

## Introduction

Randomized control trials, or natural experiments that replicate them, have become the official gold standard of empirical work in economics and many related fields. This focus on identification via experimental or quasi-experimental methods has led to the so-called “identification police” effect in many discussions of applied economics, where identification of a causal effect has become the primary qualification for a “successful” empirical study.

In response to this trend, several prominent economists have raised an alarm bell to dampen the party of the “randomistas,” emphasizing that cleanly identified counterfactual analysis is not the end goal of econometrics and that external validity should be considered equally important (Shadish, T. D. Cook, and D. T. Campbell 2002, Heckman 2008, Deaton 2010, Manski 2013, Deaton and Cartwright 2018).

One concern is that this focus on counterfactual identification comes at the detriment of the other parts of the process of scientific induction needed to build knowledge that can be applied by policy makers. Heckman (2008) worries that “this emphasis on randomization or its surrogates, like matching or instrumental variables, rules out a variety of alternative channels of identification of counterfactuals from population or sample data.” Similarly, Deaton and Cartwright (2018) worry that “the lay public, and sometimes researchers, put too much trust in RCTs over other methods of investigation.”

Banerjee and Snowberg (2016) echo the need for more formal systems for the external validity of experimental studies, saying “it is our belief that creating a rigorous framework for external validity is an important step in completing an ecosystem for social science field experiments, and a complement to many other aspects of experimentation.”

Manski (2013) voices the concern that experimental studies have tended to “be silent” on the question of external validity and that “from the perspective of policy choice, it makes no sense to value one type of validity above the other. What matters is the informativeness of a study for policy making, which depends jointly on internal and external validity.”

Applied research in economics, if it is meant to be “applied” to inform policy making, must therefore deal with external validity one way or another. Internal validity, identifying counterfactual effects, is not enough. Many top researchers are concerned about a lack of a rigorous framework for external validity in much applied research.

Following up on these theoretical concerns, a small but growing literature has sprung up around empirically proving that results from promi-

nent RCT studies do not extrapolate to new contexts (Pritchett and Sandefur 2015, Gechter 2015, Allcott 2015, Bisbee et al. 2017, Rosenzweig and Udry 2019).

The purpose of the present work is to build on those results by:

1. Building context to understand the role of applied research in economics through review of the history of econometrics and scientific inference.
2. Reviewing the assumptions of the treatment effect literature to show that results from counterfactual analysis, including RCTs, cannot be expected to extrapolate in a social sciences setting.
3. Providing a framework for extrapolation, posed as a prediction problem with labeled data in a set of source domains and a specific target domain of interest in which no labeled data is available.

## Definitions

Critiques against the randomistas have focused on their preference for internal validity and tendency to completely ignore external validity. It is worth defining these terms. The most agreed upon definition seems to come from Shadish, T. D. Cook, and D. T. Campbell 2002, where they update their taxonomy of validities from T. Cook and D. Campbell 1979:

**Statistical Conclusion Validity:** The validity of inferences about the correlation (covariation) between treatment and outcome.

**Internal Validity:** The validity of inferences about whether observed covariation between A (the presumed treatment) and B (the presumed outcome) reflects a causal relationship from A to B as those variables were manipulated or measured.

**Construct Validity:** The validity of inferences about the higher order constructs that represent sampling particulars.

**External Validity:** The validity of inferences about whether the cause-effect relationship holds over variation in persons, settings, treatment variables, and measurement variables.

Many authors use the term external validity to refer to what Shadish, Cook, and Campbell separate into construct and external validity. As both are involved in generalization, and both are external to the particulars of

the sample, I will follow that abuse of terminology and refer to all the challenges of both as “external validity.”

What, then, is meant by the term “inference?”

Following from Aristotelian tradition of logic, inference is the process of reasoning and can be broken into two parts: reasoning from particulars to generals (induction) and reasoning from generals to particulars (deduction). Deduction is often recognized by Aristotle’s syllogisms, such as:

All men are mortal  
Socrates is a man  
Therefore, Socrates is mortal

Once one has induced a general law (“all men are mortal”), one can deduce facts that might otherwise not yet be apparent (“Socrates will die”). There is, of course, a natural contradiction in this process: how can one know that all men are mortal, if one did not already know that Socrates will die? In other words, how can one ever claim that “all men are mortal” until one has seen every man die?

This problem forms the foundation of David Hume’s “Problem of Induction”:

“As to past Experience, it can be allowed to give direct and certain information of those precise objects only, and that precise period of time, which fell under its cognizance: but why this experience should be extended to future times, and to other objects, which for aught we know, may be only in appearance similar, this is the main question on which I would insist” (Hume).

There are two distinct problems Hume raises, that of generalizing from one object to another (from seeing some men die to assuming all men have died) and that of generalizing from the past to the future (because all men have died, thus, all men will die). He goes on to explain that this extrapolation is only valid under strong assumptions as to the “uniformity of nature.” One must assume nature is uniform in such a way as to enable extrapolation from one object to another or from the past to the future.

R.A. Fisher framed his statistical techniques in terms of “inductive inference.” In the introduction to *The Design of Experiments* (1935), he explicitly frames his canonical book and its techniques in the terms of logicians such as Hume, arguing for the possibility of induction via statistical methods:

“it is possible to draw valid inferences from the results of experimentation... as a statistician would say, from a sample to the population from which the sample was drawn, or, as a logician might put it, from the particular to the general.” (Fisher )

Fisherian statistical inference is a tool in the process of induction that seeks to address Hume’s problem of extending experience with one object to that of similar objects. In particular, the “similar objects” to which conclusions are extended are not just similar in appearance, but rather have a distinct relationship to the experienced objects: they are the population from which the experienced objects represent a sample.

Fisher’s methodologies for significance testing relate to drawing conclusions about populations given a sample. The validity of the use of such techniques in a study falls squarely under the category of “statistically conclusion validity” in the taxonomy of Shadish, Cook, and Campbell.

Fisher’s theory of experiments (in particular, the RCT) addresses internal validity and causality. The connection between the RCT and the identification of a causal relationship comes straight from John Stuart Mill’s (1843) “method of difference” for causal discovery:

“If an instance in which the phenomenon under investigation occurs, and an instance in which it does not occur, have every circumstance save one in common, that one occurring only in the former; the circumstance in which alone the two instances differ, is the effect, or cause, or a necessary part of the cause, of the phenomenon.”

Fisher (1935) clearly had this in mind when he defended randomization, claiming that holding all other variables constant was not feasible, and thus, holding them to the same distribution, by making the assignment of treatment independent of those variables, was desirable (Rosenbaum 2005). It should be noted, however, that for the subjects of interest to Fisher, the difference between something being a “cause” or “a necessary part of the cause” was not especially important. What Fisher was essentially interested in was interventional prediction: what is the effect when one makes individual changes to the growing conditions of these plants.

Holland (1986) begins his landmark paper, before formulating the Rubin-Neyman causal model, by framing his goal:

“Others are concerned with deducing the causes of a given effect. Still others are interested in understanding the details of causal mechanisms. The emphasis here will be on measuring

the effects of causes because this seems to be a place where statistics, which is concerned with measurement, has contributions to make.”

The success of Fisher’s framework of randomization and the Rubin-Neyman causal model comes down to this razor focus in purpose: they make no claims to discover all the causes of a given effect, to discover the mechanism of the cause, or even to separate between a cause or a necessary part of a cause. They allow us to reason about counterfactuals: what would have happened, on average and in the past, had we treated our entire population rather than a randomized part of a randomized sample drawn from that population. It operationalizes Mill’s method of differences, creating a pathway to internal validity that is achievable in the real world.

The counterfactual causal model, however, provides no framework for generalizing from a specific population to a more general one or from the past to the future (Heckman 2008). In Fisher’s line of work (agriculture), neither of those shortcomings were problematic. He was able to randomly sample from the exact population (seeds of grain) to which his inferences needed to generalize.

The success of Fisher’s randomization in his field of agriculture, and the subsequent success of the Rubin-Neyman causal model in epidemiology, is in no way incidental. These are fields that deal with encapsulated biological units where agreed-upon scientific theory tells us that the relationships in these systems will be invariant to a wide degree of changes that happen in the world from one year to the next or from one country to the next.

For example, it is implicitly assumed that the growth of corn will not be affected by its expectations of how it will be cut down and processed during the harvest. Corn grows according to the properties of the soil and the sun it receives. Its growth will be independent of its destination in corn flakes or arepas, conditional on those properties. Opioids will inhibit pain in humans, regardless of their political ideology, faith in their governmental institutions, or their love of Shark Tank.

These arguments are not made explicitly, but their validity is absolutely necessary to enable the application of their findings: they create laws defined in relation to the entire range of contextual changes that one might want for prediction- and decision-making and that allows the laws to be applied deductively in a wide array of useful situations.

While the validity of these arguments is taken for granted in contained biological processes, this is simply not the case in the social sciences. This

is why Shadish, Cook, and Campbell lay out 19 different threats to construct and external validity of social science experiments. In the case of growing corn, the threats either simply do not apply or are implicitly neutralized through basic scientific understanding of plant growth.

In the case of economics, the outcomes are regularly based on individuals' decisions to consume, work, study, invest, or move. The treatments are regularly subjected to a gauntlet of mediating factors and interacting variables that are highly context-dependent and correlated across individuals in a single place and time. The population for which one wants to draw actionable inference is in the future and it is fundamentally different from the population the sample from drawn from. Arguments for external validity must be made explicit, the internal validity of a study is rarely sufficient for scientific inference in the social sciences.

## **The Danger of Informal Inference**

It might be argued that it is, and should be, up to the sound judgement and expert opinion of the policy maker to determine if a given counterfactual analysis should extrapolate to their context or not. Empirical studies only need to provide internal validity, according to this argument, as the extrapolation is done by experts who know their target domain.

This is inline with the understanding that the invariance of a law must be defined in relation to the prediction problem, as proposed by Hurwicz. However, there is a difference between using a formal statistical framework and using an informal framework of judgement. John Stuart Mill, in his —, reflects on these difference and the dangers of inferring without formal frameworks.

He begins by denying that the only process of inference consists of separately applying induction (particulars to generals) and then deduction (general law to particular context):

“All inference is from particulars to particulars: General propositions are merely registers of such inferences already made, and short formulae for making more: The major premise of a syllogism, consequently, is a formula of this description: and the conclusion is not an inference drawn from the formula, but an inference drawn according to the formula: the real logical antecedent, or premise, being the particular facts from which the general proposition was collected by induction.” (John Stuart Mill )

In other words, in the process of creating the general law, one has created a series of particular laws, and only once assured that all the particular laws are valid can one be assured of the more general law. He goes on to caution against the direct reasoning of particulars to particulars because it is informal and we are likely to bring our own biases into the process and make mistakes:

“In reasoning from a course of individual observations to some new and unobserved case, which we are but imperfectly acquainted with (or we should not be inquiring into it), and in which, since we are inquiring into it, we probably feel a peculiar interest; there is very little to prevent us from giving way to negligence, or to any bias which may affect our wishes or our imagination, and, under that influence, accepting insufficient evidence as sufficient.” (John Stuart Mill )

John Stuart Mill argues that formal procedures, such as that implied by the framework of induction and deduction, allow individuals to avoid these biases. In his world, there was no formal procedure for reasoning from particulars to particulars, but there was for reasoning from particulars to general. As such, he recommends the latter as a way to avoid biases of “wishes” and “imagination.”

In an ideal world, the research community has discovered a set of general laws that are invariant to all contexts and the policy maker can apply them, via the process of deduction, to get the desired result in their circumstance. But what if that general law has not yet been discovered? Then the policy maker must look at individual studies (particulars) and attempt to infer a prediction for the result of a similar policy in their context. This is exactly the situation that John Stuart Mill has warned is fertile ground for bias and imagination.

## **Previous Approaches to Dealing with External Validity**

Shadish, T. D. Cook, and D. T. Campbell 2002 lay out, along with their taxonomy of validities, a taxonomy of “threats” to each type of validity. While not a formal framework, per say, by creating the taxonomy they invite researchers to address each threat in turn. If a researcher is able to argue that all the threats to external validity have been addressed and protected against, then one might consider the work of generalizing to be finished.

Banerjee and Snowberg (2016) create a formal system of “speculation” to create “falsifiable claims” of research studies as an attempt to codify the

process of generalization and external validity that can be attached to any empirical study from the counterfactual paradigm. The falsifiable claims would presumably be used by other researchers to test the assumptions necessary for external validity of the original findings to hold true.

The most obvious alternative to the treatment effect approach, which addresses the problem of external validity, is that of structural economics (Heckman 2008).

(TODO: some shortcoming of structural models).

It is worth reviewing the history of structure in economics and seeing how they thought about the problem of external validity.

## **The Origins of Structure**

Economists during the same period as Fisher took a different approach to conceptualizing and thinking about the inference they were doing. Ragnar Frisch, theorizing about macro-dynamic analysis, set out several key ideas relating to the structure of a system and the autonomy of a structure (Frisch 1995). For Frisch, the “structure” of a system was all the characteristics of the phenomena that could be quantitatively described. In his macrodynamic systems, the structure is defined by a set of functional (simultaneous) equations. He then poses the question: what would happen to the system due to an arbitrary change in a single variable? To do so could imply a different “structure” than the one which the equations describe, requiring a different set of equations altogether to describe the new system.

“But when we start speaking of the possibility of a structure different from what it actually is, we have introduced a fundamentally new idea. The big question will now be in what directions should we conceive of a possibility of changing the structure?... To get a real answer we must introduce some fundamentally new information. We do this by investigating what features of our structure are in fact the most autonomous in the sense that they could be maintained unaltered while other features of the structure were changed... So we are led to constructing a sort of super-structure, which helps us to pick out those particular equations in the main structure to which we can attribute a high degree of autonomy in the above sense. The higher this degree of autonomy, the more fundamental is the equation, the deeper is the insight which it gives us into the way in which the system functions, in short, the nearer it comes



to being a real explanation. Such relations form the essence of 'theory'."

This concept, that of "the essence of theory" being the discovery of some relationship that is autonomous and invariant to a great degree of changes we can imagine performing to a system, is taken up by Trygve Haavelmo (1944), who writes that:

"The principal task of economic theory is to establish such relations as might be expected to possess as high a degree of autonomy as possible."

He then goes on to consider a distinction between the "invariance" of a relationship under hypothetical changes in structure versus the "persistence" of a relationship under observed changes in structure:

"...if we always try to form such relations as are autonomous with respect to those changes that are in fact *most likely to occur*, and if we succeed in doing so, then, of course, there will be a very close connection between actual persistence and theoretical degree of autonomy."

This implies a connection between autonomy and the *type* of changes to which it is invariant *with respect to*. This point is made even more explicitly by Leonid Hurwicz (1966). Similar to his predecessors, his model consists of a system of equations that constrain the state of the world, given a history of states. He calls this system of equations a "behavior pattern." He states that:

"A great deal of effort is devoted in econometrics and elsewhere to attempts at finding the behavior pattern of an observed configuration... But do we really need the knowledge of the behavior pattern of the configuration?... It will be approached here from the viewpoint of prediction... That is, the word 'need' in the above question will be understood as 'need' for purposes of prediction."

He then goes on to define what he calls a "structural form" as one which is identified and identical across all possible behavior changes that one *needs* to predict within. He stresses that:

"The most important point is that the concept of structure is relative to the domain of modifications anticipated."

Thus, there is an inherent and irrevocable connection between what we consider a “law” and the degree of changes we require the law to persist across. The law is defined in relation to those changes. Following Hume, the performance of induction is always connected to a specific assumption about the uniformity of nature. Additionally, the exact way in which nature must be uniform, for a particular system under study, is defined by the predictions we need to make with the discovered relations in that system.

## Invariant Conditionals

Robert Engle, building on the work of Frisch and Hurwicz regarding invariant/autonomous structures, creates a statistical definition of what he terms “super exogeneity.” A good review of this historical evolution of autonomy can be found in Aldrich 1989.

Super exogeneity is defined by Engle as follows. Consider a model in which the “structure” (the functional form) of a relationship between outcome  $y$  and variable  $z$  is parameterized by “structural” parameters  $\lambda_1, \lambda_2 \in \lambda$ . If the joint density implied by the model can be factorized as follows:

$$P(y, z, \lambda) = P(y|z, \lambda_1)P(z|\lambda_2)$$

and the conditional,  $P(y|z, \lambda_1)$  remains invariant to changes in the marginal  $p(z)$  (presumably caused by changes in its generating process, parameterized by  $\lambda_2$ ), then  $z$  is super exogenous. This definition allows super exogeneity to be refuted by data:

“It is clear that any assertion concerning super exogeneity is refutable in the data for past changes in  $D(z, |X_{t-1}, \lambda_2)$  by examining the behavior of the conditional model for invariance when the parameters of the exogenous process changed...However, super exogeneity for all changes in the distribution of  $z$ , must remain a conjecture until refuted, both because nothing precludes agents from simply changing their behavior at a certain instant and because only a limited range of interventions will have occurred in any given sample period.”

Writing a system in terms of super exogenous variables is akin to finding Frisch’s “super-structure.” This is the part of the system that stays invariant to a set of allowable modifications, parameterized by  $\lambda_2$ . This is the part of the system that must be known in order to make policy predictions, when  $\lambda_2$  includes the changes in the policy, whose total causal effect (in the

sense of Pearl 2000) is transmitted to the output variable  $y$  through  $z$ . The existence of such an invariant super-structure is a necessary prerequisite to successfully predict the effects of policy and therefore to successfully inform policy choice from empirical data.

It should be clear that, even if such a super-structure exists, it is possible that  $z$  is either fully or partially unobserved. How will that effect the invariance? Consider again the model with a slight modification (we drop  $\lambda_1$  for ease of notation, as we are only interested in the conditions under which the conditional distribution is invariant and thus  $\lambda_1$  is static):

$$P(y, z_1, z_2, \lambda) = P(y|z_1, z_2)P(z_1|z_2, \lambda_2)p(z_2|\lambda_3)$$

Where we consider a latent variable,  $z_2$ , which is independent of the policy modification of interest,  $\lambda_2$ , and whose generating process is controlled by structural parameter  $\lambda_3$ . We can marginalize out  $z_2$  by fixing  $\lambda_3 = \ell$ :

$$P(y, z_1, z_2, \lambda_2, \lambda_3 = \ell_3) = P(y|z_1, \lambda_3 = \ell_3)P(z_1|\lambda_2, \lambda_3 = \ell_3)$$

Thus, our conditional is still invariant to modifications to  $\lambda_2$ , but it is fixed as regards the structural parameter  $\lambda_3$  which determined the distribution of the latent variable  $z_2$ . If the latent variable,  $z_2$ , was also effected by the structural parameters  $\lambda_2$ , then one would have to fix that as well in order to get an invariant conditional:

$$P(y|z_1, \lambda_2 = \ell_2, \lambda_3 = \ell_3)$$

It is worth considering the implications of the existence of latent variables in the super-structure that are evident evTechniques for en in this simple exercise of probability algebra:

1. If the latent variable is not independent of the set of modifications to which a relationship should be invariant ( $P(z|\lambda_2) \neq P(z)$ ), then the relationship cannot be determined generally.
2. If the latent variable is independent of the set of modifications to which a relationship should be invariant ( $P(z|\lambda_2) = P(z)$ ), then marginalizing out the latent variable results in an invariant relationship.

This requirement is proved rigorously in Pearl, Bareinboim, and Mar 2014, where they refer to a relationship as “transportable” if it is invariant across a set of modifications.

Given that  $z_2$  is latent, it might be difficult, in practice, to know whether or not it is independent of  $\lambda_2$ : one cannot directly obtain an empirical estimate of  $P(z_2)$ . What about going in the reverse direction: if one had empirical data across a set of modifications (different values of  $\lambda_2$ ) and one discovered an empirical conditional distribution  $P(y|z_1)$  that is invariant across those modifications, does that imply that  $P(z_2|\lambda_2) = P(z_2)$ ?

This method of looking in the data for a conditional distribution that is invariant to “structural” changes that lead to differences in the marginal distribution of its “inputs” has formed the basis of much recent work in statistics and machine learning around causal discovery (**peters2015**, ...).

## Problem Formulation

We consider the utility of individual  $i$  given as  $u(\pi, X_i)$ , where  $X_i$  is a set of covariates, potentially unique to the individual, and  $\pi$  some policy under question. The utility function is considered common across all individuals, but arbitrarily parameterized by individual covariates  $X_i$ , thus this assumption is non-restrictive.

The social planner’s problem consists of finding the “best” policy, where best can be defined in a number of different ways: greatest average utility, pareto optimal, least inequality, etc:

$$\pi^* = h(\pi, X)$$

Where  $h(\cdot)$  represents a function that determines the best policy given a set of policies  $\pi$  and the population covariates  $X$ . We will make two assumptions to make this problem tractable for our framework:

1. We replace the utility function,  $u(\cdot)$ , with a surrogate outcome  $Y(\cdot)$  of interest to the social planner. The surrogate is considered linear separable into two parts:

$$Y(\pi, X) = Y_1(\pi, Z) + Y_2(W)$$

Where  $Z \cup W = X$ .

2. In comparing two policies, a policy maker can pick one based solely on the individual differences in outcomes between the two policies:

$$\pi^* = h(Y(\pi_1, Z_1) - Y(\pi_0, Z_1), \dots, Y(\pi_1, Z_N) - Y(\pi_0, Z_N))$$

When  $\pi = \{\pi_0, \pi_1\}$ .

The first assumption is non-restrictive, as  $W$  can be null. The second assumption is a restriction on the type of policy objectives the social planner can pursue, however many naturally desirable objectives can still be pursued in realistic scenarios<sup>1</sup>.

Finally, we will restrict our policy space,  $\pi$ , to one of finite policies<sup>2</sup> and, without loss of generalization, consider the situation of two policies,  $\{\pi_0, \pi_1\}$ , where  $\pi_0$  can be thought of as the null policy, or control, and  $\pi_1$  the treatment under question. This allows us to rewrite:

$$\pi^* = h(\tau_1, \dots, \tau_n)$$

Where  $\tau_i := Y(\pi_1, Z_i) - Y(\pi_0, Z_i)$ , the individual treatment effect of the policy. At the point in time in which the social planner is deciding on a policy,  $\tau_i$  is unknown and can be formulated as a random variable.

Consider  $\hat{P}(\tau_i|X, \lambda = \lambda_T)$  to be a predictive probability distribution of the treatment effect of the policy on individual  $i$  in a target context (domain) described by  $\lambda = \lambda_T$ <sup>3</sup>. The planner knows the covariates for each individual,  $X_i$ , and estimates the predictive probability distribution via a prediction function,  $f(\cdot)$ , trained on a set of 4-tuples,  $(Y_i, X_i, \pi_i, \lambda_i)$  where  $\lambda_i \in \Lambda_S$  and  $\Lambda_S$  consists of a series of domains in which the policy maker has labeled data and  $\lambda_T \notin \Lambda_S$ . Thus, the decision function that picks the “best” policy must now accept probability distributions:

$$\pi^* = h(\hat{P}(\tau_1|X, \lambda_T), \dots, \hat{P}(\tau_n|X, \lambda_T))$$

The treatment effect can be reasonably replaced by its expectation,  $\mathbb{E}[\tau_i|X, \lambda_T]$ , if the policy objective is maximizing average (or total) welfare. If the policy objective incorporates any sort of aversion to negative outcomes (“let’s not completely ruin any of our citizens’ lives”), risk aversion, or concerns about pareto efficiency, then the expectation of this random variable will not be sufficient information to pick the best policy  $\pi^*$ .

<sup>1</sup>The decision maker can directly pursue the greatest average utility and objectives based on pareto optimality, but cannot directly pursue least inequality, as an example. In realistic scenarios, however, reduction of inequality can be pursued via the maximization of utility (likely replaced with income) for those who currently are in the lowest x% and minimization of income for those who are currently in the highest y%, assuming that the class of policies,  $\pi$  is reasonable enough so that one doesn’t accidentally flip the relationship and maintain the inequality!

<sup>2</sup>Considering continuous policy spaces should be considered of great interest. This restriction is done to simplify the problem here, not because it is necessarily desirable. Embedding policies into continuous spaces is, additionally, not a solved problem and is a natural prerequisite to such a formulation being useful in practise.

<sup>3</sup>The parameter  $\lambda$  is the same as  $\lambda_2$  in Engle’s formulation. We drop the subscript for ease of notation here.

We will assume that every policy object can be translated into a loss function that aligns with the decision strategy  $h(\cdot)$ :

$$\ell(\tau, \hat{P}(\tau|X, \lambda_T))$$

Unfortunately, this loss function is technically impossible to calculate, even after the fact, due to Rubin’s “fundamental problem of causal inference”, the fact that  $\tau_i$  is unobserved. While the formulation and minimization such a specific loss function would be desirable in the case of different policies, I will, for this article, pose a general formulation that will asymptotically minimize any reasonable loss function: the existence of a consistent estimator for  $P(\tau|X)$  such that

$$\hat{P}(\tau|X, \lambda \in \Lambda_S) \rightarrow P(\tau|X, \lambda = \lambda_T)$$

Such an estimator can be created if we have the following two conditions:

1. There exists a consistent estimator  $\hat{P}(\tau|X, \lambda = \lambda_S) \rightarrow P(\tau|X, \lambda = \lambda_S)$  for any single domain defined by  $\lambda_S$ .
2.  $P(\tau|X, \lambda_S) = P(\tau|X) \forall X, P(X|\lambda_T) > 0$ . The conditional is invariant across the differences that exist between the source domains and the target domain, within the support of the target domain.

It should be noted that this general framework works for any predictive output that might be used in the policy choice. Thus, if the policy choice relies only on the average treatment effect,  $h(\mathbb{E}[\tau|X, \lambda_T])$ , then one only needs a consistent estimator for  $\mathbb{E}[\tau|X, \lambda_S]$  and that the estimator is invariant across domains,  $\mathbb{E}[\tau|X, \lambda_S] = \mathbb{E}[\tau|X]$ , in order to have a consistent estimator that will asymptotically minimize the loss function related that policy choice.

## Quantile Treatment Effects

rank preservation, if not, it might in and of itself be of interest to the policy maker, see blah for discussion

We will apply this observation, that a QTE defined in this way is identical to the individual QTE with an assumption of rank preservation, and calculate the latter directly. Within each leaf, we will preserve the rank of the individuals and calculate the difference. Extra individuals in either group are compared to their closest match from the other group.

## Picking causal covariates vs. creating them

Often the direct causes of the outcome in consideration are not observed. They are, as such, latent variables. These latent variables might be proxied by an observable (cause) or be caused by an observable. The two factors have very different effects:

$P(X|Z)$  should be invariant in the case where the latent variable causes its observable proxy, thus, for the transformation to go from  $\hat{Z} = f(X)$ , it is  $f^{-1}$  that must be invariant across domains, requiring a generative model of  $X$  from the latent variables to be learned.

On the contrary, if  $P(Z|X)$  is invariant, then a model which generates the latent variables which in turn cause the effect,  $Y$ , must be invariant. It should be noted that  $P(Z)$  is not needed to be constant across domains, as long as the two conditionals can be recovered.

## Forests as Nonparametric Estimator of the Conditional Treatment Effect Distribution

Quantile treatment effect with the assumption of rank persistence.

It follows that any consistent estimator of ATE is an consistent estimator of quantiles and the distribution as well.

Causal forests are a consistent estimator of ATE ()

Random forests are a consistent estimator of the full distribution ()

## Distributional Invariance Across Domains

Peters, Bühlmann, and Meinshausen 2015 develop a technique where, given an outcome variable  $Y$ , and given the assumption that there exists a conditional distribution of that outcome variable that is invariant across domains ( $P(Y|X^*, \lambda) = P(Y|X^*)$ ) for some set of covariates  $X^* \in X$ , where  $X$  is a set of potential covariates that have been measured, one can discover the subset  $X^*$  by exploiting the invariance of the conditional distribution. They do this by representing the conditional distribution by a function  $g(X)$ , parameterizing the function, and looking for a set of invariant parameters across the domains.

Rojas-Carulla, Schölkopf, and Turner 2018 propose a similar idea, but modify it in two ways which we will follow:

1. They use the formulation of Domain Adaptation to frame the problem and measure the effectiveness of their technique.

2. They consider the invariance of the conditional to its domain through an independence test between the conditional distribution and the index label of the domain:  $P(Y|X^*, \lambda) = P(Y|X^*)$ . Where  $\lambda \in \{1, 2, \dots, S\}$  for  $S$  source domains.

heinz-deml proposes a similar solution to the problem of domain adaptation in image recognition. Using a series of images in which the same individual, with the same causal characteristics, is captured across multiple domains where orthogonal changes take place. A regularization term is added to the optimization problem of the neural network trained on the source domains. The term penalizes the conditional variance...

Much of the domain adaptation literature from machine learning focuses on the case where covariate shift holds. Covariate shift describes the situation where  $P(Y|X)$  is assumed to be consistent and  $P(X)$  is changing across domains. As we are in the situation of discovering the  $x \in X$  which is causal for  $Y$ , we cannot simply make that assumption. Many of the techniques in domain adaptation, however, are developed for situations in which the model is learned on a latent space, thus the reweighting of  $X$  consists of a transformation and checking of distributional differences between source domains. One technique for minimizing distances between distributions is that of minimizing the Wasserstein distance. This distance measure has grown in popularity recently due to its advantageous qualities for optimization: it maintains a gradient even when distributions lack mutual positive support. Thus, the gradient is computable even when distributions are very different from one another.

These two ideas can easily be combined, that of Wasserstein distance minimization for enforcing distributional similarity and that of regularization of the conditional differences to enforce domain-invariant conditionals.

Thus, the optimization problem will contain a regularization term:

$$R(\cdot) = \sum_{i,j \in S} W(P(\tau|X_i, \lambda_i), P(\tau|X_j, \lambda_j))$$

Which sums the pairwise Wasserstein distance,  $W(\cdot)$ , of the conditional treatment effect distribution across different domains,  $S$ .

Each split seeks to minimize the variance of the treatment effect ,

## Targeted Forests

My methodology can be considered an extension of Causal Forests (), where the objective function of node splitting is augmented by an additional reg-



ularization term that penalizes dependence of the conditional treatment distribution across environments during training time.

Additionally, the splits are not created so as to minimize the loss function across both leafs, but rather are “targeted” in that they only minimize the loss function in the leafs where observations from the target distribution fall. Thus, areas of the covariate space,  $p(X)$  outside of the support of the target domain are ignored.

Traditional forests, Causal forests included, are meant to be “generic predictors.” That is to say, after being trained on a set of labelled  $(X, Y)$  data, they will make a prediction,  $\hat{Y}$  for *any* new data point,  $X_i$  that is given to them. This is true for many generic correlation algorithms that are not designed for domain adaption: they are trained on a  $P(X, Y)$  and meant to predict on that same joint distribution, thus the training attempts to minimize some loss function across the entire support of the training distribution.

Targeted trees, on the other hand, is a prediction algorithm meant to predict in a new, known domain. The data points,  $X_i$ , for which the outcome is predicted are known at training time. This allows us to ignore parts of the distribution from our training data that is not on the support of the target domain. This ensures that the invariant distribution is, in particular,  $P(Y|X_T)$  rather than  $P(Y|X_S)$ .

## Empirical Performance

Data consists of 5 recent RCT studies performed on the impact of micro-credit programs on business profit and consumption in developing countries.

With 5 different domains, I test my method by training on 4 source domains and predicting on the 5th. Results are compared with the estimated ATE implied by the studies, as well as with a “baseline” prediction using the coefficient of the CATE as estimated by a linear model in a single domain, comparable to coefficients reported in the original studies.

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