Nasib Adriano Naimi

Swiss Citizen, born 28.08.1998

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Education		
09.2021 - Present	MSc. in Electrical Engineering & Information Technology GPA: 5.63/6 Eidgenösische Technische Hochschule Zürich (ETH Zürich) Specialising in Signal Processing and Machine Learning.	Zurich, CH
09.2017 - 09.2021	BSc. in Electrical Engineering & Information Technology GPA: 5.33/6 Eidgenösische Technische Hochschule Zürich (ETH Zürich)	Zurich, CH
Experience		
10.2021 - Present	Research Assistant - Autonomous Systems Lab ETH Zurich • 30% employment to improve the DroGone prototype for a Demo for NATO SPS	Zurich, CH
02.2022 - 06.2022	Teaching Assistant - Networked Systems Group ETH ZurichFor the course Communication Networks taught by Prof. Laurent Vanbever	Zurich, CH
03.2021 - 09.2021	 Co-Founder - DroGone Integrated and developed algorithm for fusion of mmWave sensor and RGB camera. Integration of mobile hardware accelerator. Co-developed multicopter detection algorithm based on YoloV4 architecture. Secured financing of CHF 140'000+ for R&D of drone-catching drone. 	Zurich, CH
Publications		
11.2022	 Multi-robot System for Autonomous Cooperative Counter-UAS Missions: Design, Integration and Field Testing Propose the use of a multi-robot system for autonomous and cooperative counter-UAS missions with acompanying field experiments. Published in Main Conference as Oral Presentation, SSRR 2022. 	SSRR 2022
07.2022	 Adversarial Defense in Self-Supervised Vision Transformers Research for the course Deep Learning Fall 2021 offered at ETH Zurich. Grade: 6/6. Explored the emerging properties of adversarial attacks on vision transformers trained using DINO and defense strategies. Published in the workshop New Frontiers in Adversarial Machine Learning, ICML 2022. 	ICML 2022
Projects		
11.2022 - Present	 Safe Reinforcement Learning Python, JAX, Git Semester project with Prof. Andreas Krause at the Learning and Adaptive Systems Lab of ETH Zurich Formulating and implementing novel algorithm for safe exploration in reinforcement learning to enable safe adaptation in sim2real problems. 	
10.2020 - 03.2021	 Reinforcement Learning for Landing Python, PyTorch, Unreal Engine, Git Site Detection Semester project with Prof. Roland Siegwart at the Autonomous Systems Lab of ETH Zurich titled Reinforcement learning for implicit Landing Site Detection and Autonomous Landing of MAVs. Trained a reinforcement learning agent in an Unreal Engine environment. Studied the feasibility of reinforcement learning for landing an autonomous aerial robot in unknown settings using RGB image information. Grade: 5.75/6. 	
09.2019 - 09.2020	Focus Project DroGone C++, ROS, Python, Git • A one year long student project offered by ETH Zurich and industry partners.	

Worked with Prof. Roland Siegwart to build an autonomous drone-catching drone.
Co-lead of the software team. Developed tracker based on Extended Kalman Filters.

- Acquired 5 sponsors (cantonal police department of Zurich, Aurora Aerospace).
- Achieved a grade of 5.75/6.

Activities

09.2018 - 12.2020 **Vice P**

Vice President of External Relations - Unicorn Labs

Zurich, CH

- A non-profit helping entrepreneurs build MVPs in a hackathon-like setting.
- Initiated the Rainbow Road challenge: Challenge for students to pitch their idea for the chance to win a MVP building session. Acquired 4 partners and sponsors.
- Facilitated or participated in 5 hackathons, generating CHF 10'000+ in revenue.

09.2018 - 06.2019

Committee Member Finance Team - ETH Entrepreneur Club

Zurich, CH

• Maintained relationships with corporate sponsors. Assisted in operations for events.

Competitions

11.2022

Junction 2022 | 2nd Place - Crypto Trading Helper

Espoo, FI

- Competed in the largest hackathon in Europe with 1300 participants.
- Implemented AI powered indicators to enhance algorithmic trading of cryptocurrencies by classified sentiment on Twitter and Kline information to predict the whether volatility, volume, or price will rise or fall.
- Runner up in the Crypto Trading Helper Challenge

02.2020

Mohammed Bin Zaved International Robotics Competition | Grand Challenge

UAE

- The <u>MBZIRC</u> is an international robotics competition between leading universities of the world. Three challenges are presented, each meant to be completed by autonomous robots.
- Worked on challenge 1: Intercept a ball attached to a drone flying in the arena with an autonomous drone.
- Participated as a part of the ETH Zurich team.

04.2016

Swiss Young Physicists Tournament (SYPT) | 2nd Place

Zurich, CH

- The <u>SYPT</u> is an annual competition where students investigate one of 16 pre-selected problems, present their findings, and defend their hypothesis in front of a jury.
- Investigated Magnetic Train: battery with magnets propels through solenoid.
- Devised experiments to determine which parameters affected the terminal velocity and acceleration and consolidated findings with theory.

Skills

Programming Languages Frameworks & Libraries Languages Python(strong), C/C++(strong), Bash, Java, HTML/CSS, LaTex Eigen, ROS, PCL, libigl, Pandas, NumPy, PyTorch, JAX, Open MPI, Open MP English(Native), German(Native), French(Fluent), Italian(Fluent), Mandarin(Basic)