Decision Trees

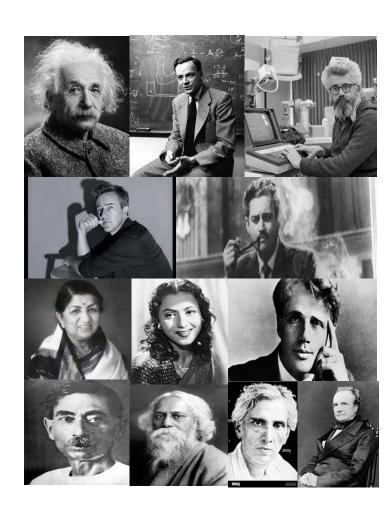
A brief introduction

Support Vector Machines

- SVM's are powerful and versatile algorithms, with some limitations and shortcomings.
- 1. Choice of Kernel
- 2. Computational Intensity
- 3. Binary Classification
- 4. Interpretability
- 5. Parameter Sensitivity

Let's play a game: "WHO AM I"

- Who Am I's main game objective is for players to guess the famous person correctly.
- You can ask a set of questions. Can you guess the person based on my answers?
- What question to ask?
 - Is it a person/character?
 - Is the person an artist (celebrity)?
 - Is the person a politician?
 - Is the person a historical figure?
 - Is the person male/female?
 - Is (s)he old? Or is still alive?
 - Does (s)he live in INDIA?
 - Is the person controversial?

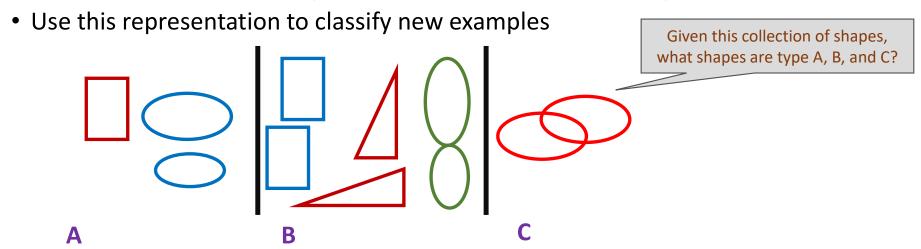


Decision Trees

- A hierarchical data structure that represents data by implementing a divide and conquer strategy
 - Can be used as a non-parametric classification and regression method (real numbers associated with each example, rather than a categorical label)

Process:

• Given a collection of examples, learn a decision tree that represents it.

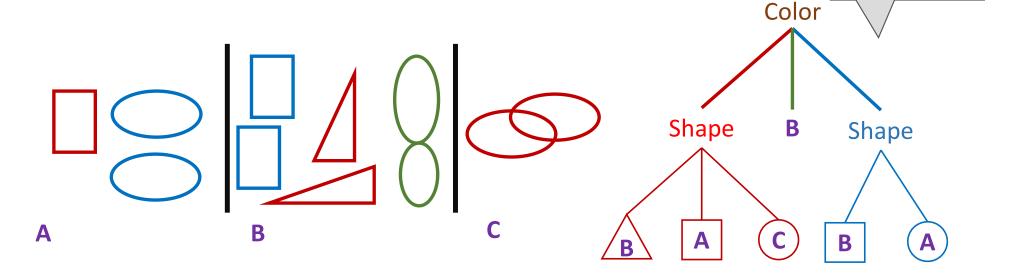


Decision Trees

- Decision Trees are classifiers for instances represented as feature vectors
 - color={red, blue, green}; shape={circle, triangle, rectangle}; label= {A, B, C}
 - An example: <(color = blue; shape = rectangle), label = B>
- Can categorize instances into multiple disjoint categories

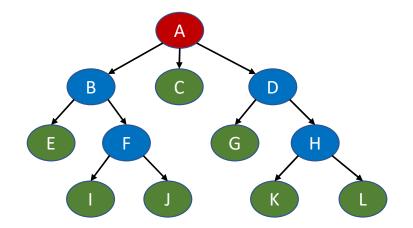
Learning a Decision Tree?

- Check the color feature.
- If it is blue than check the shape feature
- if it is ...then...



Tree: Terminologies

- Node: Each element of a set that forms the tree [vertices]
- Edge: A line between two connected nodes
- Root: A special node with no incoming edges
- Leaf: A node with no outgoing edges
- Internal Node: A node that is not a root or leaf
- Depth: Distance from a node to the root
- Height: Max distance to a leaf



- Path: A sequence of nodes with edges between consecutive pairs
- Parent, Child: Nodes with edge from parent to child.
- Ancestor, Descendant: Path from ancestor to descendant.
- Siblings: Nodes with same parent
- Degree: Number of edges from a node (in and out) [branching factor; binary tree]

Classification using a Decision Tree

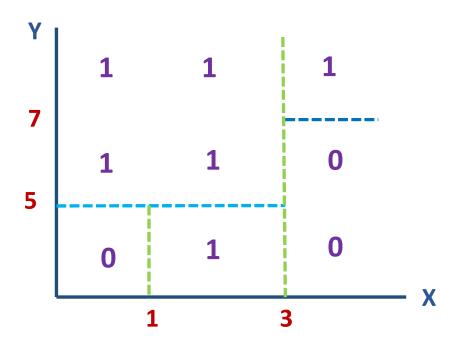
- Each Node (except leaves) has a question / decision.
- Depending on the answer, the set of possible answers shrink.
- Leaf nodes have class labels
- Given a test sample, we traverse the path from the root to a leaf based on decisions at each node.

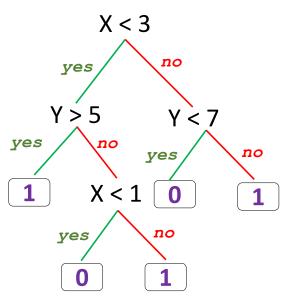
Decision Boundaries

- Usually, instances are represented as attribute-value pairs (colour = red, shape = square, A)
- Numerical values can be used either by discretizing or by using thresholds for splitting nodes

We consider the case, where the tree divides the feature space into axis-parallel rectangles,

each labelled with one of the labels





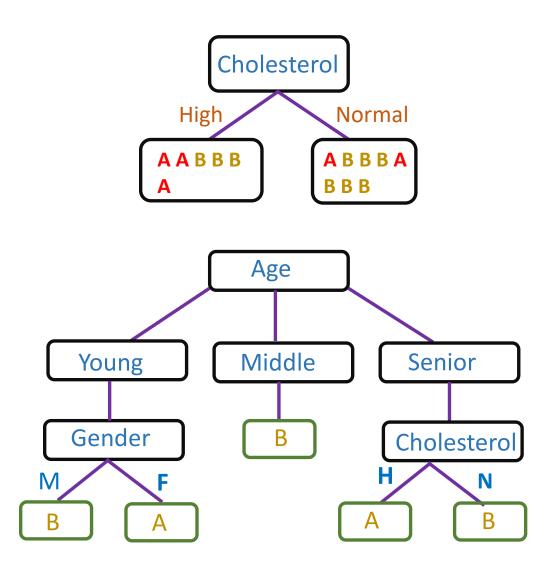
Features for Classification

- Decision trees can handle
 - Numerical Data (Price in Rs, Height in cms)
 - Divide into two based on a threshold on its value
 - Categorical Data ([sedan, SUV, coupe, hatchback], [red, white green])
 - Divide into k groups based on value
 - Ordinal data ([bad, fair, good, excellent])
 - Divide into two at any point of the values
- Approaches
 - Use features as above
 - Convert all features to categorical
- Clearly, given data, there are many ways to represent it as a decision tree
- Learning a good representation from data is the challenge

Good Decision Tree

- Each classification decision can be explained in plain text (if features are meaningful)
- Decision Trees can represent any Boolean Function. The tree will in the worst case require exponentially many nodes, however
- Useful in many industries
 - Medical Diagnosis
 - Credit Risk Analysis
- Given data, you can always represent it using a decision tree
- If so, what is a "good" decision tree?
 - What is a "good" question to start with?

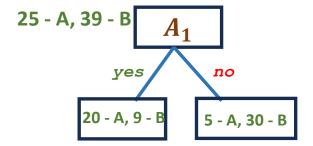
Age	Gender	ВР	Cholesterol	Drug
Young	F	High	Normal	Α
Young	F	High	High	Α
Middle	F	High	Normal	В
Senior	F	Norm	Normal	В
Senior	М	Low	Normal	В
Senior	М	Low	High	Α
Middle	М	Low	High	В
Young	F	Norm	Normal	А
Young	М	Low	Normal	В
Senior	М	Norm	Normal	В
Young	М	Norm	High	В
Middle	F	Norm	High	В
Middle	М	High	Normal	В
Senior	F	Norm	High	Α
Young	F	Low	Normal	?

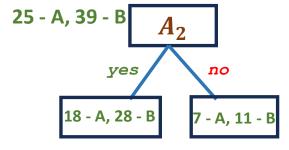


Attributes

- Algorithm has to learn a decision tree from data. What should be the goal of the first step of the algorithm?
- Choosing the Best Attribute (i.e. features or inputs)

Which attribute is the best?





Many different frameworks for choosing BEST have been proposed!

What is a Good Question?

- Which question if answered will reduce the possible number of classes the most?
- More precisely, which question (feature+threshold) will reduce our uncertainty the most
- The goal is to have the resulting decision tree as small as possible (Occam's Razor)
 - But, finding the minimal decision tree consistent with the data is NP-hard
- The recursive algorithm is a greedy heuristic search for a simple tree, but cannot guarantee optimality.
- The main decision in the algorithm is the selection of the next attribute to condition on.
- Mathematically, reduce the Entropy the most

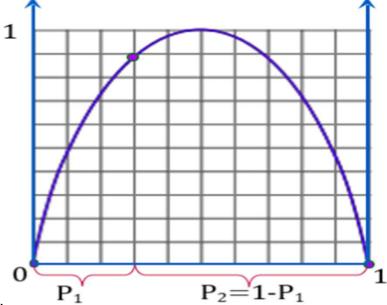
What is Entropy?

Entropy (impurity, disorder) is a measure of Uncertainty

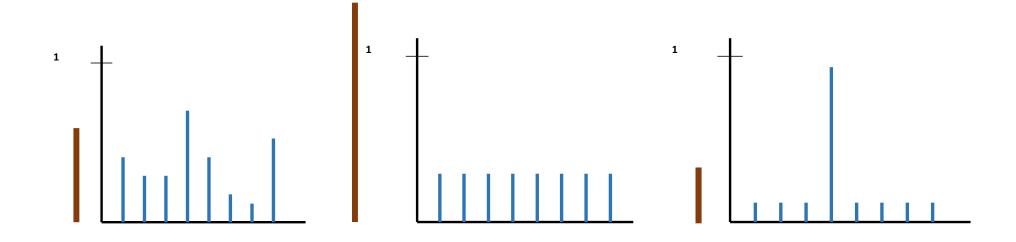
$$\mathbf{H}(S) = -\sum_{i} P_{i} \log_{2} P_{i}$$

$$= -P_{+} \log_{2} P_{+} - P_{-} \log_{2} P_{-} \text{ (for binary classes)}$$

- P_+ is the proportion of positive examples in S and
- P_ is the proportion of negatives examples in S
 - If all the examples belong to the same category [(1,0) or (0,1)]: Entropy = 0
 - If all the examples are equally mixed (0.5, 0.5): Entropy
 = 1
- Entropy is a measure of the "degree of surprise"
 - Some dominant classes ⇒ small entropy (less uncertainty)
 - Equiprobable classes ⇒ high entropy (more uncertainty)



Entropy



Information Gain

- Information Gain: It is the measurement of changes in <u>entropy</u> after the segmentation of a dataset based on an attribute. Uses Algorithm ID3
- Information Gain on a feature F

$$IG(S,F) = H(S) - \sum_{f \in F} \frac{|S_f|}{|S|} H(S_f)$$

- S_f number of elements of S with feature F having value f
- IG(S,F) denotes the increase in our certainty about S once we know the value of the feature F
- Partitions of low entropy (imbalanced splits) lead to high gain

Solution: Maximize Information Gain

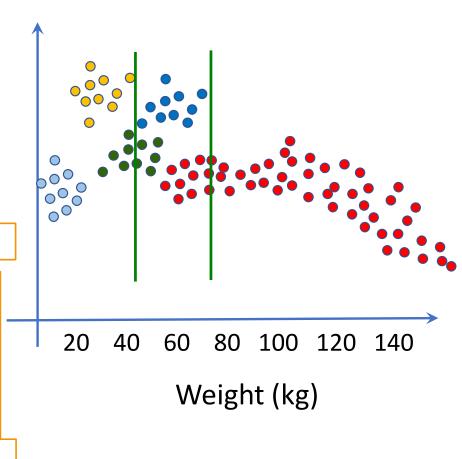
Initial Entropy: $5 \times (-0.2 \log_2 0.2) = 2.32$

$$H_{1} = \frac{1}{2} \begin{pmatrix} (-0.4 \log_{2} 0.4) + (-0.4 \log_{2} 0.4) \\ + (-0.2 \log_{2} 0.2) \end{pmatrix}$$

$$+ \frac{1}{2} \begin{pmatrix} (-0.4 \log_{2} 0.4) + (-0.4 \log_{2} 0.4) \\ + (-0.2 \log_{2} 0.2) \end{pmatrix}$$

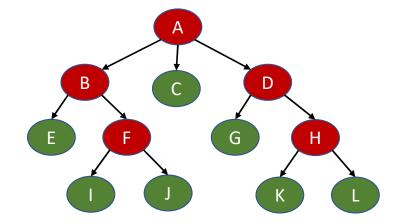
$$= 1.52$$
Information Gain = 0.8

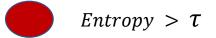
$$\begin{split} H_2 &= \frac{1}{6} (-1.0 \ log_2 1.0) \\ &+ \frac{5}{6} \begin{pmatrix} (-0.22 \ log_2 0.22) + (-0.22 \ log_2 0.22) + \\ (-0.22 \ log_2 0.22) + (-0.22 \ log_2 0.22) + \\ (-0.12 \ log_2 0.12) \end{pmatrix} \\ &= 1.91 \end{split}$$
 Information Gain = 0.41

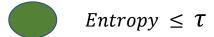


Building a Decision Tree

- 1. Find the best feature (and threshold) to split the training data
 - Use an objective metric like Entropy/Gini Index to decide
- 2. Partition the training data as per the selected feature and threshold
- 3. For each partition, if the entropy is low, stop.
 - else, Repeat the first two steps for that partition







Summary of Decision Trees

- Efficient, Compact and Effective
- Interpretable as a set of rules
- Ability to handle categorical and numerical features
- Can indicate most useful features
- Can also do regression
- Computationally expensive to train
- Does not handle non-rectangular regions well
- Not suitable for continuous variable regression
- Tends to overfit