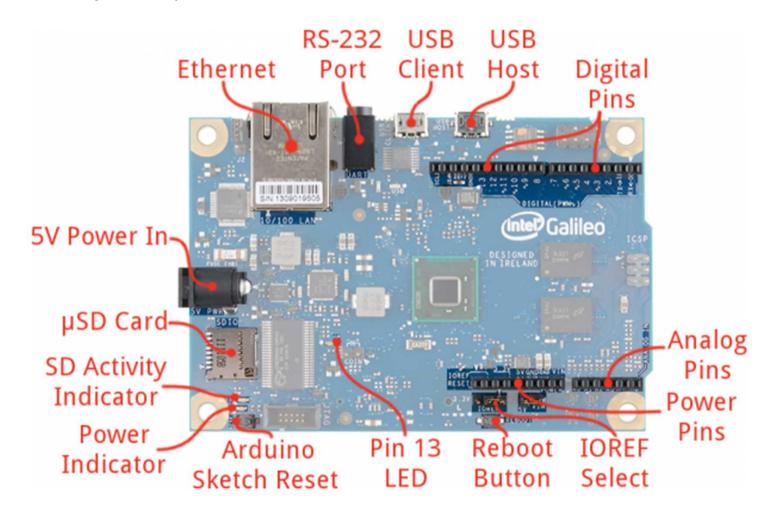
Arquitetura II

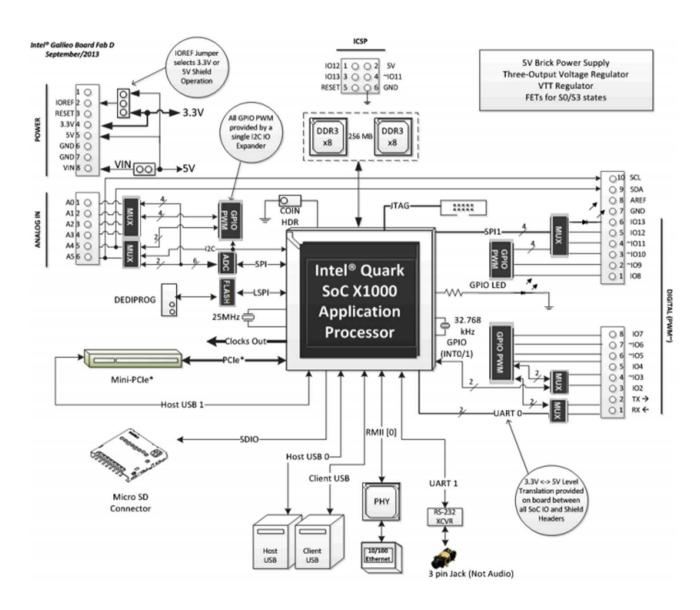
Galileo: Hardware e Ambiente de desenvolvimento

SOC Intel Quark



Localização componentes do hardware

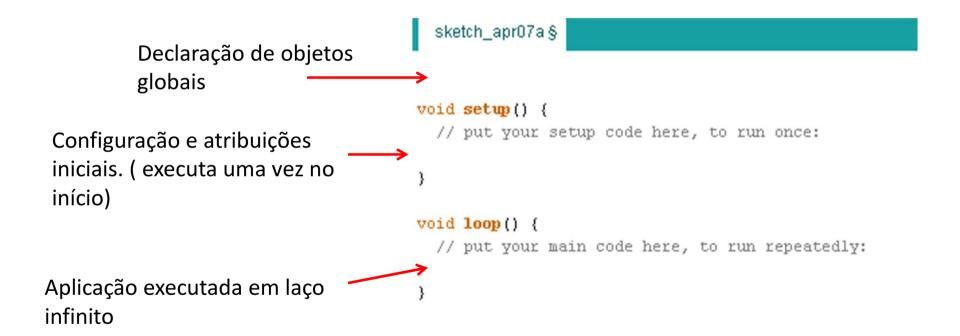




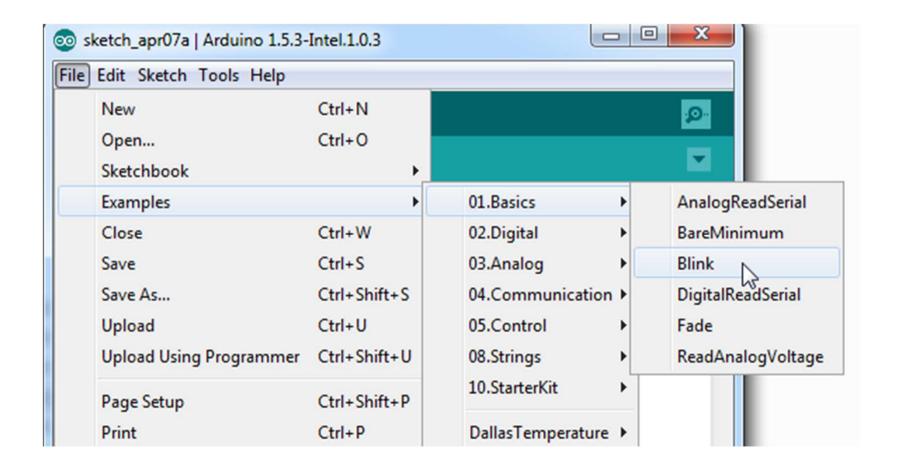
Ambiente de desenvolvimento Arduino

```
- - X
sketch_apr07a | Arduino 1.5.3-Intel.1.0.3
File Edit Sketch Tools Help
  sketch_apr07a
void setup() {
  // put your setup code here, to run once:
void loop() {
  // put your main code here, to run repeatedly:
                                                    Intel® Galileo on COM4
```

Estrutura de projeto/código



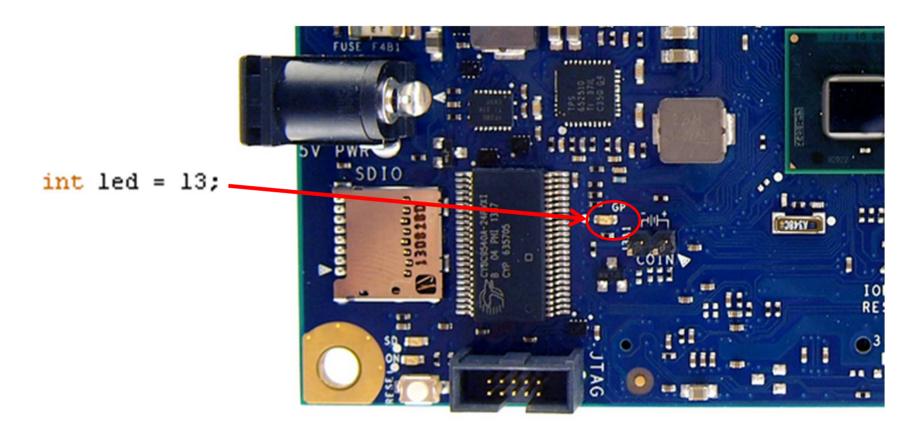
Aplicação 01 – "Hello World"



Aplicação 01 – "Hello World"

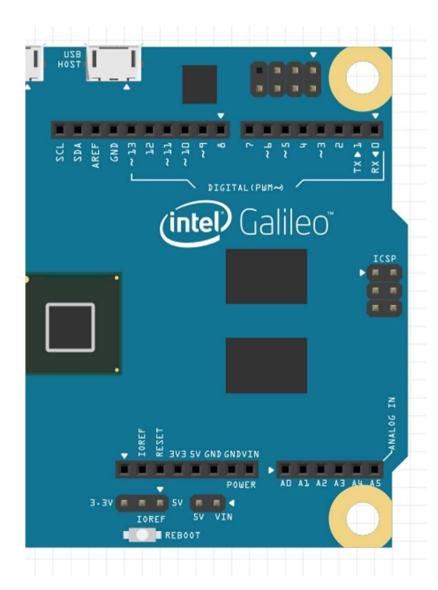
```
// Pin 13 has an LED connected on most Arduino boards.
// give it a name:
int led = 13;
// the setup routine runs once when you press reset:
void setup() {
  // initialize the digital pin as an output.
 pinMode(led, OUTPUT);
// the loop routine runs over and over again forever:
void loop() {
  digitalWrite(led, HIGH); // turn the LED on (HIGH is the voltage level)
                     // wait for a second
  delay(1000);
  digitalWrite(led, LOW); // turn the LED off by making the voltage LOW
                         // wait for a second
  delay(1000);
```

Aplicação 01 – "Hello World"

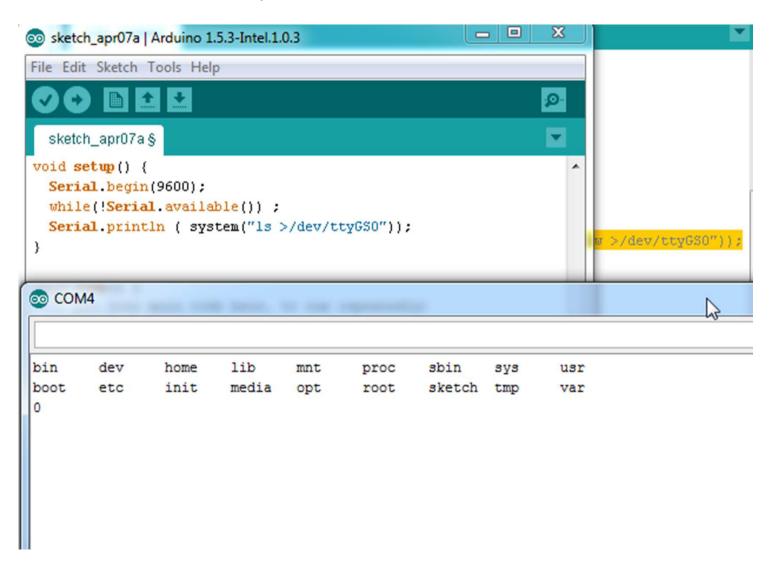


pinMode(led, OUTPUT);

Entradas e Saídas

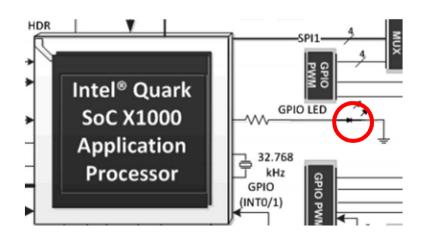


Ambiente Arduino: system



Acesso a E/S via Linux Sysfs

echo -n "3" > /sys/class/gpio/export echo -n "out" > /sys/class/gpio/gpio3/direction echo -n "strong" > /sys/class/gpio/gpio3/drive echo -n "1" > /sys/class/gpio/gpio3/value



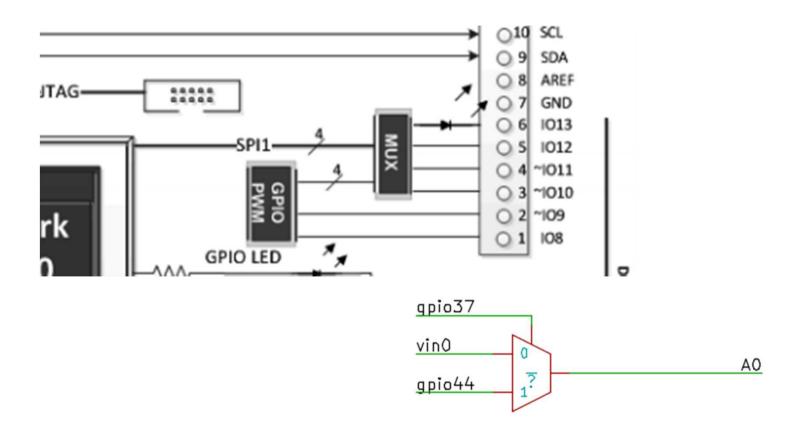


Acesso a E/S via Linux Sysfs

```
void setup() {
   system ("echo -n \"3\" > /sys/class/gpio/export");
   system("echo -n \"out\" > /sys/class/gpio/gpio3/direction");
   system("echo -n \"strong\" > /sys/class/gpio/gpio3/drive");
   system("echo -n \"1\" > /sys/class/gpio/gpio3/value");
}

void loop() {
   // put your main code here, to run repeatedly:
}
```

Pinos de E/S multiplexados



Desafio: Controlar o pino 13 como saída

