

A Preliminary Study on Preference Elicitation in DCOPs for Scheduling Devices in Smart Buildings

**Atena M. Tabakhi
Ferdinando Fioretto
William Yeoh**

New Mexico State University

July 9, 2016



Home Automation

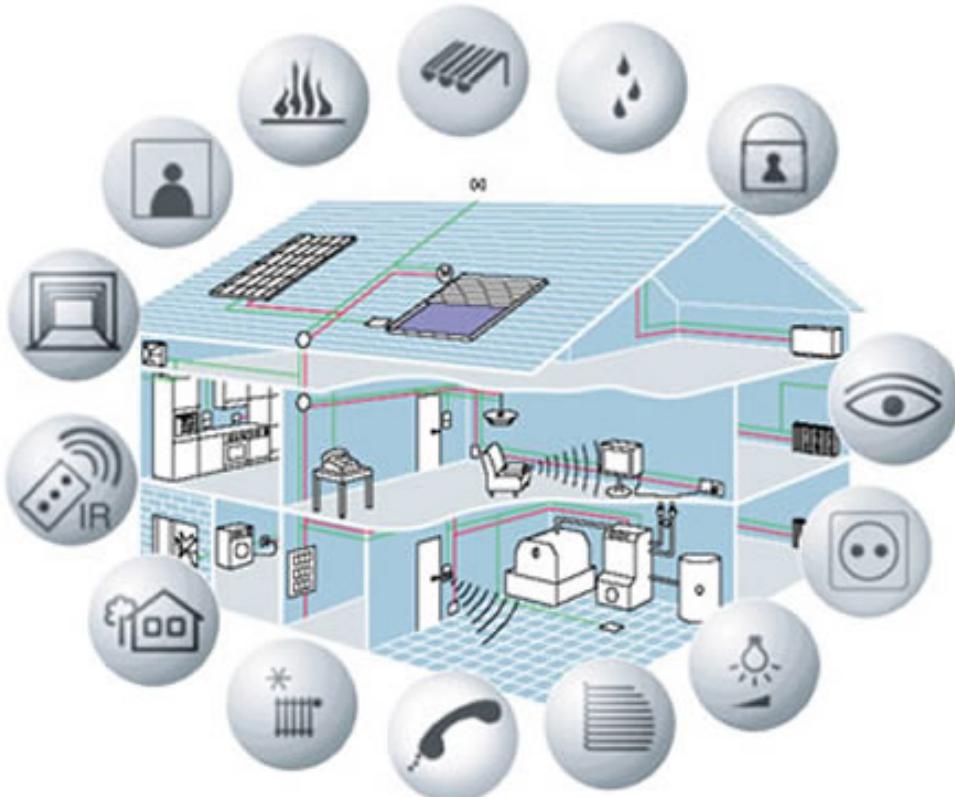


Fig.1



Fig.2

The culture of impatience



Fig.3



Fig.4



Fig.5

Network of smart buildings

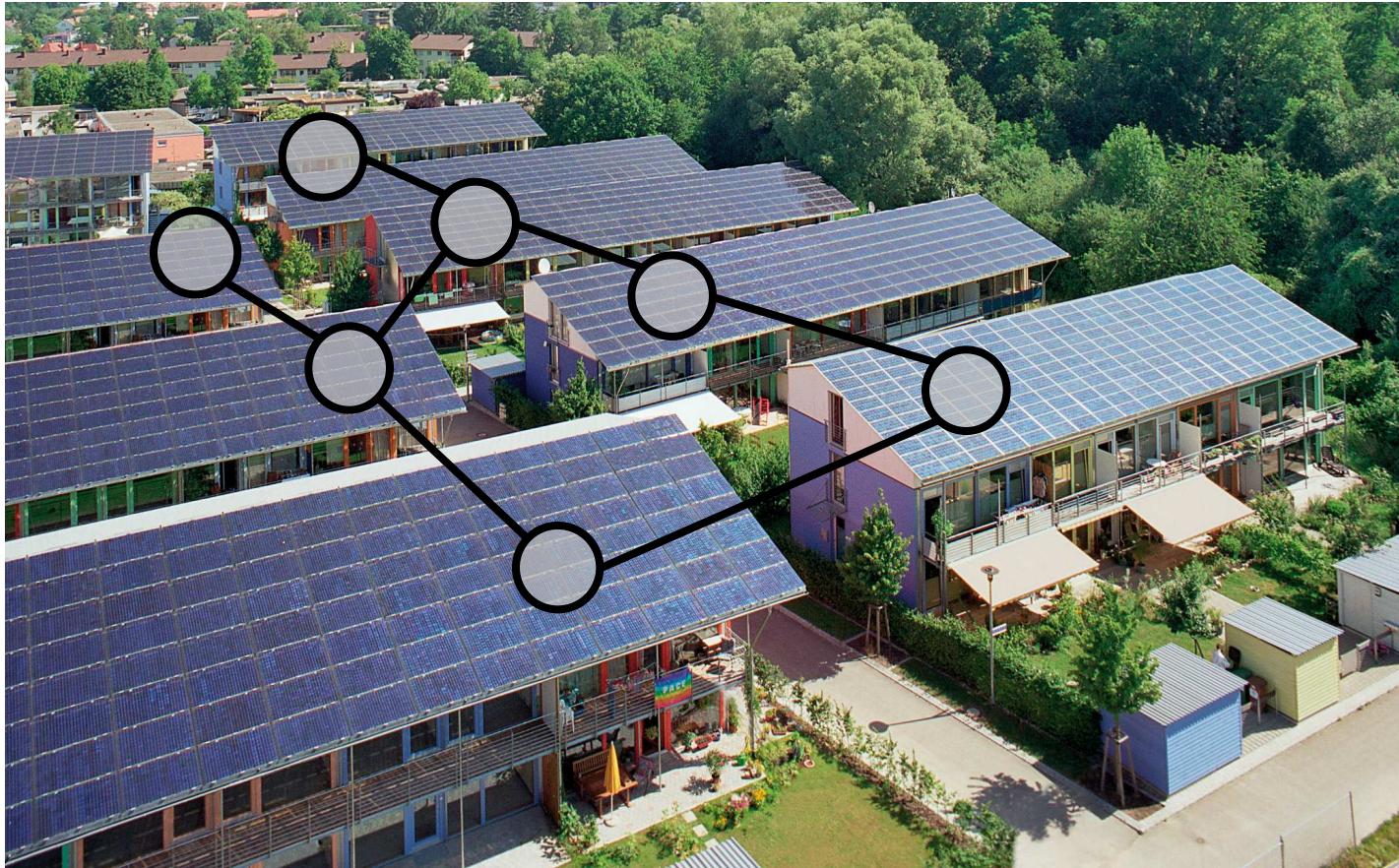


Fig.6

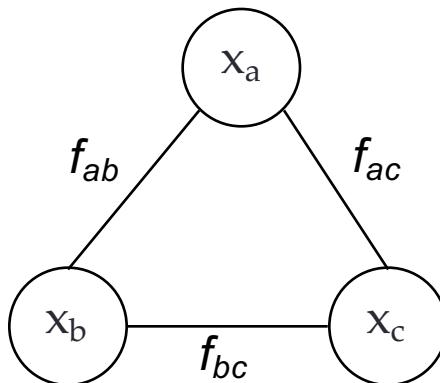
Outline

- Background (DCOPs)
- Smart Building Device Scheduling (SBDS)
- Preference Elicitation in DCOPs
- Preliminary Results
- Conclusions and Future work

Distributed Constraint Optimization

$\langle \mathcal{X}, \mathcal{D}, \mathcal{F}, \mathcal{A}, \alpha \rangle$:

- \mathcal{X} : Set of variables.
- \mathcal{D} : Set of finite domains for each variable.
- \mathcal{F} : Set of constraints between variables.
- \mathcal{A} : Set of agents, controlling the variables in \mathcal{X} .
- α : Mapping of variables to agents.



Constraint graph

x_a	x_b	cost
0	0	3
0	1	∞
1	0	2
1	1	5

Constraint (cost table)

Distributed Constraint Optimization

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- \mathcal{A} : Set of agents, controlling the variables in \mathcal{X} .
- α : Mapping of variables to agents.
- **GOAL**: Find a cost minimal assignment.

$$\begin{aligned}\mathbf{x}^* &= \arg \min_{\mathbf{x}} \mathbf{F}(\mathbf{x}) \\ &= \arg \min_{\mathbf{x}} \sum_{f \in \mathcal{F}} f(\mathbf{x}|_{\text{scope}(f)})\end{aligned}$$

DCOP: Assumptions

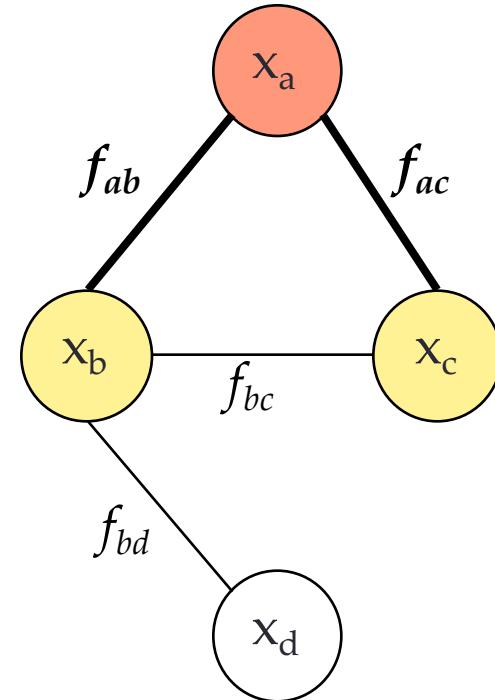
- Agents coordinate an assignment for their variables.
- Agents operate distributedly.

Communication:

- By exchanging messages.
- Restricted to agent's local neighbors.

Knowledge:

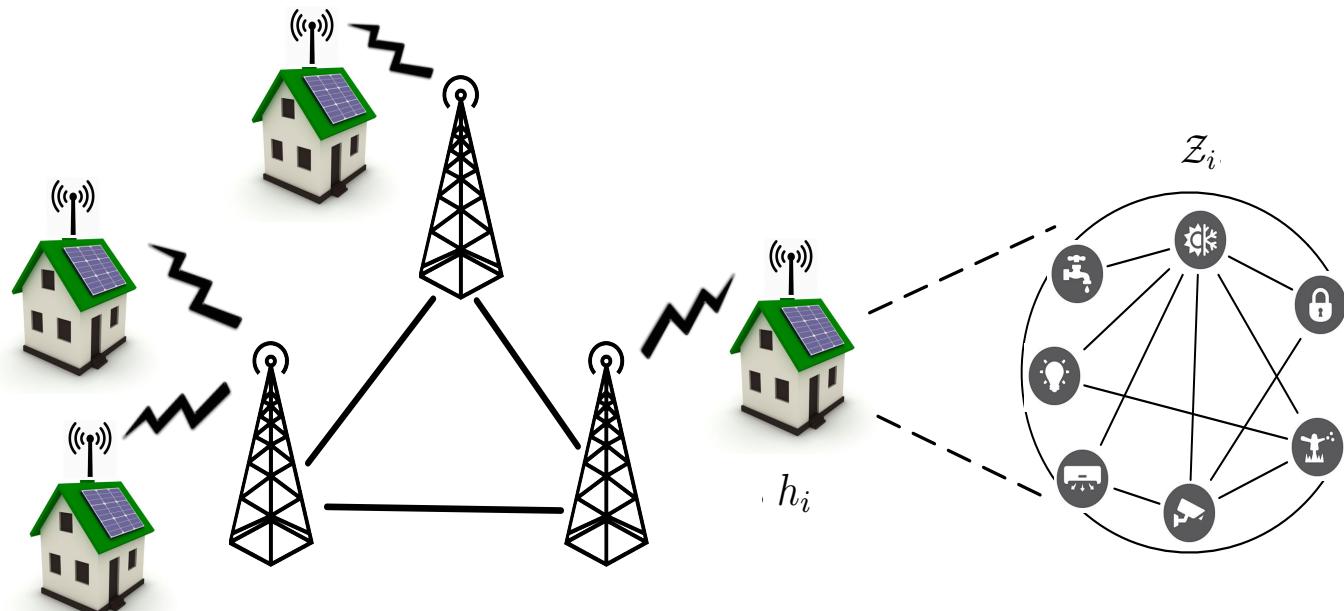
- Restricted to agent's sub-problem.
- Privacy preserving.



Smart Building Device Scheduling (SBDS)

A SBDS problem is composed of:

- \mathcal{H} : A neighborhood of smart buildings.
- Z_i : A set of smart electric devices within each building h_i .
- H : A time horizon for the device scheduling.

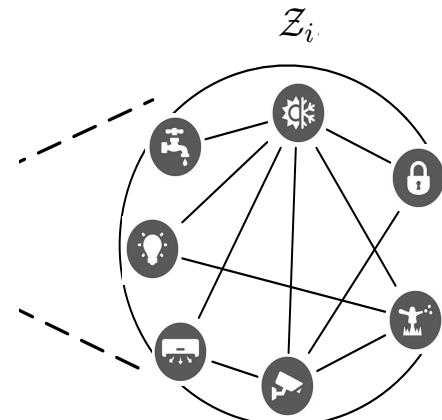


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Device	Power (kWh)	Duration (min.)
dish washer	0.75	120
washing machine	1.20	90
dryer	2.50	60
cooker hob	3.0	30
cooker oven	5.0	30
microwave	1.70	30
laptop	0.10	120
desktop computer	0.30	180
vacuum cleaner	1.20	30
fridge	0.30	360
electrical vehicle	3.50	180



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- θ : A pricing function expressing cost per kWh of energy consumed.

Time (min.)	[0-60]	[60-120]	[120-180]	[180-240]	[240-300]	[300-360]
RTP (\$/kWh)	0.172	0.161	0.191	0.145	0.149	0.174

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Preferences:

users express their discomfort for scheduling a device at a given time.



Smart Building Device Scheduling (SBDS)

- SBDS objective:

$$\text{minimize} \quad \sum_{t \in \mathbf{T}} \sum_{h_i \in \mathcal{H}} \alpha_c \cdot C_i^t + \alpha_u \cdot U_i^t$$

monetary cost of h_i schedule at time t

discomfort for the h_i schedule at time t

subject to:

$$1 \leq s_{z_j} \leq T - \delta_{z_j} \quad \forall h_i \in \mathcal{H}, z_j \in \mathcal{Z}_i$$

$$\sum_{t \in \mathbf{T}} \phi_{z_j}^t = \delta_{z_j} \quad \forall h_i \in \mathcal{H}, z_j \in \mathcal{Z}_i$$

$$\sum_{h_i \in \mathcal{H}} P_i^t \leq \ell^t \quad \forall t \in \mathbf{T}$$

Smart Building Device Scheduling (SBDS)

- SBDS objective:

$$\text{minimize} \quad \sum_{t \in \mathbf{T}} \sum_{h_i \in \mathcal{H}} \alpha_c \cdot C_i^t + \alpha_u \cdot U_i^t$$

subject to:

start time

duration

$$1 \leq s_{z_j} \leq T - \delta_{z_j} \quad \forall h_i \in \mathcal{H}, z_j \in \mathcal{Z}_i$$

$$\sum_{t \in \mathbf{T}} \phi_{z_j}^t = \delta_{z_j} \quad \forall h_i \in \mathcal{H}, z_j \in \mathcal{Z}_i$$

$$\sum_{h_i \in \mathcal{H}} P_i^t \leq \ell^t \quad \forall t \in \mathbf{T}$$

h_i load at time t

Device scheduling feasibility

Maximum total load limit

DCOP mapping

SBDS

- A building $h_i \in \mathcal{H}$.
- Start time s_{zj} for a device z_j
(in building h_i)
- Schedule costs for a device z_j
- Schedule preferences for z_j
- Device scheduling feasibility
- Maximum total power limit

DCOP

- Agent $a_i \in \mathcal{A}$
- Variable $x_i \in X$ (controlled by a_i)
with domain $D_i = \{1,..,H\}$
- Local soft constraint
- Local soft constraint
- Local hard constraint
- Global hard constraint

Preference Elicitation in DCOPs

- DCOP assumption: Cost tables are known a priori.
- Unrealistic assumption in SBDS!
- User populated cost tables expressing preferences for each device schedule.
- Lots of devices!



Preference Elicitation in DCOPs

How to effectively elicit user's preferences
asking a few questions?

- Ask for the user's input.
- Use historical data.



Preference Elicitation in DCOPs

If we could ask only k questions,
which k cost tables should be asked for user elicitation?



Preference Elicitation in DCOPs

- Uncertain DCOP: $\hat{\mathcal{P}} = \langle \mathcal{X}, \mathcal{D}, \hat{\mathcal{F}}, \mathcal{A}, \alpha \rangle$

revealed cost tables (by the user)

where: $\hat{\mathcal{F}} = \mathcal{F}_r \cup \mathcal{F}_u$

uncertain cost tables (estimated from historical data)

x_a	x_b	cost
0	0	3
0	1	1
1	0	2
1	1	5

Scalars

x_a	x_b	cost
0	0	$\mathcal{N}(\mu_0, \sigma^2_0)$
0	1	$\mathcal{N}(\mu_1, \sigma^2_1)$
1	0	$\mathcal{N}(\mu_2, \sigma^2_2)$
1	1	$\mathcal{N}(\mu_3, \sigma^2_3)$

Random variables

Preference Elicitation in DCOPs

- Oracle DCOP: $\mathcal{P} = \langle \mathcal{X}, \mathcal{D}, \mathcal{F}, \mathcal{A}, \alpha \rangle$
 - \mathcal{F} = accurate cost tables.
 - Costs are sampled from the corresponding distributions of the uncertain tables.

x_a	x_b	cost
0	0	3
0	1	1
1	0	2
1	1	5

samples

cost
$\mathcal{N}(\mu_0, \sigma^2_0)$
$\mathcal{N}(\mu_1, \sigma^2_1)$
$\mathcal{N}(\mu_2, \sigma^2_2)$
$\mathcal{N}(\mu_3, \sigma^2_3)$

Random
variables

Preference Elicitation in DCOPs

- Given an **oracle DCOP** \mathcal{P} and a value $k \in \mathbb{N}$, construct an **uncertain DCOP** $\hat{\mathcal{P}}$ that reveals exactly k constraints per agent, minimizing the error:

optimal solution for the oracle DCOP \mathcal{P}

$$\epsilon_{\hat{\mathcal{P}}} = \mathbb{E} \left[\left| \underbrace{\mathbf{F}_{\hat{\mathcal{P}}}(\hat{\mathbf{x}}^*) - \mathbf{F}_{\mathcal{P}}(\mathbf{x}^*)}_{\text{optimal solution for a realization of } \hat{\mathcal{P}}} \right| \right]$$

optimal solution for a **realization** of $\hat{\mathcal{P}}$

Preference Elicitation in DCOPs

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optimal solution for a **realization** of $\hat{\mathcal{P}}$

- Challenge:** there are $\binom{|\mathcal{F}|}{k \cdot |\mathbf{A}|}$ possible uncertain DCOPs.
- Solving each DCOP is NP-hard.
- We propose 5 **heuristics** to construct an uncertain DCOP.

Preference Elicitation Heuristics

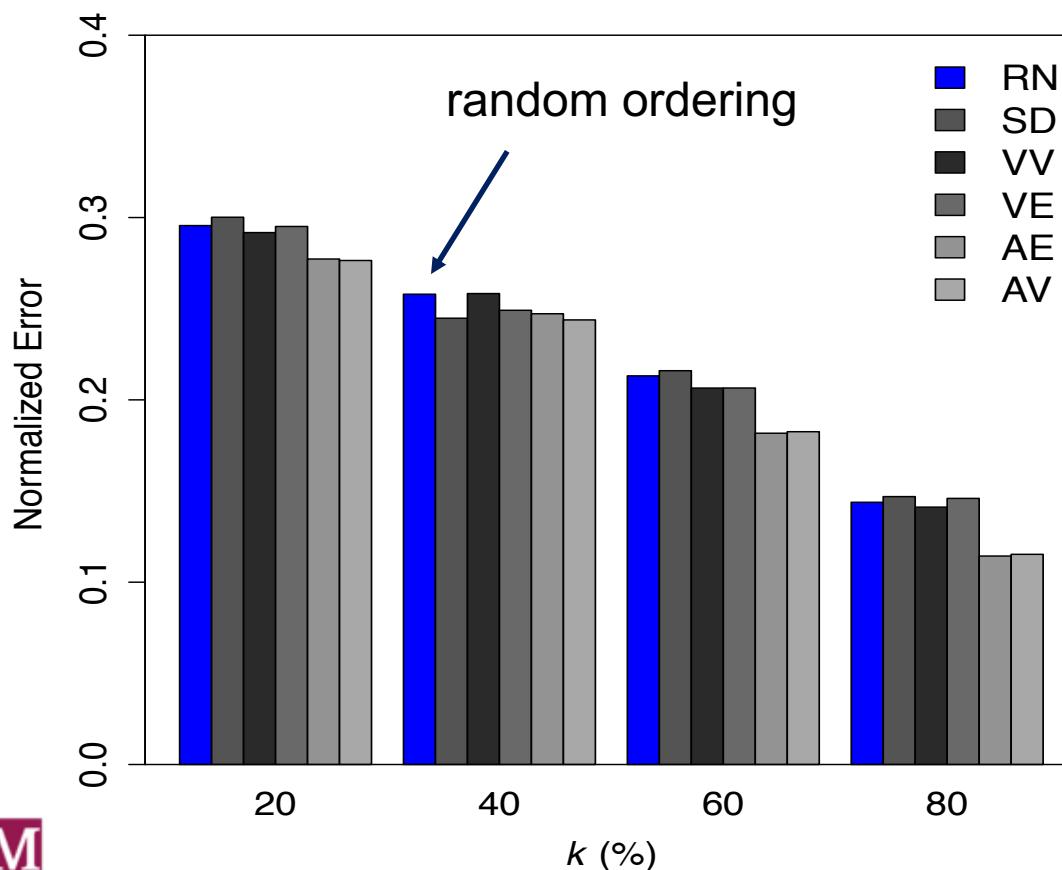
Goal: Elicit the first k cost tables, according to an ordering \preceq_{\circ} .

Heuristics to enforce an **ordering over cost tables**:

- $\geq_{[AE]}$ Average of the expected costs of the uncertain constraints.
- $\geq_{[AV]}$ Average of the variance of the uncertain constraints.
- $\geq_{[VE]}$ Variance of the expected costs of the uncertain constraints.
- $\geq_{[VV]}$ Variance of the variance of the uncertain constraints.
- $\geq_{[SD]}$ Second-order stochastic dominance: Takes into account the notion of the risk.

Evaluation

- Analysis of $\epsilon_{\hat{\mathcal{P}}}$ at the increasing of the cost tables to elicit (k).
- 50 realizations of the uncertain DCOP.
- Results are averaged over 50 oracle DCOPs.



Settings:

- $|\mathcal{H}| = 10$
- $|\mathcal{Z}_i| = 10$
- $H = 12$ (step = 30 min)
- Preferences sampled from $\mathcal{N}(\hat{\mu}, \hat{\sigma}^2)$

$\hat{\mu}$ sampled in $[1, 100]$
 $\hat{\sigma}^2$ sampled in $[1, \frac{\sqrt{\hat{\mu}}}{2}]$

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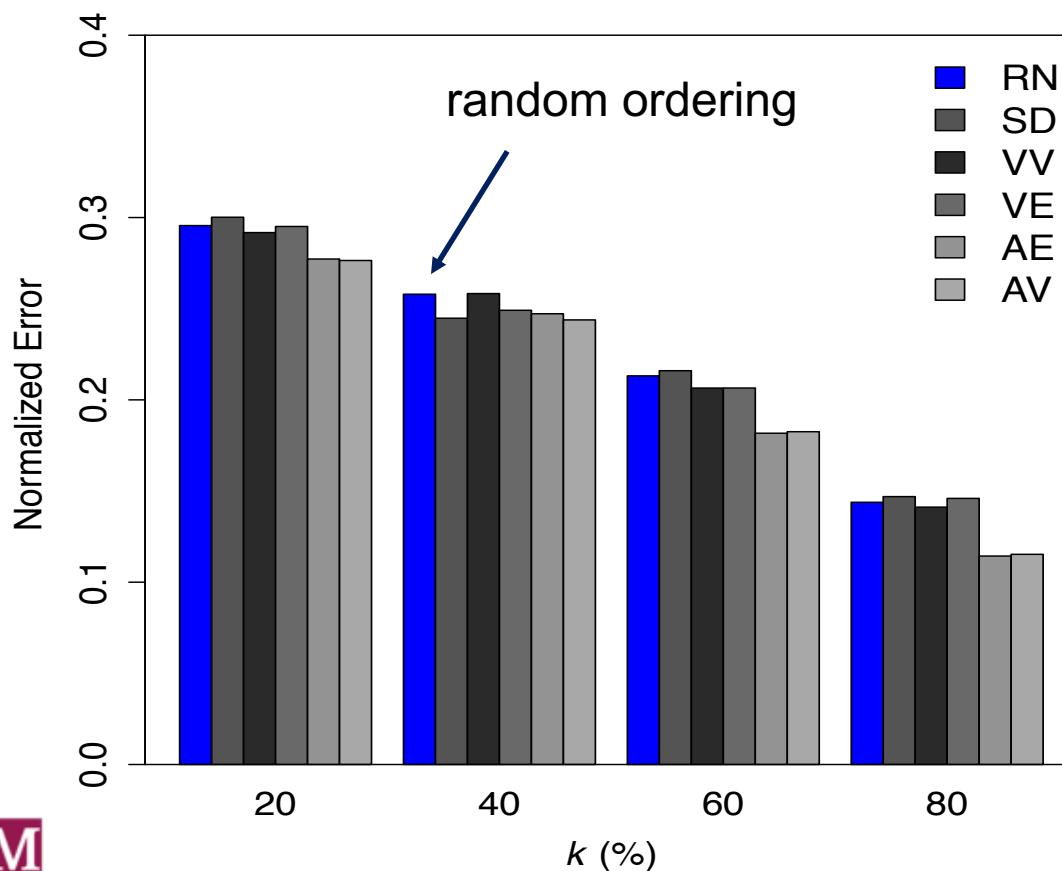
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Main Results:

1. The error decreases as the k increases.
2. AE and AV outperform other heuristics.

Conclusions and Future Work

- We studied the effect of preference elicitation in scheduling smart appliances within a network of interconnected buildings.
- We propose the SBDS problem and cast it as a DCOP.
- We propose 5 heuristics to select a subset of cost tables to elicit.
- **Preliminary results:**
 - Our best heuristics are more accurate than a baseline method.
- **Future work:**
 - More extensive analysis of our methods.
 - More realistic setting for the SBDS agents.

Thank You!

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References:

- Fig. 1: <http://goo.gl/5znqip>
- Fig. 2: goo.gl/dqwUz2
- Fig. 3: goo.gl/daWjOP
- Fig. 4: goo.gl/CeWvSn
- Fig. 5: goo.gl/afyUXV
- Fig. 6: goo.gl/WFzMhv

Preference Elicitation Heuristics (extra)

- $\geq_{[SD]}$ Second-order stochastic dominance:

$f_i \geq_{[SD]} f_j$ iff:

$$\sum_{m=1}^{|\Sigma_x^{f_i}|} (f_i(m) - f_j(m)) \geq 0$$

where $f_i(m)$ is the expected cost of the m-th value assignment for the variables in the scope of f_i .