: bValidateMaxVersion

## Method: bValidateMaxVersion

This bValidateMaxVersion validates the current version with required minimun version.

## Arguments:

• tCurrentVersion

```
/ Condition: required / Type: tuple
Current RobotFramework AIO version.
```

• tMinVersion

```
/ Condition: required / Type: tuple
The minimum version of RobotFramework AIO.
```

#### Returns:

• True or False

## 3.2.6 Method: bValidateSubVersion

### Method: bValidateSubVersion

This bValidateSubVersion validates the format of provided sub version and parse it into sub tuple for version comparision.

## **Arguments:**

• sVersion

```
/ Condition: required / Type: string
The version of RobotFramework AIO.
```

#### Returns:

• lSubVersion

```
/ Type: tuple /
```

## 3.2.7 Method: tupleVersion

## Method: tupleVersion

This tuple Version returns a tuple which contains the (major, minor, patch) version. (remaining content needs to be fixed and restored)

## Arguments:

```
    sVersion
    / Condition: required / Type: string
    The version of RobotFramework AIO.
```

### Returns:

```
• lVersion / Type: tuple /
```

## 3.2.8 Method: versioncontrol\_error

## Method: versioncontrol\_error

Wrapper version control error log:

Log error message of version control due to reason and set to unknown state. reason can only be "conflict\_min", "conflict\_max" and "wrong\_minmax".

## Arguments:

/ Condition: required / Type: string

### Returns:

• No return variable

# COnFailureHandle.py

## 4.1 Class: COnFailureHandle

Imported by:

from RobotFramework\_Testsuites.Keywords.COnFailureHandle import COnFailureHandle

4.1.1 Method: is\_noney

4.1.2 Method: register\_keyword\_run\_on\_failure

TBD

## CSetup.py

## 5.1 Class: CSetupKeywords

Imported by:

from RobotFramework\_Testsuites.Keywords.CSetup import CSetupKeywords

## Class: CSetupKeywords

This CSetupKeywords class uses to define the setup keywords which are using in suite setup and teardown of

robot test script.

Testsuite Setup keyword loads the RobotFramework AIO configuration, checks the version of RobotFramework AIO,

and logs out the basic information of the robot run.

Testsuite Teardown keyword currently do nothing, it's defined here for future requirements.

Testcase Setup keyword currently do nothing, it's defined here for future requirements.

Testcase Teardown keyword currently do nothing, it's defined here for future requirements.

## 5.1.1 Method: testsuite\_setup

### Method: testsuite\_setup

This testsuite\_setup defines the Testsuite Setup which is used to loads the RobotFramework AIO configuration,

checks the version of RobotFramework AIO, and logs out the basic information of the robot run.

## **Arguments:**

```
* sTestsuiteCfgFile
```

```
/ Condition: required / Type: string
```

sTestsuiteCfgFile='' and vairiable config\_file is not set Robotframework AIO will check

for configuration level 3, and level 4.

sTestsuiteCfgFile is set with a <json\_config\_file\_path> and vairiable config\_file is not set

Robotframework AIO will load configuration level 2.

### Returns:

• No return variable

## 5.1.2 Method: testsuite\_teardown

#### Method: testsuite\_teardown

This testsuite\_teardown defines the Testsuite Teardown keyword, currently this keyword does nothing.

it's defined here for future requirements.

## 5.1.3 Method: testcase\_setup

### Method: testcase\_setup

This testcase\_setup defines the Testcase Setup keyword, currently this keyword does nothing, it's defined here for future requirements.

## 5.1.4 Method: testcase\_teardown

### Method: testcase\_teardown

This testcase\_teardown defines the Testcase Teardown keyword, currently this keyword does nothing, it's defined here for future requirements.

## 5.1.5 Method: update\_config

## Method: update\_config

This update\_config defines the Update Config keyword which is using update the configuration object of RobotFramework AIO.

## **Arguments:**

• sCfgFile

```
/ Condition: required / Type: string
The path of Json configuration file.
```

## Returns:

• No return variable

## 5.2 Class: CGeneralKeywords

Imported by:

 ${\tt from\ RobotFramework\_Testsuites.} Keywords. {\tt CSetup\ import\ CGeneral} Keywords$ 

## Class: CGeneralKeywords

This CGeneral Keywords class uses to define the keywords which will be using in Robot Framework AIO test script.

Get Config keyword gets the current config object of robot run.

Load Json keyword loads json file then return json object.

In case, new robot keyword is required, it will be defined and implemented in this class.

## 5.2.1 Method: get\_config

## Method: get\_config

This get\_config defines the Get Config keyword gets the current config object of RobotFramework AIO.

## **Arguments:**

• No parameter is required

## Returns:

```
• oConfig.oConfigParams

/ Type: json /
```

## 5.2.2 Method: load\_json

## Method: load\_json

This load\_json defines the Load Json keyword which loads json file then return json object.

## **Arguments:**

• jsonfile

/ Condition: required / Type: string
The path of Json configuration file.

• level

```
/ Condition: required / Type: int Level = 1 -> loads the content of jsonfile. level != 1 -> loads the json file which is set with variant (likes loading config level2)
```

## Returns:

• oJsonData
/ Type: json /

# CStruct.py

## 6.1 Class: CStruct

Imported by:

from RobotFramework\_Testsuites.Utils.CStruct import CStruct

Class: CStruct

This CStruct class creates the given attributes dynamically at runtime.

# Event.py

7.1 Class: Event

 $Imported\ by:$ 

from RobotFramework\_Testsuites.Utils.Events.Event import Event

## 7.1.1 Method: trigger

# ScopeEvent.py

8.1 Class: ScopeEvent

Imported by:

from RobotFramework\_Testsuites.Utils.Events.ScopeEvent import ScopeEvent

8.1.1 Method: trigger

8.2 Class: ScopeStart

 $Imported\ by:$ 

from RobotFramework\_Testsuites.Utils.Events.ScopeEvent import ScopeStart

8.3 Class: ScopeEnd

Imported by:

 $from \ RobotFramework\_Testsuites. Utils. Events. ScopeEvent \ import \ ScopeEnd$ 

# $\_$ init $\_$ .py

9.1 Function: on

9.2 Function: dispatch

9.3 Function: register\_event

# LibListener.py

## 10.1 Class: LibListener

Imported by:

from RobotFramework\_Testsuites.Utils.LibListener import LibListener

## Class: LibListener

This LibListener class defines the hook methods.

- \_start\_suite hooks to every starting testsuite of robot run.
- \_end\_suite hooks to every ending testsuite of robot run.
- $\bullet$  \_start\_test hooks to every starting test case of robot run.
- \_end\_test hooks to every ending test case of robot run.

## $\_$ init $\_$ .py

## 11.1 Class: RobotFramework\_Testsuites

Imported by:

from RobotFramework\_Testsuites.\_\_init\_ import RobotFramework\_Testsuites

RobotFramework\_Testsuites is the Bosch testing library for Robot Framework. RobotFramework\_Testsuites control peripheral devices, tools and target under testing. Method: run\_keyword -------

11.1.1 Method: get\_keyword\_tags

11.1.2 Method: get\_keyword\_documentation

11.1.3 Method: failure\_occurred

11.2 Class: CTestsuitesCfg

Imported by:

from RobotFramework\_Testsuites.\_\_init\_\_ import CTestsuitesCfg

# version.py

## 12.1 Function: robfwaio\_version

Return testsuitemanagement version as Robot framework AIO version

# Appendix

## About this package:

Table 13.1: Package setup

Setup parameter	Value
Name	RobotFramework_Testsuites
Version	0.2.2
Date	18.07.2022
Description	Functionality to manage RobotFramework testsuites
Package URL	robotframework-testsuitesmanagement
Author	Mai Dinh Nam Son
Email	son.maidinhnam@vn.bosch.com
Language	Programming Language :: Python :: 3
License	License :: OSI Approved :: Apache Software License
OS	Operating System :: OS Independent
Python required	>=3.0
Development status	Development Status :: 4 - Beta
Intended audience	Intended Audience :: Developers
Topic	Topic :: Software Development

# History

0.1.0	06/2022
Initial version	on

 ${\bf Robot Framework\_Test suites.pdf}$ 

Created at 02.11.2022 - 15:16:59 by GenPackageDoc v. 0.32.0