



MODEL 430 POWER SUPPLY PROGRAMMER

**INCLUDING HIGH-STABILITY OPTION &
MULTI-AXIS APPLICATIONS**

**INSTALLATION, OPERATION, AND
MAINTENANCE INSTRUCTIONS**

American Magnetics, Inc.

P.O. Box 2509, 112 Flint Road, Oak Ridge, TN 37831-2509, Tel: 865-482-1056, Fax: 865-482-5472

Foreword	ix
Purpose and Scope	ix
Contents of this Manual	ix
Applicable Hardware	x
General Precautions	xi
Cryogen Safety.....	xi
Treating Cold Burns	xi
Handling Cryogenic Liquids	xii
Material Safety at Cryogenic Temperatures.....	xii
Magnet Quenches in LHe-Cooled Systems	xiii
Risk of Explosion	xiii
Magnetic Fields	xiii
Safety Summary.....	xiv
Minimum Recommended Safety Equipment	xiv
Safety Legend	xv
Introduction	1
Model 430 Programmer Features	1
Digitally-Controlled	1
Superior Resolution and Stability	1
High-Stability Option.....	2
Intuitive Human-Interface Design.....	2
Flexibility.....	2
Standard Remote Interfaces.....	2
Programmable Safety Features	2
Condition-Based Magnet Auto-Rampdown	3
Model 430 Front Panel Layout	4
Model 430 Rear Panel Layout	5
Model 430 Specifications @ 25 °C	7
Operating Characteristics.....	9
Single-Quadrant Operation.....	9
Dual-Quadrant Operation	10
Four-Quadrant Operation	11

Installation.....	13
Inspecting and Unpacking	14
Model 430 Programmer.....	14
Power Requirements.....	14
Changing the Model 430 Programmer Operating Voltage	15
Collecting Necessary Information	16
System Interconnects (Single-Axis Systems)	16
Unipolar Power Supply System.....	18
Bipolar Power Supply System.....	21
High-Stability Bipolar Power Supply System.....	24
High-Current Four-Quadrant Power Supply System.....	28
High-Current, High-Stability 4-Quadrant Power Supply System.....	31
Low-Current, High-Resolution 4-Quadrant Power Supply System	34
System Interconnects (Multi-Axis Systems).....	37
General	37
Load Cables	37
Instrumentation Cables	37
Standard (non-recondensing) Helium-based 2-Axis System Signal Interconnects	38
Standard (non-recondensing) Helium-based 3-Axis System Signal Interconnects	39
Recondensing Helium-based 2-Axis System Signal Interconnects	40
Recondensing Helium-based 3-Axis System Signal Interconnects	41
Cryogen-Free 2-Axis System Signal Interconnects	42
Cryogen-Free 3-Axis System Signal Interconnects	42
Third-Party Power Supplies	43
Special Configurations	43
Superconducting Magnets with No Persistent Switch.....	43
Short-Circuit or Resistive Load	44
Power-Up and Test Procedure	45
Operation	49
System Power On/Off Sequence	49
Model 430 Programmer Power On/Off	49
Energizing the Power Supply and Components	50
Model 430 Programmer Default Display	51

Field / Current Display	51
Voltage Display	52
Status Indicator	53
Main Display	53
Entering Numeric Values	54
Using the Fine Adjust Knob	55
Selecting Picklist Values	57
Single-key Commands / Menus	58
Persistent Switch Control Key	58
Target Field Setpoint Key	61
Ramp / Pause Key	62
Ramp To Zero Key	62
SHIFT+key Commands / Menus	62
Ramp Rate (Shift+1)	63
Voltage Limit (Shift+2)	66
Reset Quench (Shift+3)	67
Increment Field (Shift+4)	67
Field <> Current (Shift+5)	68
Decrement Field (Shift+6)	68
Field Units (Shift+7)	68
Persistent Switch Heater Current (Shift+8)	69
Stability (Shift+9)	69
Vs <> Vm (Shift+0)	69
Volt Meter (Shift+.)	69
Fine Adjust (Shift +/-)	69
Shift + Persist. Switch Control	70
LED Indicators	71
Power-on Indicator	71
Magnet Status Indicators	71
Shift Indicator	72
Setup Menu	73
Entering / Exiting Setup Menu	73
Menu Navigation	73
Setup Submenu Descriptions	74
Supply Submenu	74
Load Submenu	80
Switch Submenu	86

Protection Submenu	92
Misc Submenu	99
Net Settings Submenu	108
Net Setup Submenu	110
Example Setup.....	112
Ramping Functions	114
Ramping States and Controls	114
Manual Ramping.....	115
Automatic Ramping.....	115
Ramping to Zero	116
Fine Adjust of Field / Current in Holding Mode	116
Persistent Switch Control.....	117
Procedure for Initial Heating of the Switch	117
Procedure for Entering Persistent Mode	118
Procedure for Exiting Persistent Mode	121
Toggling the State of the Persistent Switch Heater.....	124
Ramping Functions Example	125
Quench Detection	127
Quench Detection Method	127
External Quench Detection	128
Disabling Internal Quench Detection.....	128
External Rampdown	129
External Rampdown while in Persistent Mode	130
External Rampdown while not in Persistent Mode	131
Summary of Limits and Default Settings	132
Remote Interface Reference.....	133
SCPI Command Summary	133
Programming Overview	141
SCPI Language Introduction.....	141
SCPI Status System	141
Status Byte Register	143
Standard Event Register.....	144
Command Handshaking	145
RS-232 Configuration	147

Serial Connector	147
Termination Characters	147
Ethernet Configuration	147
Ethernet Connector	148
Termination Characters	148
Port Assignments	148
Telnet Port 23 Broadcast Function	148
Command Reference.....	152
System-Related Commands.....	152
Status System Commands.....	155
Supply Setup Configuration Queries	157
Load Setup Configuration Commands and Queries.....	159
Switch Setup Configuration Commands and Queries	161
Protection Setup Configuration Commands and Queries.....	162
Misc Setup Configuration Commands and Queries	165
Lock Commands and Queries	166
Net Setup Configuration Commands and Queries	172
Ramp Target/Rate Configuration Commands and Queries	172
Measurement Commands and Queries	174
Ramping State Commands and Queries	175
Switch Heater Command and Query	177
Quench State Commands and Queries	178
Rampdown State Commands and Queries	179
Trigger Functions	181
Error Messages	183
Command Errors	183
Query Errors	185
Execution Errors	186
Device Errors	187
Remote Applications and Examples	189
Magnet-DAQ: Comprehensive Model 430 Remote Control	189
SCPI-Based Communication via RS-232	192
SCPI-Based Communication via Ethernet	194
Service	197
System Component Routine Maintenance	197
Model 430 Firmware Upgrades	197

Manually Upgrading the Firmware via FTP	198
Troubleshooting Hints	201
Electrostatic Discharge Precautions	201
Hints for Commonly Encountered Errors	201
Additional Technical Support.....	208
Return Authorization.....	209
Appendix	211
Magnet Station Connectors	211
LHe Level / Temp Connectors	213
Programmer Shunt Terminals	214
Current Transducer Connector	215
Program Out Connector	216
Quench I/O Connector	217
External Quench Detection Input	218
External Rampdown Input	218
External Quench Detection Output	219
Auxiliary Inputs Connector	220
Ethernet Connector.....	221
RS-232 Connector.....	222
Abbreviations and Acronyms used in this Manual	223
Short-Sample Mode.....	226
Index.....	229

Foreword

PURPOSE AND SCOPE

This manual contains the operation and maintenance instructions for the American Magnetics, Inc. Model 430 Programmer and outlines various system configurations. Since it is not possible to cover all equipment combinations for all magnet systems offered by AMI, only the most common configurations are discussed. The user is encouraged to contact an authorized AMI Technical Support Representative for information regarding specific configurations not explicitly covered in this manual.

CONTENTS OF THIS MANUAL

Introduction introduces the reader to the functions and characteristics of the Model 430 Power Supply Programmer. It provides illustrations of the front and rear panel layouts as well as documenting the performance specifications. Additional information is provided in the form of system circuit diagrams.

Installation describes how the Model 430 Power Supply Programmer is unpacked and installed in conjunction with ancillary equipment in typical superconducting magnet systems. Block-level diagrams document the interconnects for various system configurations.

Operation describes how the Model 430 Programmer is used to control a superconducting magnet. All Model 430 Programmer displays and controls are documented. The ramping functions, persistent switch heater controls, and the quench detect features are also presented.

Remote Interface Reference documents all remote commands and queries available through the Model 430 Programmer RS-232 and Ethernet interfaces. A quick-reference summary of commands is provided as well as a detailed description of each.

Service provides guidelines to assist the user in troubleshooting possible system and Model 430 Programmer malfunctions. Information for contacting AMI Technical Support personnel is also provided.

Appendix provides additional details and/or procedures in the following areas:

- Model 430 Programmer rear panel connectors.
- Establishing RS-232 or Ethernet communications with the Model 430.
- Model 430 firmware upgrade procedures.
- Abbreviations and acronyms used in this manual.
- Optional Short-Sample operational mode.

APPLICABLE HARDWARE

The Model 430 Programmer has been designed to operate with a wide variety of switch mode and linear power supplies from a variety of manufacturers. However, not all compatible power supplies have been tested. The Model 430 Programmer has been tested and qualified with the following power supplies or power supply systems:

AMI Model 12100PS switching power supply (12 V @ 100 A)
AMI Model 12200PS switching power supply (12 V @ 200 A)
AMI Model 7.5-140PS switching power supply (7.5 V @ 140 A)
AMI Model 10100PS switching power supply (10 V @ 100 A)
AMI Model 10200PS switching power supply (10 V @ 200 A)
AMI Model 08150PS switching power supply (1200 Watt)
AMI Model 03300PS (multiple Model 08150PS w/ Energy Absorbers; ±3 V @ 300 A)
AMI Model 05100PS (Model 08150PS w/ Energy Absorber; ±5 V @ 100 A)
AMI Model 05120PS (Model 08150PS w/ Energy Absorber; ±5 V @ 120 A)
AMI Model 05240PS (multiple Model 08150PS w/ Energy Absorbers; ±5 V @ 240 A)
AMI Model 05360PS (multiple Model 08150PS w/ Energy Absorber; ±5 V @ 360 A)
AMI Model 05400PS switching power supply w/ Energy Absorber (±5 V @ 400 A)
AMI Model 05600PS (multiple Model 08150PS w/ Energy Absorber; ±5 V @ 600 A)
AMI Model 4Q06125PS 4-quadrant switching power supply (±6 V @ ±125 A)
AMI Model 4Q06250PS 4-quadrant switching power supply (±6 V @ ±250 A)
AMI Model 4Q12125PS 4-quadrant switching power supply (±12 V @ ±125 A)
AMI Model 4Q05100PS 4-quadrant switching power supply (±5 V @ ±100 A)
Xantrex Model XFR 12-100 switching power supply (12 V @ 100 A)
Xantrex Model XFR 12-220 switching power supply (12 V @ 220 A)
Xantrex Model XHR 7.5-130 switching power supply (7.5V @ 130 A)
Hewlett-Packard 6260B linear power supply (10 V @ 100 A)
Kepco BOP 20-5M 4-quadrant linear power supply (±20 V @ ±5 A)
Kepco BOP 20-10M 4-quadrant linear power supply (±20 V @ ±10 A)
Kepco BOP 20-20M 4-quadrant linear power supply (±20 V @ ±20 A)
Accel Instruments TS250-8 4-quadrant power supply ((±7 V @ ±5 A)

Consult with an AMI Technical Support Representative for other approved power supplies.

GENERAL PRECAUTIONS

CRYOGEN SAFETY

The two most common cryogenic liquids used in superconducting magnet systems are nitrogen (LN₂) and helium (LHe). Both of these cryogens are extremely cold at atmospheric pressure (-321°F and -452°F, respectively). The following paragraphs outline safe handling precautions for these liquids.

Personnel handling cryogenic liquids should be thoroughly instructed and trained as to the nature of the liquids. Training is essential to minimize accidental spilling. Due to the low temperature of these materials, a cryogen spilled on many objects or surfaces may damage the surface or cause the object to shatter, often in an explosive manner.

Inert gases released into a confined or inadequately ventilated space can displace sufficient oxygen to make the local atmosphere incapable of sustaining life. Liquefied gases are potentially extreme suffocation hazards since a small amount of liquid will vaporize and yield a very large volume of oxygen-displacing gas. Always ensure the location where the cryogen is used is well ventilated. Breathing air with insufficient oxygen content may cause unconsciousness without warning. If a space is suspect, purge the space completely with air and test before entry. If this is not possible, wear a forced-air respirator and enter only with a co-worker standing by wearing a forced-air respirator.

Cryogenic liquids, due to their extremely low temperatures, will also burn the skin in a similar manner as would hot liquids. Never permit cryogenic liquids to come into contact with the skin or allow liquid nitrogen to soak clothing. Serious burns may result from careless handling. Never touch uninsulated pipes or vessels containing cryogenic liquids. Flesh will stick to extremely cold materials. Even nonmetallic materials are dangerous to touch at low temperatures. The vapors expelled during the venting process are sufficiently cold to burn flesh or freeze optic tissues. Insulated gloves should be used to prevent frost-bite when operating valves on cryogenic tanks. Be cautious with valves on cryogenic systems; the temperature extremes they are typically subjected to cause seals to fail frequently.

TREATING COLD BURNS

In the event a person is burned by a cryogen or material cooled to cryogenic temperatures, the following first aid treatment should be given

pending the arrival and treatment of a physician or other medical care worker:

1. If any cryogenic liquid contacts the skin or eyes, immediately flush the affected area gently with tepid water (102°F – 105°F, 38.9°C – 40.5°C) and then apply cold compresses.
2. Do not apply heat. Loosen any clothing that may restrict circulation. Apply a sterile protective dressing to the affected area.
3. If the skin is blistered or there is any chance that the eyes have been affected, get the patient immediately to a physician for treatment.

HANDLING CRYOGENIC LIQUIDS

Containers of cryogenic liquids are self pressurizing (as the liquid boils off, vapor pressure increases). Hoses or lines used to transfer these liquids should never be sealed at both ends (i.e. by closing valves at both ends).

When pouring cryogenic liquids from one container to another, the receiving container should be cooled gradually to prevent damage by thermal shock. The liquid should be poured slowly to avoid spattering due to rapid boil off. The receiving vessel should be vented during the transfer.

MATERIAL SAFETY AT CRYOGENIC TEMPERATURES

Introduction of a substance at or near room temperature into a cryogenic liquid should be done with great caution. There may be a violent gas boil-off and a considerable amount of splashing as a result of this rapid boiling. There is also a chance that the material may crack or catastrophically fail due to forces caused by large differences in thermal contraction of different regions of the material. Personnel engaged in this type of activity should be instructed concerning this hazard and should always wear a full face shield and protective clothing. If severe spraying or splashing could occur, safety glasses or chemical goggles along with body length protective aprons will provide additional protection.

The properties of many materials at extremely low temperatures may be quite different from the properties that these same materials exhibit at room temperatures. Exercise extreme care when handling materials cooled to cryogenic temperatures until the properties of these materials under these conditions are known.

Metals to be used for use in cryogenic equipment application must possess sufficient physical properties at these low temperatures. Since ordinary carbon steels, and to somewhat a lesser extent, alloy steels,

lose much of their ductility at low temperatures, they are considered unsatisfactory and sometimes unsafe for these applications. The austenitic Ni-Cr alloys exhibit good ductility at these low temperatures and the most widely used is 18-8 stainless steel. Copper, Monel®, brass and aluminum are also considered satisfactory materials for cryogenic service.

MAGNET QUENCHES IN LHe-COOLED SYSTEMS

When an energized superconducting magnet transitions from superconducting state to normal state, the magnet converts magnetic energy to thermal energy thereby rapidly converting the liquid helium to a vapor. When this phase transformation occurs, pressures can build rapidly in the cryostat due to the fact that one part of liquid helium will generate 782 parts of gaseous helium at STP (standard temperature and pressure). The cryostat must be designed to allow the generated vapor to rapidly and safely vent to an area of lower pressure. Cryostats are designed with pressure relief valves of sufficient capacity so as to limit the pressure transients within the container in order to prevent damage to the vessel. Operating a superconducting magnet in a cryostat without properly sized relief mechanisms or disabled relief mechanism is unsafe for the operator as well as for the equipment. If there is any doubt as to the sufficiency of the pressure relief system, contact the manufacturer of the magnet and cryostat for assistance.

RISK OF EXPLOSION

Ensure cryogen container and/or magnet system vent relief valves are *kept clear*. An improperly ventilated cryostat/system may become blocked by ice with subsequent RISK OF EXPLOSION and uncontrolled release of cryogens from the system. Relief valves and rupture disks may also discharge cold gas violently without warning. Relief valves should always be pointed in a safe direction. Care must be taken not to disable pressure relief devices or otherwise create a condition where pressure buildup can occur in a magnet system or cryogen container because of the RISK OF EXPLOSION. FAILURE TO HEED THIS WARNING COULD RESULT IN INURY OR DEATH.

MAGNETIC FIELDS

The following notices should be posted to warn personnel of the dangers of strong magnetic fields produced by superconducting magnets:

- i. **WARNING:** The operation of medical electronic implants, such as cardiac pacemakers, may be affected by magnetic fields, WHICH COULD CAUSE INJURY OR DEATH.
- ii. **WARNING:** Medical implants, such as aneurysm clips, surgical clips or prostheses may contain ferromagnetic materials and therefore would be subject to strong forces near a magnet. THIS COULD RESULT IN INURY OR DEATH. In the vicinity of rapidly changing field (e.g. pulsed gradient

fields), eddy currents may be induced in the implant resulting in heat generation.

iii. **WARNING:** Metal materials in someone's body as a result of an old injury may be affected by magnetic fields in this facility. THIS COULD RESULT IN INJURY OR DEATH.

iv. **WARNING:** Large attractive forces may be exerted on equipment brought near to the magnet. The force may become large enough to move the equipment uncontrollably towards the magnet. Pieces of equipment may become projectiles and large equipment (e.g. gas bottles, power supplies) could trap bodies or limbs between the equipment and the magnet. EITHER TYPE OF OBJECT MAY CAUSE INJURY OR DEATH. The closer to the magnet you get, the larger the force is. The larger the mass of the equipment the larger the force pulling it.

v. **CAUTION:** The operation of equipment may be directly affected by the presence of large magnetic fields. Items such as watches, tape recorders, and cameras may be magnetized and irreparably damaged if exposed to magnetic fields. Information encoded magnetically on credit cards and magnetic tape including computer floppy discs, may be irreversibly corrupted. Electrical transformers may become magnetically saturated. Safety characteristics of equipment may also be affected.

SAFETY SUMMARY

Superconducting magnet systems are complex systems with the potential to seriously injure personnel or equipment if not operated according to procedures. The use of cryogenic liquids in these systems is only one factor to consider in safe and proper magnet system operation. Proper use of safety mechanisms (pressure relief valves, rupture disks, etc.) included in the cryostat and top plate assembly are necessary. Furthermore, an understanding of the physics of the magnet system is needed to allow the operator to properly control the large amounts of energy stored in the magnetic field of the superconducting coil. The Model 430 Programmer has been designed with safety interlocks to assist the operator in safe operation, but these designed-in features cannot replace an operator's understanding of the system to ensure the system is operated in a safe and deliberate manner.

MINIMUM RECOMMENDED SAFETY EQUIPMENT

- First Aid kit
- Fire extinguisher rated for class C fires
- Cryogenic gloves
- Face shield

- Signs to indicate that there are potentially hazardous magnetic fields in the area and that cryogens are in use in the area.

SAFETY LEGEND



Instruction manual symbol: the product is marked with this symbol when it is necessary for you to refer to the instruction manual in order to protect against damage to the product or personal injury.



Hazardous voltage symbol.



Alternating Current (Refer to IEC 417, No. 5032).



Off (Supply) (Refer to IEC 417, No. 5008).



On (Supply) (Refer to IEC 417, No. 5007).

WARNING

The Warning sign denotes a hazard. It calls attention to a procedure or practice, which if not correctly adhered to, could result in personal injury. Do not proceed beyond a Warning sign until the indicated conditions are fully understood and met.

CAUTION

The Caution sign denotes a hazard. It calls attention to an operating procedure or practice, which if not adhered to, could cause damage or destruction of a part or all of the product. Do not proceed beyond a Caution sign until the indicated conditions are fully understood and met.

Introduction

MODEL 430 PROGRAMMER FEATURES

The AMI Model 430 Programmer is a sophisticated digital power supply controller which allows an operator to manage a superconducting magnet system with unprecedented accuracy and ease of use. The Model 430 Programmer provides a degree of flexibility and accuracy previously unavailable in an economical commercial product.

Typical components of a power supply system include a Model 430 Programmer with optional zero flux current sensing system (high-stability option), one or more energy absorbers (for bipolar systems), and one or more power supplies (unipolar or four-quadrant) to achieve the rated system output current.

DIGITALLY- CONTROLLED

The Model 430 Programmer is controlled by a microcomputer which performs all analog data conversion, display/keypad functions, communications I/O, generation of analog programming signals for the external power supply, and control law computations. The Model 430 Programmer incorporates digital signal processing (DSP) functions that provide for accurate control, low drift, and flexibility of use.

SUPERIOR RESOLUTION AND STABILITY

The Model 430 Programmer incorporates high-resolution converters to translate signals between the analog and digital domains. Precision instrumentation techniques and potentiometer-free designs are employed throughout the Model 430 Programmer to ensure accurate signal translation for a wide range of conditions. The magnet current is sampled at 24-bit resolution in hardware and is software-programmable to 15-digits resolution. All pause and hold functions are performed in the digital domain which provides for excellent stability and drift of the programmed magnetic field.

**HIGH-STABILITY
OPTION**

For greater stability and accuracy, the Model 430 Programmer can be configured with a zero-flux precision current measuring device instead of the standard resistive shunt. This option typically increases the system stability and accuracy by an order of magnitude. The power supply systems incorporating this technique are referred to as "high-stability" systems.

**INTUITIVE HUMAN-
INTERFACE DESIGN**

The Model 430 Programmer was designed to simplify the interface where possible. All functions were analyzed and subsequently programmed so that the most commonly used functions are addressed with the least number of keystrokes. The menus are also presented in a logical fashion so that the operation of the Model 430 Programmer is intuitive to the user.

The provision of a velocity-sensitive rotary encoder on the front panel also allows the operator to interactively fine-adjust many of the operating parameters of the magnet system.

FLEXIBILITY

The Model 430 Programmer can be configured with the supporting hardware as a two- or four-quadrant power supply system which is able to both supply and remove electrical energy from the superconducting magnet system. The Model 430 Programmer is engineered to be compatible with most power supplies with remote analog programming capabilities.

From simple single-quadrant supplies, to more elaborate four-quadrant units, the Model 430 Power Supply Programmer is user-configurable such that the operational paradigm complies with the specific magnet system requirements.

**STANDARD REMOTE
INTERFACES**

The Model 430 Programmer provides an RS-232 serial port as well as an Ethernet port as standard features. All settings can be controlled via the remote interfaces and the front panel can be remotely locked to prevent accidental operation. The Model 430 Programmer also provides remote trigger functions for data collection and/or logging during operation.

**PROGRAMMABLE
SAFETY FEATURES**

The Power Supply System is designed to be operated from the front panel of the Model 430 Programmer or remotely with operational parameters which must not be exceeded for the given conditions of the system. Once set, should an operator inadvertently attempt to take the magnet system to an excessive magnetic field strength or charge at an excessive voltage, the Model 430 Programmer will not accept the

parameter and will alert the operator that a value was rejected because it was outside the user-defined limits.

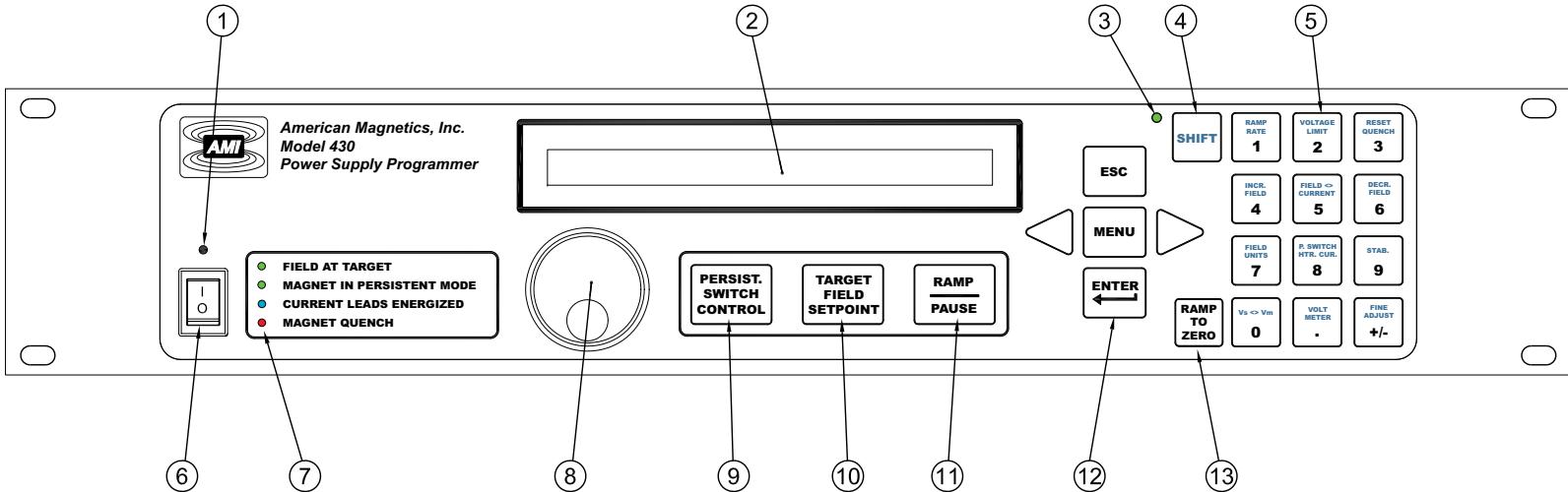
In addition, each setup parameter can be individually selected for locking. A user-defined password is required to lock or unlock settings. This allows an administrator to set and password protect any critical parameters that should not be changed by the operator. Then the administrator can be confident that an operator will not subsequently change any of these critical parameters, and yet will be free to change any non-critical (unlocked) parameters.

CONDITION-BASED MAGNET AUTO- RAMPDOWN

The Model 430 Programmer can be connected to an AMI Model 1700 Liquid Level Instrument, with the LHe measurement option, to allow automatic rampdown of the magnet (even in persistent mode) should the liquid helium (LHe) level drop to a preset level. This feature ensures the magnet will be protected and not experience a quench should the LHe level reach an unsafe level for magnet operation. A single cable is required to use this feature and is covered in more detail on page 219 of the *Appendix*. Contact AMI for more information.

In addition to low LHe level, inputs to the Model 430 Programmer can be used with other instrumentation as well. Other uses include faults from a cryocooler, temperature measurement limit, etc.

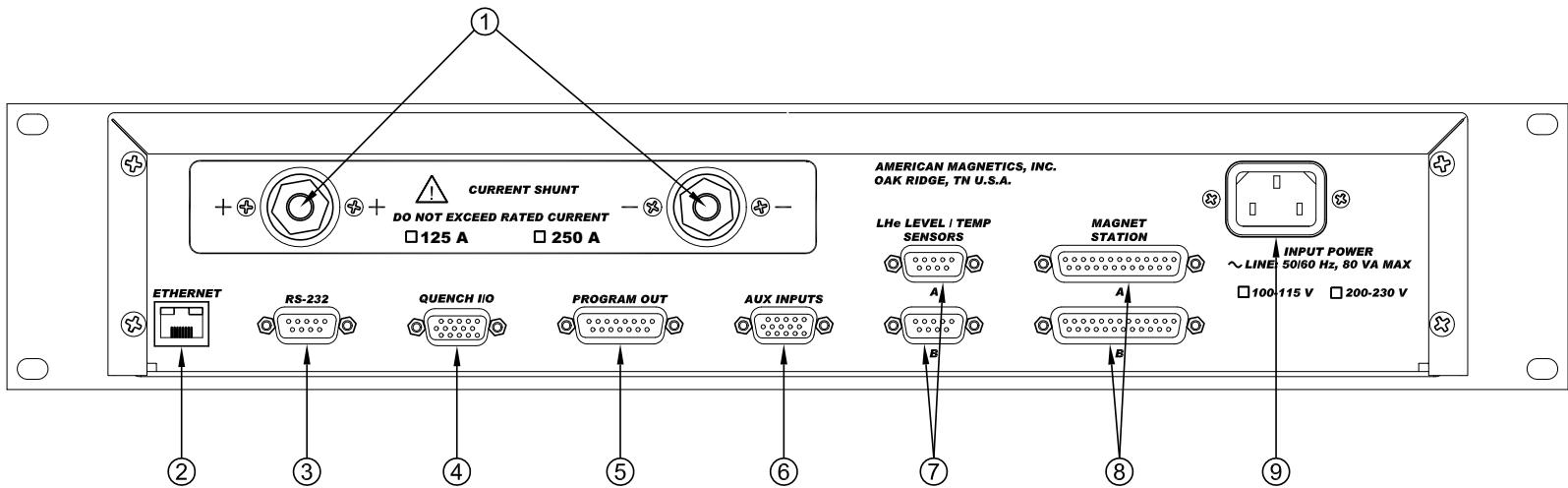
MODEL 430 FRONT PANEL LAYOUT



1 Power Indicator LED	8 Fine Adjust Knob
2 280 x 16 Dot Graphic VF Display	9 Persistent Switch Heater Control Key
3 Shift Indicator LED	10 Target Field Setpoint Key
4 Shift Key	11 Ramp/Pause Switch
5 4 Row x 3 Column Keypad	12 Menu Navigation and Data Entry Keys
6 Power Switch	13 Ramp to Zero Key
7 Magnet Status Indicator LEDs	

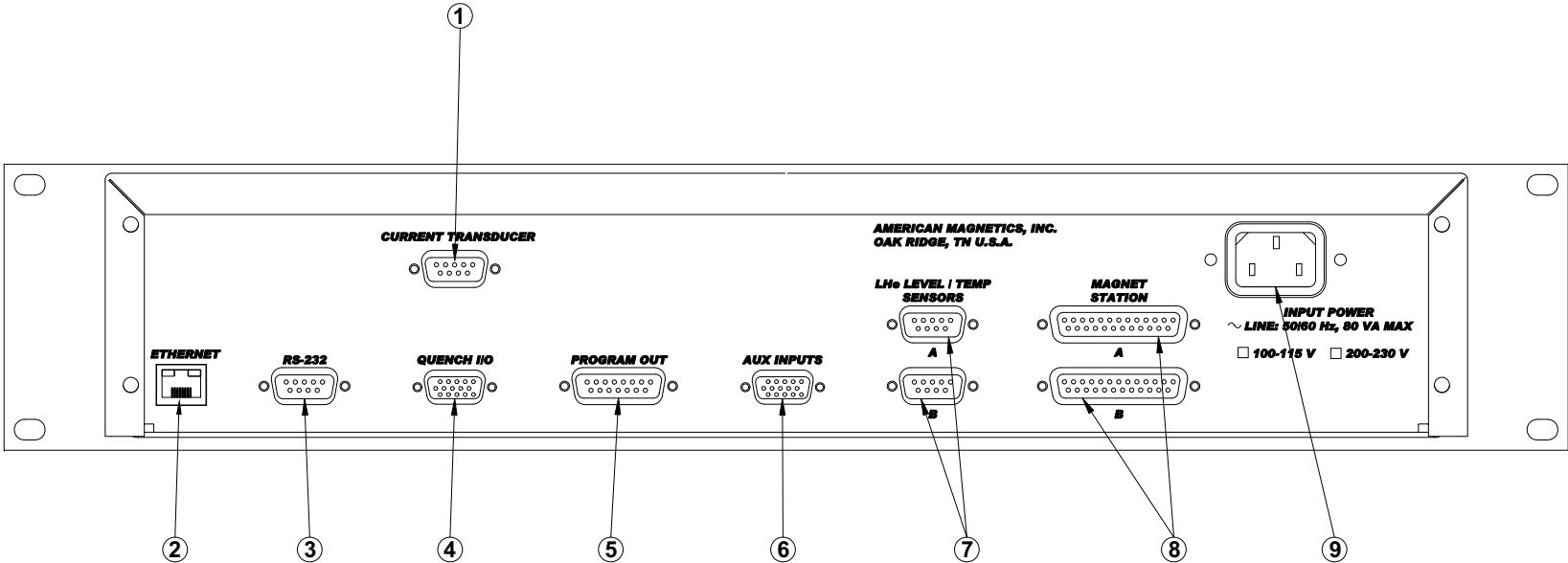
Model 430 Front Panel Description

MODEL 430 REAR PANEL LAYOUT



1 Current Shunt Terminals	6 Aux Inputs 15-pin Female HD D-sub Connector
2 Ethernet RJ-45 Connector	7 Dual Auxiliary LHe Level/Temp 9-pin Male D-sub Connectors
3 RS-232 9-pin Female D-sub Connector (Male for legacy devices)	8 Dual Magnet Station 25-pin Female D-sub Connectors
4 Quench I/O 15-pin Male HD D-sub Connector	9 Input Power IEC 60320 C14 Male Connector
5 Program Out 15-pin Male D-sub Connector	

Model 430 Resistive Shunt Configuration Rear Panel Description



1 Current Transducer 9-pin Female D-sub Connector	6 Aux Inputs 15-pin Female HD D-sub Connector
2 Ethernet RJ-45 Connector	7 Dual Auxiliary LHe Level/Temp 9-pin Male D-sub Connectors
3 RS-232 9-pin Female D-sub Connector (Male for legacy devices)	8 Dual Magnet Station 25-pin Female D-sub Connectors
4 Quench I/O 15-pin Male HD D-sub Connector	9 Input Power IEC 60320 C14 Male Connector
5 Program Out 15-pin Male D-sub Connector	

Model 430 High-Stability Configuration (w/Current Transducer) Rear Panel Description

MODEL 430 SPECIFICATIONS @ 25 °C

Magnet Current Control Parameters		Standard Model 430 Factory Configurations: Programmable Limits						
I_{max} :		± 5 A	± 10 A	+100 A	± 125 A	± 250 A	+300 A	+600 A
Measurement Resolution (μ A):		0.625	1.25	12.5	15.6	31.2	37.4	75.0
Accuracy (% of I_{max})	Internal Shunt:	0.0075	0.015	0.04	0.05	0.05	N/A	N/A
	High-Stability:	0.005	0.005	0.005	0.005	0.005	0.005	0.005
Minimum Ramp Rate (μ A/min)	Internal Shunt:	3	6	60	75	150	N/A	N/A
	High-Stability:	0.3	0.6	6	7.5	15	18	36
Maximum Ramp Rate (A/sec):		0.5	1	10	12.5	25	30	60

Additional Model 430 Programmer Specifications

Magnet Current Control

Temperature Coefficient:	0.01% of I_{max} / °C
Stability (w/ internal shunt):	With standard internal shunt, better than 0.002% of I_{max} after 20 minutes at desired current
w/ High-Stability Option:	With High-Stability Option (zero flux current transducer), better than 0.001% of I_{max} after 10 minutes at desired current
Noise Floor Relative to I_{max} :	-127 dB w/ internal shunt, -138 dB with High-Stability Option
Target Setpoint Entry Precision:	15 digits ^a
Ramp Rate Entry Precision:	15 digits ^a
Nominal Load Inductance Range:	0.05 to 200 H (extended range of 0.01 to 1000 H available)

Program Out Voltage

Programmable Limits:	-10 to +10 VDC
Accuracy:	3 mV (0.03% of V_{max})
Temperature Coefficient:	0.2 mV / °C (0.002% of V_{max} / °C)
Resolution:	0.3 mV
Stability:	Better than 10 mV p-p when paused or holding (with 0.05 to 200 H load)

Magnet Voltage Measurement

Maximum Limits:	-20 to +20 VDC
Accuracy:	20 mV (0.1% of V_{max} / °C)
Temperature Coefficient:	1.5 mV / °C (0.0075% of V_{max} / °C)
Resolution:	10 mV

Persistent Switch Heater Output

Programmable Limits:	0.0 to 125 mA DC
Accuracy:	0.2 mA
Temperature Coefficient:	0.01 mA / °C
Maximum Compliance:	14 V
Resolution:	0.03 mA

Rampdown and Quench Inputs

Open Circuit Voltage:	5 VDC ±5%
Input Resistance:	10 kΩ ±1%

Quench Dry Contact Output

Maximum Switching Voltage:	60 VDC
Maximum Switching VA:	10 VA
Maximum Switching Current:	500 mA, unless limited by VA rating
Galvanic Isolation:	125 VDC

Power Requirements

Primary:	100-115 VAC or 200-230 VAC ±10% 50 / 60 Hz, 100 VA max., 30 W max.
Real-time Clock Backup Battery:	3 V CR2032 Lithium coin cell

Physical

Dimensions:	89 mm H x 483 mm W x 191 mm D (3.5" H x 19" W x 10.75" D)
Weight:	8.5 lbm (3.9 kg)
Terminal Torque Limit:	48 in-lb (5.4 N-m)

Environmental

Ambient Temperature:	Operating: 0 °C to 50 °C (32 °F to 122 °F) Nonoperating: -20 °C to 70 °C (-4 °F to 158 °F)
Relative Humidity:	0 to 95%; non-condensing

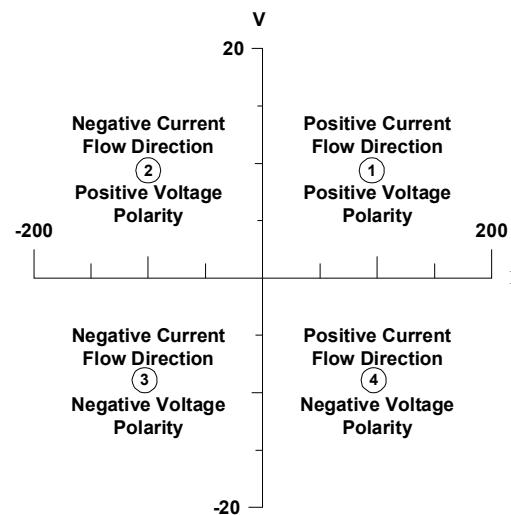
Standards

EMI/EMC Standards:	EN 61000-4-2 EN 61000-4-4 EN 61000-4-6 EN 61000-4-11 EN 61000-3-3	EN 61000-4-3 EN 61000-4-5 EN 61000-4-8 EN 61000-3-2 EN 55011
Safety Standard:	EN61010-1	
Installation Category:		Pollution Degree 2, Overvoltage Category II as defined by IEC664

- a. Resolution of the IEEE 754 double-precision floating point type consisting of a 52-bit fraction and 11-bit exponent. Actual *controlled* accuracy and resolution depend upon the specific load configuration and hardware performance limits.

OPERATING CHARACTERISTICS

The Model 430 Programmer has been designed to perform with various power supplies to allow the user the greatest degree of system flexibility. The power supply and Programmer combination are categorized by one of three forms: *single-quadrant*, *dual-quadrant*, and *four-quadrant*. For sake of clarity, the term *quadrant* is defined as one of four areas of a cartesian coordinate system where the abscissa is current and the ordinate is voltage. Refer to the figure below:



The Four Regions, or Quadrants, of System Operation

NOTE The resistive current measurement shunt in the following system diagrams, which is internal to the Model 430 chassis, can be optionally replaced with an external high-stability, precision zero-flux current measurement device for additional cost. This is termed the "High-Stability" option for AMI power supply systems. The zero-flux device does not exhibit the self-heating physics of a resistive shunt and is therefore, more accurate with less drift with increasing current magnitude.

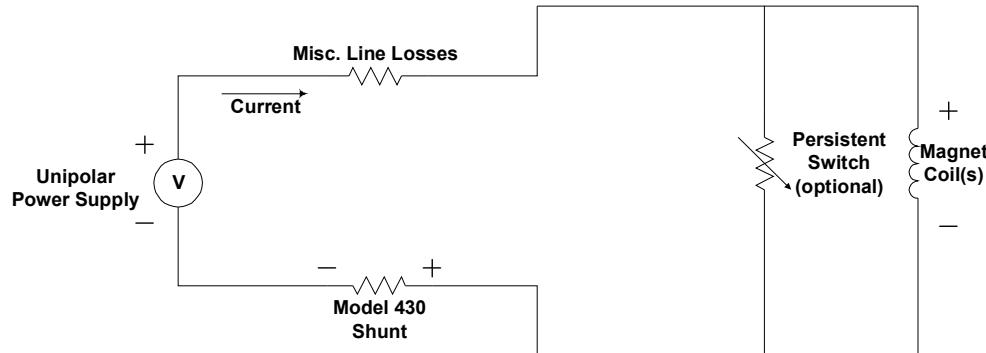
SINGLE-QUADRANT OPERATION

The simplest form of a Programmer-Power Supply system is the single-quadrant system as illustrated in the figure at the top of the following page. The system is composed of a Model 430 Programmer, unipolar power supply, and superconducting magnet.

This system allows current to flow in a single direction in the magnet thereby giving a magnetic field vector of varying magnitude but in a

single direction. This corresponds to operating in quadrant ①. The electrical energy can be stored as magnetic energy as fast as the magnet and power supply voltage will allow.

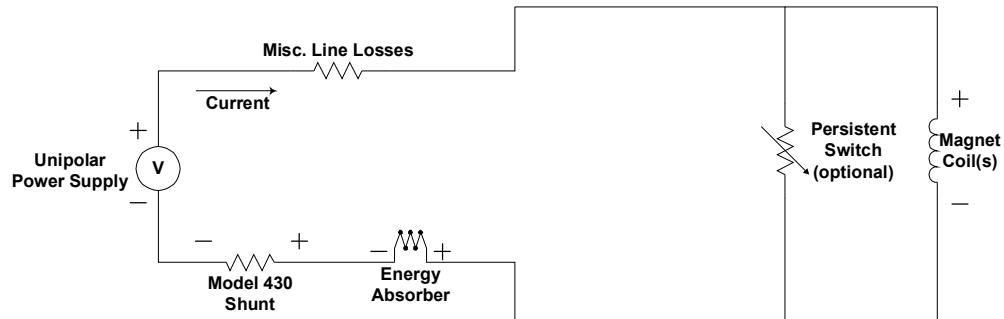
In order to reduce the magnetic field, the magnetic energy is converted to electrical energy and then to thermal energy in the resistive elements of the system. The magnitude of the resistive elements determines how fast the magnetic field can be collapsed and is typically very slow in the single-quadrant system. AMI does not recommend single-quadrant operation with large inductive loads due to the extremely long discharge times involved.



Single-Quadrant System with Resistive Shunt

DUAL-QUADRANT OPERATION

In the Bipolar Power Supply System, an energy absorber is added in series with the unipolar supply; this allows stored magnetic energy to be converted to thermal energy, thereby allowing much faster magnetic field reduction. This corresponds to operation in quadrants ① and ④, referring to the figure on page 9.



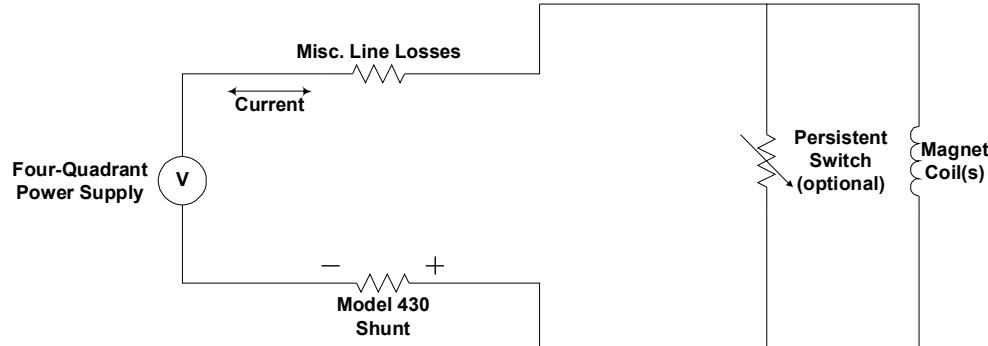
Dual-Quadrant (Bipolar) System with Resistive Shunt

The disadvantage to this type of system is that energy is being dissipated in the energy absorbing element whenever current is flowing. This loss is sometimes a significant portion of the power required to operate the system. It also does not provide for field polarity reversal.

FOUR-QUADRANT OPERATION

The Four-Quadrant Magnet Power Supply System illustrated in the figure below offers the most control of all the modes of operation. Efficiency is increased and reversible magnetic field profiles are attainable without discontinuities in the current. The magnetic energy sink returns a significant portion of the power to the AC line instead of dissipating it as heat.

Disadvantages of the four-quadrant system include somewhat increased cost of the power supply over unipolar power supplies or bipolar power supply systems, and added complexity in protecting the power supply in the event of AC power loss or magnet quenching. Nonetheless, modern four-quadrant power supplies which include integral output protection against AC power loss and magnet quenching are available at reasonable prices.



Four-Quadrant System with Resistive Shunt

Installation

WARNING

Before energizing the equipment, the earth ground of the power receptacle must be verified to be at earth potential and able to carry the rated current of the power circuit. Using extension cords should be avoided; however, if one must be used, ensure the ground conductor is intact and capable of carrying the rated current.

WARNING

In the event that the ground path becomes less than sufficient to carry the rated current of the power circuit, the equipment should be disconnected from power, labeled as unsafe, and removed from place of operation.

WARNING

Do not operate this equipment in the presence of flammable gases. Doing so could result in a life-threatening explosion.

WARNING

Do not modify this equipment in any way. If component replacement is required, return the equipment to AMI facilities as described in the Service section of this manual.

WARNING

If used in a manner not specified in this manual, the protection provided by the design, manufacture and documentation of the Model 430 Programmer may be impaired.

INSPECTING AND UNPACKING

Carefully remove the equipment, interconnecting cabling, and documentation CD (and/or printed material) from the shipping carton, and remove all packaging material.

NOTE If there is any shipping damage, save all packing material and contact the shipping representative to file a damage claim. Do not return to AMI unless prior authorization has been received.

MODEL 430 PROGRAMMER

If the Model 430 Programmer system is to be used on a table top, place it on a flat, secure surface capable of handling the weight. The Model 430 Programmer uses an internal fan for forced-air cooling. Allow at least 1/2 inch spacing on each side of the unit for proper ventilation.

WARNING



Do not remove the cabinet feet and then reinsert the original screws. Doing so could present a severe, life-threatening electrical hazard. If the cabinet feet are removed, do not reinstall the screws. If screws must be installed where the feet were mounted, replace the original screws with screws not to exceed 1/4 inch in length.

If the Model 430 Programmer is to be rack mounted, install it in a 19" wide instrument rack using the mounting hardware supplied by the rack cabinet manufacturer. Secure the front panel to the rail in each of the four corners.

POWER REQUIREMENTS

WARNING

The Model 430 Programmer operates on 50/60 Hz power and may be configured for 100-115 VAC or 200-230 VAC. The power requirement is marked on the rear panel adjacent to the power entry connector. Be sure the Model 430 Programmer is configured for the power source prior to plugging in the line cord. Do not fail to connect the input ground terminal securely to an external earth ground.

CAUTION

If the system includes the High-Stability Option, operating the system without power applied to the current transducer (CT) can result in loss of control, and may damage the CT.

NOTE

AMI recommends energizing the Model 430 Programmer from the same power source as the power supply to be controlled. Since both the Programmer and the power supply are floating, if the ground potentials of the Programmer 115 VAC outlet and the Power Supply 230 VAC outlet different, an AC ground loop can form which can cause control anomalies. Refer to following section if the line voltage needs to be changed to 230 VAC.

Ensure the front panel power switches are in the **O** (OFF) position. Verify that the Model 430 Programmer and power supply component(s) are configured for the proper operating voltage by referring to the label adjacent to the power entry connector on the equipment rear panels. If the operating voltage is correct, plug the line cords into the power entry connectors, and then into the appropriate facility power receptacles.

CHANGING THE MODEL 430 PROGRAMMER OPERATING VOLTAGE

WARNING

The following procedure is to be performed only when the Model 430 Programmer is completely de-energized by removing the power-cord from the power receptacle. Failure to do so could result in personnel coming in contact with high voltages capable of producing life-threatening electrical shock.

NOTE

The voltage selector switch is labeled "115" for nominal line voltages from 100 to 115 VAC. The switch is labeled "230" for nominal line voltages of 200 to 230 VAC.

If the Model 430 Programmer operating voltage must be changed, ensure the instrument is de-energized by disconnecting the power cord from the power source. Remove the Model 430 Programmer cover by removing the four screws on both sides of the cover and the four screws from the corners of the cover on the back panel; slide the voltage selector switch on the main printed circuit board to the proper voltage. Replace the Model 430 Programmer cover.

COLLECTING NECESSARY INFORMATION

In order to properly configure the Model 430 Programmer, specific system information is required. Such parameters as the magnet electrical properties, type of power supply, persistent switch heating current requirements, and voltage and current constraints of the magnet are entered into the Model 430 Programmer once and nonvolatile memory will retain the data even after power is removed from the instrument. An example of the data to be entered and how it is entered is described on page 112.

If the Model 430 Programmer was purchased as part of a magnet system, essential data will have already been entered at the AMI factory and a configuration sheet will have been provided detailing the settings.

SYSTEM INTERCONNECTS (SINGLE-AXIS SYSTEMS¹)

If the Model 430 Programmer was purchased as part of a magnet system, all applicable system components and wiring harnesses will have been shipped with the system. Since many different configurations are possible, use the system interconnection diagram that most closely matches your system; this is usually determined by the operating characteristics of the power supply.

For maximum immunity to AC line noise, ensure that the chassis of the Model 430 Programmer has a direct, low impedance electrical connection to the chassis of the power supply to which the **PROGRAM OUT** is connected. The connection can be made via a grounding strap, or if rack mounted, through the rack itself if it is constructed of electrically-conductive material.

The system diagrams that follow will assist in system equipment connections.

CAUTION

The wiring between the power supply and the magnet current leads must be of sufficient size to carry the full rated current of the power supply. Typically, for short runs (less than 25 ft, or 7.6 m), 2 AWG wire is sufficient for 125 A current, and 2/0 AWG wire is best for 250 A current. Consult with an AMI Technical Support Representative for higher current applications.

1. For additional multi-axis system details, refer the information on page 37.

Note that an AMI Model 1700 Liquid Level Instrument (with the LHe measurement option) is shown as a possible component of each integrated system. The main instrumentation cable connecting the magnet support stand to one of the Model 430 Programmer **MAGNET STATION** connectors contains all the instrumentation and control connections needed to control and monitor the magnet. The signals in this cable which are required to monitor LHe level and temperatures are also presented at the LHe Level/Temp Connectors. Refer to the *Appendix* for pin-outs of these and other connectors.

UNIPOLAR POWER SUPPLY SYSTEM

The Model 430 Programmer can be used in the single-quadrant mode. The magnet power supply system consists of the Model 430, a unipolar power supply and associated interconnection cabling. AMI does not recommend single-quadrant operation with large inductive, high-current loads due to the extremely long discharge times involved.

The diagram on page 19 shows this integrated system. Ensure the cabling is connected in the following manner:

NOTE The use of locking hardware is recommended for all high-current connections.

WARNING



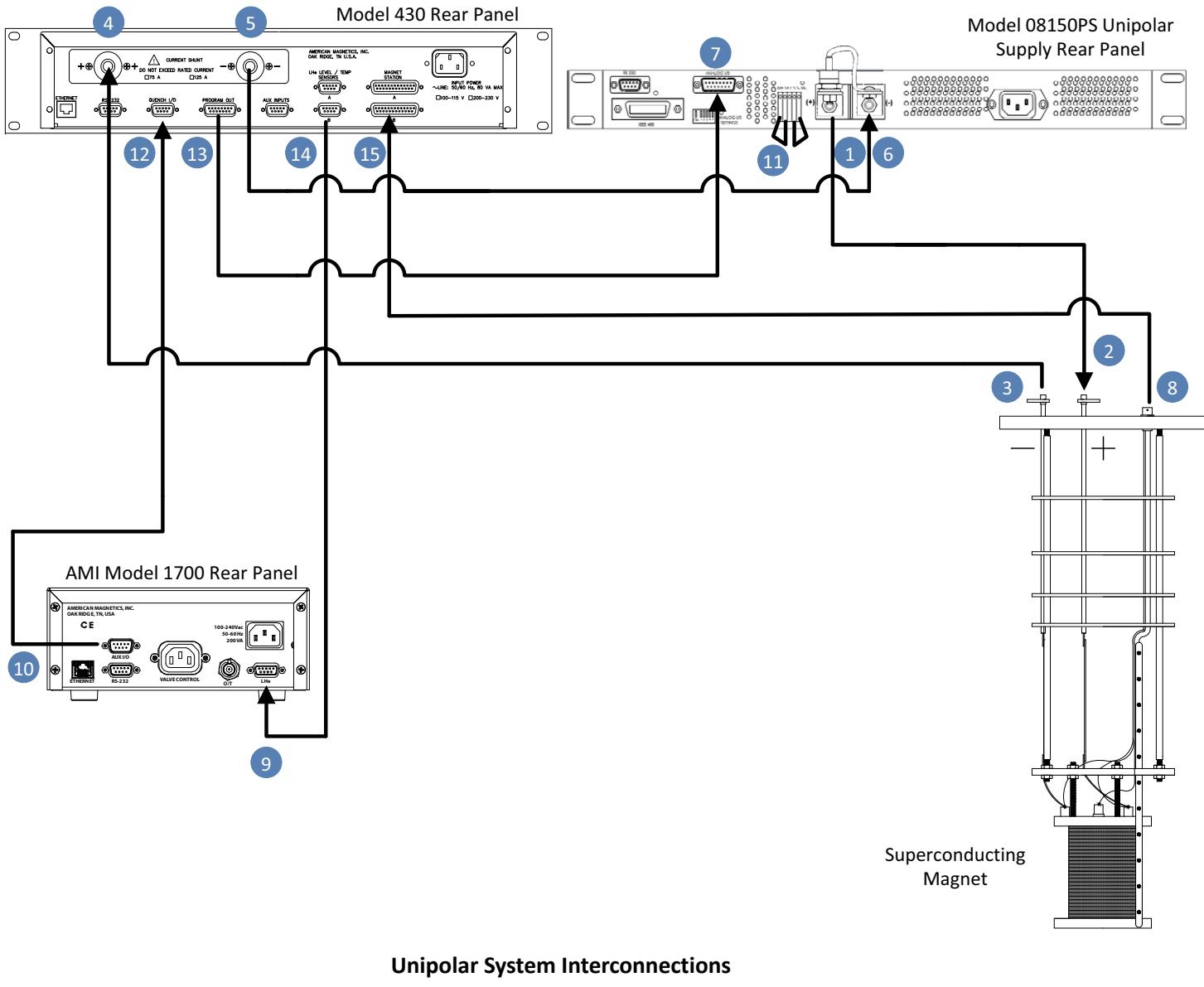
Ensure the protective diode is installed across the output terminals of the power supply with the anode at the negative (-) terminal and the cathode at the positive (+) terminal. Removal or omission of this protective diode may cause serious injury to personnel and damage to the power supply under loss of AC power conditions.

- a. Connect the protective diode across the output terminals of the power supply: anode to the negative (-) terminal and the cathode to the positive (+) terminal.
- b. Connect the positive (+) power supply terminal **1** to the positive magnet current lead **2**.
- c. Connect the negative magnet current lead **3** to the positive (+) resistive shunt terminal **4** on the back of the Model 430 Programmer.

CAUTION

Do not overtighten the hardware on the interconnection terminals (refer to specifications table on page 8 for torque limits). Overtightening can result in damage to the terminals.

- d. Connect the negative (-) resistive shunt terminal **5** on the back of the Model 430 Programmer to the negative (-) power supply terminal **6**.
- e. Connect two jumpers **11** from terminal block position S- to M- and from S+ to M+.
- f. Connect the DB15 analog I/O cable from the **ANALOG I/O** connector on the rear of the power supply **7** to the **PROGRAM OUT** connector **13** on the back of the Model 430 Programmer.



- g. Install an instrumentation cable between the magnet support stand top plate connector **8** and one of the **MAGNET STATION** connectors **15** on the rear of the Model 430 Programmer.
- h. Optional: Install an instrumentation cable between one of the **LHe LEVEL / TEMP** connectors **14** on the rear of the Model 430 Programmer and the Model 1700 Liquid Level Instrument LHe connector and/or temperature instrument **9**. Refer to page 213.
- i. Optional: Install an instrumentation cable between the **QUENCH I/O** connector **12** on the rear of the Model 430 Programmer and Aux I/O connector on the rear panel of the Model 1700 Liquid Level Instrument **10**. Refer to page 218.
- j. Connect each device line cord from the respective device to the appropriate power receptacle.
- k. Remote communications via Ethernet and/or RS-232 can be accomplished by connecting suitable cabling to the Model 430 Programmer rear panel **ETHERNET** and/or **RS-232** connectors.

BIPOLAR POWER SUPPLY SYSTEM

For the bipolar (dual-quadrant) mode with shunt method of current sensing, the magnet power supply system consists of the Model 430 Programmer, one or more unipolar 08150PS power supplies (each typically configured for +10 VDC/120 A output), and one or more Model 601 Energy Absorber with associated interconnection cabling and buswork.

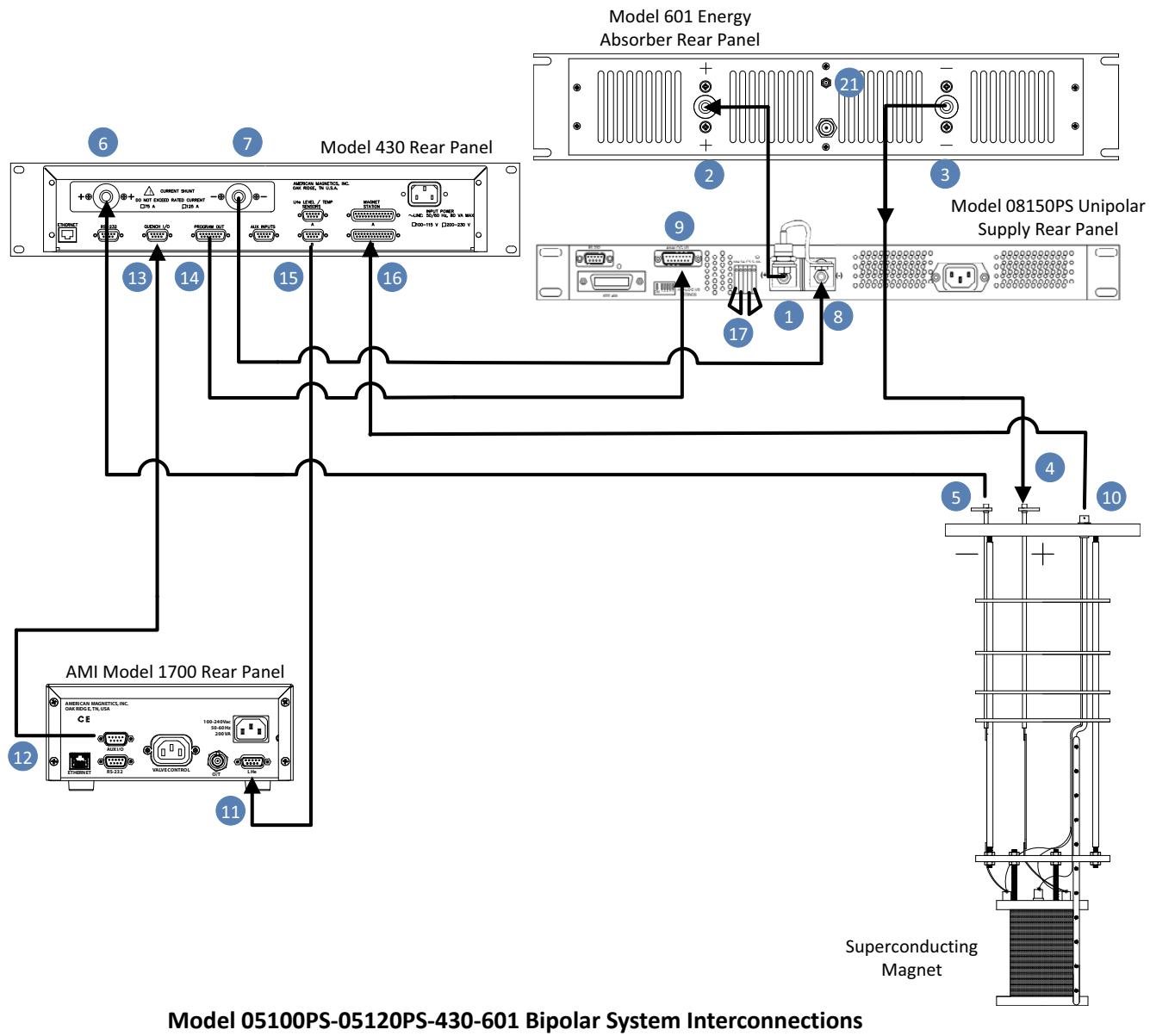
Referring to the diagram on page 22, ensure the cabling is connected in the following manner:

NOTE The use of locking hardware is recommended for all high-current connections.

CAUTION Do not overtighten the hardware on the interconnection terminals (refer to specifications table on page 8 for torque limits). Overtightening can result in damage to the terminals.

WARNING  Ensure the protective diode is installed across the output terminals of the power supply with the anode at the negative (-) terminal and the cathode at the positive (+) terminal. Removal or omission of this protective diode may cause serious injury to personnel and damage to the power supply under loss of AC power conditions.

- a. Connect the protective diode between the output terminals of the power supply: anode to the negative (-) terminal and the cathode to the positive (+) terminal.
- b. Connect the positive (+) output terminal **1** of the power supply to the Model 601 Energy Absorber positive (+) terminal **2**.
- c. Connect the negative (-) terminal **3** of the Model 601 Energy Absorber to the positive (+) magnet current lead **4**.
- d. Connect the negative (-) magnet current lead **5** to the positive (+) resistive shunt terminal **6** on the back of the Model 430 Programmer.
- e. Connect the negative (-) resistive shunt terminal **7** of the Model 430 Programmer to the negative (-) output terminal of the power supply **8**.
- f. Connect two jumpers **17** from terminal block position S- to M- and from S+ to M+ on the power supply unit.



- g. Connect the DB15 analog I/O cable from the **PROGRAM OUT** connector **14** on the back of the Model 430 Programmer to the DB15 **ANALOG I/O** connector **9** on the rear of the power supply unit.
- h. Install an instrumentation cable between the magnet support stand top plate connector **10** and one of the **MAGNET STATION** connectors **16** on the rear of the Model 430 Programmer.
- i. Optional: Install an instrumentation cable between one of the **LHe LEVEL / TEMP** connectors **15** on the rear of the Model 430 Programmer and the Model 1700 Liquid Level Instrument LHe connector and/or temperature instrument **11**. Refer to page 213.
- j. Optional: Install an instrumentation cable between the **QUENCH I/O** connector **13** on the rear of the Model 430 Programmer and Aux I/O connector **12** on the rear panel of the Model 1700 Liquid Level Instrument. Refer to page 218.
- k. Connect Model 601 power adapter **21** and device line cords, and plug them into appropriate power receptacles.
- l. Remote communications via Ethernet and/or RS-232 can be accomplished by connecting suitable cabling to the Model 430 Programmer rear panel **ETHERNET** and/or **RS-232** connectors.

HIGH-STABILITY BIPOLAR POWER SUPPLY SYSTEM

Current stability of the system can be increased by an order of magnitude through application of the zero flux method of current sensing. For the bipolar (dual-quadrant) mode high-stability magnet power supply, the system consists of the Model 430 Programmer with precision current sensing, one or more unipolar 08150PS Power Supplies and Model 601 Energy Absorbers, and associated interconnection cabling. The diagram on page 25 illustrates typical interconnects for the integrated bipolar high-stability magnet supply system.

Referring to the diagram on page 25, ensure the cabling is connected in the following manner:

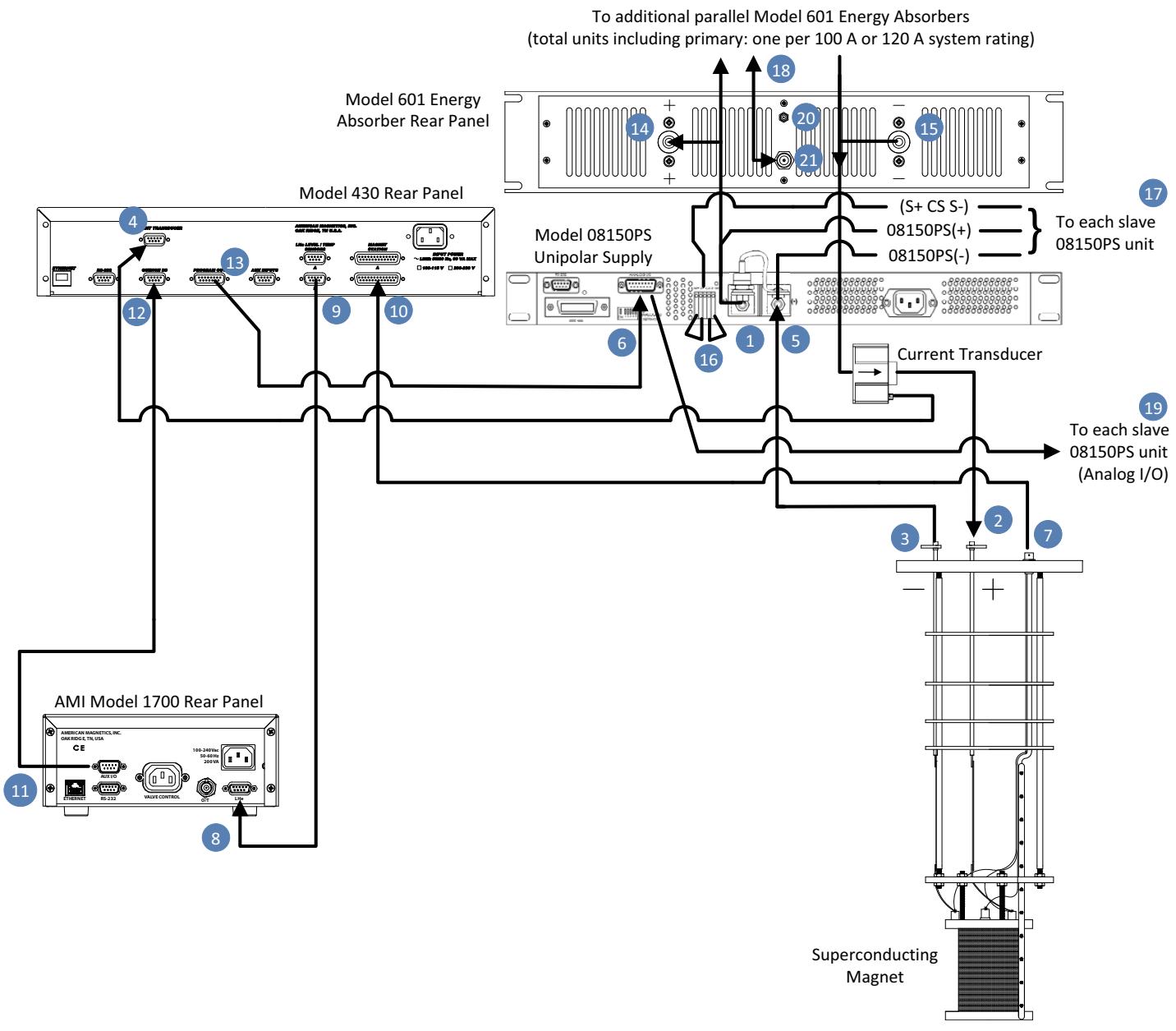
NOTE The use of locking hardware is recommended for all high-current connections.

CAUTION Do not overtighten the hardware on the interconnection terminals (refer to specifications table on page 8 for torque limits). Overtightening can result in damage to the terminals.

WARNING  Ensure the protective diode is installed across the output terminals of the power supply with the anode at the negative (-) terminal and the cathode at the positive (+) terminal. Removal or omission of this protective diode may cause serious injury to personnel and damage to the power supply under loss of AC power conditions.

- a. Connect **18** the Model 601 parallel hardware bus between Model 601 current terminals, plus-to-plus and minus-to-minus.
- b. Connect **17** the power supply parallel hardware bus between power supply current terminals, plus-to-plus and minus-to-minus.
- c. Connect the protective diode between the output bus bars of the power supply: anode to the negative (-) terminal and the cathode to the positive (+) terminal.
- d. Connect the positive (+) **OUTPUT** bus **1** of the power supply to the positive (+) bus **14** of the Model 601 Energy Absorber(s).

NOTE When routing the magnet cable (+) from Model 601 negative (-) bus through the current transducer (CT), the current-direction arrow on the CT must point toward the magnet.



- e. Connect the negative (-) bus **15** of the Model 601 Energy Absorber(s) and route it through the CT (see note). Connect the other end to the positive (+) magnet current lead **2**.
 - f. Connect the negative magnet current lead **3** to the negative power supply bus **5**.
 - g. Connect Model 05100PS Master unit terminal block positions CS, S-, and S+ to each corresponding Slave terminal **17**. Connect Master to first Slave, first Slave to second Slave, etc.
 - h. Connect two jumpers **16** from terminal block position S- to M- and from S+ to M+ on the Master² power supply unit.
 - i. Connect the current transducer output to the **CURRENT TRANSDUCER** connector **4** on the rear of the Model 430 Programmer.
 - j. Connect the special DB15 analog I/O cable from the **PROGRAM OUT** connector **13** on the back of the Model 430 Programmer to the DB15 **ANALOG I/O** connectors on the rear of the Master **6** and each Slave **19** power supply unit.
 - k. Install an instrumentation cable between the magnet support stand top plate connector **7** and one of the **MAGNET STATION** connectors **10** on the rear of the Model 430 Programmer.
 - l. Optional: Install an instrumentation cable between one of the **LHe / TEMP** connectors **9** on the rear of the Model 430 Programmer and the Model 1700 Liquid Level Instrument LHe connector and/or temperature instrument **8**. Refer to page 213.
 - m. Optional: Install an instrumentation cable between the **QUENCH I/O** connector **12** on the rear of the Model 430 Programmer and Aux I/O connector **11** on the rear panel of the Model 1700 Liquid Level Instrument. Refer to page 218.
 - n. Connect Model 601 power adapter **20** and device line cords, and plug them into appropriate power receptacles.
 - o. On the rear of each parallel Model 601 Energy Absorber, interconnect BNC coaxial connectors **21** with coaxial cables. If more than two units are connected in parallel, use standard BNC "T" adapters on the inner units. The "end" units should be connected directly to the coaxial cable — no BNC terminators should be used.
-
2. Do not add terminal block jumpers to the slave units. Only the single or master unit is jumpered.

- p. Remote communications via Ethernet and/or RS-232 can be accomplished by connecting suitable cabling to the Model 430 Programmer rear panel **ETHERNET** and/or **RS-232** connectors.

HIGH-CURRENT FOUR-QUADRANT POWER SUPPLY SYSTEM

For a four-quadrant power supply system, the components include the Model 430 Programmer, the four-quadrant 4Q06125PS power supply, and associated interconnection cabling. The diagram on page 29 illustrates the interconnects for the AMI Model 4Q06125PS-430 Power Supply system.

Referring to the diagram on page 29, ensure the cabling is connected in the following manner:

CAUTION For multi-axis systems³, ensure the power supply and magnet load cables are connected only to the equipment associated with the axis (Z-axis, Y-axis, or X-axis) for which the cable is labeled.

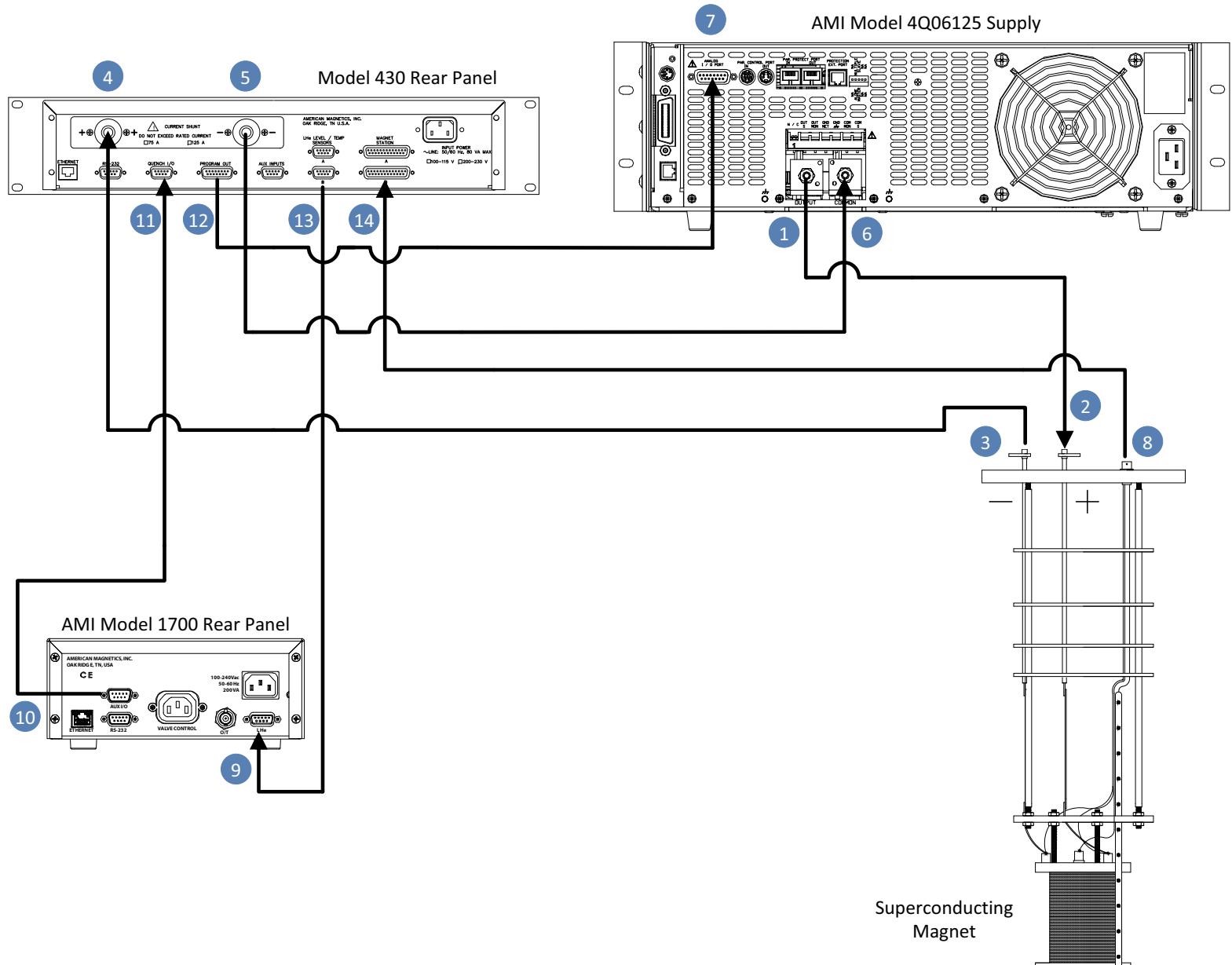
- a. Connect the power supply **OUTPUT** terminal **1** to the positive magnet current lead **2**.

NOTE The use of locking hardware is recommended for all high-current connections.

CAUTION Do not overtighten the hardware on the interconnection terminals (refer to specifications table on page 8 for torque limits). Overtightening can result in damage to the terminals.

- b. Connect the negative magnet current lead **3** to the positive (+) resistive shunt terminal **4** on the back of the Model 430 Programmer.
- c. Connect the negative (-) resistive shunt terminal **5** on the back of the Model 430 Programmer to the power supply **COMMON** terminal **6**.
- d. Connect the DB15 cable from the **PROGRAM OUT** connector **12** on the back of the Model 430 Programmer to the **ANALOG I/O** connector **7** on the rear of the power supply.
- e. Install an instrumentation cable between the magnet support stand top plate connector **8** and one of the **MAGNET STATION** connectors **14** on the rear of the Model 430 Programmer.
- f. Optional: Install an instrumentation cable between one of the **LHe LEVEL / TEMP** **13** connectors on the rear of the Model 430

3. Refer to page 37.



Model 4Q06125PS-430 System Interconnections

Programmer and the Model 1700 Liquid Helium Level Instrument LHe connector and/or temperature instrument ⑨. Refer to page 213.

- g. Optional: Install an instrumentation cable between the **QUENCH I/O** connector ⑪ on the rear of the Model 430 Programmer and Aux I/O connector ⑩ on the rear panel of the Model 1700 Liquid Level Instrument. Refer to page 218.
- h. Connect each device line cord from the respective device to the appropriate power receptacle.
- i. Remote communications via Ethernet and/or RS-232 can be accomplished by connecting suitable cabling to the Model 430 Programmer rear panel **ETHERNET** and/or **RS-232** connectors.

HIGH-CURRENT, HIGH-STABILITY 4-QUADRANT POWER SUPPLY SYSTEM

Current stability of the system can be increased by an order of magnitude through application of the zero flux method of current sensing. For the high-stability four-quadrant high-current power supply system, the components include the Model 430 Programmer, a four-quadrant power supply (typically an AMI Model 4Q06125PS), a precision current sensing system, and associated interconnecting cabling. The diagram on page 32 illustrates the interconnects for a High-Stability Model 4Q06125PS-430 power supply.

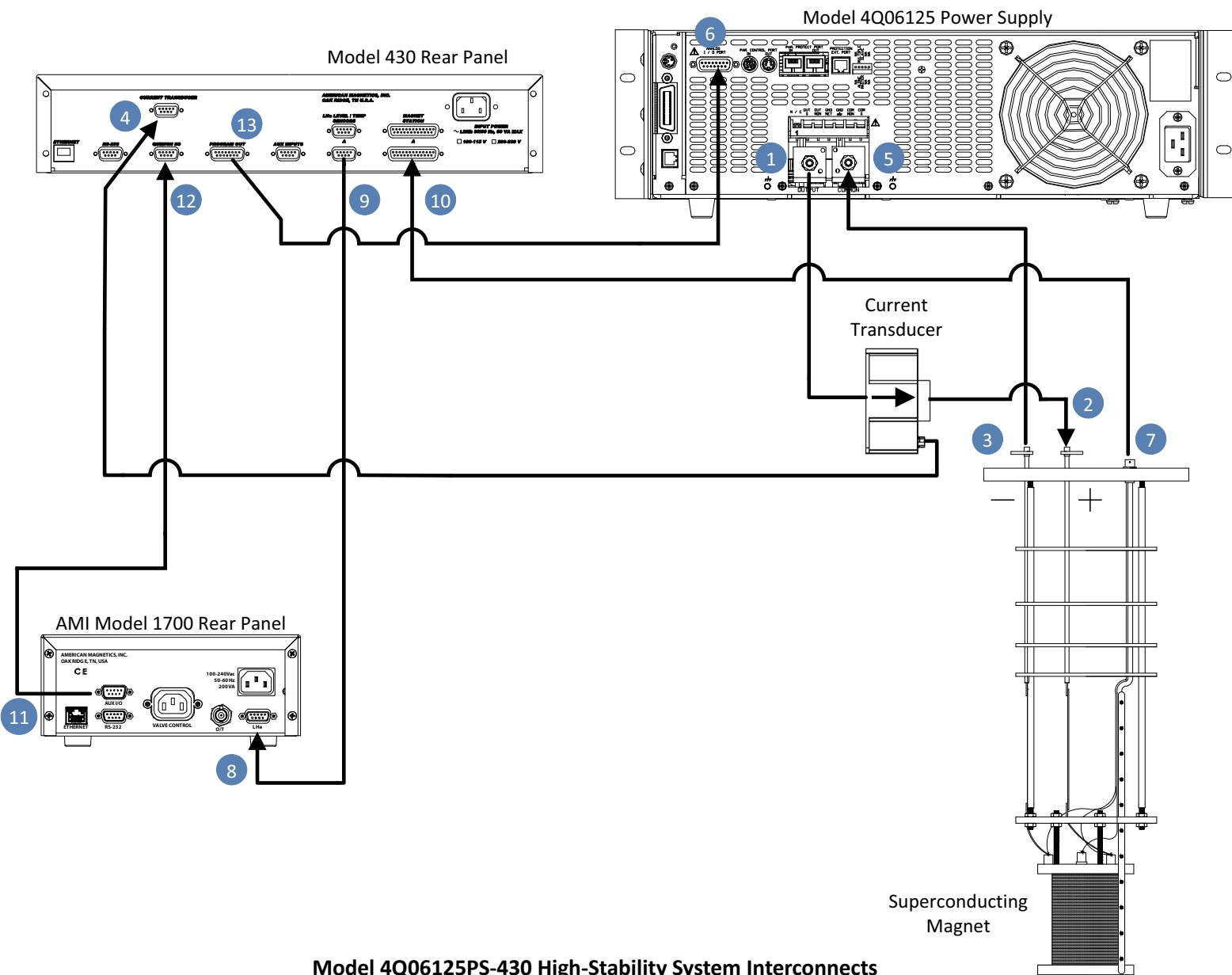
Referring to the diagram on page 32, ensure the cabling is connected in the following manner:

NOTE The use of locking hardware is recommended for all high-current connections.

CAUTION Do not overtighten the hardware on the interconnection terminals (refer to specifications table on page 8 for torque limits). Overtightening can result in damage to the terminals.

NOTE If routing the magnet cable (+) from power supply **OUTPUT** through the current transducer (CT), the current-direction arrow on the CT must point toward the magnet.

- a. Connect the **OUTPUT** power supply terminal **1** and route it through the zero flux current transducer (see note). Connect the other end to the positive magnet current lead **2**.
- b. Connect the negative magnet current lead **3** to the **COMMON** power supply terminal **5**.
- c. Connect the CT output to the current transducer **CURRENT TRANSDUCER** connector **4** on the rear of the Model 430 Programmer.
- d. Connect the DB15 cable from the **PROGRAM OUT** connector **13** on the back of the Model 430 Programmer to the **ANALOG I/O** connector **6** on the rear of the power supply.
- e. Install an instrumentation cable between the magnet support stand top plate connector **7** and one of the **MAGNET STATION** connectors **10** on the rear of the Model 430 Programmer.
- f. Optional: Install an instrumentation cable between one of the **LHe / TEMP** connectors **9** on the rear of the Model 430 Programmer and



the Model 1700 Liquid Level Instrument LHe input and/or temperature instrument **8**. Refer to page 213.

- g. Optional: Install an instrumentation cable between the **QUENCH I/O** connector **12** on the rear of the Model 430 Programmer and Aux I/O connector **11** on the rear panel of the Model 1700 Liquid Level Instrument. Refer to page 218.
- h. Connect each device line cord from the respective device to the appropriate power receptacle.
- i. Remote communications via Ethernet and/or RS-232 can be accomplished by connecting suitable cabling to the Model 430 Programmer rear panel **ETHERNET** and/or **RS-232** connectors.

LOW-CURRENT, HIGH-RESOLUTION 4-QUADRANT POWER SUPPLY SYSTEM

AMI offers a low-current (5 A or 10 A rated) system option to achieve high-resolution control of the magnet current. The components include a Model 430 Programmer, a Model 4Q1005PS or Model 4Q1010PS low-current four-quadrant power supply, and associated interconnecting cabling. The diagram on page 35 illustrates the interconnects for the low-current integrated power supply system.

NOTE Due to continuous discharge power limitations present in the BOP series supplies, for maximum safety AMI limits both the charging and discharging voltage, via the Model 430 Programmer, to a maximum of 10 volts.

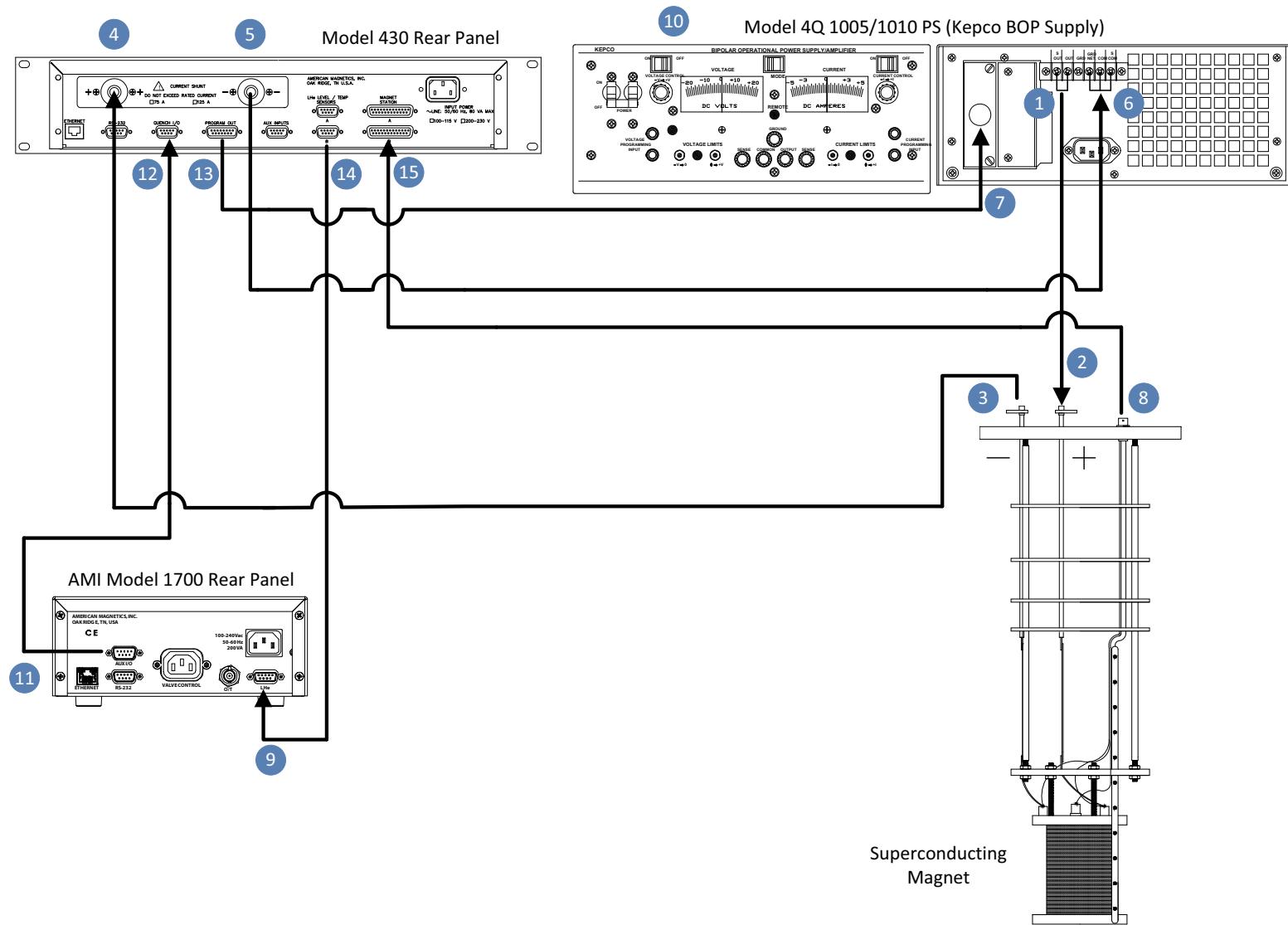
CAUTION Do not overtighten the hardware on the interconnection terminals (refer to specifications table on page 8 for torque limits). Overtightening can result in damage to the terminals.

Referring to the diagram on page 35, ensure the cabling is connected in the following manner:

- a. Connect the **OUT** power supply terminal **1** to the positive magnet current lead **2**.
- b. Install three jumpers on the terminal board (back of power supply):

S OUT to OUT
GRD NET to COM
COM to S COM.

- c. Connect the negative magnet current lead **3** to the positive (+) resistive shunt terminal **4** on the back of the Model 430 Programmer.
- d. Connect the negative (-) resistive shunt terminal **5** on the back of the Model 430 Programmer to the **COM** power supply terminal **6**.
- e. Connect the DB15 end of the program cable to the **PROGRAM OUT** connector **13** on the back of the Model 430 Programmer.
Connect the other end (the 50-pin edge connector) to the rear of the power supply **7**.
- f. Install an instrumentation cable between the magnet support stand top plate connector **8** and one of the **MAGNET STATION** connectors **15** on the rear of the Model 430 Programmer.
- g. Optional: Install an instrumentation cable between one of the **LHe LEVEL / TEMP** connectors **14** on the rear of the Model 430



Model 4Q1005PS-430 Low-Current System Interconnections

Programmer and the Model 1700 Liquid Level Instrument LHe connector and/or temperature instrument **9**. Refer to page 213.

- h. Optional: Install an instrumentation cable between the **QUENCH I/O** connector **12** on the rear of the Model 430 Programmer and Aux I/O connector **11** on the rear panel of the Model 1700 Liquid Level Instrument. Refer to page 218.
- i. Connect each device line cord from the respective device to the appropriate power receptacle.
- j. Remote communications via Ethernet and/or RS-232 can be accomplished by connecting suitable cabling to the Model 430 Programmer rear panel **ETHERNET** and/or **RS-232** connectors.
- k. On the power supply front panel, set the MODE to VOLTAGE (to the left), and set both the VOLTAGE CONTROL and the CURRENT CONTROL switches to the OFF position (to the right).

SYSTEM INTERCONNECTS (MULTI-AXIS SYSTEMS)

GENERAL

Each axis of AMI's two and three axis superconducting magnet systems incorporates a Model 430 Programmer, a four-quadrant power supply, and a set of power-supply and magnet interconnecting high-current load cables. In addition, a combination of instruments to monitor or control temperature, level, pressure and/or other parameters may be included. Actual instrumentation depends on the configuration and type of multi-axis system (standard helium-based, helium-recondensing, or cryogen-free).

LOAD CABLES

Interconnecting high-current load cables are connected in the same way as for a single axis system as described on page 28, or for the high-stability system on page 31. A separate set of cables is provided for each axis of a multi-axis system; the cable device connection labels include the associated axis (Z-axis, Y-axis, or X-axis).

For the high-stability system, as depicted in the diagram on page 32, the *current transducer* is also duplicated for each axis along with the load cables.

CAUTION

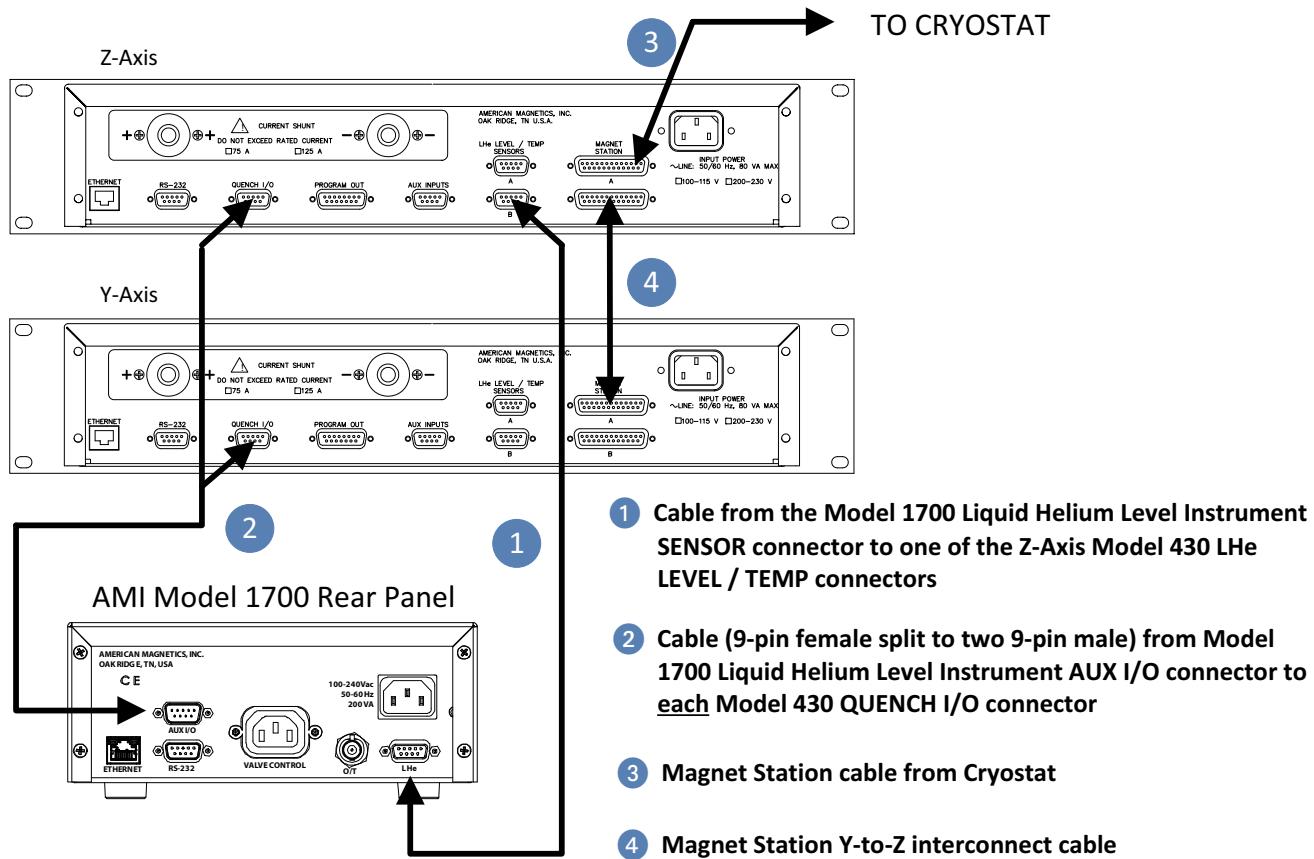
For multi-axis systems, ensure the power supply and magnet load cables are connected only to the equipment associated with the axis for which the cable is labeled.

INSTRUMENTATION CABLES

Instruments such as level, temperature, pressure, etc. that are part of the system are typically not duplicated for each axis since they have the capability to be switched among the various sensor and control devices connected to them. The instrumentation cables are designed to distribute the cryostat sensor and control signals to/from the associated instrument.

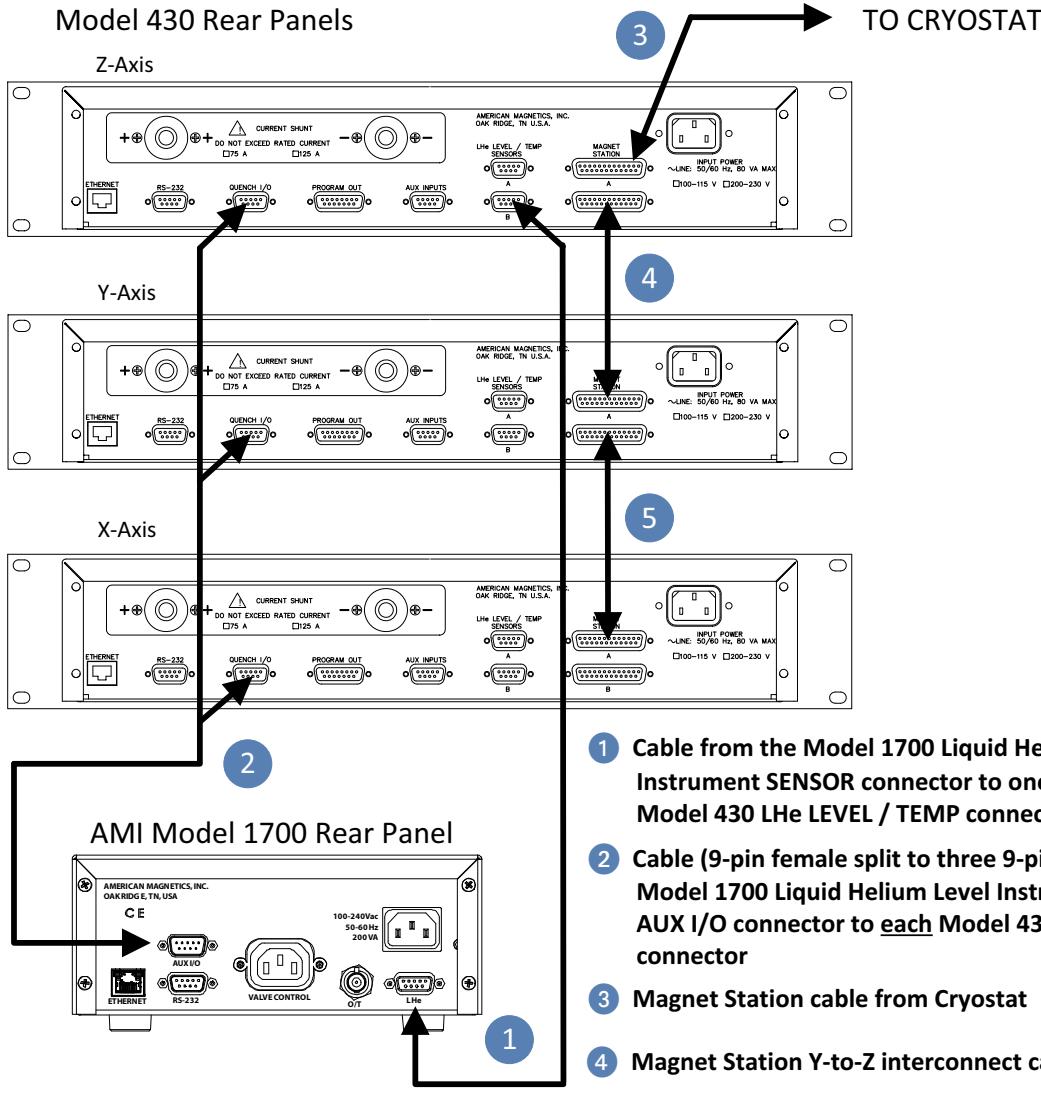
The Magnet Station Cable carries the signals between the cryostat and system rack equipment. For standard helium-based (non-recondensing) systems, the Magnet Station Cable connects directly to the Model 430 Power Supply Programmer. However, for helium-recondensing or cryogen-free systems, the Magnet Station Cable connects to the Model 430 through a distribution or breakout box. The temperature and pressure instruments have electrical signals that pass through the breakout box. Refer to the illustrations that follow.

STANDARD (NON-RECONDENSING) HELIUM-BASED 2-AXIS SYSTEM SIGNAL INTERCONNECTS



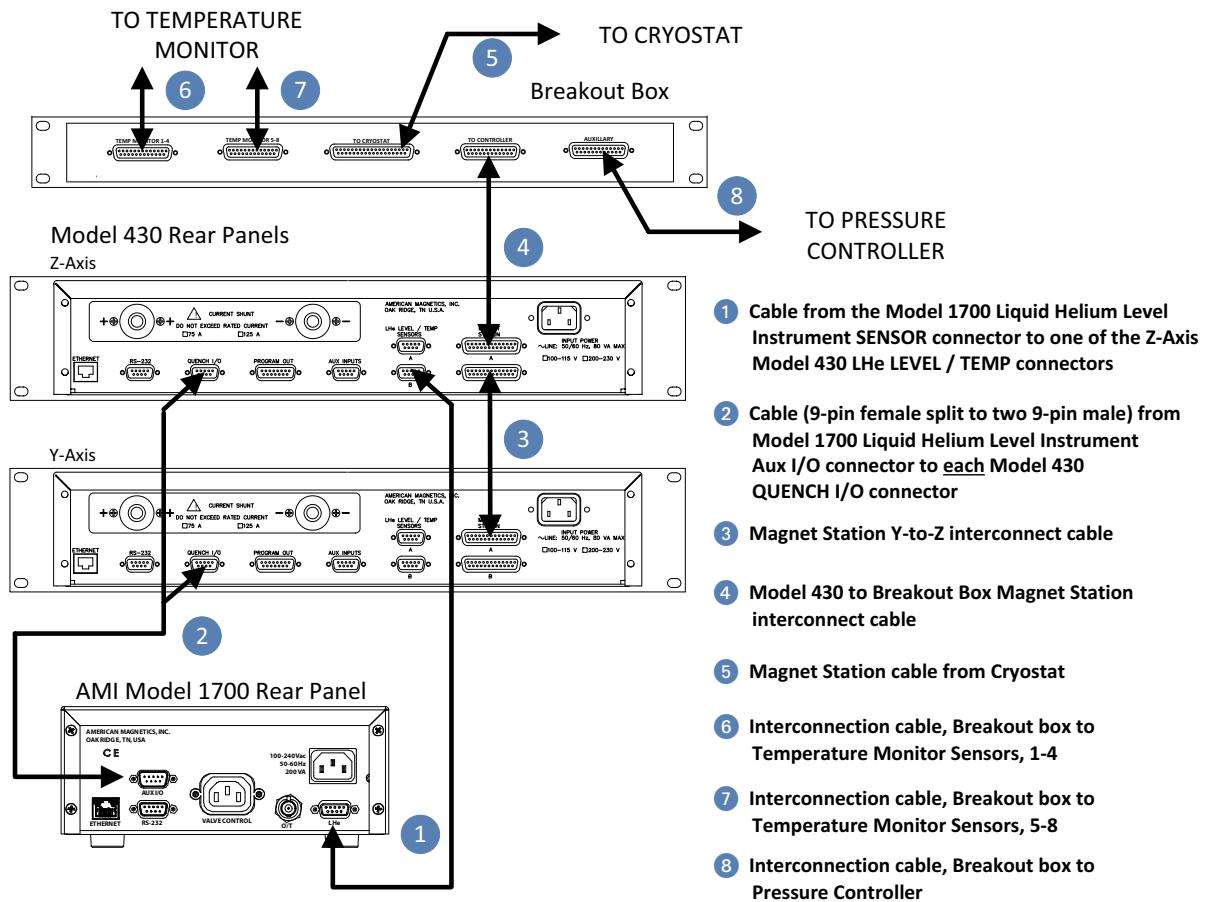
Two-Axis Standard Helium System Signal Interconnections

STANDARD (NON-RECONDENSING) HELIUM-BASED 3-AXIS SYSTEM SIGNAL INTERCONNECTS



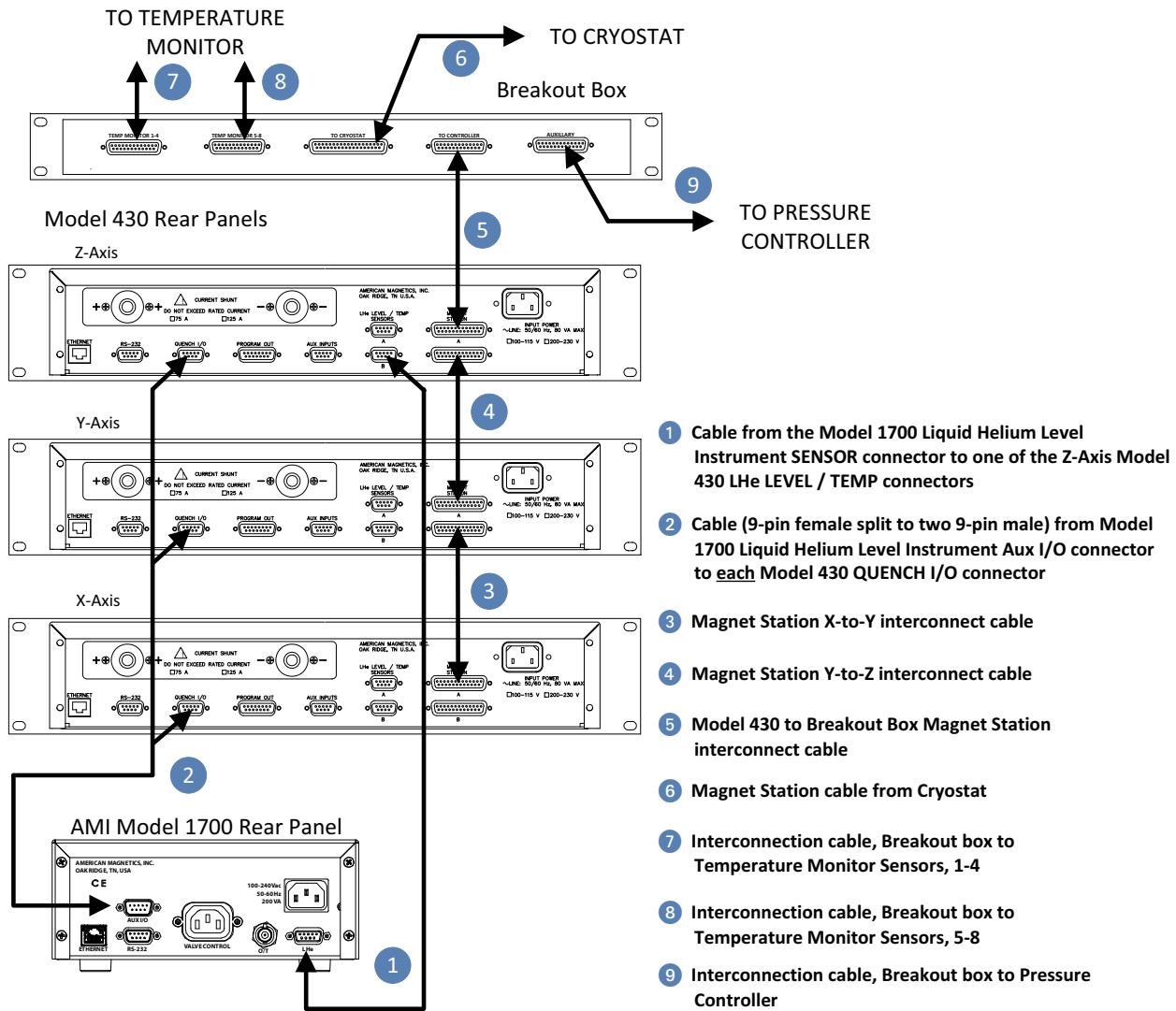
Three-Axis Standard Helium System Signal Interconnections

RECONDENSING HELIUM-BASED 2-AXIS SYSTEM SIGNAL INTERCONNECTS



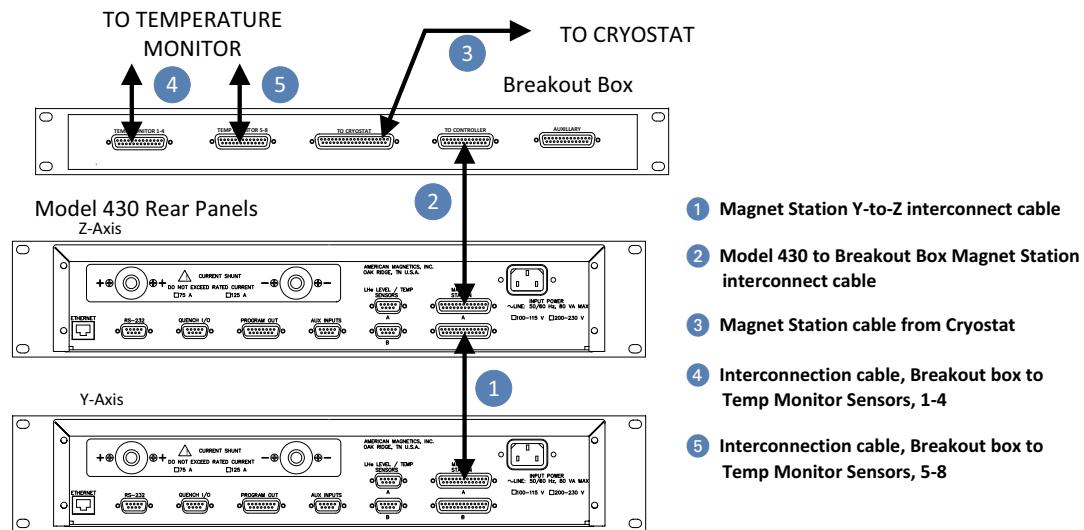
Two-Axis Recondensing Helium System Signal Interconnections

RECONDENSING HELIUM-BASED 3-AXIS SYSTEM SIGNAL INTERCONNECTS



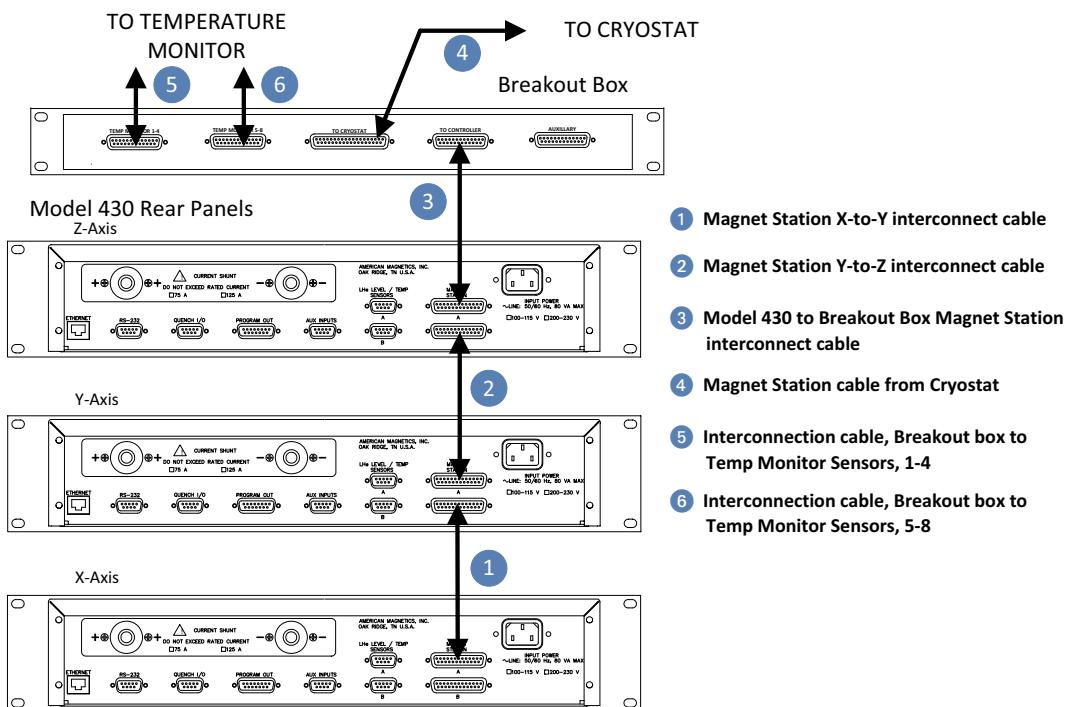
Three-Axis Recondensing Helium System Signal Interconnections

CRYOGEN-FREE 2-AXIS SYSTEM SIGNAL INTERCONNECTS



Two-Axis Cryogen-free System Signal Interconnections

CRYOGEN-FREE 3-AXIS SYSTEM SIGNAL INTERCONNECTS



Three-Axis Cryogen-free System Signal Interconnections

THIRD-PARTY POWER SUPPLIES

The Model 430 Programmer has been designed to function with a wide variety of third-party power supplies. Please contact an AMI Technical Support Representative for compatibility with specific models. Custom modifications can sometimes be made to accommodate supplies that are not compatible with the standard Model 430 configurations.

SPECIAL CONFIGURATIONS

The Model 430 Programmer has been designed for optimal operation with a superconducting magnet (i.e. a very low resistance, high inductance load) with a persistent switch. The Model 430 Programmer is capable of controlling current to other loads; however, some modification to the Model 430 Programmer settings and/or connections must usually be made. Two commonly encountered configurations are: 1) superconducting magnets without a persistent switch, and 2) operation on a short-circuit or low resistance load.

SUPERCONDUCTING MAGNETS WITH NO PERSISTENT SWITCH

An external stabilizing resistor for superconducting magnets without a persistent switch is no longer required⁴. However, electronically stabilizing such magnets requires a filter that has a differentiating action which can appear to amplify voltage noise across the magnet. If the magnet voltage noise, as indicated by V_m on the Model 430 status screen, is considered excessive for a user's experiment, the user may opt instead to use a stabilizing resistor.

OPTIONAL STABILIZING RESISTOR INSTALLATION

The stabilizing resistor, along with the proper Model 430 configuration, can reduce the apparent voltage noise across the magnet terminals by an order of magnitude or more.

To configure the Model 430 to use the stabilizing resistor, perform the following steps:

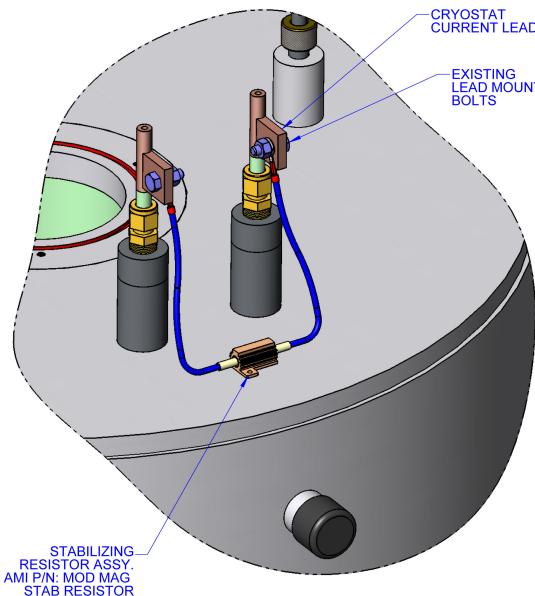
4. Effective with Model 430 firmware version 1.62 or later.

1. Place a 20 Ohm resistor, rated for 1W or higher, across the magnet current leads at the top of the cryostat as shown in the figure at right.
2. Ensure the Model 430 is configured for no persistent switch installed (see page 86).

3. Use the
CONF:STAB:RES 1
remote command (see
page 159) to configure
the Model 430 for opera-
tion with the stabilizing
resistor.

Optionally use the Magnet-DAQ application provided with the Model 430 to indicate a stabilizing resistor is installed (see page 189).

4. Ensure the Stability Mode setting (see page 80) is configured for Auto Stability Mode and manually entering the connected magnet inductance as shown on page 85.



Cryostat with Stabilizing Resistor across the Magnet Current Leads

SHORT-CIRCUIT OR RESISTIVE LOAD

If operating with a short-circuit as a load *without the presence of a superconducting magnet or with the power leads shorted at the cryostat*, the Model 430 Programmer Stability Mode must be configured for Test (see page 80).

NOTE If you have purchased a superconducting magnet with the Model 430 Programmer, AMI will normally provide a recommended stability setting for optimal operation of the magnet system. If you operate the Model 430 Programmer with a different load, be sure to restore the Stability Mode and Stability Settings after testing to the AMI-recommended values when the superconducting magnet is reconnected.

A *special test case* is with the energy absorber designs available from AMI connected to the system. The Model 601 Energy Absorber is a nearly infinite-resistance device until 5 VDC is achieved across its terminals. Once the 5 VDC "bias" is present, the Model 601 allows current flow with a nominal 2 mΩ series resistance. Therefore, the Model

430 Programmer will require an “integration time” to overcome the 5 VDC bias. Once the bias is achieved, the series resistance is minimal, the Model 601 appears as a short-circuit, and test ramping will proceed. It is not possible to avoid this integration time.

However, when operating *with a superconducting magnet in the circuit*, the increased integration gain of the Model 430 Programmer will be adequate to quickly “bias” the Model 601 and achieve a proper current ramping profile. The only time the “integration time” is long is when an energy absorber is connected, and the load is a short circuit.

POWER-UP AND TEST PROCEDURE

It is important to verify that the magnet system has been properly connected before the superconducting magnet is energized. This is especially recommended if the system is to be controlled via a computer since this setup will allow software debugging without the potential for damage to the magnet. The following procedures will assist the user in verifying key system components.

1. Using the appropriate diagram from the Installation section as a guide, verify all system components are connected as shown. If there is any doubt as to the correct connection of a component, contact an AMI Technical Support Representative. The user may be required to properly make a few connections between the various system components which were disconnected to facilitate packing and shipping.
2. Temporarily place a short across the magnet current terminals. Often this is most easily accomplished by unfastening the heavy cables from the magnet current leads and fastening them together.⁵ This will allow rudimentary power supply checks without energizing the superconducting magnet.

NOTE It is important that the full length of the power leads to the magnet be connected during the *Test mode* since the leads provide some resistive load (albeit in the tens of $m\Omega$ range) for the power supply. The output current of a truly shorted supply output (i.e. zero resistance load) is very difficult to control in voltage mode and may be unstable.

3. Energize the Model 430 Programmer by placing the power switch in the **I** (ON) position.
5. If the system shipped with CamLoc quick-disconnect connectors, they may be quickly disconnected from the magnet leads and connected together.

NOTE If energy absorbers are in use, ensure all the power adapters are properly connected to the energy absorbers and their respective AC power receptacles.

4. When prompted by the Model 430 Programmer, energize the power supply(s), allow an appropriate amount of time for the supply(s) to start (some produce an audible “click” during power-up), and then press **ENTER** on the Model 430 Programmer. If there is more than one power supply, observe the proper master/slave power-up procedure.
5. Configure the Model 430 Programmer for *Test* Stability Mode. Refer to page 80.

NOTE The Model 430 Programmer Stability Mode must be set to *Test* for the power supply system to be stable on a short circuit test load.

6. Verify the various setup menu values for the system. If the power supply system was purchased with an AMI magnet, AMI has preset the setup menu values for proper operation. See page 73 for more discussion of the setup menu values and their entry into the Model 430 Programmer.
7. Set the Target Setpoint to 10 A. Refer to page 54 and page 61.
8. Initiate ramping to the target current by pressing the **RAMP / PAUSE** key (status indicator changes from  to ).
9. The system should ramp to 10 A in approximately 2 seconds.⁶ Verify this is the case.

NOTE If an energy absorber unit is connected, the Model 430 Programmer may take significantly longer to ramp the current to 10 A. The Model 430 must first develop a supply output voltage to overcome the forward voltage drop of a connected energy absorber. During actual magnet operation, the presence of an energy absorber will not significantly delay the ramping operation since the Model 430 control gain is increased by orders of magnitude when an inductive load is connected.

10. When the target current is achieved, the **FIELD AT TARGET** LED will be illuminated. The display should show “+10.00 A –” indicating that the Model 430 Programmer is in the holding mode at the target current value (+10.00 A).
11. If the connected power supply has a display, verify that the power supply output current display indicates that a total of approximately 10 A is being supplied to the load (which is only the cabling in this case).
6. When controlling a magnet, the ramp is very accurate because the system gain is relatively high. When controlling current through a short-circuit, the loop gain is relatively low and it is difficult to track high ramp rates.

NOTE There may be a discrepancy between the current shown on the power supply display⁷ and the current displayed on the Model 430 Programmer. The current measurement system incorporated in the Model 430 is more accurate than the power supply shunt.

12. Set the Target Setpoint to the Current Limit value. Refer to page 92 to determine the Current Limit value. After the new Target Setpoint current value is entered, the Model 430 Programmer should ramp automatically to the new setting.
13. When the new target current value is reached, the power supply current display (if provided) should also indicate the new value.
14. Press the **RAMP TO ZERO** key to ramp the system to zero current.
15. Perform remote control software checkout as required.
16. Turn off the power supply(s).
17. Reset the Stability Mode to *Auto* or *Manual* as appropriate for the magnet system to be operated and, if necessary, the parameters for an installed Persistent Switch. Then turn off the Model 430.
18. Remove the short from the power supply leads and connect the leads to the current leads on the cryostat.

After successful completion of this test, the system is ready for operation with a superconducting magnet. Refer to the ramping function example presented on page 125 for a discussion of the various available ramping methods.

7. Not all power supplies have a local current readout.

Operation

This section describes the operation of the Model 430 Programmer. Every menu and submenu item is illustrated and described in detail. An example setup of the Model 430 Programmer is presented on page 112. An example ramping operation is presented on page 125.

SYSTEM POWER ON/OFF SEQUENCE

The Model 430 Programmer should always be energized *before* the power supply(s) that it is controlling. The Model 430 Programmer is designed to prompt the user in order to ensure the power supply is energized at the proper time. The Model 430 Programmer should always be de-energized *after* the power supply is shut down.

MODEL 430 PROGRAMMER POWER ON/OFF

Place the Model 430 Programmer power switch in the **I** (ON) position. After the Model 430 Programmer is powered on and fully initialized (about 20 seconds), the following display will appear:

```
0.00 A - Turn on power supply  
0.00 US Press ENTER to continue
```

After this screen is displayed, the power supply can be powered up (See “Energizing the Power Supply and Components” on page 50.) *followed by* pressing the **ENTER** key on the Model 430 Programmer. This brings up the default display.

NOTE If the display instead appears as illustrated below, turn the Model 430 Programmer off, wait 15 seconds or more, and power the Model 430 Programmer back on.

AMI Model 430 Programmer
FAILURE TO LOAD.

When powering the system off, first turn off the power supply controlled by the Model 430 Programmer followed by the Model 430 Programmer. The controller will then ensure the load sees no abnormal power transients as the power supply is turning off.

ENERGIZING THE POWER SUPPLY AND COMPONENTS

WARNING Do not change power supply jumpers, dip-switches, or other factory settings. If not rack-mounted, always position power supply(s) for convenience in disconnecting the power cords.

CHECK THE ZERO FLUX CURRENT TRANSDUCER

If the system includes the High-Stability Option, then a zero flux current transducer is provided. The current transducer must be connected to the Model 430 rear panel **CURRENT TRANSDUCER** connector.

CAUTION Operating the system without power applied to the current transducer (CT) can result in loss of control, and may damage the CT.

The current transducer receives power from the Model 430 Programmer through the **CURRENT TRANSDUCER** connection (that connects directly to the transducer) on the rear panel of the Model 430 Programmer.

ENERGIZING THE POWER SUPPLY

CAUTION The master unit must be turned on between 2 to 5 seconds before the slave, otherwise the units will fault and the power-up sequence will have to be repeated.

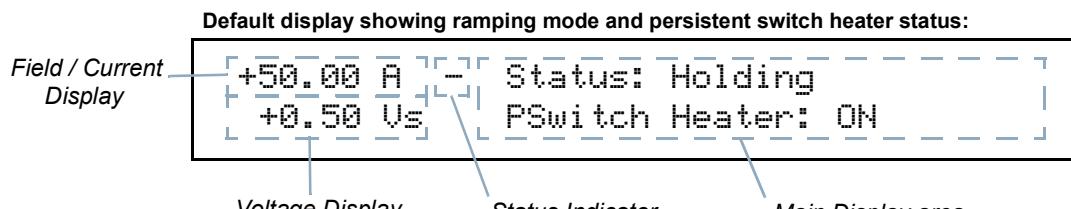
Place the power supply switches in the **I** (ON) position in sequence (see Caution above). No front panel adjustments or

connections are required since the power supply control mode and other parameters have been factory-configured for control by the AMI Model 430 Power Supply Programmer.

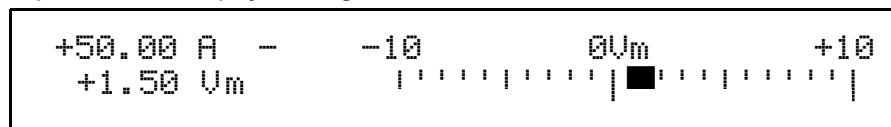
When powering the system off, turn off the power supply(s) (master unit *last*) *before* powering off the Model 430 Programmer.

MODEL 430 PROGRAMMER DEFAULT DISPLAY

The default display is illustrated in the figure below. It is displayed whenever no menus are being accessed and no errors are active. The default display can be thought of as being logically divided into four display areas — the Field / Current Display area, the Voltage Display area, the Status Indicator area and the Main Display area.



Optional default display showing a voltmeter:



Illustrations of the default displays

FIELD / CURRENT DISPLAY

The field / current display indicates either the field strength or current¹. This is always displayed in the upper left corner of the display (see the figure above), regardless of what else is being displayed on the Model 430 Programmer display. The parameter displayed (field or current) is toggled by pressing **SHIFT** followed by **FIELD < > CURRENT**.

Thus, if field strength is being displayed, pressing **SHIFT** followed by **FIELD < > CURRENT** will cause the current to be displayed; conversely,

1. The value is always displayed in current (A) when an installed persistent switch is in the *cooled state* since the value represents power supply current only, independent of the stored (i.e. persistent) magnet current/field.

if current is being displayed, pressing **SHIFT** followed by **FIELD <> CURRENT** will cause the field strength to be displayed.

Operating current is always displayed in amperes (A). Operating field strength may be displayed in kilogauss (kG) or tesla (T) if a coil constant has been specified in the setup². If field strength is being displayed, the units (kG or T) in which it is displayed can be toggled by pressing **SHIFT** followed by **FIELD UNITS**.

NOTE The displayed field strength is not directly measured, but rather is calculated by multiplying the coil constant entered in the setup menu by the measured current flow of the Model 430 power supply system.

VOLTAGE DISPLAY

The voltage display indicates either the voltage across the magnet (**Vm**) or the power supply output voltage (**Vs**). This is always displayed in the lower left corner of the display (see the figure on page 51), regardless of what else is being displayed on the Model 430 Programmer display.

The parameter displayed (magnet voltage or power supply voltage) is toggled by pressing **SHIFT** followed by **Vs <> Vm** (i.e. SHIFT+0).

NOTE The right and left arrow keys can also be used to toggle the Voltage Display area to show the present temperature in Kelvin as optionally read via the Auxiliary Input 3. For more details, see page 95.

Vm indicates the voltage measured across the terminals of the connected superconducting magnet. In order for the Model 430 Programmer to measure the magnet voltage, the magnet voltage taps must be connected to the Model 430. Normally this is done through the Magnet Station Cable provided by AMI (if the whole magnet system is provided by AMI). **Vs** indicates the Model 430 Programmer-controlled power supply output voltage.

NOTE The displayed power supply voltage (**Vs**) is not directly measured, but rather is calculated based on power supply control voltage being provided by the Model 430 Programmer and the power supply input control voltage and output voltage values entered in the setup menu.

2. Refer to page 83.

STATUS INDICATOR

Description of Status Indicators

P	Paused
↑	Ramping Up
↓	Ramping Down
-	Holding
◊	Heating Persistent Switch
	Cooling Persistent Switch
V	Voltage Limited
C	Current Limited
T	Temperature Limited

The status indicator displays the Model 430 Programmer operating status. It is always visible (except during a quench condition) and is displayed just to the right of the field / current display (see the figure on page 51). The status indicator may be one of the symbols indicating a condition as described in the table at left.

If the ramping mode character is blank, then a quench condition exists and the red **MAGNET QUENCH** LED on the front panel will be illuminated.

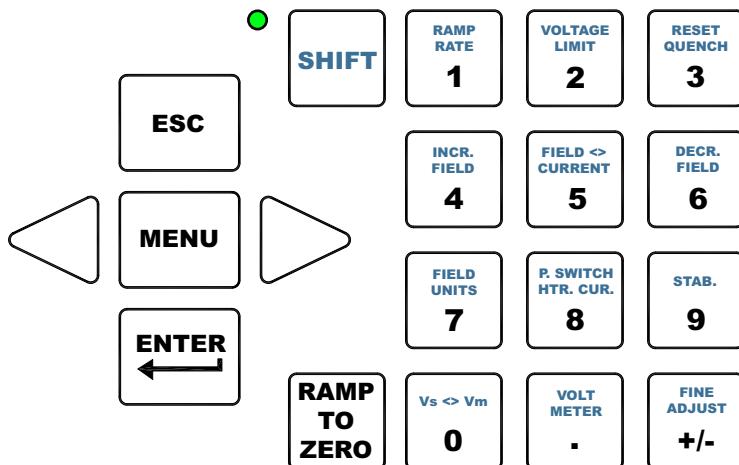
See page 114 for a more detailed discussion of the meaning of the ramping modes (Paused, Ramping Up, Ramping Down and Holding).

MAIN DISPLAY

The default main display (the rightmost portion of the display – see the figure on page 51) shows either a voltmeter indicating magnet voltage or ramp mode and persistent switch heater state. Ramp mode is displayed on the top line of the main display; it will be one of ten states, as listed in the table on page 115.

The persistent switch heater state is displayed on the bottom line of the main display. If the Model 430 Programmer has been setup for use with a persistent switch, it will indicate either ON or OFF for the persistent switch heater state; otherwise, it will display “No PSwitch Installed.”

ENTERING NUMERIC VALUES



Numeric Keypad and Associated Keys

A consistent method of entering values is used within menus requiring numeric entries. Once a menu is selected, the user may start an entry by pressing a digit (**0** through **9**), the decimal key (**.**), or the sign key (**+/-**).³ The display will begin a new entry and display a cursor (**_**) as a prompt for the next digit or decimal entry. Also, once entry is initiated, the display will show an asterisk (*****) indicating that numeric entry is *active*.

Alternately, the **ENTER** key may be pressed before any of the numeric keypad keys; the display will begin a new entry and display a cursor (**_**) as a prompt for the next digit or decimal entry, and the display will show an asterisk (*****) indicating that numeric entry is *active*.

An example of a numeric entry in progress (numeric entry active) is illustrated below:

```
+50.00 A - Target Current (A)*
+0.50 Vs +74_
```

Once the numeric value has been entered, press the **ENTER** key to accept the numeric value. Values are *not* applied to the operation of the Model 430 Programmer until the **ENTER** key is pressed and the asterisk disappears from the display. Attempts to set a parameter to a value

3. Certain menu items requiring numeric data can also be entered using the fine adjust knob (see page 55).

outside of the valid range are ignored, and if attempted the Model 430 Programmer will beep once, indicate the error, and revert to the previous setting.

If the **ESC** key is pressed while numeric entry is active and digits have been entered, the entered digits will be cleared and the cursor will remain for reentry of a new desired value. If the **ESC** key is pressed with no entered digits on the display, the setting will revert to the previous value and numeric entry will be made inactive.

Thus, if digits have been entered, the first time **ESC** is pressed, the entered digits are cleared, but numeric entry remains active; if **ESC** is then pressed again (with no entered digits displayed), the setting reverts to its previous value and numeric entry is made inactive.

Note that if the **ESC** key is pressed when numeric entry is *not* active, the current submenu will be exited and the next higher level submenu will be entered.

USING THE FINE ADJUST KNOB

For menu items requiring entry of a numeric value, the value may alternatively be adjusted with the front panel fine adjust knob. These menu items include:

- Target Field Setpoint (in holding mode or while ramping)
- Voltage Limit
- Ramp Rate (if there is no PSwitch or if PSwitch is fully heated). Disallowed during switch heating/cooling transition.
- Custom Supply Menu (Min Output Voltage, Max Output Voltage, Min Output Current, Max Output Current)
- Stability Setting
- Coil Constant
- Current Limit
- PSw P/S Ramp Rate if PSwitch is fully cooled. Disallowed during switch heating/cooling transition.
- PSwitch Current
- PSwitch Heated Time
- PSwitch Cooled Time
- PSwitch Cooling Gain

Instead of entering a value using the numeric keypad, the operator can press the **SHIFT** key, followed by **FINE ADJUST** (i.e SHIFT +/-). The display will then show an up/down arrow (\pm) indicating that the fine adjust knob is active.

When the fine adjust knob is live, adjustments made using it take place *immediately*. This can be a useful and powerful functionality. Any numeric value can be incrementally adjusted using the fine adjust knob, and its affect on the system can be observed *as the adjustment is being made*.

For example, with the persistent switch heater on, the persistent switch heater current can be adjusted incrementally to find the persistent switch heater superconducting/normal thresholds.

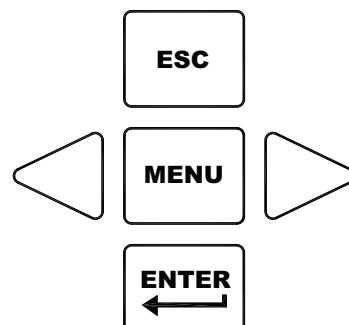
An example of a fine adjust in progress (fine adjust knob is live) is illustrated below:

+50.00 A	- PSwitch Current (mA)	Φ
+0.50 Vs	46.7	

NOTE The fine adjust knob is velocity-sensitive, meaning that the faster the knob is turned, the more coarse the adjustment. Slow manipulation of the knob will yield very fine resolution even beyond that displayed by the Model 430 Programmer.

When the desired numeric value has been set using the fine adjust knob, the **ENTER** key is pressed to store the value. Pressing the **ESC** key while the fine adjust knob is live will cause the adjusted value to revert to its previous setting and make the fine adjust knob inactive. In fact, pressing *any* key other than **ENTER** will cause the adjusted value to revert to its previous setting and make the fine adjust knob inactive.

SELECTING PICKLIST VALUES



Menu Navigation Keys

Some submenu items require the user to select a value from a list of predefined values (picklist values). Such menus will display an item selector (►) which points to the picklist value currently selected. To change the value to another value in the picklist, first press the **ENTER** key; the display will show an asterisk (*) indicating that picklist entry is *active and can be edited*.

While picklist entry is active, the left and right *keypad* arrows (to the left and right of the **MENU** key) move the item selector between the different picklist values. Pressing the left keypad arrow moves the item selector one picklist value to the left and pressing the right keypad arrow moves the item selector one picklist value to the right.

When the last picklist value is reached, and the right keypad arrow is pressed, the item selector will move to the first picklist value. Likewise, when the item selector is pointing to the first picklist value, and the left keypad arrow is pressed, the item selector will move to the last picklist value.

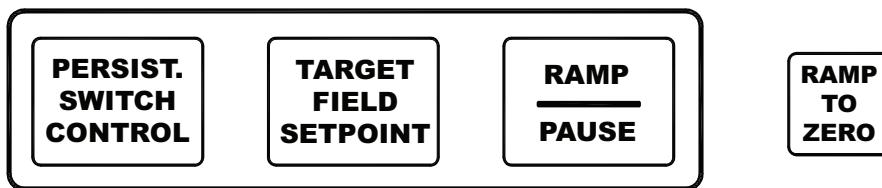
An example of a picklist entry in progress (picklist entry active) is illustrated below:

```
+50.00 A - Field Units*
+0.50 Vs    ►Kilogauss    Tesla
```

When the item selector is pointing at the desired picklist value, press the **ENTER** key to accept the picklist value. Values are *not* applied to the operation of the Model 430 Programmer until the **ENTER** key is pressed and the asterisk disappears from the display.

If the **ESC** key is pressed while picklist entry is active, the setting will revert to the previous value and picklist entry will be made inactive. Note that if the **ESC** key is pressed when numeric entry is *not* active, the current submenu will be exited and the next higher level submenu will be restored (if it exists).

SINGLE-KEY COMMANDS / MENUS



Single Input Keys

All ramping controls (**PERSIST. SWITCH CONTROL**, **TARGET FIELD SETPOINT**, **RAMP / PAUSE** and **RAMP TO ZERO**) are accessed with a single keystroke. See page 114 for details of ramping controls. Below is a brief summary of the function of each of these keys.

PERSISTENT SWITCH CONTROL KEY

Pressing the **PERSIST. SWITCH CONTROL** key toggles the Model 430 Programmer persistent switch heater control function.

If the persistent switch heater is *energized* and this key is pressed, the persistent switch heater is de-energized. The power supply output is then maintained for the time set by the PSwitch Cooled Time setting before being ramped down to zero at the PSw P/S Ramp Rate setting (default rate is 10 A/sec, note that the magnet is *not* in the circuit after the heater is de-energized).

If the persistent switch heater is *de-energized* and this key is pressed, the power supply is ramped to the current present in the magnet when the switch was cooled at the rate set by the PSw P/S Ramp Rate (i.e. "matching the last known current") and then the persistent switch heater is energized.

NOTE Since the magnet is isolated from the power supply output while the persistent switch is in the cooled state, it is possible to ramp the power supply output current up/down at the much faster PSw P/S Ramp Rate setting.

PRESSING THE SHIFT KEY TO AVOID AUTOMATIC RAMPING

Pressing **SHIFT** followed by the **PERSIST. SWITCH CONTROL** key only toggles the Model 430 Programmer persistent switch heater between energized (turned on) and de-energized (turned off). If the persistent switch heater is energized and this key is pressed, the persistent switch heater is de-energized. If the persistent switch heater is de-energized and this key is pressed, the persistent switch heater is energized. The switch heater heating and cooling times, or voltage-based sensing, as described in the following sections will apply.

NOTE The power supply output current remains unchanged when **SHIFT** followed by **PERSIST. SWITCH CONTROL** is used. Only the state of the persistent switch heater is changed.

When the persistent switch heater is energized, the Model 430 Programmer is supplying current to the appropriate pins (9 & 10) of the Magnet Station Connectors in order to drive the persistent switch into a normal state, which takes the magnet out of persistent mode. Magnet persistent mode is indicated by the **MAGNET IN PERSISTENT MODE** LED⁴.

The Model 430 Programmer will beep once (indicating an error) if the user attempts to activate the switch heater control without first indicating a persistent switch is installed in the Switch submenu and specifying the switch heating current, switch transition detect method, and the heated time and cooled time⁵ for timer-based transitions.

The nominal switch heating current is listed on the magnet specification sheet, and may be entered in the Model 430 Programmer by accessing the Switch submenu⁶. In addition to the *heating current*, the user must also specify the *switch transition* detection method, *PSw P/S Ramp Rate* and *cooling gain*. If the switch transition is timer-based, then the *heated time* and *cooled time* must also be specified.

TIMER-BASED SWITCH TRANSITIONS

The heated time allows the Model 430 Programmer to delay compensating the internal control logic until the magnet is guaranteed to be in the circuit. The heated time can be set from a minimum of 5 seconds to a maximum of 120 seconds within the Load submenu⁷. The default heating period of 20 seconds is

4. See page 71.
5. See page 86 and page 88.
6. See page 88.
7. See page 89.

adequate for the majority of persistent switches. If the magnet appears unstable just after the switch heating period expires, increase the switch heated time to allow for complete heating.

The cooled time allows the persistent switch sufficient time to be cooled to superconducting state before the current is changed in the magnet. The cooled time can be set from a minimum of 5 seconds to a maximum of 3600 seconds within the Load submenu⁸. The default cooling period of 20 seconds is adequate for the majority of wet persistent switches. Conduction-cooled switches may require longer times to transition from resistive to superconducting state and can benefit from direct magnet voltage-based transition detection as described below.

During timer countdowns, the remaining time in seconds is displayed in the default display status area. A value of (0) indicates the respective timer has expired.

MAGNET VOLTAGE-BASED SWITCH TRANSITIONS

For magnet voltage-based switch detections, a running average and variance of the magnet voltage is calculated. If the running average is less than 0.5 mV *and* the variance is less than an adjustable preset limit (typically 10 nV²), the switch is considered in the cooled state. The variance must exceed six times (6x) the preset limit to be considered as exiting the cooled state.

The average *and* variance limits essentially describe a constant magnet voltage of zero (0) volts given the internal Model 430 resolution of the voltage measurement, which is the expected value a *cooled* persistent switch should exhibit in the superconducting state. An additional safety factor delay of 5 seconds is added for each transition once the limits are exceeded.

Magnet voltage-based transition detection *requires* magnet voltage taps connected to pins 11 & 12 of the Magnet Station connector as described on page 212.⁹

During magnet voltage-based transitions, the running variance in nanovolts² (nV squared) is shown in the default display status area. A continuous value of (0) indicates a cooled switch state.

The default cooling gain of 0.0% may be adequate for the majority of wet persistent switches. However, this setting may result in some magnet

8. See page 90.

9. The additional provision of connecting the magnet voltage taps to Auxiliary Input 1 must be addressed if using a Model 430 with firmware prior to version 3.00. See page 220.

drift during persistent switch cooling, especially with conduction cooled switches. Increasing the cooling gain adds control loop gain during the switch cooling cycle. Too little may result in magnet drift during switch cooling. Too much may result in power supply instability during switch cooling, which could potentially prevent the switch from cooling. Most systems requiring some cooling gain to control magnet drift will likely work with value set to 25%.

NOTE During the period the switch is being heated or cooled, the Model 430 Programmer will not allow ramping functions to be executed, and will beep once and indicate an error if the user attempts to initiate a ramping operation.

Refer to page 117 for a complete description of the magnet persistent switch control sequences.

TARGET FIELD SETPOINT KEY

Pressing the **TARGET FIELD SETPOINT** key provides a menu for setting the target field/current. The target field/current is the field or current to which the Model 430 Programmer ramps the superconducting magnet when it is not paused. The target field/current may be set equal to or less than the Current Limit¹⁰ or equivalent field (per defined coil constant).

The target field/current requires a sign for four-quadrant systems since it defines a single setpoint within the entire field/current range of the system (positive and negative).

```
+50.00 A - Target Field (kG)  
+0.50 Vs      +50.000
```

When on the default display, pressing the **SHIFT + TARGET FIELD SETPOINT** keys will display the Magnet Current/Field for three seconds before reverting to the default display. Pressing any key will clear the display. The value displayed is as follows:

- When in driven mode, the present current/field will be displayed.
- When in persistent mode, the current/field displayed is the value that was circulating in the magnet at the time persistent switch was cooled.

```
+0.25 A P Magnet Current (A)  
0.00 Vs      +10.00 A
```

10. See page 92.

RAMP / PAUSE KEY

Pressing the **RAMP / PAUSE** key toggles the Model 430 Programmer between the ramping mode and the paused mode. If the **RAMP / PAUSE** key is pressed while the Model 430 is ramping, the ramping is paused. If the **RAMP / PAUSE** key is pressed while the Model 430 is paused, the Model 430 continues ramping.

RAMP TO ZERO KEY

Pressing the **RAMP TO ZERO** key causes the Model 430 Programmer to immediately begin ramping field/current up or down to zero field/current at the defined ramp rate(s). Ramping to zero may be interrupted at any time by pressing the **RAMP / PAUSE** key, which causes the Model 430 Programmer to enter the PAUSED mode and maintain the field/current present at the point it was paused.

The **RAMP TO ZERO** function is very useful for returning the system to zero field/current without disturbing the Target Setpoint value.

NOTE If the **RAMP TO ZERO** function is paused and then the **RAMP / PAUSE** button is pressed a second time, the Model 430 Programmer will begin ramping to the target field, not to zero. If it is desired to ramp to zero after the **RAMP / PAUSE** button is pressed, press the **RAMP TO ZERO** button again to continue ramping to zero from the paused state.

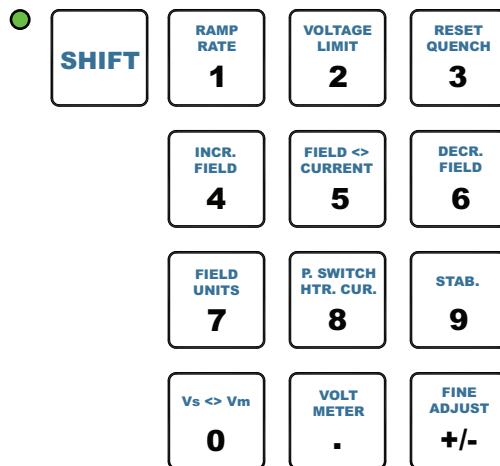
NOTE If the magnet is persistent (i.e. switch heater is not energized) when the **RAMP TO ZERO** key is pressed, the Model 430 Programmer ramps the power supply current to zero; the magnet current will remain constant since the magnet is in persistent mode.

SHIFT+KEY COMMANDS / MENUS

The most commonly used commands and menus (other than ramping controls) are accessed using the **SHIFT** key followed by a numeric keypad key. Use of the specific SHIFT+key commands and menus is described in sections specific to the functionality of that specific SHIFT+key combination.

In general, a SHIFT+key command is executed or a menu is accessed by first pressing the **SHIFT** key (which turns on the **SHIFT** LED), and then pressing¹¹ one of the keys of the numeric keypad (**0** through **9**, **.**,,

11. Note the SHIFT key plus the following key-press are sequential, not simultaneous.

**SHIFT+Key Functions**

or “+/-”). The SHIFT+key command / menu for each key of the numeric keypad is shown in light blue text at the top of each key.

To access the voltage limit menu, for example, press the **SHIFT** key, and then press the **VOLTAGE LIMIT** key (also the **2** key). Note that some of the SHIFT+key menus can also be accessed using the setup menu.

Pressing the **ESC** key or the **SHIFT** key a second time will clear the **SHIFT** function and return the keypad to its numeric function.

RAMP RATE (SHIFT+1)

Use of the **RAMP RATE** (SHIFT+1) key provides a menu for setting ramp rate(s). The ramp rate may be set¹² within the range specified for the specific Model 430 Programmer configuration (refer to the specifications on page 7). If field units are being used, then the ramp rate setting is displayed and set in units of kG/sec or T/sec.

The allowable range is defined by the setting of the coil constant and the allowable range of the ramp rate in terms of current as specified in the table on page 7. If the Ramp Segments value¹³ is greater than 1, then the menu also allows setting of the field or current range for each ramp rate segment.

The Model 430 Programmer will ramp at the specified rate if the available compliance of the power supply is sufficient and the Voltage Limit is not exceeded. The Model 430 automatically decreases the ramp rate internally during operation if either the available compliance of the power supply is insufficient, or the Voltage Limit is active.

12. Using numerical keys as described on page 54 or the fine adjust knob (page 55).

13. See page 99.

RAMP RATE EXAMPLE

An example (using a magnet with rated current of 60 A¹⁴) will illustrate the use of the ramp rate menus. The example assumes that the field/current units have been set to amperes and the ramp segments value has been set to three (3) segments. The ramping is chosen with rates as follows:

1. ± 0.2 A/s from 0 to ± 55 A
2. ± 0.1 A/s from ± 55 to ± 58 A
3. ± 0.05 A/s above ± 58 A.

In the following discussion, the fine adjust knob¹⁵ can optionally be used for ramp rate adjustment if the persistent switch is heated (or if no persistent switch is installed). If the user attempts to edit ramp rate segments using the fine adjust knob while an installed switch is cooled, the Model 430 Programmer will produce one beep to indicate an error¹⁶. Similarly, if the switch is heated (or no switch is installed), attempting to use the fine adjust knob for PSw P/S ramp rate will produce one beep¹⁷.

Pressing **SHIFT** and then **RAMP RATE** will access the ramp rate menu. The numeric and **ENTER** keys (or the fine adjust knob) are used to set the segment #1 ramp rate to a value of 0.2 A/sec.

```
+50.00 A - Seg.1 Ramp Rate (A/sec)
+0.50 Us    ±0.2000
```

The right arrow key is pressed once to access the segment #1 range display. The numeric and **ENTER** keys (or fine adjust knob) are used to set the segment #1 current range upper bound to a value of 55 A.

```
+50.00 A - Seg.1 Range (A)
+0.50 Us    0.0 to ±55.0
```

-
14. In this example, the Current Limit is set at the rated magnet current of 60 A.
 15. See page 55.
 16. Since the PSw P/S ramp rate is active in that scenario, and not the segmented ramp rate.
 17. Since the standard segmented ramp rate is active in that scenario, and not the PSw P/S ramp rate.

Pressing the right arrow key accesses the next (second) segment ramp-rate display. The segment #2 ramp rate is set to a value of 0.1 A/sec.

+50.00 A	-	Seg.2 Ramp Rate (A/sec)
+0.50 Vs		±0.1000

The right arrow key is pressed once to access the segment #2 range display. The segment #2 current range upper bound is set to a value of 58 A.

+50.00 A	-	Seg.2 Range (A)
+0.50 Vs		±55.0 to ±58.0

Pressing the right arrow key accesses the next (third) segment ramp rate display. The segment #3 ramp rate is set to a value of 0.05 A/sec.

+50.00 A	-	Seg.3 Ramp Rate (A/sec)
+0.50 Vs		±0.0500

Pressing the right arrow key accesses the segment #3 current range display.

NOTE If there is more than one segment, the upper bound of the last segment is always the Current Limit¹⁸ and it will be displayed as “±Limit” as shown below and cannot be edited.

+50.00 A	-	Seg.3 Range (A)
+0.50 Vs		±58.0 to ±Limit

Now, when current is in the range of 0 to ±55 A, ramping will be controlled at ±0.2 A/sec. When current is in the range of ±55 to ±58 A, ramping will be controlled at ±0.1 A/sec and when current is greater than ±58 A (up to the limit of 60 A), ramping will be controlled at ±0.05 A/sec.

If ramp rate of a ramp segment is being edited while the Model 430 is ramping and the system current/field transitions from the currently edited segment to the next before the adjustment has

18. Refer to page 92.

been committed with the **ENTER** key, the adjusted value *will be discarded*. The display will update to show the new segment ramp rate, and the fine adjust knob will apply to the new segment (assuming the **ENTER** key is pressed before the segment has completed).

If at some later time it is desired to set the Current Limit to a value less than 58 A, only the first two ramp segments would remain active since the new “limit” falls within the range of segment #2. The display for segment 2 range would then appear as follows¹⁹.

```
+50.00 A - Seg.2 Range (A)
+0.50 Vs   ±55.0 to ±Limit
```

Any unused segment(s) above the Current Limit will remain in memory (retaining their original parameters) until one or more become active again when the Current Limit is raised into or above the respective ranges. When displayed, the higher-range *unused* segments will show a range of “±Limit to ±Limit” until re-activated²⁰.

```
+50.00 A - Seg.3 Range (A)
+0.50 Vs   ±Limit to ±Limit
```

VOLTAGE LIMIT (SHIFT+2)

Use of the **VOLTAGE LIMIT** (SHIFT+2) key provides a menu for setting the limit for output voltage for the power supply the Model 430 Programmer controls. This value should be set to a high enough value so that under normal conditions, the Voltage Limit is never reached. The value can be set by using either the numeric keypad entry as described page 54 or the fine adjust knob (on page 55).

Note that the voltage drop in the leads must be accounted for when setting the Voltage Limit, as well as the voltage drop of an energy

-
19. If the Current Limit were to be set below 55 A, only segment #1 would be active, and would display the upper bound of “±Limit”.
 20. Also if the number of segments is increased, the new segments are added to the upper end of the ramp range, and default to the ramp rate of the previous segment with the range of ±Limit to ±Limit until set up.

absorber if in use (see page 114 for details of how to determine the appropriate Voltage Limit).

+50.00 A	-	Voltage Limit (U)
+0.50 Vs		± 2.000

The Voltage Limit may be set less than or equal to the maximum output voltage of the power supply.²¹ The Voltage Limit functions as a bipolar limit.

If Voltage Limit becomes active while ramping, it will be indicated by a reverse illumination character “V” for the status indicator.

+40.92 A	↑	Mode: Ramping
+2.50 Vs	V	PSwitch Heater: ON

Once the Voltage Limit function becomes active, the current, and therefore field, will no longer be ramping linearly with time as the voltage available to charge the magnet will be reduced as the total loop voltage will be limited. As the $i \times R$ drop of the leads increases with current, the voltage available to charge the magnet will be reduced.

RESET QUENCH (SHIFT+3)

The **RESET QUENCH** (SHIFT+3) key is used whenever a quench detection has occurred and is being indicated on the display (example shown below).

0.00 A	-	Quench Detect @ +45.81 A
0.00 Vs		PSwitch Heater: ON

When a quench detection has occurred, the Model 430 Programmer will respond to no further input until the **RESET QUENCH** key is pressed, or until the quench condition is cleared by a remote command. For more discussion of quench detection see page 127.

INCREMENT FIELD (SHIFT+4)

The **INCR. FIELD** (SHIFT+4) key is used to manually increase the field. This is done at the defined ramp rate(s).

When the **INCR. FIELD** key is pressed, the current/field begins ramping up. If the **INCR. FIELD** key is pressed again (while the current/field is manually ramping up), the ramping will be paused. Alternately, the

21. Refer to the table on page 76.

RAMP / PAUSE key may be pressed to pause manual ramping. Manual ramping will continue until paused or the Current Limit²² is achieved.

NOTE If the current/field is negative, using the **INCR. FIELD** key to increase (make more positive) the current/field, the magnitude of the current/field decreases.

FIELD <> CURRENT (SHIFT+5)

The **FIELD <> CURRENT** (SHIFT+5) key is used to toggle between the use of field units, either kG (kilogauss) or T (tesla), and the use of current units (A)²³. If the Model 430 Programmer is using field units (either kG or T) and the **FIELD <> CURRENT** SHIFT-key is pressed, the Model 430 Programmer will begin using current units (A). Conversely, if the Model 430 is using current units (A) and the **FIELD <> CURRENT** SHIFT-key is pressed, the Model 430 will begin using field units (either kG or T).

NOTE The Model 430 Programmer cannot use field units unless a valid coil constant has been entered²⁴.

DECREMENT FIELD (SHIFT+6)

The **DECR. FIELD** (SHIFT+6) key is used to manually decrease the current/field. This is done at the defined ramp rate(s).

When the **DECR. FIELD** key is pressed, the current/field begins ramping down. If the **DECR. FIELD** key is pressed again (while the current/field is manually ramping down), the ramping will be paused. Alternately, the **RAMP / PAUSE** key may be pressed to pause manual ramping. Manual ramping will continue until paused or the Current Limit²⁵ is achieved.

NOTE If the current/field is negative, using the **DECR. FIELD** key to decrease (make less positive) the current/field, the magnitude of the current/field increases.

FIELD UNITS (SHIFT+7)

Use of the **FIELD UNITS** (SHIFT+7) key provides a shortcut to the picklist menu²⁶ for defining whether the field is specified and displayed in

22. See page 92.

23. The value is always displayed in current (A) when an installed persistent switch is in the *cooled state* since the value represents power supply current only, independent of the stored (i.e. persistent) magnet current/field.

24. See page 83.

25. See page 92.

26. See page 100.

units of kilogauss (kG) or tesla (T). The selected option also applies to remote interface commands. The default setting is kilogauss.

+50.00 A	-	Field Units
+0.50 Vs	►	Kilogauss Tesla

PERSISTENT SWITCH HEATER CURRENT (SHIFT+8)

Use of the **P. SWITCH HTR. CUR.** (SHIFT+8) key provides a shortcut to the menu²⁷ for setting persistent switch heater current. The value can be set to between 0.0 and 125.0 mA. The default value is 10.0 mA unless preset by AMI to match a specific superconducting magnet.

+50.00 A	-	PSwitch Current (mA)
+0.50 Vs		10.0

STABILITY (SHIFT+9)

Use of the **STAB.** (SHIFT+9) key provides a shortcut to the menu for defining the Model 430 stability setting. The stability setting is specified in percent and controls the transient response and stability of the system. The valid input range is from 0.0 to 100.0%. The default value is 0.0% unless preset by AMI to match a specific superconducting magnet.

See page 81 for details of how to determine the stability setting to use.

Vs <> Vm (SHIFT+0)

The **Vs <> Vm** (SHIFT+0) key is used to toggle the voltage display between display of the voltage across the magnet (Vm) and the power supply output voltage (Vs). See page 52 for details.

VOLT METER (SHIFT+.)

The **VOLT METER** (SHIFT+.) key is used to toggle the main display between display of a voltmeter indicating magnet voltage (Vm) or supply voltage (Vs), and display of ramp mode and persistent switch heater state. See page 53 for details.

FINE ADJUST (SHIFT +/-)

The **FINE ADJUST** (SHIFT +/-) key is used to enable the use of the front panel fine adjust knob to adjust numeric values. See page 55 for details.

27. See page 88.

**SHIFT + PERSIST.
SWITCH CONTROL**

This keystroke enables persistent switch control *without* some automatic sequencing features. Refer to page 58.

LED INDICATORS

The Model 430 Programmer has six front panel LED indicators. See the front panel illustration and table on page 4 for the location of these indicators.

POWER-ON INDICATOR

The green power-on LED indicates that the Model 430 Programmer is powered on.

MAGNET STATUS INDICATORS

Four LEDs are grouped together to show the magnet status.

- **FIELD AT TARGET**
- **MAGNET IN PERSISTENT MODE**
- **CURRENT LEADS ENERGIZED**
- **MAGNET QUENCH**

Magnet Status LED Indicators

FIELD AT TARGET INDICATOR

The green **FIELD AT TARGET** LED indicates that the current is at the target value. If the magnet is not in persistent mode (persistent switch heater is on), then this is an indication that the magnet field has reached the target value. If the magnet is already in persistent mode, then this is an indication that the current being supplied to the magnet system has reached the target value.

MAGNET IN PERSISTENT MODE INDICATOR

CAUTION If the Model 430 Programmer power is turned off while the persistent switch is heated, persistent switch heating will be lost and the magnet will enter persistent mode. The Model 430 will not have a record of that event. Therefore the **MAGNET IN PERSISTENT MODE** LED state will be incorrect (remain OFF) when the Model 430 Programmer power is restored.

CAUTION

If the Model 430 Programmer power supply system is powered off and moved from one magnet system to another, the **MAGNET IN PERSISTENT MODE** LED may not correctly indicate the state of the magnet system until the first time the persistent switch heater is turned off.

NOTE

Should the magnet quench while the magnet is in persistent mode and the Model 430 Programmer is off, the persistent mode indicator LED will be incorrect when the Model 430 Programmer is turned on again.

The green **MAGNET IN PERSISTENT MODE** LED indicates that the persistent switch heater is off, and that when it was turned off, the magnet had greater than 0.1% of the maximum system current²⁸ flowing through it. The state of this LED is kept in nonvolatile memory when the Model 430 is powered off, so that the LED state is retained even during a power cycle of the Model 430. Thus, the **MAGNET IN PERSISTENT MODE** LED is an indicator that the magnet is persistent and has at least some persistent field.

CURRENT LEADS ENERGIZED INDICATOR

The blue **CURRENT LEADS ENERGIZED** LED indicates that at least 0.1% of the maximum system current²⁹ is flowing in the Model 430 power supply system output current leads.

MAGNET QUENCH INDICATOR

The red **MAGNET QUENCH** LED indicates that a magnet quench condition has been detected. See page 127 for details.

SHIFT INDICATOR

The green **SHIFT** LED indicates that the **SHIFT** key has been pressed, and the next numeric keypad key pressed will actuate the shifted function (shown in light blue text on the key label) rather than the numeric keypad function. See page 62 for details of **SHIFT** key use.

28. Example: For a system with an I_{max} value of 125 A, 0.1% of the current would be 0.125 A.

29. Example: For a system with an I_{max} value of 250 A, 0.1% of the current would be 0.250 A.

SETUP MENU

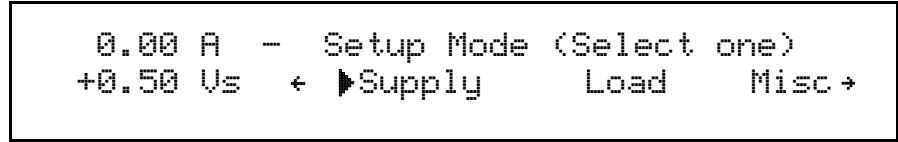
Setup of the Model 430 Programmer requires the user to navigate the setup menu. Navigation of the setup menu is intuitive — quite similar, for example, to the use of a cell phone menu.

ENTERING / EXITING SETUP MENU

To enter the setup menu, simply press the **MENU** key. When in any of the setup menus, pressing the **MENU** key will exit the setup menu. The **MENU** key toggles the Model 430 Programmer in and out of setup mode. Alternately, if the top level setup menu is being displayed, pressing the **ESC** key exits the setup menu.

MENU NAVIGATION

Pressing the **MENU** key enters the menu structure at the top level. The display will look approximately as shown below:



0.00 A - Setup Mode (Select one)
+0.50 Vs → Supply Load Misc →

The item selector (►) points to whichever submenu was last used. The left and right arrows at the ends of the displayed submenu selections indicate that there are other submenu selections off screen, to the left and/or right of the submenu selections shown.

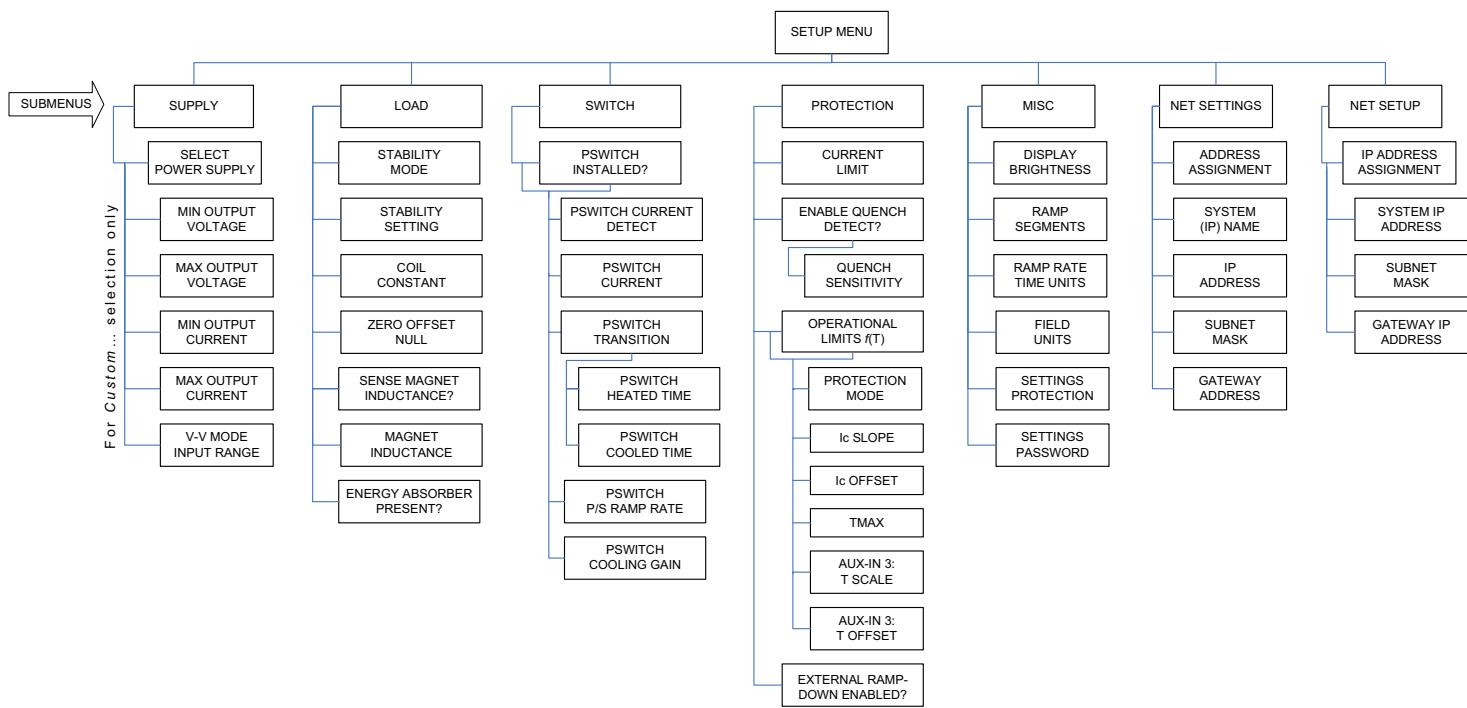
The left and right *keypad* arrows (to the left and right of the **MENU** key) move the item selector between the different submenu items. Pressing the left keypad arrow moves the item selector one item to the left and pressing the right keypad arrow moves the item selector one item to the right. When the last item is reached, and the right keypad arrow is pressed, the item selector will move to the first item. Likewise, when the item selector is pointing to the first item, and the left keypad arrow is pressed, the item selector will move to the last item.

Pressing the **ENTER** key opens the submenu to which the item selector is pointing when the **ENTER** key is pressed. See page 74 through page 110 for detailed descriptions of each submenu.

Pressing the **ESC** key exits a submenu and moves the next higher level submenu if it exists. If the top level setup menu is being displayed, pressing the **ESC** key exits the setup menu.

SETUP SUBMENU DESCRIPTIONS

When a submenu is entered by selecting a submenu item and pressing **ENTER** (see page 73 for details of menu navigation), the user will be able to edit parameters under that submenu. The Setup menu structure is summarized in the figure below:



Setup Menu Structure

The Setup submenus include: Supply, Load, Switch, Protection, Misc, Net Settings (present status), and Net Setup. Each submenu is discussed in detail in the following sections.

SUPPLY SUBMENU

The Supply submenu provides for the specification of the *power supply parameters*. If you wish to set the limits of operation for a connected magnet, refer to the Current Limit³⁰ and the Voltage Limit³¹ configuration sections.

If using a standard power supply supported by AMI, selecting a power supply within the Select Supply picklist sets all the remaining parameters in the supply submenu per the table on page 76.

30. See page 92.

31. See page 66.

NOTE The Supply submenu is unique in that it has only the Select Supply picklist as a sublevel (unless Custom is chosen from the picklist of Select Supply options). For this reason, picklist entry is active as soon as the Supply submenu is selected; it is not necessary to first press **ENTER**. The menu becomes active as soon as a left or right arrow is pressed. If the SUPPLY selection is changed (as marked by the asterisk), then a subsequent **ENTER** key press is required to make it active. **ESC** makes the list inactive and resets to the prior SUPPLY selection.

SELECT SUPPLY PICKLIST

```
0.00 A - Select Supply*
+0.50 Vs ← ►AMI 4006125PS →
```

The Select Supply picklist provides a set of picklist items that contain *presets for standard AMI power supplies*. The left and right keypad arrows are used to cycle through the list of selections.

When the item selector points at the desired power supply in the picklist, **ENTER** is pressed to select that power supply; all power supply parameters are set when the power supply model is selected. Pressing **ESC** while viewing the Select Supply picklist leaves the power supply selection where it was when the Supply submenu was selected, and exits the Select Supply picklist. The available Select Supply picklist values and associated power supply parameters are provided in the following table.

Select Supply picklist values and associated parameters.

Power Supply	Min Output Voltage (V)	Max Output Voltage (V)	Min Output Current (A)	Max Output Current (A)	V-V Mode Input Range (V)	
AMI 08150PS	0	+8.000	0	+150.000	0 to +10.000	
AMI 12100PS	0	+12.000	0	+100.000	0 to +10.000	
AMI 12200PS				+200.000		
AMI 4Q05100PS	-5.000	+5.000	-100.000	+100.000	-10.000 to +10.000	
AMI 4Q06125PS	-6.000	+6.000	-125.000	+125.000		
AMI 4Q06250PS			-250.000	+250.000		
AMI 4Q12125PS	-12.000	+12.000	-125.000	+125.000		
AMI 10100PS	0	+10.000	0	+100.000	0 to +5.000	
AMI 10200PS				+200.000		
AMI 05120PS		+10.000 ^a		+100.000	0 to +10.000	
AMI 05240PS				+200.000		
AMI 05360PS				+300.000		
AMI 05600PS				+500.000		
AMI 03300PS		+8.000		+300.000		
HP 6260B	-10.000	+10.000	0.000	+100.000		
Kepco BOP 20-5M ^b	-20.000	+20.000	-5.000	+5.000	-10.000 to +10.000	
Kepco BOP 20-10M ^b			-10.000	+10.000		
Xantrex XFR 7.5-140	0	+7.500	0	+140.000	0 to +10.000	
Accel Instr TS250-8 ^c	-10.000	+10.000	-5.000	+5.000	-10.000 to +10.000	
Custom... ^d	-20.000	+20.000	-200.000	+200.000	-10.000 to +10.000	

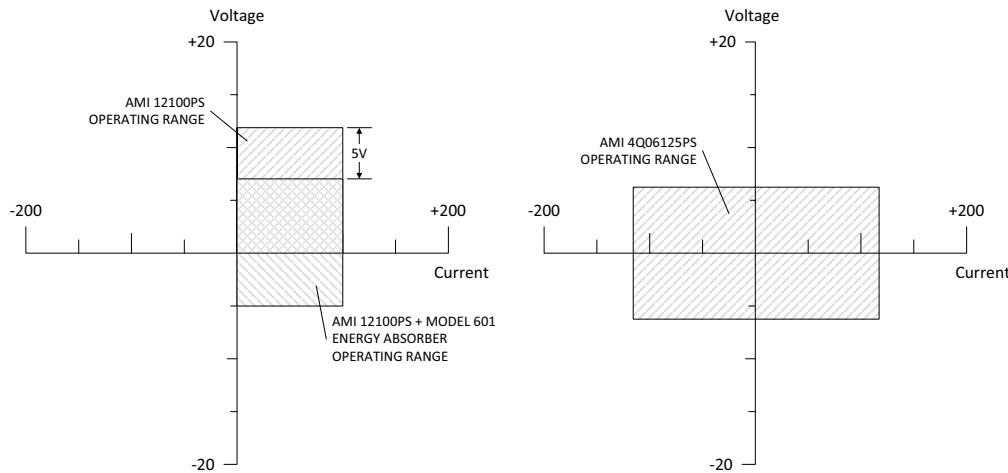
- a. The individual 05100PS power supply unit will source +10.000 VDC at up to 120 A. However, the standard configuration of this series of power supplies includes the Model 601 Energy Absorber to provide bipolar operation. The 05xx0-430-601 series of power supply systems provides a maximum available voltage to the load of ± 5.000 VDC at multiples of 120 or 150 A, up to 600 A depending on the system selected.
- b. The Kepco BOP power supplies used in the 4Q1005PS-430 and 4Q1010PS-430 systems are voltage-limited during operation to ± 10.000 VDC since the supplies are de-rated to *dissipate* only one-half the rated power output continuously at maximum output current.
- c. The Accel Instruments TS250-8 maximum voltage is limited during operation to ± 7.000 VDC in order to avoid overheating.
- d. The values shown for the Custom... option are defaults. The user should enter the appropriate values within the respective submenus. Custom values, once entered, are saved in nonvolatile memory.

NOTE The current must be less than 0.1% of I_{max} in order to change the Select Supply picklist value. If a change is attempted with current above this value, the Model 430 Programmer will beep and ignore the keypress. Power supply selection should also preferably be performed with the power supply off for maximum safety.

The power supply settings define the output voltage and current ranges for a specific power supply. For example, V-I diagrams are presented in the diagram below for the AMI 12100PS and AMI 4Q06125PS selections.

The AMI 12100PS operates as a one-quadrant system without the addition of an energy absorber. As shown at left in the diagram, with the addition of an AMI Model 601 energy absorber, the AMI 12100PS system can also function as a two-quadrant supply providing +7V to -5V at the power supply system output terminals.

The AMI 4Q06125PS power supply operates as a four-quadrant power supply *without* the addition of an energy absorber as shown at right in the diagram below.



Example Power Supply Outputs

The addition of an energy absorber to the system does not change the capabilities of the power supply itself (or the values entered for the supply). The addition of an energy absorber does, however, change the system operating ranges.

CUSTOM... PICKLIST ITEM

Custom... is a unique Select Supply picklist item. When selected, it opens a deeper submenu in which the custom power supply parameters (Min Output Voltage, Max Output Voltage, Min

Output Current, Max Output Current and V-V Mode Input Range) are entered. Entry of each of these parameters is described below.

MIN OUTPUT VOLTAGE

```
0.00 A - Min Output Voltage (U)
0.00 Vs    -6.000
```

The minimum output voltage is specified in volts (V) and reflects the minimum output voltage compliance of a connected power supply. The valid range is 0.000 to -20.000 V, and can be set by using either the numeric keypad as described on page 54 or the fine adjust knob (on page 55). A *unipolar* power supply has a minimum output voltage of 0.000 V.

MAX OUTPUT VOLTAGE

```
0.00 A - Max Output Voltage (U)
0.00 Vs    +6.000
```

The maximum output voltage is specified in volts (V) and reflects the maximum output voltage compliance of a connected power supply. The valid range is +0.001 to +20.000 V, and can be set by using either the numeric keypad as described on page 54 or the fine adjust knob (on page 55).

MIN OUTPUT CURRENT

```
0.00 A - Min Output Current (A)
0.00 Vs    +0.000
```

The minimum output current is specified in amperes (A) and reflects the minimum output current capacity of a connected power supply. The valid range is 0.000 to -100,000 A³², and can be set by using either the numeric keypad as described on page 54 or the fine adjust knob (on page 55). A *unipolar* power supply has a minimum output current of 0.000 A.

32. The minimum current is also bounded by the Model 430 Programmer configuration (refer to specifications on page 7 and in the Appendix). The entered value cannot exceed the input current measurement hardware limits.

MAX OUTPUT CURRENT

0.00 A	-	Max Output Current (A)
0.00 Vs		+100.000

The maximum output current is specified in amperes (A) and reflects the maximum output current capacity of a connected power supply. The valid range is 0.001 to +100,000 A³³, and can be set by using either the numeric keypad as described on page 54 or the fine adjust knob (on page 55).

V-V MODE INPUT RANGE

0.00 A	-	U-U Mode Input Range (U)
0.00 Vs	►	-10.000 to +10.000

The voltage-to-voltage mode input range defines the remote programming voltage input range required by the connected power supply. The remote programming voltage is the output signal provided by the Model 430 Programmer as an input to the connected power supply.

This submenu item provides a picklist of six preset selections and does not allow numeric entry of a range. The picklist values are shown in the table below.

V-V Mode Input Range Picklist Selections

+0.000 to -5.000	+0.000 to +8.000
+0.000 to +5.000	-5.000 to +5.000
+0.000 to +10.000	-10.000 to +10.000

33. The maximum current is also bounded by the Model 430 Programmer configuration (refer to specifications on page 7 and in the Appendix). The entered value cannot exceed the input current measurement hardware limits.

LOAD SUBMENU

When the Load submenu is selected, several parameters associated with the superconducting magnet load can be viewed and/or changed.

STABILITY MODE

0.00 A	- Stability Mode
+0.50 Vs	►Auto Manual Test

The stability mode provides configuration of the loop control gain for operating with a magnet or testing a system on a short-circuit load. The three available selections are *Auto*, *Manual*, and *Test*.

The *Auto* stability mode automatically sets the control gain based on the configured presence or absence of a persistent switch, and the entered or measured magnet inductance value as described on page 85. A reasonably accurate guess (e.g. within 25%) or measurement must be provided for the Auto mode to function correctly.

The *Manual* stability mode allows adjustment of the control gain based on a numerical entry for the stability setting. The Manual mode *requires* the operator to enter a stability setting per the guidelines beginning on page 81.

The *Test* stability mode is designed to allow the user to test the function of the system with *the power leads to the magnet shorted together at the magnet connection point*. This allows ramping of the system to verify proper setup. The Test mode should only be used with shorted magnet power leads for system checkout purposes. See the suggested Power-Up and Test Procedure beginning on page 45.

NOTE It is important that the full length of the power leads to the magnet be connected during the *Test* mode since the leads provide some resistive load (albeit in the milliohm range) for the power supply. The output current of a truly shorted supply output (i.e. zero resistance load) is very difficult to control in voltage mode and may be unstable.

STABILITY SETTING

0.00 A	-	Stability Setting (%)
+0.50 Vs		0.0

The stability setting is specified in percent and controls the transient response and stability of the system. The value can be set by using either the numeric keypad as described on page 54 or the fine adjust knob (on page 55). The valid range is from 0.0 to 100.0%. The default value is 0.0% unless preset by AMI to match a specific superconducting magnet.

STABILITY SETTING FOR MAGNETS WITHOUT A PERSISTENT SWITCH³⁴

Superconducting magnets *without* a persistent switch³⁵ require a specific Model 430 Programmer stability setting based on the magnet inductance as follows:

For magnet inductance \leq 100 Henries (H):
Stability Setting = (100 - H)

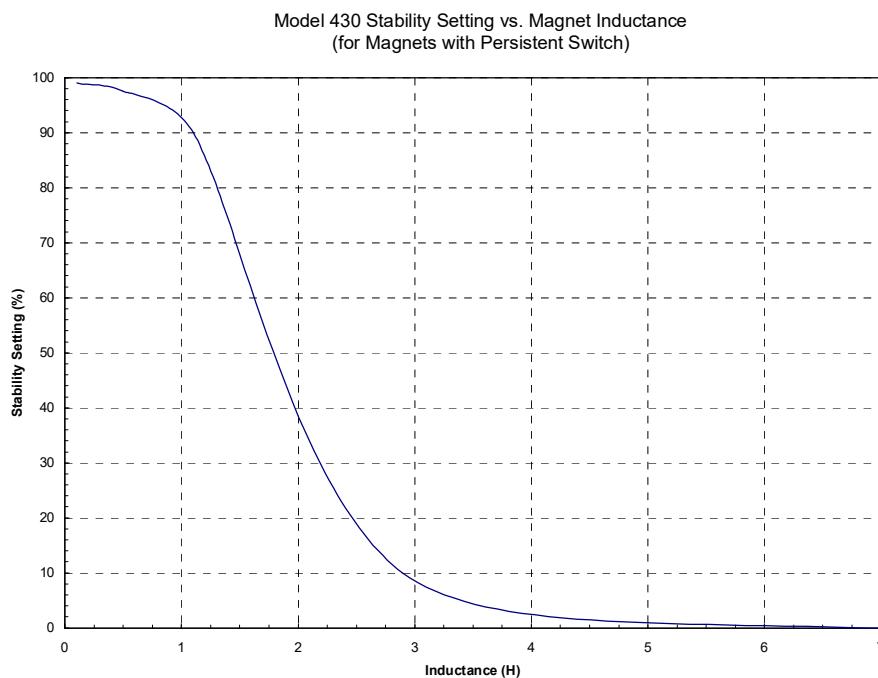
For magnet inductance $>$ 100 Henries:
Stability Setting = 0

34. For maximum Vm stability, you may opt to use a stabilizing resistor instead. See page 43 for details. For stabilizing resistor configurations, use the Stability Setting plot specified in the next section for magnets with a persistent switch.

35. Effective with Model 430 firmware version 1.62 or later, magnets without a switch may be operated without a stabilizing resistor present using the Stability Settings specified.

STABILITY SETTING FOR MAGNETS WITH A PERSISTENT SWITCH

The graph below may be used as a guide to set the stability setting for magnets *with a persistent switch* installed and inductance of less than 3 henries. Magnets with an inductance of greater than 3 henries that have a persistent switch installed should operate with a stability setting of 0.0%.



Stability Setting vs. Magnet (with PSwitch) Inductance

The Model 430 Programmer internal control loop gain is proportional to the multiplier ($100\% - [\text{Stability Setting}]$). For this reason, small changes in stability setting have a large effect on stability as the value approaches 100%. Changing the stability setting from 99.9% to 99.8% changes the gain multiplier from 0.1% to 0.2% (changing the gain multiplier by a factor of 2, a 100% increase in the gain multiplier). Note, however, that the same 0.1% change in Stability Setting from 90% to 89.9% only changes the gain multiplier from 10% to 10.1% (changing the gain multiplier by a factor of 1.01, a 1% change in gain multiplier).

What this means is that if the stability setting is being adjusted to *experimentally* determine its optimum setting (using the graph above as a starting point) the recommended incremental

changes for various stability setting ranges are shown in the following table.

Maximum Recommended Stability Setting Changes

Stability Setting Range	Maximum Recommended Stability Setting Change
98% to 100%	0.1%
94% to 98%	0.2%
84% to 94%	0.5%
44% to 84%	2%
0% to 44%	5%

NOTE The Model 430 will not operate in a stable fashion on a short-circuit load unless it is configured for Test stability mode (see page 80). Otherwise the Model 430 control logic assumes an inductive superconducting magnet load is connected to the circuit.

COIL CONSTANT

0.00 A	-	Coil Constant (kG/A)
+0.50 Vs		0.90000

The coil constant is a scaling factor which converts the current to kilogauss (kG) or tesla (T). It is also often referred to as the *field-to-current ratio*. The coil constant is specified in kilogauss/ampere or tesla/ampere. The value can be set by using either the numeric keypad as described on page 54 or the fine adjust knob (on page 55).

Values from 0.001 to 999.99999 are acceptable for the coil constant. The default value is 1.00000 kG/A (or 0.10000 T/A) unless preset by AMI to match a specific superconducting magnet. If the coil constant value is 0.0 kG/A (or 0.0 T/A), then no conversion from amperes to kilogauss or tesla is performed — all operations will be performed and displayed in terms of amperes.

If the coil constant is not explicitly stated within a superconducting magnet's specifications, the value can be obtained by dividing the rated field by the rated current. Note that 1 T = 10 kG.

ZERO OFFSET NULL

```
0.00 A - Zero Offset Null (Cleared)
0.00 Vs ►ENTER to set, 0 to Clear
```

This menu requires legacy firmware version 2.64 or later, or firmware version 3.14 or later for newer units, and is only displayed if the Model 430 is configured for the “high-stability” option. The menu does not apply to and is not shown for shunt configurations.

The current transducer used for the high-stability option is a fluxgate measurement device that can exhibit drift in the zero value. The magnitude of this drift can be up to 20 ppm of the maximum rated current of the transducer. This drift is typically observed after power cycling, or when power cycling the system while magnet current is flowing through the current transducer head. This zero offset drift can optionally be nulled by the following procedure:

1. Turn on power to the Model 430 with the appropriate magnet power lead routed through the high-stability Current Transducer connected to the Model 430. **The power supply should remain OFF.**
2. Allow the Model 430 and powered Current Transducer to warm-up for 20 minutes.
3. Press **ENTER** to proceed past the power supply power-on prompt on the Model 430 (**but the power supply should remain OFF**) and access the **MENU** > Load > Zero Offset Null selection.

NOTE The **CURRENT LEADS ENERGIZED** LED must not be lit for the Zero Offset Null to function, otherwise an error will appear and the offset null is not performed. Any connected magnet should also be *fully discharged or in persistent mode*, otherwise safely disconnect the power leads from the cryostat to ensure the current flowing through the power leads is zero.

4. Press the **ENTER** key and release. This will trigger the Model 430 to collect and average several measurements from the Current Transducer device and save the Zero Offset Null value. The value is immediately applied to the current measurement of the Model 430. Note the “Cleared” indication will be removed from the display as illustrated below:

```
0.00 A - Zero Offset Null
0.00 Vs ►ENTER to set, 0 to Clear
```

5. After a short delay, the Model 430 display is reset to the initial prompt for the power supply to be turned on.

6. Turn on the connected power supply and press **ENTER** to continue normal operation with the new Zero Offset Null value applied.

The Zero Offset Null value is retained by the Model 430 between power cycles. It can be cleared by pressing the **0** key in the menu.

SENSE MAGNET INDUCTANCE

```
0.00 A - Sense Magnet Inductance?  
0.00 Vs      ►Calculate (start w/ENTER)
```

This menu pick will start a process to measure the inductance of the load magnet. The inductance is determined by measuring the voltage developed across the magnet (V_m) with a fixed di/dt (current rate-of-change in A/sec) passed through the load. *The function must be executed with the magnet ramping.*³⁶ When the sense is initiated by pressing the **ENTER** key, the algorithm will wait for 2 seconds to allow the charge rate to stabilize and then make voltage and current measurements for 5 seconds, calculate the inductance, and display the result.

```
+46.19 A ↑ Sense Magnet Inductance?  
+0.50 Vs            32.13 H
```

The sensed magnet inductance is automatically saved as the present magnet inductance and is immediately used to adjust the control gains if the Model 430 is configured for Auto stability mode (see page 80).

If the magnet is persistent, not ramping, or encounters a ramp rate change during the measurement, the measurement will be aborted with a displayed error notification, and any existing magnet inductance value is retained.

MAGNET INDUCTANCE

```
0.00 A - Magnet Inductance (H)  
0.50 Vs            32.13
```

The magnet inductance submenu displays the present inductance value for the magnet load and allows manual entry of

36. See page 115.

a new value or initial guess (an initial guess within ~25% is adequate). The magnet inductance value *is saved* between power cycles.

The magnet inductance value, when entered, is immediately used for control gain configuration if the Model 430 is set for Auto stability mode (see page 80).

NOTE If connecting a different magnet load, please ensure that the magnet inductance is set with a known value or an initial guess in order to ensure proper operation.

ENERGY ABSORBER PRESENT

+50.00 A	-	Energy Absorber Present?
+0.50 Vs	►	NO YES

This picklist value indicates whether an energy absorber, such as the AMI Model 601, is connected to the power supply system. The default setting is *NO*.

It is important for this setting to be correct since the control gain tables of the Model 430 Programmer compensate for the additional load of the energy absorber if present. The increased gain when an energy absorber is present will also decrease (but not eliminate) the time required for the system to “forward bias” the energy absorber.³⁷

SWITCH SUBMENU

The Switch submenu provides a top menu for indicating if a persistent switch is installed on the presently connected magnet load, and, if so, several submenus for configuring the various operating parameters for the switch.

PSWITCH INSTALLED

0.00 A	-	PSwitch Installed?
0.00 Vm	►	NO YES

This picklist value indicates whether or not a persistent switch is installed.

37. The Model 430 Programmer will bring the output voltage of the power supply to the point where the energy absorber can provide current to the magnet.

If YES is selected, the PSwitch Current Detect, PSwitch Current, PSwitch Transition, PSwitch Heated Time, PSwitch Cooled Time, PSw P/S Ramp Rate, and PSwitch Cooling Gain settings are made available within the Switch submenu.

If NO is selected, the various settings are *not* made available within the Switch submenu and the **PERSIST. SWITCH CONTROL** key becomes inoperable.

The default value is YES unless preset by AMI to match a specific superconducting magnet.

PSWITCH CURRENT DETECT (mA)

0.00 A	P	PSwitch Current Detect(mA)
0.00 Vm		►Auto detect

This function will automatically determine the proper value of heater current in a persistent switch installed on a magnet connected to the power supply system. The power supply should be energized and at zero current. When the **ENTER** key is pressed to initiate the process, the following steps occur:

1. The persistent switch current is set to 0.1 mA.
2. The power supply current is ramped to 2 A³⁸ at 0.1 A/sec.
3. After the power supply current reaches 2 A, the persistent switch current is slowly increased (as shown on the display) until the Model 430 Programmer detects a change in the load, indicative of the persistent switch transitioning from superconducting to resistive. Before this transition is detected, the display will show the heater current value as it is increased in the persistent switch heater; the magnet current is changed back to zero during this process.

+2.00 A	P	PSwitch Current Detect(mA)
+0.37 Vm		Detecting... (26.7mA)

38. 4 A if >= 1000 A system

4. The current that was present when the superconducting to resistive transition occurred is displayed.

0.00 A	P	PSwitch Current Detect(mA)
0.00 Vs	►	27.2

NOTE If the PSwitch Current determined by this method is accepted as described below, the detection process will exit to the heated switch mode in the PAUSED state.

5. If the **ENTER** key is pressed, the determined value of PSw current is stored in the Model 430 Programmer. If the escape key is pressed, the value determined in step 4 above is discarded and the previously set persistent switch current is retained.

PSWITCH CURRENT

+50.00 A	-	PSwitch Current (mA)
+0.50 Vs		10.0

The persistent switch heater current can be manually set to any value between 0.0 and 125.0 mA. The value can be set by using either the numeric keypad as described on page 54 or the fine adjust knob (on page 55). The default value is 10.0 mA unless preset by AMI to match a specific superconducting magnet.

PSWITCH TRANSITION

+50.00 A	-	PSwitch Transition
+0.50 Vs	►	Timer Magnet Voltage

The persistent switch transition (from heated-to-cooled and vice-versa) can be detected by one of two methods: timer-based or by direct sensing of the magnet voltage.

The timer-based method is the default and simply uses heated and cooled state timers as entered by the operator in the PSwitch Heated Time and PSwitch Cooled Time settings.

Optionally, the operator can choose to use the magnet voltage method. This method works by directly sensing the running mean and variance of the magnet voltage and comparing them to preset limits. This method has the advantage of typically

requiring much less time to sense the transition of the persistent switch from the heated to cooled state.

NOTE In order to use the magnet voltage switch transition detection, higher resolution of the magnet voltage measurement is necessary. This is achieved by connecting the magnet voltage to Auxiliary Input 1, which has a ± 1.0 VDC input range with 20 times more resolution (~ 0.5 mV/bit) than the standard magnet voltage input.

Model 430 units that ship with version 3.00 or later firmware installed have internally connected the magnet voltage input from the Magnet Station connector to the Auxiliary Input 1 (therefore, the Auxiliary Input 1 is consumed and is not available for general use). For older, already fielded units the user will be required to install an external jumper cable from one of the Magnet Station connectors to the Auxiliary Input 1 to use the magnet voltage based switch transition feature. See page 220 for more details.

NOTE The magnet voltage method of sensing persistent switch transitions *requires* the magnet voltage input to the rear panel Magnet Station connector as described on page 211. Please note that some magnet system manufacturers do not provide magnet voltage taps.

PSWITCH HEATED TIME

+50.00 A	- PSwitch Heated Time (sec)
+0.50 Us	20

The persistent switch heated time is only displayed for, and applies only to, the timer-based switch transition method and is the amount of time required for the persistent switch to heat completely and become fully normal (resistive). The time may be set to any value between 5 and 3600 seconds³⁹. The value can be set by using either the numeric keypad as described on page 54 or the fine adjust knob (on page 55). The default is 20 seconds unless preset by AMI to match a specific superconducting magnet.

During the persistent switch heating period, the Model 430 Programmer ramping functions are disabled. The time delay is necessary to ensure that the Model 430 will not switch to the

39. During the heating cycle, a “countdown” will be displayed indicating the number of seconds remaining in the cycle.

higher control gain required for proper magnet operation before the magnet is actually available in the circuit (not being shunted by the persistent switch). If magnet operation is not stable after expiration of the heating period, increase the heated time to allow more time for the switch to heat. The default value of 20 seconds is adequate for the majority of wet and dry persistent switches.

PSWITCH COOLED TIME

+50.00 A	- PSwitch Cooled Time (sec)
+0.50 Vs	20

The PSwitch Cooled Time is only displayed for, and applies only to, the timer-based switch transition method and is the amount of time required for the persistent switch to cool completely and become fully superconducting. The time may be set to any value between 5 and 3600 seconds⁴⁰. The value can be set by using either the numeric keypad as described on page 54 or the fine adjust knob (on page 55). The default is 20 seconds unless preset by AMI to match a specific superconducting magnet.

During the persistent switch cooling period, the Model 430 Programmer ramping functions are disabled. The default value of 20 seconds is adequate for many wet persistent switches. Persistent switches on conduction cooled magnets (dry switches) can require significantly longer cooling times than wet switches.

For dry switches, the operator may want to consider the optional magnet voltage switch transition detection method if magnet voltage taps are available and connected to the Model 430 Programmer.

PSWITCH POWER SUPPLY RAMP RATE

+50.00 A	- PSw P/S Ramp Rate (A/sec)
+0.50 Vs	10

The persistent switch power supply ramp rate is the rate at which the magnet power supply will automatically be ramped up or down while an installed persistent switch is in the cooled state. The rate may be set to any value between 0.1 A/sec and the maximum ramp rate for the Model 430 configuration.

40. During the cooling cycle, a "countdown" will be displayed indicating the number of seconds remaining in the cycle.

The purpose of this parameter is to reduce the amount of time the system requires to either match an existing persistent magnet current, or to reach zero current for powering off a system with the magnet in a persistent state. This ramp rate can be set much higher than the rate required while charging/discharging the magnet (note that a *persistent* magnet is not in-circuit). In fact, the typical practice is to set this parameter to its maximum value.

The value can be set by using either the numeric keypad as described on page 54 or the fine adjust knob (on page 55). The default is 10 A/sec unless preset by AMI to match a specific Model 430 configuration or superconducting magnet system.

PSWITCH COOLING GAIN

```
0.00 A P PSwitch Cooling Gain (%)  
0.00 Vs 0.0
```

The default cooling gain of 0.0% may be adequate for the majority of wet persistent switches. However, this setting can offset magnet field/current drift during persistent switch cooling, especially with conduction cooled switches which generally require longer cooling times.

Increasing the cooling gain adds control loop gain during the switch cooling cycle. Too little cooling gain may result in magnet field drift during a long period of switch cooling. Most systems that require some cooling gain to control magnet drift will likely work with value set to about 25%. The value can be set by using either the numeric keypad as described on page 54 or the fine adjust knob (on page 55).

PROTECTION SUBMENU

The Protection submenu configures parameters related to protective measures that can be applied to magnet operation to prevent accidental damage and respond during a quench or other critical events.

CURRENT LIMIT

0.00 A	P	Current Limit (A)
0.00 Vm		±100.000

CAUTION

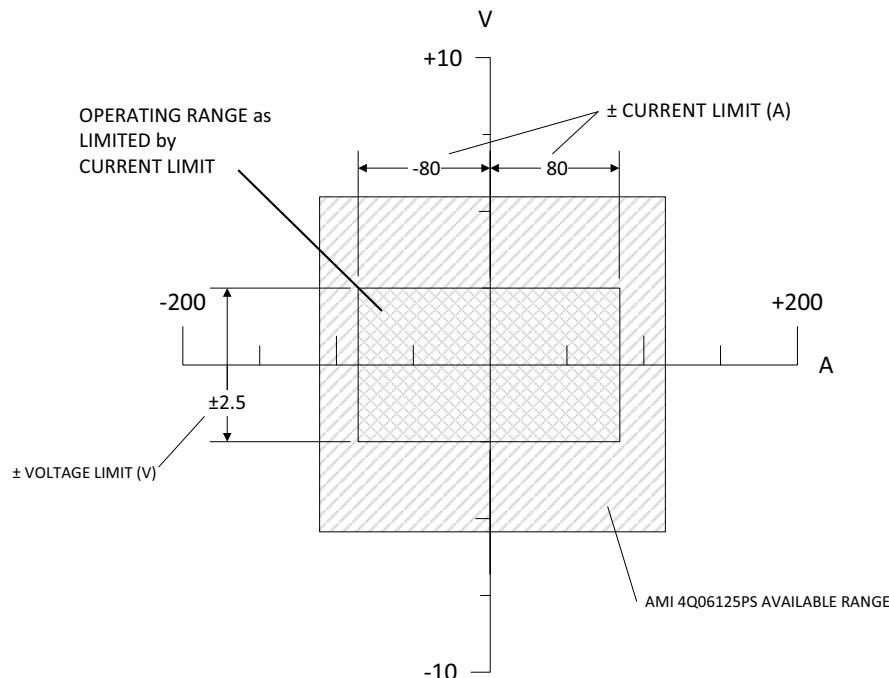
The Current Limit is normally set to the Magnet Rated Current specific to the connected superconducting magnet. The setting should not be changed unless a different magnet is to be used; always refer to the magnet specifications (see page 112) before changing the Current Limit.

A magnet operates within the capabilities of the associated power supply. The Current Limit must be selected to be within the current output range of the connected power supply, which is not user-adjustable.

If the power supply is four-quadrant, the Current Limit applies to both the positive and the negative current direction (current limit symmetry).

The Current Limit is normally preset by AMI to match a specified superconducting magnet. If AMI is not supplying the magnet or if the specific magnet data has not been provided by the customer, the Model 430 will ship with the Current Limit set at the default value of ±80 A. The figure on the following page shows the default Current Limit (±80 A) and a Voltage Limit (±2.5 V) as a sub-range within the 4Q06125PS power supply output limits.

The Current Limit can be set by using either the numeric keypad as described on page 54 or the fine adjust knob (on page 55). The Model 430 Programmer will beep once, indicate an error, and deny the change if the user attempts to set the Current Limit below the present Target Field Setpoint or above the maximum output current of the selected power supply.



Current and Voltage Limits set within the Supply Ranges

ENABLE QUENCH DETECT

+50.00 A	-	Enable Quench Detect?
+0.50 Vs	NO	▶YES

The internal quench detection function of the Model 430 Programmer may be enabled or disabled according to the preference of the user. The default value is NO.

A user input for *external quench detection* is also provided on the rear panel of the Model 430 Programmer⁴¹. The external input overrides the internal quench detection function of the Model 430 and cannot be disabled. For further discussion of the quench detection logic and operation, please refer to on page 127.

41. Refer to page 218.

ADDITIONAL QUENCH DETECTION SELECTIONS

If the optional *Operational Limits f(T)* functionality is enabled (see page 95), then the quench detection menu includes some additional selections as illustrated below:

```
+50.00 A - Enable Quench Detect?  
+0.50 Vs      Off  ►Current  Tmax  Both
```

As described previously, the quench detect can be set to *Off* and is inactive. If set to *Current*, the detection is based on magnet current only which is the same as the base quench detection functionality as described above.

If set to *Tmax*, the detection logic will only be based on the input temperature from an external measurement device that is connected to Auxiliary Input 3 on the rear panel of the Model 430 (see page 220).

If set to *Both*, the quench detection logic will operate on both the magnet current *and* the temperature measurement provided via Auxiliary Input 3. If either violates the predefined detection logic, a quench will be detected.

QUENCH SENSITIVITY

```
+50.00 A P Quench Sensitivity (Rate)  
+0.50 Vs      Less < ►Normal > More
```

This picklist value specifies the sensitivity (formerly called “rate”) of the quench detection algorithm. The default “Normal” value will be appropriate for most magnets. Occasionally, some magnets quench very slowly and the value of this parameter may need to be adjusted to a more sensitive value so that the Model 430 Programmer detects the gradual, slow quench.

The available range for this parameter is five (5) steps from least to most sensitivity. If the magnet quenches and the Model 430 Programmer does not detect the quench, the sensitivity should be increased (i.e. More sensitivity) until all quenches are detected.

OPERATIONAL LIMITS⁴²

+50.00 A	-	Operational Limits f(T)
+0.50 Vs		►Edit Constants

This heads a menu subsection containing various constants associated with protection based on a linear relationship for a maximum allowable current, termed as **Ic**, given a temperature measured via the Auxiliary Input 3 (see page 220). Press the **ENTER** key to access the associated submenu parameters.

The equations that relate the parameters in this subsection are defined as:

$$\begin{aligned} \text{If } T \leq T_{max} &\Rightarrow Ic = (IcSlope)T + (IcOffset) \\ \text{If } T > T_{max} &\Rightarrow Ic = 0 \end{aligned}$$

where **Ic** is in Amperes, **IcSlope** is Amperes/Kelvin, **T** is the Auxiliary Input channel 3 temperature in Kelvin, **IcOffset** is in Amperes, and **T_{max}** is in Kelvin. The **Ic** limit is applied in a bipolar fashion, i.e. it is applied to the magnet current *magnitude*.

The equations above define an operating region that is illustrated in the “Ic vs. Temperature” plot at the top of the following page, with example parameter values of -22 A/K for **IcSlope**, 180 A for **IcOffset**, and 5.5 K for **T_{max}**. **The valid operational region is along and to the left of the line.**

PROTECTION MODE

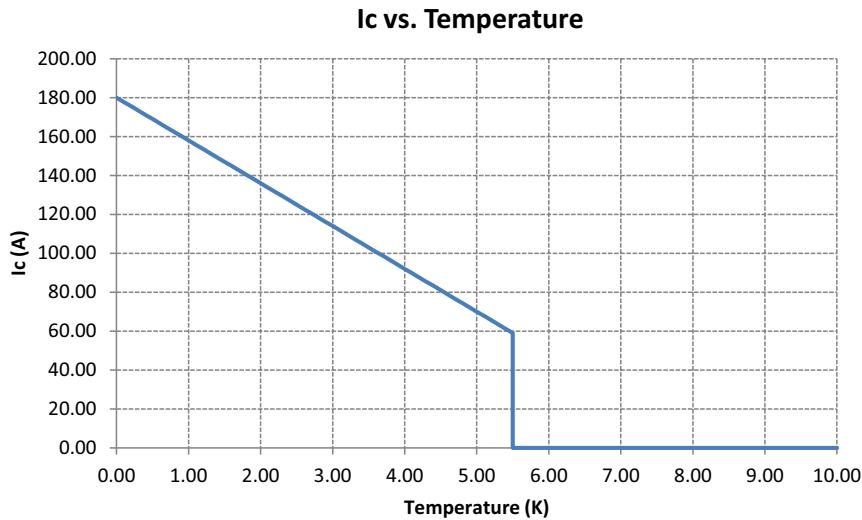
+50.00 A	-	Protection Mode
+0.50 Vs		►Off On Entry Cont f(T)

This setting controls how the maximum current protection is applied. If the Protection Mode setting is *Off*, then no additional protection is applied.⁴³

If the Protection Mode setting is *On Entry*, the Target Field Setpoint is checked *only during a new entry* against the presently calculated value of **Ic** and the new entry must be less than or equal to **Ic**. The Model 430 Programmer will beep once, indicate

42. The Operational Limits menu can be hidden with an internal hardware switch. If this menu is not visible, then the hardware switch has been set to hide it. Contact an Authorized AMI Technical Support Representative if you wish to enable this feature.

43. The Tmax parameter may still be used as part of the quench detection logic, see page 127.



Example of **Ic** (i.e. critical current) vs. Temperature protection line

an error, and deny the new entry to the Target Field/Current Setpoint if the value exceeds **Ic**.

If the Protection Mode setting is *Cont f(T)*, representing the continuous function of temperature, the Target Field Setpoint entry protection is applied *and* the operating current of the magnet is continuously checked against the calculated value of **Ic** based on the present temperature measured via the Auxiliary Input channel 3. This mode actively limits the magnet current to less than or equal to **Ic**.

If the temperature increases during operation and the present magnet current then exceeds **Ic**, the magnet is automatically ramped down in current magnitude to satisfy the **Ic** limit at the specified system ramp rate (this includes ramping the magnet to zero field/current if the present temperature exceeds T_{max}). If attempting to ramp the magnet current above **Ic**, the magnet current is held at the value of **Ic**. Either limited condition is indicated by an inverse video **I** character in the status indicator display which indicates the “Temperature Limited” state.

If the Protection Mode is “Off”, the present temperature measured via Auxiliary Input channel 3 can be displayed in the default display by pressing the right or left arrow keys. If the Protection Mode is “On Entry” or “*Cont f(T)*” both the real-time calculated value of **Ic** *and* the current temperature are displayed. **Ic** is always displayed in Amperes. This default display option is illustrated below along with an illustration of the status indicator

indicating a temperature-limited condition (i.e. the reverse-video T character):

+50.53 A	█	Mode: Ramping: Ic=50.5
4.50 K		No PSwitch Installed

Illustration of optional default display showing the value of *Ic*, the present Aux-In 3 temperature, and a temperature-limited condition.

To remove the *Ic* and/or temperature display, simply press the left or right arrow key again.

Ic SLOPE

+50.00 A	-	Ic Slope (A/K)
+0.50 Vs		-22.000

This value sets the *Ic Slope* parameter in Amperes/Kelvin. Note that for superconducting magnets, the slope value will be negative since the maximum current density increases with decreasing temperature.

Ic OFFSET

+50.00 A	-	Ic Offset (A)
+0.50 Vs		+150.000

This value sets the *Ic Offset* parameter in Amperes. This value shifts the entire *Ic* line by a current offset. A higher offset value will increase the value of *Ic* for a given temperature.

TMAX

+50.00 A	-	Tmax (K)
4.50 K		6.000

This value is a maximum allowable system temperature as measured via the Auxiliary Input channel 3 in Kelvin. The Model 430 Programmer will limit entry of the Target Field/Current Setpoint to a value of zero if the present temperature exceeds T_{max} . If the Protection Mode is set for “Cont f(T)”, then the magnet will also be ramped to zero field/current if the temperature exceeds T_{max} .

Aux-In 3: T Scale

+50.00 A	-	Aux-In 3: T Scale (K/V)
4.50 K		+1.000

This value controls the scaling of the voltage measured via the Auxiliary Input channel 3 (see page 220). The measured voltage is multiplied by this scale factor in Kelvin/Volts. The value is determined by the specific output scaling applied by the external temperature measurement device.

NOTE The correctness of this scaling parameter is critical to the accurate operation of the protection afforded by the Operational Limits function.

Aux-In 3: T Offset

+50.00 A	-	Aux-In 3: T Offset (K)
4.50 K		0.000

This value controls the offset in Kelvin of the temperature measured via the Auxiliary Input channel 3 (see page 220). The measured voltage is first multiplied by the *T Scale* factor and then the *T Offset* is added to determine the voltage-to-temperature conversion. The value is determined by the specific output offset applied by the external temperature measurement device.

NOTE The correctness of this offset parameter is critical to the accurate operation of the protection afforded by the Operational Limits function.

ENABLE EXTERNAL RAMPDOWN

0.00 A	-	External Rampdown Enabled?
0.00 Vs	►	NO YES

The External Rampdown function of the Model 430 Programmer can be used to allow an external contact-signal to cause the magnet to be ramped to zero field (even if it is in persistent mode) should a fault or alarm occur in a magnet system. Signals such as low liquid levels, cryocooler compressor faults, or abnormal temperatures can be used to trigger a controlled

magnet rampdown, even if the magnet is in persistent mode. See page 218.

The external rampdown function may be enabled or disabled according to the preference of the user. The default value is NO. With the exception of enable control, the ramp settings for the external rampdown function can be edited *only* via the remote interface (see page 179) or by using Magnet-DAQ (see page 189).

A user input for initiating an *external rampdown* is provided on the rear panel of the Model 430 Programmer⁴⁴. For further discussion of the rampdown logic and operation, please refer to page 129.

MISC SUBMENU

When the Misc submenu is selected, several miscellaneous parameters may be viewed and/or changed.

DISPLAY BRIGHTNESS

```
+50.00 A - Display Brightness (%)  
+0.50 Vs      25    50    75    ▶100
```

This picklist value controls display brightness. As shown above, there are four brightness settings from which to choose (25%, 50%, 75% and 100%). The default setting is 100%.

RAMP SEGMENTS

```
+50.00 A - Ramp Segments (1-10)  
+0.50 Vs      1
```

The ramp segments value specifies the number of current ranges which can be given unique ramp rate values. The default value is 1 unless preset by AMI to match a specific superconducting magnet.

When this value is 1, there is only one ramp rate for the Model 430 Programmer, used for the full available current range. For multiple ramp rates, set the value to the number of ramp segments desired (up to ten segments). See page 63 for details regarding the use of ramp rate segments.

44. Refer to page 218.

RAMP RATE TIME UNITS

```
+50.00 A - Ramp Rate Time Units  
+0.50 Vs    ►Seconds      Minutes
```

This picklist value specifies the unit of time used to enter and the display ramp rate. If Seconds is selected, ramp rate is entered in A/s, kG/s or T/s; if Minutes is selected, ramp rate is entered in A/min, kG/min or T/min. The selected unit value also applies to remote interface commands. The default setting is Seconds.

FIELD UNITS

```
+50.00 A - Field Units  
+0.50 Vs    ►Kilogauss    Tesla
```

This picklist value specifies whether the field is specified and displayed in units of kilogauss (kG) or tesla (T). The units selected also applies to remote interface commands. The default setting is kilogauss.

SETTINGS PROTECTION

```
+50.00 A - Settings Protection  
+0.50 Vs    ►Edit Settings
```

Settings Protection allows virtually every command and menu/submenu setting to be protected from alteration or use. If a setting is locked, it cannot be used from the front panel without first unlocking the setting, which requires entering the correct password. Note that settings protection only applies to front panel access, and not to remote access (via Ethernet or RS-232).

The use of settings protection allows specific commands and/or settings to be locked by a magnet system “administrator,” so that the general user cannot execute those commands and/or modify those settings. The implementation of settings protection in the Model 430 Programmer is very flexible; it allows as many or as few commands and/or settings to be locked as the magnet system administrator desires. The magnet system administrator may lock all but a few commands/settings, so that, for instance, the general user has access to only the **RAMP / PAUSE** and **RAMP TO ZERO** keys. Conversely, the administrator may lock,

for instance, only the Current Limit setting from use by the general user.

If an attempt is made to use a locked command or setting, the Model 430 Programmer beeps twice; the command is not accepted and the setting is not altered.

When **ENTER** is pressed to change settings protection, the password must be correctly entered before settings protection can be edited.

```
+50.00 A - Enter Password*
+0.50 Vs -
```

Using the keypad, type the numeric password (up to 4-digits) and press **ENTER**. The default password is 1234. If an incorrect password is entered, the Model 430 Programmer beeps and again prompts for the password. Once the password has been correctly entered, the protection value (Locked or Unlocked) can be edited for each setting. The default protection value for all settings is Unlocked.

NOTE Once the password has been correctly entered, if no keys are pressed for one minute, the Settings Protection submenu will be exited, and the password must be entered again if further changes to settings protection are desired.

If the password has been forgotten, contact AMI Technical Support for assistance. To change the password, see page 107.

PSWITCH CONTROL LOCK

```
+50.00 A - PSwitch Control Lock
+0.50 Vs Locked ►Unlocked
```

This picklist value specifies whether use of the **PERSIST. SWITCH CONTROL** key is locked or unlocked. The default value is Unlocked.

TARGET FIELD SETPT LOCK

+50.00 A	-	Target Field Setpt Lock
+0.50 Vs	Locked	►Unlocked

This picklist value specifies whether use of the **TARGET FIELD SETPOINT** key is locked or unlocked. The default value is Unlocked.

RAMP / PAUSE LOCK

+50.00 A	-	Ramp / Pause Lock
+0.50 Vs	Locked	►Unlocked

This picklist value specifies whether use of the **RAMP / PAUSE** key is locked or unlocked. The default value is Unlocked.

RAMP TO ZERO LOCK

+50.00 A	-	Ramp To Zero Lock
+0.50 Vs	Locked	►Unlocked

This picklist value specifies whether use of the **RAMP TO ZERO** key is locked or unlocked. The default value is Unlocked.

RAMP RATE SETTINGS LOCK

+50.00 A	-	Ramp Rate Settings Lock
+0.50 Vs	Locked	►Unlocked

This picklist value specifies whether ramp rate settings are locked or unlocked. Ramp rate settings protected by this setting are: use of the **RAMP RATE** key menu, editing of the Ramp Segments value (under the Misc submenu) and editing of the Ramp Time Units value (under the Misc submenu). The default value is Unlocked.

POWER SUPPLY LOCK

+50.00 A	-	Power Supply Lock
+0.50 Vs	Locked	►Unlocked

This picklist value specifies whether the Select Supply picklist value is locked or unlocked. If the Select Supply value is

Custom..., then setting Power Supply Lock to Locked also prevents the custom power supply parameters (Min Output Voltage, Max Output Voltage, Min Output Current, Max Output Current and V-V Mode Input Range) from being edited. The default value is Unlocked.

VOLTAGE LIMIT LOCK

+50.00 A	-	Voltage Limit Lock
+0.50 Vs	Locked	►Unlocked

This picklist value specifies whether use of the **VOLTAGE LIMIT** SHIFT-key menu is locked or unlocked. The default value is Unlocked.

RESET QUENCH LOCK

+50.00 A	-	Reset Quench Lock
+0.50 Vs	Locked	►Unlocked

This picklist value specifies whether use of the **RESET QUENCH** SHIFT-key command is locked or unlocked. The default value is Unlocked.

INCR./DECR. FIELD LOCK

+50.00 A	-	Incr./Decr. Field Lock
+0.50 Vs	Locked	►Unlocked

This picklist value specifies whether use of the **INCR. FIELD** and **DECR. FIELD** SHIFT-key commands is locked or unlocked. The default value is Unlocked.

FIELD <> CURRENT LOCK

+50.00 A	-	Field <> Current Lock
+0.50 Vs	Locked	►Unlocked

This picklist value specifies whether use of the **FIELD <> CURRENT** SHIFT-key command is locked or unlocked. The default value is Unlocked.

FIELD UNITS LOCK

+50.00 A	-	Field Units Lock
+0.50 Vs	Locked	►Unlocked

This picklist value specifies whether the Field Units value is locked or unlocked (whether accessed through the **FIELD UNITS** key menu or under the Misc submenu). The default value is Unlocked.

STABILITY SETTING LOCK

+50.00 A	-	Stability Setting Lock
+0.50 Vs	Locked	►Unlocked

This picklist value specifies whether the Stability Mode and Stability Setting values are locked or unlocked (whether accessed through the **STAB.** key menu or under the Load submenu). The default value is Unlocked.

INDUCTANCE LOCK

+50.00 A	-	Inductance Lock
+0.50 Vs	Locked	►Unlocked

This picklist value specifies whether the Sense Magnet Inductance function and Magnet Inductance value are locked or unlocked (under the Load submenu). The default value is Unlocked.

Vs <> Vm Lock

+50.00 A	-	Vs <> Vm Lock
+0.50 Vs	Locked	►Unlocked

This picklist value specifies whether use of the **Vs <> Vm SHIFT-** key command is locked or unlocked. The default value is Unlocked.

VOLT METER LOCK

+50.00 A	-	Volt Meter Lock
+0.50 Vs	Locked	►Unlocked

This picklist value specifies whether use of the **VOLT METER** SHIFT-key command is locked or unlocked. The default value is Unlocked.

FINE ADJUST LOCK

+50.00 A	-	Fine Adjust Lock
+0.50 Vs	Locked	►Unlocked

This picklist value specifies whether use of the **FINE ADJUST** SHIFT-key command is locked or unlocked. The default value is Unlocked.

COIL CONSTANT LOCK

+50.00 A	-	Coil Constant Lock
+0.50 Vs	Locked	►Unlocked

This picklist value specifies whether the Coil Constant value (under the Load submenu) is locked or unlocked. The default value is Unlocked.

CURRENT LIMIT LOCK

+50.00 A	-	Current Limit Lock
+0.50 Vs	Locked	►Unlocked

This picklist value specifies whether the Current Limit value (under the Load submenu) is locked or unlocked. The default value is Unlocked.

PSWITCH SETTINGS LOCK

+50.00 A	-	PSwitch Settings Lock
+0.50 Vs	Locked	►Unlocked

This picklist value specifies whether persistent switch settings are locked or unlocked. Persistent switch settings protected by this setting (all under the Switch submenu) are: PSwitch Installed

picklist value, PSwitch Current Detect, PSwitch Current value, PSwitch Transition picklist value, PSwitch Heated Time value, PSwitch Cooled Time value, PSwitch P/S Ramp Rate value, and the PSwitch P/S Cooling Gain value. The default value is Unlocked.

QUENCH DETECT LOCK

+50.00 A	-	Quench Detect Lock
+0.50 Vs	Locked	►Unlocked

This picklist value specifies whether the Enable Quench Detect picklist value (under the Protection submenu) is locked or unlocked. The default value is Unlocked.

QUENCH SENSITIVITY LOCK

+50.00 A	-	Quench Sensitivity Lock
+0.50 Vs	Locked	►Unlocked

This picklist value specifies whether the Quench Sensitivity picklist value (under the Protection submenu) is locked or unlocked. The default value is Unlocked.

ABSORBER PRESENT LOCK

+50.00 A	-	Absorber Present Lock
+0.50 Vs	Locked	►Unlocked

This picklist value specifies whether the Energy Absorber Present picklist value (under the Load submenu) is locked or unlocked. The default value is Unlocked.

EXTERNAL RAMPDOWN LOCK

+0.00 A	-	External Rampdown Lock
+0.50 Vs	Locked	►Unlocked

This picklist value specifies whether the external rampdown function (under the Protection submenu) is locked or unlocked. The default value is Unlocked.

DISPLAY BRIGHTNESS LOCK

+50.00 A	-	Display Brightness Lock
+0.50 Vs	Locked	►Unlocked

This picklist value specifies whether the Display Brightness picklist value (under the Misc submenu) is locked or unlocked. The default value is Unlocked.

NET SETUP LOCK

+50.00 A	-	Net Setup Lock
+0.50 Vs	Locked	►Unlocked

This picklist value specifies whether the Net Setup submenu is locked or unlocked. The default value is Unlocked.

OPERATIONAL LIMITS LOCK

+50.00 A	-	Operational Limits Lock
+0.50 Vs	Locked	►Unlocked

This picklist value specifies whether the Operational Limits (that are a function of input temperature) submenus are locked or unlocked (under the Protection submenu). The default value is Unlocked.

SETTINGS PASSWORD

+50.00 A	-	Settings Password
+0.50 Vs	►Change Password	

Settings Password is a password protected submenu under the Misc submenu. It provides a means of changing the settings protection password.

When **ENTER** is pressed to change the settings protection password, the current password must be correctly entered before a new password can be entered.

+50.00 A	-	Enter Current Password*
+0.50 Vs	-	

Using the keypad, type the current 4-digit (maximum) numeric password and press **ENTER**. The default password is 1234. If an incorrect password is entered, the Model 430 Programmer beeps and again prompts for the password. Once the password has been correctly entered, the user is prompted for the new password.

```
+50.00 A - Enter New Password*
+0.50 Vs -
```

Using the keypad, type the new 4-digit (maximum) numeric password and press **ENTER**. The user is then prompted to re-enter the new password for confirmation.

```
+50.00 A - Enter New Password Again*
+0.50 Vs -
```

Using the keypad, again type the new 4-digit (maximum) numeric password and press **ENTER**. If the second password entry does not match the first password entry, the Model 430 Programmer beeps and the user is prompted again to re-enter the new password. The new password is not accepted until it is confirmed by entering the same password a second time. If **ESC** is pressed before confirmation is completed, the display returns to the Settings Password submenu, and the current password remains unchanged.

NET SETTINGS SUBMENU

Selecting the Net Settings submenu allows all currently assigned network settings to be *viewed* (but not edited). To *edit* network settings, select the Net Setup submenu.

ADDR ASSIGNMENT (PRESENT)

```
+50.00 A - Addr Assignment (Present)
+0.50 Vs DHCP
```

This submenu item displays the currently selected method of IP address assignment. The value will either be DHCP or Static. The default value is DHCP, which means that the system IP address, the subnet mask and the gateway IP address are dynamically determined by the network DHCP server.

SYSTEM NAME (PRESENT)

+50.00 A	-	System Name (Present)
+0.50 Us		AMI

This submenu item displays the currently assigned system name (also known as *host name* or *computer name*), the name by which the Model 430 Programmer is identified on a network. This setting can *only* be modified using remote communications (either Ethernet or RS-232); it cannot be edited using the front panel keypad.

IP ADDRESS (PRESENT)

+50.00 A	-	IP Address (Present)
+0.50 Us		0.0.0.0 (DHCP)

This submenu item displays the currently assigned system IP address for the Model 430 Programmer. The value in parentheses after the IP address value indicates how the IP address is assigned. DHCP indicates that the value is dynamically assigned by a DHCP server; Static indicates that the value is static, assigned by the Model 430 user. The default value is 0.0.0.0. However, since the default method of IP address assignment is by DHCP server, this value is typically set by the network DHCP server.

SUBNET MASK (PRESENT)

+50.00 A	-	Subnet Mask (Present)
+0.50 Us		0.0.0.0 (DHCP)

This submenu item displays the currently assigned subnet mask for the Model 430 Programmer. The value in parentheses after the subnet mask value indicates how the subnet mask is assigned. DHCP indicates that the value is dynamically assigned by a DHCP server; Static indicates that the value is static, assigned by the Model 430 user. The default value is 0.0.0.0. However, since the default method of subnet mask assignment is by DHCP server, this value is typically set by the network DHCP server.

GATEWAY ADDRESS (PRESENT)

```
+50.00 A - Gateway Address (Present)
+0.50 Vs   0.0.0.0 (DHCP)
```

This submenu item displays the currently assigned gateway IP address for the Model 430 Programmer. The value in parentheses after the gateway IP address value indicates how the gateway IP address is assigned. DHCP indicates that the value is dynamically assigned by a DHCP server; Static indicates that the value is static, assigned by the Model 430 user. The default value is 0.0.0.0. However, since the default method of subnet mask assignment is by DHCP server, this value is typically set by the network DHCP server.

NET SETUP SUBMENU

Selecting the Net Setup submenu allows network settings to be *edited* (except for the system name, which can only be modified using remote communications). Note also that the system IP address, the subnet mask and the gateway IP address can only be assigned by the user if the currently selected method of IP address assignment is Static; if the currently selected method of IP address assignment is DHCP, then these three values will be set by the network DHCP server.

IP ADDRESS ASSIGNMENT

```
+50.00 A - IP Address Assignment
+0.50 Vs   ►DHCP     Static
```

This picklist value specifies method of IP address assignment. The value can be set to either DHCP or Static. If the value is DHCP, then the system IP address, the subnet mask and the gateway IP address are dynamically assigned by the network DHCP server. If the value is Static, then the system IP address, the subnet mask and the gateway IP address are assigned static values by the user. The default value is DHCP.

NOTE If the IP Address Assignment value is changed, the Model 430 Programmer power must be cycled off for at least 15 seconds and then back on to complete the change. The previous value will continue to be used until the Model 430 is restarted.

SYSTEM IP ADDRESS

+50.00 A	-	System IP Address
+0.50 Vs		0.0.0.0

If IP Address Assignment is Static, then the system IP address can be assigned by the user. The default value is 0.0.0.0.

NOTE This item is only available in the Net Setup submenu if IP Address Assignment is Static. If IP Address Assignment is DHCP, the system IP address is assigned by the network DHCP server and cannot be assigned by the user.

SUBNET MASK

+50.00 A	-	Subnet Mask
+0.50 Vs		0.0.0.0

If IP Address Assignment is Static, then the subnet mask can be assigned by the user. The default value is 0.0.0.0.

NOTE This item is only available in the Net Setup submenu if IP Address Assignment is Static. If IP Address Assignment is DHCP, the subnet mask is assigned by the network DHCP server and cannot be assigned by the user.

GATEWAY IP ADDRESS

+50.00 A	-	Gateway IP Address
+0.50 Vs		0.0.0.0

If IP Address Assignment is Static, then the gateway IP address can be assigned by the user. The default value is 0.0.0.0.

NOTE This item is only available in the Net Setup submenu if IP Address Assignment is Static. If IP Address Assignment is DHCP, the gateway IP address is assigned by the network DHCP server and cannot be assigned by the user.

EXAMPLE SETUP

As a precursor to operating a superconducting magnet with the Model 430 Programmer and power supply, all of the setup items should be reviewed and set if necessary with appropriate values for the connected superconducting magnet.

American Magnetics, Inc.

P.O. Box 2509, 112 Flint Road, Oak Ridge, TN 37831-2509
Phone: (865) 482-1056 Fax: (865) 482-5472
Internet: <http://www.americanmagnetics.com> E-mail: sales@americanmagnetics.com



MAGNET SPECIFICATIONS

AMI JOB #024856-2-1 MAGNET #33109

TYPE: Solenoid

MODEL: Custom

FOR: A&W CryoEngineering, Ltd.

DATE: 23 May 2008

Rated Central Field @ 4.2K ¹	-----	80 kG
Rated Current	-----	85.6 amps
Max. Field Tested	-----	82 kG
Field to Current Ratio	-----	934 gauss/amp
Homogeneity over a 1 cm DSV	-----	±0.5%
Measured Inductance	-----	9.7 henrys
Charging Voltage	-----	2.1 volts
Axial Clear Bore	-----	3.0 inches
Overall Length (flange to flange)	-----	4.74 inches
Maximum Outside Diameter	-----	6.4 inches
Weight	-----	41 lbs.
Recommended Persistent Switch Heater Current	-----	41 mA
Persistent Switch Heater Nominal Resistance ²	-----	94.8 ohms
Magnet Resistance in Parallel with Switch ²	-----	16.0 ohms
Mounting:3 holes tapped for M6 X 1.0 on top flange, equally spaced on a 4.724 inch bolt circle diameter		

1. Magnet not warranted for operation above 80 kG.
2. All resistance measurements made at room temperature.

EXCELLENCE IN MAGNETICS AND CRYOGENICS

Example Magnet Specification Sheet

The figure at left shows an example magnet specifications sheet. Several parameters needed to operate the magnet are specified. These values should be entered into the appropriate setup menu of the Model 430 Programmer. For the purposes of this example, the AMI Model 4Q06125PS power supply will be assumed, since rated current for the example magnet is 85.6 A.

The Current Limit accessible in the Protection submenu should be set to the rated current to prevent accidental operation of the magnet above rated field/current. The magnet specification sheet also indicates whether a persistent switch is installed and provides the recommended heating current. The persistent switch information is entered in the Switch submenu.

If your magnet, Model 430 Programmer, and power supply were purchased as a system from AMI, the setup menus are preset by AMI to match the magnet purchased.

The table below provides a summary of the Model 430 Programmer setup parameters for this example.

Example Setup Configuration

Parameter	Setting
Select Supply	AMI 4Q06125PS
Stability Mode	Auto
Coil Constant ^a (kG/A)	0.934
Inductance (H)	9.7
Energy Absorber Present	NO
PSwitch Installed	YES
PSwitch Current (mA)	41.0
PSwitch Heated Time (sec)	20
PSwitch Cooled Time (sec)	20
PSwitch P/S Ramp Rate (A/sec)	10
PSwitch Cooling Gain (%)	0.0%
Current Limit (A)	85.600
Enable Quench Detect	YES
Extern Rampdown Enabled	YES
Voltage Limit (V)	3.500 ^b
Ramp Rate (A/sec)	0.2165 ^c

- a. Also referred to as the Field-to-Current Ratio. Obtained by dividing the rated field by the rated current if not explicitly stated.
- b. Value is the 2.1 V charge rate plus allowances for power lead drop (typically about 10-20 milliohms) at the rated current. If a Model 601 energy absorber(s) is present, add an additional 5 V to the value.
- c. Value is obtained by dividing the magnet charging voltage (V) by the magnet inductance (H).

RAMPING FUNCTIONS

The ramping functions are used to control charging of the superconducting load. The Model 430 Programmer allows piecewise-linear charging profiles to be defined and executed (up to 10 segments, each with a unique ramp rate). The basic charging equation for a superconducting magnet is:

$$V = L \frac{di}{dt}$$

where V is the charging voltage (V), L is the magnet inductance (H), and di/dt is the ramp rate (A/s). The relationship may also be defined in terms of a ramp rate in kG/s by the relationship:

$$V = \frac{L}{C} \frac{dB}{dt}$$

where C is the coil constant (or field-to-current ratio) in kG/A, and dB/dt is the ramp rate expressed in kG/s.

A desired ramp rate should be selected by the user and entered into the Model 430 Programmer. A Voltage Limit should also be specified that is greater than or equal to the voltage calculated from the equations above plus energy absorber voltage (if installed) plus power lead voltage drop (usually less than 2 V).

Once the ramp rate and Voltage Limit are specified, the Model 430 Programmer provides two modes of ramping: *manual* and *automatic*. Manual ramping will ramp to the Current Limit via manual direction control by the user. Automatic ramping will ramp to the target field/current automatically. Automatic ramping can be thought of as a “next point” operation, whereby the Model 430 determines the appropriate ramp direction based on the present magnet current and the target value.

NOTE You may enter up to 10 digits beyond the decimal point within the ramping control menus. These extra digits are maintained in the internal memory of the Model 430 Programmer even though the full precision is not displayed after entry.

RAMPING STATES AND CONTROLS

The ramping state may be one of several values as described in the table below.

If the **RAMP / PAUSE** key is pressed while ramping, the PAUSED mode becomes active. To begin automatic ramping, press the **RAMP / PAUSE** key to deactivate the PAUSED mode. If manual ramping is desired, use

either the **INCR. FIELD** or **DECR. FIELD** SHIFT+keys for manual control of ramping up or ramping down, respectively.

Ramp modes and descriptions.

Mode	Description
Ramping	Automatic ramping to the target field/current ^a is in progress.
Holding	The target field/current has been achieved and is being maintained.
Paused	Ramping is suspended at the field/current achieved at the time the PAUSED mode was entered.
Manual Up/Down	Ramping is being controlled by the manual control (INCR. FIELD and DECR. FIELD) SHIFT-key functions available on the front panel.
Zeroing Current	RAMP TO ZERO is active, and the Model 430 Programmer is ramping current to 0 A.
Zero Current	RAMP TO ZERO is still active, and the current is less than 0.1% of I_{max} .
Heating Switch	The persistent switch heater has been activated. Ramping is disabled during the persistent switch heating period.
Cooling Switch	The persistent switch heater has been deactivated. Ramping is disabled during the persistent switch cooling period.
External Rampdown	An external rampdown has been triggered. The system will rampdown using any defined rampdown ramp rates and <i>cannot be interrupted</i> until zero current is achieved.

a. The target field/current setting is discussed on page 61.

Voltage limit and ramp rate may be specified from quickly accessible SHIFT+key menus from the front panel keypad⁴⁵. The settings for Voltage Limit and ramp rate(s) are applicable to both manual and automatic ramping.

MANUAL RAMPING

The **INCR. FIELD** and **DECR. FIELD** SHIFT+key functions control manual ramping. Manual ramping ramps field/current up or down at the defined ramp rate(s). See page 67 for details regarding the use of these SHIFT+key functions.

AUTOMATIC RAMPING

Automatic ramping differs from manual ramping in that the Model 430 Programmer automatically performs ramping in the appropriate direction to achieve the value of the target field/current setting. To use automatic ramping, enter the target field/current with which ramping is desired⁴⁶. If

45. Refer to on page 63 and on page 66.

ramping is not PAUSED, ramping to the target field/current begins immediately. If ramping is PAUSED, ramping to the target field/current will begin when the **RAMP / PAUSE** key is pressed to take the Model 430 Programmer out of PAUSED mode. The ramp rate will be controlled by the preset ramp rate variables as described in on page 63.

RAMPING TO ZERO

Pressing the **RAMP TO ZERO** key activates an immediate ramp to zero field/current. See page 62 for details. Use the feature to zero the field/current instead of setting the target field/current to a value of zero.

FINE ADJUST OF FIELD / CURRENT IN HOLDING MODE

If the target field/current menu is active *and* the Model 430 Programmer is in HOLDING mode (indicated by a “–” Status Indicator), the fine adjust knob can be used to manipulate the output current. While at the target field/current menu, press **SHIFT**, followed by **FINE ADJUST**. This will allow fine adjustment of the field/current (see page 69).

+20.02 A	-	Target Current (A)♦
+0.20 Vs		+20.0239

When the fine adjust knob is turned the Model 430 Programmer will follow the target current as it is adjusted, at the defined ramp rate for the segment in which it is operating. Adjustment of the current is prevented from exceeding the Current Limit specified in the Load setup menu (see page 92). The *resolution* of the adjustment is 15 digits, which is greater than the resolution of the display.

When the field/current is adjusted to the desired value, press the **ENTER** key to keep that value as the target field/current. If any other operation is performed before **ENTER** is pressed, the target field/current value will revert back to what it was before adjustment using the fine adjust knob was initiated, and the current will immediately begin ramping back to that value.

46. See page 61.

PERSISTENT SWITCH CONTROL

The Model 430 Programmer includes an integral persistent switch heater that provides the capability of controlling the persistent mode of the magnet either locally from the front panel of the Model 430 Programmer using the **PERSIST. SWITCH CONTROL** key⁴⁷, or remotely through a communications interface. The persistent mode of the magnet is indicated by the **MAGNET IN PERSISTENT MODE** LED⁴⁸.

See page 58 for details of the use of the **PERSIST. SWITCH CONTROL** key.

NOTE The following procedures include several automatically sequenced steps once initiated. It is possible to interrupt the process at any point by pressing the **SHIFT+ESC** keys. Please note that the state in which the system will remain after this interruption depends on the specific active step during which the **SHIFT+ESC** was pressed. Use this abort override keystroke with caution.

PROCEDURE FOR INITIAL HEATING OF THE SWITCH

The Model 430 Programmer remembers the state of the persistent switch during the time that the Programmer is de-energized. If the Model 430 is turned on when its shut down state was such that the persistent switch was heated and commanding zero current (the normal state after the magnet is discharged), the following screen will be displayed.

0.00 A		Mode: Paused
0.00 Vs		PSwitch Heater: OFF

In order to charge the magnet, the persistent switch heater must be energized. Perform the following steps.

47. See page 58.

48. See page 71.

1. Turn on the persistent switch heater by pressing the **PERSIST. SWITCH CONTROL** key to heat the persistent switch heater.

0.00 A	0	Mode: Heating Switch (4)
0.00 Vs		PSwitch Heater: ON

NOTE If the PSwitch Transition setting⁴⁹ is set to Timer, the number in parentheses in the display indicates the number of seconds remaining in the timer countdown. If the PSwitch Transition setting is set to Magnet Voltage, the number in parentheses is the running magnet voltage variance. For the magnet voltage-based switch transition, a variance value of zero indicates the switch is in the cooled state.

2. After the persistent switch heater has been heated for the preset heating time specified by the PSwitch Heated Time setting, or a transition is detected by the magnet voltage-based option, the display will show the default display and wait at zero current for a command from the operator. The magnet is no longer isolated from the power supply output.

0.00 A	P	Mode: Paused
0.00 Vs		PSwitch Heater: ON

PROCEDURE FOR ENTERING PERSISTENT MODE

In order to enter the persistent mode of magnet operation, the user should perform the following steps:

1. Use either automatic or manual ramping to achieve the desired field or current in the magnet.
2. The Model 430 Programmer must be in either the HOLDING or PAUSED mode at the target field or current.
3. The Model 430 Programmer must be at the default field/current display.⁵⁰
4. Press the **PERSIST. SWITCH CONTROL** key to turn off the persistent switch heater and automatically ramp the power supply to zero current:
 - a. After the **PERSIST. SWITCH CONTROL** key is pressed, the Model 430 Programmer requests that the **ENTER** key be pressed as

49. Refer to page 88.

50. Refer to page 51.

a confirmation that the magnet should be placed in persistent mode.⁵¹

+50.00 A - Press ENTER to begin
0.00 Vm Persistent Mode

- b. When **ENTER** is pressed, the persistent switch is cooled for the preset persistent switch cooling time (set by the PSwitch Cooled Time⁵²). The display indicates that the persistent switch is being cooled and indicates the number of seconds (4 in this example) remaining in the cooling cycle for timer-based switch transitions, or *optionally* indicates the running variance of the magnet voltage for magnet voltage-based switch transitions.

+50.00 A ⚭ Mode: Cooling Switch (4)
+0.01 Vm PSwitch Heater: OFF

NOTE For the magnet voltage-based switch transitions, a variance value of zero indicates a cooled switch. Therefore, during the cooldown the display will show a seemingly random sequence of numbers that should gradually decrease and eventually decay to a value of zero. Once the variance remains at zero for at least five seconds, the switch will be considered cooled.

- c. When the cooled time is complete, the green **MAGNET IN PERSISTENT MODE** LED will illuminate and the power supply will ramp to zero at the PSw P/S Ramp Rate value⁵³.

+42.89 A ↓ Mode: Power Supply ramping
0.00 Vm to zero current

NOTE The magnet voltage (Vm) is monitored during the power supply ramp to zero. For a cooled switch, the magnet voltage should remain at zero. The following steps d through f apply only if the magnet voltage does *not* remain at zero.

51. Pressing the **ESC** key will terminate the command and return the Model 430 Programmer to the default screen.
52. Refer to on page 90 for timer-based switch transitions.
53. Refer to on page 90.

- d. If the magnet voltage exceeds 0.5 V during this ramp to zero, the Model 430 Programmer beeps to indicate the persistent switch did not transition to the superconducting state. The Model 430 will then turn the switch heater back on *immediately* and then begin ramping the field/current back to the value before the present cooling cycle initiation:

```
+45.39 A ↑ Mode: Power Supply Ramping  
+1.52 Vm      to match magnet field
```

NOTE The ramp back to the value before the cooling cycle was initiated can be interrupted at any time by pressing the **RAMP/PAUSE** key. The ramping will then PAUSE and hold.

- e. When the field/current reaches the value before the cooling cycle initiation, the display will indicate the persistent mode transition malfunction:

```
+50.00 A - Mode: Paused w/PSW error  
+0.06 Vm      Press ENTER to continue
```

- f. After pressing **ENTER**, the Model 430 Programmer will revert to the default field/current display.

```
+50.00 A P Mode: Paused  
+0.00 Vm      PSwitch Heater: ON
```

5. If there is no magnet voltage error during the rampdown, and after the power supply is finished ramping to zero, the following screen will be displayed:

```
0.00 A - Magnet in Persistent Mode  
0.00 Vm      Press PER.SW.CTRL. to exit
```

NOTE If desired, press the **ESC** key in the above display to return the Model 430 Programmer to the default display.

```
0.00 A - Mode: Zero Current  
0.00 Vm      PSwitch Heater: OFF
```

NOTE Refer to page 61 for the procedure to display the magnet current that was established when the persistent switch was cooled.

6. If desired, the power supply system can be de-energized. Turn the power supply off first followed in a few seconds by the Model 430 Programmer.

NOTE The Model 430 Programmer will store the state of the magnet in memory and assist the user in exiting the persistent mode when the Model 430 Programmer is next turned on (discussed in the following paragraphs).

PROCEDURE FOR EXITING PERSISTENT MODE

To exit the persistent mode of magnet operation, the user should perform the following steps:

1. If the Model 430 Programmer *has not been* powered off since the magnet was placed in persistent mode, proceed to step 3.
2. If the Model 430 Programmer *has been* powered off since the magnet was placed in persistent mode, complete the following steps (a) and (b) below before proceeding to step 3.
 - a. Energize the Model 430 and wait for the prompt on the Model 430 display and then energize the power supply.

```
0.00 A P Turn on power supply  
0.00 Vs Press ENTER to continue
```

After the power supply has been on for a few seconds⁵⁴, press **ENTER** to clear the Model 430 screen prompt.

- b. When **ENTER** is pressed, the display will indicate that the magnet was in persistent mode⁵⁵ when the Model 430 Programmer was turned off (and display the magnet current that was established when the persistent switch was cooled).

```
Magnet in Persistent Mode (13.5A). Use  
PERSISTENT SWITCH CONTROL to exit Per. Mode
```

54. If the power supply is an AMI 4Q06125PS Type, wait for the audible click of the relay before pressing **ENTER** on the Model 430.
55. The **MAGNET IN PERSISTENT MODE** LED will also be illuminated.

3. Press **PERSIST. SWITCH CONTROL** and the Model 430 display prompts with:

```
0.00 A  P  Press ENTER to exit  
0.00 Vs  Persistent Mode
```

NOTE Should the user desire not to exit persistent mode, press **ESC** to return to the default field/current display. If the **PERSIST. SWITCH CONTROL** key is later pressed, the Model 430 Programmer will execute steps 4 through 7, below.

NOTE If persistent mode is not exited and it is later desired to display the magnet current that was established when the persistent switch was cooled, refer to on page 61 for the procedure.

4. When **ENTER** is pressed, the power supply is ramped to the current that was flowing in the magnet at the time the persistent mode was entered. The power supply will ramp at the PSw P/S Ramp Rate value⁵⁶.

```
+11.72 A  ↑  Mode: Power Supply ramping  
+0.23 Vs          to magnet current
```

5. The persistent switch heater is heated for the preset heating time as set by the PSwitch Heated Time variable⁵⁷. Optionally, if the PSwitch Transition is set for magnet voltage, the magnet voltage variance will be displayed. The variance should transition from a value of zero to some number when the switch transitions to the heated state.

```
+50.00 A  ◦  Mode: Heating Switch (4)  
+0.56 Vs      PSwitch Heater: ON
```

56. Refer to on page 90.

57. Refer to on page 89. The (4) in the display indicates the number of seconds remaining in the heating cycle (4 in this example) for timer-based switch transitions, or optionally the magnet voltage variance for magnet voltage-based transitions.

NOTE The magnet voltage (V_m) is monitored during the switch heating cycle. If the voltage is greater than 0.5 V, the Model 430 Programmer will beep and display a message to indicate a mismatch between the magnet current and power supply current.

+50.00 A ◊ Mode: Heating Switch (4)
+0.86 Vm *** Current Mismatch ***

NOTE This mismatch in current indicates the magnet current (and therefore the field) has decayed significantly during the time the magnet was in persistent mode. Since this is not a critical error⁵⁸, the screen will change back to the default display typically at some field/current less than the last recorded persistent value.

+47.59 A P Mode: Paused
0.00 Vm PSwitch Heater: ON

-
6. After the Model 430 Programmer has completed this persistent switch heating operation, the display reads:

+50.00 A P Mode: Magnet in Driven Mode
0.00 Vm Press ENTER to continue

-
7. After **ENTER** is pressed, the default field/current status screen is displayed with the power supply in the pause mode:

+50.00 A P Mode: Paused
0.00 Vm PSwitch Heater: ON

58. This current mismatch could be indicative of a problem with the magnet persistent joints.

TOGLGING THE STATE OF THE PERSISTENT SWITCH HEATER

The state of the persistent switch can be toggled by pressing **SHIFT** and then the **PERSIST. SWITCH CONTROL** key. By toggling the state of the heater in this manner, there will be no power supply ramping or other automatic functions.

ENTERING PERSISTENT MODE WITHOUT AUTOMATIC RAMP TO ZERO

1. Place the Model 430 Programmer in the HOLDING or PAUSED mode at the desired field or current.
2. Press the **SHIFT** and then the **PERSIST. SWITCH CONTROL** key to turn off the persistent switch heater current. Note that the Model 430 Programmer will enter the COOLING SWITCH mode and disallow any ramping during the switch cooling period.
3. If magnet current is greater than ~0.1% of the power supply maximum output current when the switch heater current is turned off, the **MAGNET IN PERSISTENT MODE** LED will illuminate.

EXITING PERSISTENT MODE WITHOUT AUTOMATIC RAMP TO LAST KNOWN PERSISTENT MAGNET CURRENT

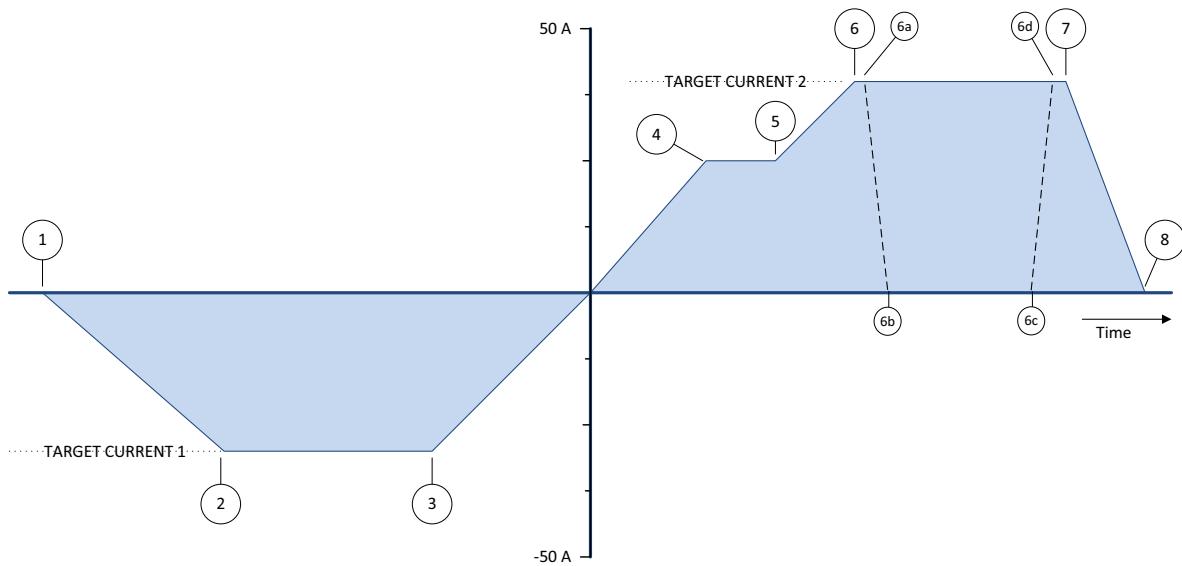
CAUTION To avoid damage to the magnet or triggering protection circuits on the magnet, the current in the power supply should match the current that was flowing in the magnet when the persistent mode was entered.

NOTE For the procedure to display the magnet current that was established when the persistent switch was cooled, refer to page 61.

1. Place the Model 430 Programmer in the HOLDING or PAUSED mode at the desired field or current.
2. Press the **SHIFT** and then the **PERSIST. SWITCH CONTROL** key to turn on the persistent switch heater current. Note that the Model 430 Programmer will enter the HEATING SWITCH mode and disallow any ramping during the switch heating period.
3. At the end of the switch heating period, the **MAGNET IN PERSISTENT MODE** LED will be turned off and the Model 430 Programmer will be in the PAUSED mode.

RAMPING FUNCTIONS EXAMPLE

As an example of ramping to two target field/current settings, refer to figure below. Each step is labeled as 1 through 8. The Model 430 Programmer, for the purposes of the example, is assumed to be in the PAUSED mode at 0 A at the beginning of the ramping example.



Ramping to Two Different Target Field/Current Settings

Point 1. The current is 0 A and the Model 430 Programmer is in the PAUSED mode. The user sets the target field/current to -28.000 A. The **RAMP / PAUSE** key is pressed so that the PAUSED mode is no longer active and the Model 430 begins ramping current.

Point 2. The target field/current setting of -28.000 A is achieved and the Model 430 Programmer switches to HOLDING mode.

Point 3. The user changes the ramp rate setting. The user also sets a new value of +40.000 A for the target field/current. As soon as the new target field/current is entered, the Model 430 Programmer automatically begins ramping at the specified ramp rate.

Point 4. The user presses the **RAMP / PAUSE** key at a current of 25.15 A and the PAUSED mode is activated. The Model 430 Programmer maintains the current in the PAUSED mode.

Point 5. The user presses the **RAMP / PAUSE** key once again to resume ramping.

Point 6. The target field/current setting of +40.000 A is achieved and the Model 430 Programmer switches to HOLDING mode. At this point the user deactivates the persistent switch heater by pressing the **PERSIST. SWITCH CONTROL** key, which removes the magnet from the circuit.

Point 6a. The dashed line between point 6a and 6b is the rapid ramping down of the power supply current which automatically happens after the PSwitch Cooled Time has elapsed. Note that the magnet current remains at the Point 6 value when the magnet was placed in persistent mode.

Point 6c. The user presses the **PERSIST. SWITCH CONTROL** key which rapidly ramps the power supply output to the current that is flowing in the magnet. The power supply matches the magnet current at point 6d.

Point 7. The user again increases the ramp rate and presses the **RAMP TO ZERO** key to begin ramping to zero current. The Model 430 Programmer automatically ramps the current to 0 A.

Point 8. The Model 430 Programmer switches to ZERO CURRENT mode at 0 A current when achieved and holds at this current until further commands are issued by the user.

QUENCH DETECTION

The Model 430 Programmer continuously monitors the superconducting magnet load and can automatically detect a field/current quench condition. If a quench is detected, the **MAGNET QUENCH** LED will be illuminated and the display will appear as shown below.

+44.36 A	Quench Detect @ +80.56 A
0.00 Vs	PSwitch Heater: ON

QUENCH DETECTION METHOD

The *primary* method for quench detection is a continual internal comparison between the reference current and the measured current. If the measured current for the system develops a mismatch to the reference (i.e. the desired control value), then if the mismatch exceeds a predefined margin a quench detection will trigger.

Optionally, if the Model 430 is configured for external temperature input, the quench detection logic can utilize a measured temperature (such as from a cold head of a cryogenic refrigerator). If the measured temperature exceeds some predefined safe limit, the Model 430 will trigger a quench detection.

The Model 430 may also be configured to use *both* the current mismatch and temperature detection methods and trigger a quench if either indicate a problem.

NOTE The Model 430 quench detection features should *never* be relied upon as the primary quench safety for *any* magnet system. The purpose of the Model 430 quench detection is simply to avoid dumping any *additional* energy into a magnet system that has *already* quenched. The only action the Model 430 can take is to force the power supply voltage output to zero volts and hold. Superconducting magnets should be internally designed to be safe in the event of a quench without any input from the Model 430.

When a quench is detected, the Model 430 automatically sets the power supply output voltage to zero volts, provides a quench output signal (dry contacts) to the rear panel Quench I/O connector (see page 217 of the Appendix for the connector pinout), and will not respond to further input until the **RESET QUENCH** (SHIFT+3) key is used to clear the quench

detect condition, or until the quench condition is cleared by a remote command.

If the **RESET QUENCH** key has been locked⁵⁹, the user will be asked to enter the password to clear the quench. The entry of this password will not unlock this reset quench feature, but will only reset the current quench event so operation may resume. Enter the password followed by the **ENTER** key to reset the quench and continue.

+44.36 A	Enter Password*
0.00 Vs	...

When the **RESET QUENCH** key is used to clear the quench condition or a remote clear command is issued, the Model 430 Programmer will automatically enter the PAUSED mode and will attempt to maintain the current present at the point the quench condition was cleared.

EXTERNAL QUENCH DETECTION

The rear panel Quench I/O connector provides pins for external quench input (contact closure — see page 217 of the *Appendix* for the connector pinout). If the quench input is asserted, then the Model 430 Programmer interprets this input as indication of a quench condition and the Model 430 automatically sets the power supply output voltage to zero and will not respond to further input until the **RESET QUENCH** key is used to clear the quench detect condition, or until the quench condition is cleared by a remote command. The rear panel input cannot be disabled; however, it may be left disconnected without the possibility of a generating a false quench condition.

NOTE If the external quench detection circuit continues to assert the quench detection input of the Model 430 Programmer, the **RESET QUENCH** (SHIFT+3) key will be unable to clear the quench condition.

DISABLING INTERNAL QUENCH DETECTION

The internal quench detection feature may be disabled in the Load submenu⁶⁰. However, the rear panel Quench I/O connector output remains active at all times.

59. See page 103.

60. See page 93.

If the internal quench detection feature is disabled, the Model 430 Programmer attempts to limit the error between the commanded current and the present current to a value that will not result in excessive voltages being introduced across the magnet terminals. Under most operating conditions this will not damage any internal protection circuits of the magnet. If an actual quench condition occurs, the Model 430 will follow the magnet current to zero unless the user intervenes.

If the rear panel Quench I/O connector is asserted, the Model 430 will force the power supply output to zero volts regardless of whether the internal quench detection is enabled or disabled.

In the event that the persistent switch becomes normal without user or remote activation of the switch heater control, the Model 430 Programmer will match the magnet current and attempt to stabilize the load *if the internal quench detection feature is disabled*. If the internal quench detection feature is *enabled*, then this event will generally trigger the quench detection logic if a difference exists between the magnet current and the real-time setpoint current of the Model 430.

EXTERNAL RAMPDOWN

This feature⁶¹ is useful in any application requiring magnet rampdown in response to any external event that can be signaled by the closure of a pair of electrical contacts⁶².

The user input for initiating external rampdown is provided on the rear panel of the Model 430 Programmer. The process is started by shorting, for at least 10 milliseconds, the input connections through closure of user-supplied external contacts. Once triggered, rampdown of the magnetic field of the magnet is initiated.

NOTE Operator intervention (such as **RAMP|PAUSE**, **ESC**, **SHIFT+ESC**, etc.) is inhibited until rampdown is completed and the external rampdown signal is cleared. There is no abort function provided, however the quench detection feature of the Model 430 remains active during the rampdown.

The external rampdown feature is ideally suited for use with AMI's Model 1700 with the liquid helium level monitor option in wet magnet systems. The Model 1700 has externally accessible normally-open relay contacts that close whenever the liquid helium level drops below a preset level.

61. When enabled. See page 98.

62. Refer to page 218. The contact closure time must be at least 10 milliseconds to ensure it doesn't fall between the sampling points of the Model 430 Programmer.

When connected to the Model 430 Programmer, these contacts can signal the Model 430 to safely and automatically ramp the magnet field to zero, thereby preventing a magnet quench due to low liquid helium level in the system.

EXTERNAL RAMPDOWN WHILE IN PERSISTENT MODE

The following steps and associated screen displays describe the process that occurs after external rampdown is initiated while the magnet is in persistent mode:

1. The Model 430 Programmer first ramps the power supply to the magnet current.

```
+3.92 A ↑ Mode: Ramping  
+0.17 Vs      PSwitch Heater: OFF
```

2. Once the power supply is at the magnet current, the **FIELD AT TARGET** LED will light and the unit will momentarily "hold":

```
+50.00 A - Mode: Holding  
+0.65 Vs      PSwitch Heater: OFF
```

3. Following a short "hold", the persistent switch will be heated to place the power supply in control of magnet current:

```
+50.00 A ◊ Mode: Heating Switch (4)  
+0.67 Vs      PSwitch Heater: ON
```

4. After heating (turning off) the persistent switch, the **MAGNET IN PERSISTENT MODE** LED extinguishes, and rampdown begins. The **FIELD AT TARGET** LED extinguishes.

```
+48.85 A ↓ Ext. Rampdown in progress  
-1.68 Vs      PSwitch Heater: ON
```

5. After rampdown, the following will display:

```
0.00 A - Ext. Rampdown completed  
0.00 Vs      Press ENTER to continue
```

NOTE The external rampdown signal **MUST** be cleared before pressing **ENTER** will yield a response. Further operator control is inhibited until the external rampdown signal is cleared.

6. Once the external signal has been cleared, **ENTER** can be pressed. User control will be re-established and the operator can continue manual operation of the system. The following will be displayed after pressing **ENTER**:

```
+0.00 A - Mode: Zero Current  
0.00 Vs PSwitch Heater: ON
```

EXTERNAL RAMPDOWN WHILE NOT IN PERSISTENT MODE

When external rampdown is initiated with the magnet **not** in PERSISTENT mode, the persistent switch is either heated or not installed so there is no need for persistent switch heating. The power supply is already at (and in control of) the magnet current, so the Model 430 Programmer executes an ordinary rampdown:

1. The rampdown begins immediately as described on page 130 (step 4 of "External Rampdown while in Persistent Mode"):

```
+48.85 A ↓ Ext. Rampdown in progress  
-1.89 Vs PSwitch Heater: ON
```

2. The sequence continues as described for the magnet in persistent mode (see page 130, steps 5 through 6).

NOTE After rampdown, the external rampdown signal **MUST** be cleared before continuing. Further operator control is inhibited until the external rampdown signal is cleared.

SUMMARY OF LIMITS AND DEFAULT SETTINGS

The table below provides a summary of the operational limits and the default setting for all Model 430 Programmer parameters. If the user attempts to enter a value outside of the limits, the Model 430 Programmer will beep once, indicate an error, and revert to the previous setting.

References to the specifications table on page 7 indicate that the absolute limit is determined by the specific configuration of the Model 430 Programmer purchased.

Summary of Model 430 Programmer Limits and Defaults

Model 430 Setting (Units)	Absolute Limits	Default Setting ^a
Min Output Voltage (V)	0.000 to -20.000	-6.000
Max Output Voltage (V)	0.001 to +20.000	6.000
Min Output Current (A)	see table on page 7	-125.000
Max Output Current (A)	see table on page 7	125.000
V-V Mode Input Range (V)	-10.000 to +10.000	-10.000 to +10.000
Stability Setting (%)	0.0 to 100.0	0.0
Coil Constant (kG/A)	0.001 to 999.99999	1.0
Inductance (H)	0.0 to 1000.0	0.0 ^b
PSwitch Current (mA)	0.0 to 125.0	10.0
PSwitch Heated Time (sec)	5 to 3600	20
PSwitch Cooled Time (sec)	5 to 3600	20
PSwitch Power Supply Ramp Rate (A/sec)	0.1 A/sec to the max ramp rate (see table on page 7)	10
PSwitch Cooling Gain	0.0 to 100.0	0.0
Current Limit (A)	\geq Min Output Current and \leq Max Output Current	80.000
Display Brightness (%)	25, 50, 75, 100	100
Voltage Limit (V)	\geq 0.001 and \leq Max Output Voltage	2.000
Ramp Rate (A/sec)	see table on page 7	0.100
Target Current (A)	\leq Current Limit	5.000

a. Unless preset by factory.

b. A value of 0.0 means the inductance is not known.

Remote Interface Reference

The Model 430 Programmer provides both RS-232 and Ethernet interfaces as standard features. The serial and Ethernet interfaces may be operated simultaneously. Separate output buffers are also provided for the serial and Ethernet return data. However, for optimal performance and simplicity of programming, AMI generally recommends limiting operation to one interface. An exception to this recommendation would be using the serial port as a debugging aid during programming of the Ethernet port (or vice-versa), which can prove to be a useful resource.

SCPI COMMAND SUMMARY

The following manual conventions are used for SCPI (*Standard Commands for Programmable Instruments*) style syntax for the remote interface commands:

- Braces { } enclose valid parameter choices.
- A vertical bar | separates multiple choices for each parameter.
- Triangle brackets < > indicate that you must supply a value.
- Parentheses () within < > indicate alternative units are available.

For example, the command `PSwitch {0|1}` indicates that the command `PSwitch` has two parameter options: 0 or 1. Refer to the detailed description of each command for information regarding specific parameter choices and their meanings. Capitalized portions of the commands indicate acceptable abbreviations (e.g. `PS`). Default settings are shown in bold.

System-Related Commands

(see page 152 for more information)

*IDN?

*RST

*TST?

*LED?

<Ctrl-C>

PRINT:SERIALnumber?

PRINT:PASSWORD?

SETTINGS?

SYSTem:LOCAL

SYSTem:REMote

SYSTem:TIME?

SYSTem:TIME:SET <date(mm/dd/yyyy) time(hh:mm:ss)>

SYSTem:ERRor?

SYSTem:ERRor:COUNT?

SYSTem:IPaddr?

Status System Commands

(see page 155 for more information)

*STB?

*SRE <enable_value>

*SRE?

*CLS

*ESR?

*ESE <enable_value>

*ESE?

*PSC {0 | 1}

*PSC?

*OPC

*OPC?

Supply Setup Configuration Queries

(see page 157 for more information)

SUPPLY:VOLTage:MINimum?

SUPPLY:VOLTage:MAXimum?

SUPPLY:CURRent:MINimum?

SUPPLY:CURRent:MAXimum?

SUPPLY:TYPE?

SUPPLY:MODE?

Load Setup Configuration Commands and Queries

(see page 159 for more information)

CONFigure:STABILITY:MODE {0|1|2}

CONFigure:STABILITY <percent>

CONFigure:STABILITY:RESistor {0|1}

CONFigure:COILconst <value (kG/A, T/A)>

CONFigure:INDuctance <inductance (H)>

CONFigure:ABsorber {0|1}

STABILITY:MODE?

STABILITY?

STABILITY:RESistor?

COILconst?

INDuctance:SENSe?

INDuctance?

ABsorber?

Switch Setup Configuration Commands and Queries

(see page 161 for more information)

CONFigure:PSwitch {0|1}

CONFigure:PSwitch:CURRent <current (A)>

CONFigure:PSwitch:TRANSition {0|1}

CONFigure:PSwitch:HeatTIME <time (sec)>

CONFigure:PSwitch:CoolTIME <time (sec)>

CONFigure:PSwitch:PowerSupplyRampRate <rate (A/s)>

CONFigure:PSwitch:CoolingGAIN <percent>

PSwitch:INSTalled?

```
PSwitch:AUTODetect?  
PSwitch:CURRent?  
PSwitch:TRANSition?  
PSwitch:HeatTIME?  
PSwitch:CoolTIME?  
PSwitch:PowerSupplyRampRate?  
PSwitch:CoolingGAIN?
```

Protection Setup Configuration Commands and Queries

(see page 162 for more information)

```
CONFigure:CURREnt:LIMit <current (A)>  
CONFigure:QUench:DETect {0|1|2|3}  
CONFigure:QUench:RATE {1|2|3|4|5}  
CONFigure:OPLimit:MODE {0|1|2}  
CONFigure:OPLimit:ICSLOPE <value (A/K)>  
  
CONFigure:OPLimit:ICOFFSET <value (A)>  
CONFigure:OPLimit:TMAX <value (K)>  
CONFigure:OPLimit:TSCALE <value (K/V)>  
CONFigure:OPLimit:TOFFSET <value (K)>  
CONFigure:RAMPDown:ENABLE {0|1}
```

```
CURREnt:LIMit?  
QUench:DETect?  
QUench:RATE?  
OPLimit:IC?  
OPLimit:TEMP?  
OPLimit:MODE?  
OPLimit:ICSLOPE?  
OPLimit:ICOFFSET?  
OPLimit:TMAX?  
OPLimit:TSCALE?  
OPLimit:TOFFSET?  
RAMPDown:ENABLE?
```

Misc Setup Configuration Commands and Queries

(see page 165 for more information)

```
CONFigure:RAMP:RATE:SEGments <value>  
CONFigure:RAMP:RATE:UNITS {0|1}  
CONFigure:FIELD:UNITS {0|1}
```

```
RAMP:RATE:SEGments?
```

RAMP:RATE:UNITS?

FIELD:UNITS?

Lock Configuration Commands

(see page 166 for more information)

```
CONFIGure:LOCK:PSwitch:CONTROL {0|1}
CONFIGure:LOCK:TARGet {0|1}
CONFIGure:LOCK:RAMP-PAUSE {0|1}
CONFIGure:LOCK:ZEROfield {0|1}
CONFIGure:LOCK:RAMPrate {0|1}
CONFIGure:LOCK:SUPPLY {0|1}
CONFIGure:LOCK:VOLTage:LIMit {0|1}
CONFIGure:LOCK:QUench:RESet {0|1}
CONFIGure:LOCK:INCR-DECR {0|1}
CONFIGure:LOCK:FIELD-CURRent {0|1}
CONFIGure:LOCK:FIELD:UNITS {0|1}
CONFIGure:LOCK:STABILITY {0|1}
CONFIGure:LOCK:INDuctance {0|1}
CONFIGure:LOCK:VOLTage:VS-VM {0|1}
CONFIGure:LOCK:VOLTMeter {0|1}
CONFIGure:LOCK:FINEadjust {0|1}
CONFIGure:LOCK:COILconst {0|1}
CONFIGure:LOCK:CURREnt:LIMIT {0|1}
CONFIGure:LOCK:CURREnt:RATING {0:1}
CONFIGure:LOCK:PSwitch:SETtings {0|1}
CONFIGure:LOCK:QUench:DETect {0|1}
CONFIGure:LOCK:QUench:RATE {0|1}
CONFIGure:LOCK:ABsorber {0|1}
CONFIGure:LOCK:RAMPDown {0|1}
CONFIGure:LOCK:BRIGHTness {0|1}
CONFIGure:LOCK:NETsetup {0|1}
CONFIGure:LOCK:OPLimit {0|1}
```

Lock Configuration Queries

(see page 166 for more information)

LOCK:PSwitch:CONTROL?

LOCK:TARGet?

LOCK:RAMP-PAUSE?

LOCK:ZEROfield?

LOCK:RAMPrate?

LOCK:SUPPLY?

LOCK:VOLTage:LIMit?

LOCK:QUench:RESet?
LOCK:INCR-DECR?
LOCK:FIELD-CURRent?
LOCK:FIELD:UNITS?
LOCK:STABility?
LOCK:INDuctance?
LOCK:VOLTage:VS-VM?
LOCK:VOLTMeter?
LOCK:FINEadjust?
LOCK:COILconst?
LOCK:CURREnt:LIMit?
LOCK:CURREnt:RATING?
LOCK:PSwitch:SETtings?
LOCK:QUench:DETect?
LOCK:QUench:RATE?
LOCK:ABsorber?
LOCK:RAMPDown?
LOCK:BRIGHTness?
LOCK:NETsetup?
LOCK:OPLimit?

Net Setup Configuration Commands and Queries

(see page 172 for more information)

CONFigure:IPNAME <system name>

IPNAME?

Ramp Target/Rate Configuration Commands and Queries

(see page 172 for more information)

CONFigure:VOLTage:LIMit <voltage (V)>
CONFigure:CURREnt:TARGet <current (A)>
CONFigure:FIELD:TARGet <field (kG, T)>
CONFigure:RAMP:RATE:CURREnt <segment>,<rate (A/s, A/min)>, <upper bound (A)>
CONFigure:RAMP:RATE:FIELD <segment>,<rate (kG/s, kG/min, T/s, T/min)>,<upper bound (kG, T)>

VOLTage:LIMit?
CURREnt:TARGet?
FIELD:TARGet?
RAMP:RATE:CURREnt:<segment>?
RAMP:RATE:FIELD:<segment>?

Measurement Commands and Queries

(see page 174 for more information)

VOLTage:MAGnet?
VOLTage:SUPPLY?
CURRent:MAGnet?
CURRent:SUPPLY?
CURRent:REFerence?
FIELD:MAGnet?
FIELD:REFerence?

Ramping State Commands and Queries

(see page 175 for more information)

RAMP
PAUSE
INCR
DECR
ZERO

STATE?

Switch Heater Commands and Queries

(see page 177 for more information)

PSwitch {0|1}
PSwitch?
PERSISTENT?

Quench State Commands and Queries

(see page 178 for more information)

QUENCH {0|1}
QUENCH?

QUENCH:COUNT?
QUENCHFILE?
QUENCHBACKUP?

Rampdown State Commands and Queries

(see page 179 for more information)

CONFigure:RAMPDown:RATE:SEGments <value>
CONFigure:RAMPDown:RATE:CURRent <segment>, <rate (A/s,
A/min)>, <upper bound (A)>
CONFigure:RAMPDown:RATE:FIELD <segment>, <rate (kG/s, kG/
min, T/s, T/min)>, <upper bound (Kg, T)>

RAMPDown:RATE:SEGments?
RAMPDown:RATE:CURRent:<segment>?
RAMPDown:RATE:FIELD:<segment>?

RAMPDown:COUNT?
RAMPDownFile?
RAMPDownBackup?

Trigger Control and Queries

(see page 181 for more information)

*ETE <enable_value>
*ETE?
*TRG

Keypress Commands

(these commands act as remote keypresses on any interface/port, see
the table on page 151)

W_KEY_SHIFT
W_KEY_TARGET
W_KEY_ZEROFIELD
W_KEY_PSWITCH
W_KEY_RAMPPAUSE
W_KEY_1
W_KEY_2
W_KEY_3
W_KEY_4
W_KEY_5
W_KEY_6
W_KEY_7
W_KEY_8
W_KEY_9
W_KEY_0

```
W_KEY_PERIOD  
W_KEY_PLUSMINUS  
W_KEY_ESC  
W_KEY_MENU  
W_KEY_RIGHT  
W_KEY_LEFT  
W_KEY_ENTER  
W_FINE_ADJ_DELTA <value>
```

PROGRAMMING OVERVIEW

The Model 430 Programmer conforms to the SCPI (*Standard Commands for Programmable Instruments*) IEEE standard. The SCPI standard is an ASCII-based specification designed to provide a consistent command structure for instruments from various manufacturers.

The Model 430 Programmer also implements a status system for monitoring the state of the Model 430 through the *Standard Event* and *Status Byte* registers.

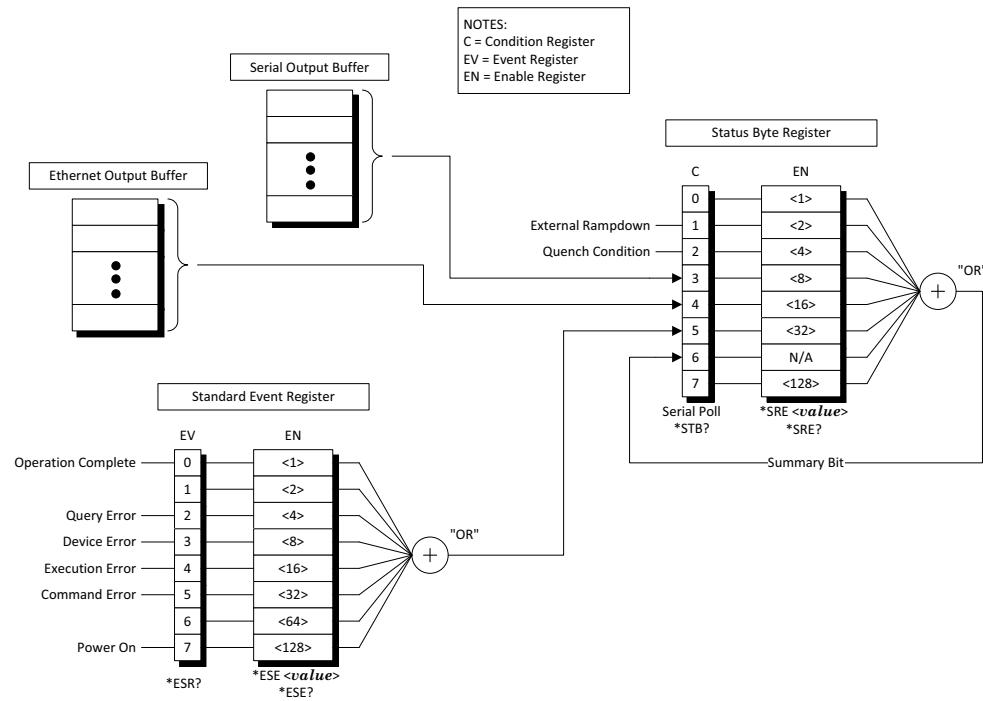
SCPI LANGUAGE INTRODUCTION

SCPI commands conform to a tree structure where commands are grouped according to common keywords. For example, commands which set a Model 430 Programmer setup or operating parameter begin with the keyword **CONF**igure. The keywords are shown in upper case and lower case to indicate acceptable abbreviations. For the example keyword **CONF**igure, the user may send either the abbreviated form of **CONF**, or the entire keyword **CONFIGURE**. Any other form of the keyword is illegal and will generate an error.

Many commands also require multiple keywords to traverse the tree structure of the entire Model 430 Programmer command set. For example, commands associated with a current setting require the prefix of **CONF**igure:**CUR**rent. Note that a colon (:) separates the keywords. No spaces are allowed before or after the colon. Parameters must be separated from the command keyword(s) by at least one space.

SCPI STATUS SYSTEM

The Model 430 Programmer status system reports various conditions of the instrument in two registers groups shown in the figure below. The register groups consist of a condition or event register, and an enable register which controls the actions of specific bits within the condition or event registers



The Model 430 Programmer Status System

A *condition* register continuously monitors the state of the instrument. The bits of a condition register are updated in real time. A condition register is read-only and is not cleared when you read the register. A query of a condition register returns a decimal value in the appropriate output buffer which corresponds to the binary-weighted sum of all bits set in the register.

An *event* register latches various events. Events are not buffered, therefore once a bit is set in the event register, further occurrences of that event are ignored. Once a bit is set in an event register, the bit remains set until the register is read (*ESR?) or a *CLS (clear status) command is issued. A query of an event register returns a decimal value in the appropriate output buffer which corresponds to the binary-weighted sum of all bits set in the register.

An *enable* register (or bitmask) defines which bits in an event register are reported to the Status Byte register group. An enable register can be both written and queried. The *CLS (clear status) command does not clear an enable register. To enable or disable bits in an enable register, write a decimal value which corresponds to the binary-weighted sum of the bits you wish reported to the Status Byte register.

STATUS BYTE REGISTER

The Status Byte register group reports conditions from the Standard Event register or output buffers. Data in the output buffer is immediately reported in the “Serial Message Available” bit (bit 3). Clearing a bit in the Standard Event register will update the corresponding bit in the Status Byte register, according to the Standard Event enable register. Reading the pending messages in the output buffers will clear the appropriate “Message Available” bit. The bit definitions for the Status Byte register are defined in the following table:

Bit Definitions for the Status Byte Register

Bit Number	Decimal Value	Definition
0 <i>Not Used</i>	1	Always “0”.
1 External Rampdown	2	An external rampdown is active.
2 Quench Condition	4	The Model 430 has detected a quench.
3 Serial Message Available	8	The serial output buffer contains unread data.
4 <i>Not Used</i>	16	Always “0”.
5 Standard Event	32	One or more enabled bits are set in the Standard Event register.
6 Status Byte Summary	64	One or more enabled bits are set in the Status Byte register.
7 <i>Not Used</i>	128	Always “0”.

Bit 2 of the Status Byte register, indicating a quench condition, remains set until the quench condition is cleared via the front panel or by remote command. Bits 3 and 4 remain set until all data has been read from the respective output buffer.

The Status Byte *condition register* is cleared when:

- A *CLS command is executed.
- The Standard Event register is read (only bit 5 of the Status Byte register is cleared).
- The indicated condition no longer exists.
- The power is turned off and then back on.

The Status Byte *enable register* is cleared when:

- The *SRE 0 command is executed.
- The power is turned off and then back on, and the Model 430 Programmer was configured for *PSC 1 (power-on status clear). The enable register set-

ting is persistent if the Model 430 Programmer is configured for *PSC 0 (no status clear on power-on).

READING THE STATUS BYTE USING *STB?

The *STB? returns the contents of the Status Byte register, but it is processed in the command queue like any other command. The *STB? command does not clear bit 6 of the Status Byte register.

USING THE MESSAGE AVAILABLE BIT(S)

The “Message Available” bits (bits 3 or 4) of the Status Byte register can be used to determine when data is available to read into your host computer. The Model 430 Programmer clears the “Message Available” bits only after all data has been read from the output buffer(s).

The “Message Available” bits of the Status Byte register are useful for determining if *queries* have executed; however, they are not useful alone for determining if *commands* have completed execution, since commands do not provide return data.

STANDARD EVENT REGISTER

The Standard Event register group reports a power-on condition, various error conditions, and indicates when an operation has completed. Any or all of the Standard Events can be reported to the Status Byte register by enabling the corresponding bit(s) in the Standard Event enable register (see the figure on page 142). To set the Standard Event enable register, write a binary-weighted decimal value using the *ESE <value> command.

The bit definitions for the Standard Event register are provided in the table on the following page. To query the Model 430 Programmer for the details of a reported error in the Standard Event register, use the SYSTem:ERRor? query. See page 183 for a complete discussion of the error buffer and messages.

The Standard Event *register* is cleared when:

- The *CLS (clear status) command is executed.
- The Standard Event register is queried using the *ESR? command.
- The power is turned off and then back on.

The Standard Event *enable register* is cleared when:

- The *ESE 0 command is executed.
- The power is turned off and then back on, and the Model 430 Programmer was configured for *PSC 1 (power-on status clear). The enable register set-

ting is persistent if the Model 430 Programmer is configured for *PSC 0 (no status clear on power-on).

Bit Definitions for the Standard Event Register

Bit Number	Decimal Value	Definition
0 Operation Complete	1	All commands prior to and including *OPC have been executed.
1 <i>Not Used</i>	2	Always "0".
2 Query Error	4	A query error occurred. See the error messages in the -200 range.
3 Device Error	8	A device error occurred. See the error messages in the -400 range.
4 Execution Error	16	An execution error occurred. See the error messages in the -300 range.
5 Command Error	32	A command error occurred. See the error messages in the -100 range.
6 <i>Not Used</i>	64	Always "0".
7 Power On	128	Power has been cycled since the last time the Standard Event register was read or cleared.

COMMAND HANDSHAKING

The Model 430 Programmer provides an internal command queue that can store up to 4 commands or queries. However, it is possible that the host computer can overwhelm the command queue by sending commands faster than the Model 430 can execute. If the Model 430 Programmer cannot process a command due to a full command queue, the command is ignored and the -303, "Input overflow" error is reported.

Handshaking is generally not a concern unless more than 4 *commands* are sent sequentially. If a *query* is sent, the user will normally wait for return data for the queries before proceeding to send the next query or command. In the case of sending numerous *commands* in sequence, there are two methods available to help prevent command queue overflows which are discussed below.

USING THE *OPC COMMAND

The *OPC command is executed within the normal command queue. Upon completed execution of the *OPC command, the "Operation Complete" bit (bit 0) of the Standard Event register will be set. This command is useful should many commands be sent to the Model 430 Programmer in rapid succession.

NOTE The *OPC command historically is designed to generate an SRQ which can be monitored by a serial poll over a GPIB interface, which operates outside of the normal command queue. Since a GPIB interface is not available in the Model 430, the *OPC command has limited value (as it would require polling the status registers *using* the command queue) and should be ignored in favor of the *OPC? query documented below for the serial and Ethernet interfaces.

USING THE *OPC? QUERY

The *OPC? query is similar to the *OPC command, but instead of setting the “Operation Complete” bit of the Standard Event register, the *OPC? query returns a “1” (plus termination characters) to the appropriate output buffer when executed.

Using *OPC? is a simple solution for determining completed remote command execution (because *commands* do not send a reply). It is also unambiguous during simultaneous serial and Ethernet operation since the result is returned directly to the requesting communication interface.

An example of a sequence of commands using the *OPC? query to handshake is the following:

```
CONF:CURR:TARG 50.0;  
CONF:RAMP:RATE:CURR 1,0.1,80.0;  
CONF:VOLT:LIM 5.0;  
*OPC?;
```

The above example sets the target current to 50.0 A, the ramp rate segment #1 to 0.1 A/s up to 80.0 A, the voltage limit to 5.0 V, and sends as the fourth command the *OPC? query for determining when execution all of the commands (including *OPC?) is completed. The *OPC? query will return a “1” to the requesting interface when it executes.

RS-232 CONFIGURATION

The Model 430 Programmer uses the following *fixed* parameters related to the RS-232 interface:

- *Baud Rate*: 115200
- *Parity*: No Parity
- *Data Bits*: 8 Data Bits
- *Number of Start Bits*: 1 bit
- *Number of Stop Bits*: 1 bit
- *Flow Control*: Hardware (RTS/CTS)

SERIAL CONNECTOR

The Model 430 Programmer is classified as a DCE (Data Connection Equipment) device. It is compatible with standard USB-to-serial adapters available for USB ports of modern computers.¹ The RS-232 connector pinout for the female DB-9 connector on the rear panel of the Model 430 Programmer is fully documented on page 222 in the *Appendix*.

TERMINATION CHARACTERS

All commands and queries are transmitted and received as ASCII values and are case insensitive. The Model 430 Programmer always transmits *<CR><LF>* (a *carriage return* followed by a *linefeed*) at the end of an RS-232 transmission. The Model 430 Programmer can accept *<CR>*, *<LF>*, *<CR><LF>*, or *<LF><CR>*, or a semicolon (;) as termination characters from an external computer.

ETHERNET CONFIGURATION

The Model 430 Programmer provides a 10/100Base-T Ethernet interface as a standard feature. It complies with the IEEE 802.3u 100Base-TX and 802.3 10Base-T standards.

The Model 430 Programmer allows its IP address, subnet mask and gateway IP address to be assigned either statically or dynamically. To make these values static and assign them manually, set IP Address Assignment to Static (see page 110) and then set the values using the parameters under the Net Setup submenu (beginning on page 111). To

1. For legacy hardware Model 430 with firmware prior to version 3.0 (Rev 9 PCB), the Model 430 is configured as a DTE (Data Terminal Equipment) device. It uses the standard DB9 male connector and identical pinout used on legacy IBM-compatible computers and requires a gender-changer *and* null modem adapter to connect to modern USB-to-serial cables. For more information, see page 222 in the Appendix.

make the values dynamically assigned by a network DHCP server, set IP Address Assignment to DHCP.

The system name (also known as *host name* or *computer name*), can be set using remote communications (either Ethernet or RS-232); it cannot be edited using the front panel keypad.

All network parameters (even those assigned by a DHCP server) can be viewed using the Net Settings submenu (see page 108).

ETHERNET CONNECTOR

The Model 430 Programmer uses a standard RJ-45 jack for Ethernet communications. The Ethernet jack pinout is fully documented on page 221 in the *Appendix*.

TERMINATION CHARACTERS

All commands and queries are transmitted and received as ASCII values and are case insensitive. The Model 430 Programmer always transmits <CR><LF> (a *carriage return* followed by a *linefeed*) at the end of an Ethernet transmission. The Model 430 can accept <CR>, <LF>, <CR><LF>, or <LF><CR>, or a semicolon (;) as termination characters from an external computer.

PORT ASSIGNMENTS

The Model 430 accepts connections to ports 23, 7180, and 7185.

Port 7180 is recommended for general command/query operation. When a connection is successfully established to the Model 430, the following “Hello” message is immediately returned:

American Magnetics Model 430 IP Interface\r\nHello.\r\n

Multiple connections to port 7180 are allowed. Multiple connections to port 23 are also allowed, but the special broadcast function described in the following section will only occur for the *last connection* made to port 23.

For stateless communication via VISA and LabVIEW, port 7185 may be used as an alternative port that does not return the “Hello” message upon connection.² Multiple connections to port 7185 are acceptable.

TELNET PORT 23 BROADCAST FUNCTION

Port 23 has a special function in that the display characters are broadcast each time the display is internally updated by the Model 430. This occurs approximately every 250 milliseconds. This feature is

2. Port 7185 support requires Model 430 firmware version 3.07, or legacy firmware version 2.57, or later. For more details about firmware revisions, see page 197.

intended to allow the user to optionally show a remote display that remains synced with the front panel display.³

The broadcast message format will be as the following example output (terminated with a <CR><LF> pair):

```
MSG_DISP_UPDATE:: +50.00 A - Mode: Holding :: 0.00 Vm PSwitch Heater: ON ::::1::0::1::0::0
```

The MSG_DISP_UPDATE:: is the delimiter text indicating the display text follows. The first line of the display is the text up to the next :: delimiter pair, followed by the second line of the display up to the next :: pair.

The state (0=OFF, 1=ON) of each front panel LED then follows delimited by :: pairs. The LED field order is: **SHIFT**, **FIELD AT TARGET**, **MAGNET IN PERSISTENT MODE**, **CURRENT LEADS ENERGIZED**, and **MAGNET QUENCH**.

Therefore, the example broadcasted output above would decode to a display as follows:

```
+50.00 A - Mode: Holding  
0.00 Vm PSwitch Heater: ON
```

with the **FIELD AT TARGET** and **CURRENT LEADS ENERGIZED** LEDs in the ON state.

If the display is in the voltmeter mode (see page 69) for either Vs or Vm, the broadcasted message format changes to the following example output (terminated with a <CR><LF> pair):

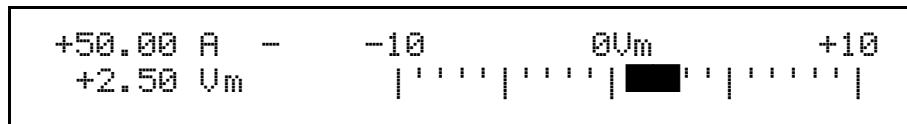
```
MSG_VOLTmeter_UPDATE:: +50.00 A - :: +2.50 Vm ::0::0::0::0::0::Vm::2.500000
```

The MSG_VOLTmeter_UPDATE:: is the delimiter text indicating the voltmeter display information follows. The field/current, status indication, and voltage displays are shown first, followed by the delimited LED states in the exact same order as described above. Then the displayed voltage value name is provided followed by the final :: pair and the actual voltage value in volts.

Therefore, the example broadcasted voltmeter output above would decode to a display as follows:

with no LEDs in the ON state.

3. The open-source Magnet-DAQ application from AMI (see page 189) utilizes this broadcast function to show the state of the Model 430 display remotely.



CUSTOM DISPLAY CHARACTERS

Please note that the ramping character and certain other display characters have custom-defined codes beyond `0x7F` that do *not* map directly to ASCII equivalents. The custom character and the actual byte value that is sent in a broadcast message are shown in the table below:

Broadcasted Custom Display Characters

Character	Byte Value	Character	Byte Value
P	0x80	o	0x86
↑	0x81	◊	0x87
↓	0x82	U	0x88
+	0x83	C	0x89
←	0x84	T	0x8A
▶	0x85		

BROADCASTED KEYPRESSES AND EVENTS

In addition to the broadcasted display message, there are additional broadcast messages related to physical keypresses (via the front panel) and certain events that will be interleaved as they occur with the broadcasted display messages. Each is terminated on transmission with the `<CR><LF>` pair. The messages are described in the table below:

Broadcasted Keypress and Event Messages

Message (ASCII format)	Meaning
MSG_KEY_SHIFT	SHIFT key pressed
MSG_KEY_TARGET	TARGET FIELD SETPOINT key pressed
MSG_KEY_ZEROFIELD	RAMP TO ZERO key pressed
MSG_KEY_PERSISTENT	PERSIST. SWITCH CONTROL key pressed
MSG_KEY_RAMP_PAUSE	RAMP/PAUSE key pressed
MSG_KEY_1	1 key pressed
MSG_KEY_2	2 key pressed
MSG_KEY_3	3 key pressed
MSG_KEY_4	4 key pressed
MSG_KEY_5	5 key pressed
MSG_KEY_6	6 key pressed
MSG_KEY_7	7 key pressed
MSG_KEY_8	8 key pressed
MSG_KEY_9	9 key pressed
MSG_KEY_0	0 key pressed
MSG_KEY_PERIOD	. key pressed
MSG_KEY_PLUSMINUS	+/- key pressed
MSG_KEY_ESC	ESC key pressed
MSG_KEY_MENU	MENU key pressed
MSG_KEY_RIGHT	Right arrow key pressed
MSG_KEY_LEFT	Left arrow key pressed
MSG_KEY_ENTER	ENTER key pressed
MSG_BEEP	Audible beep emitted
MSG_EXT_RAMPDOWN_START	External rampdown activated
MSG_EXT_RAMPDOWN_END	External rampdown ended
MSG_FINE_ADJ_DELTA <value>	Encoder adjust delta (value sent is a positive or negative integer of the number of encoder clicks, user must convert to a meaningful delta for a given parameter being edited).

COMMAND REFERENCE

The following paragraphs present all Model 430 Programmer commands and queries in related groups and a detailed description of the function of each command or query is provided. Examples are also provided where appropriate. Return strings may be up to 255 characters in length *unless otherwise noted*. The quench and rampdown histories can return very long replies.

SYSTEM-RELATED COMMANDS

- *IDN?

Returns the identification string of the Model 430 Programmer. The identification string contains the manufacturer name, model number, serial number, and firmware revision code. Example output:

```
AMERICAN MAGNETICS INC., MODEL 430, 1215001, 3.00
```

- *RST

Resets the Model 430 Programmer. This is equivalent to cycling the power to the Model 430 Programmer using the power switch. All non-volatile calibration data and battery-backed memory is restored. Status is cleared according to the *PSC setting.

- *TST?

Performs a self-test. Currently always returns “1”.

- *LED?

Returns a comma-delimited list of the LED states with 0=OFF and 1=ON. The LED field order is: **SHIFT**, **FIELD AT TARGET**, **MAGNET IN PERSISTENT MODE**, **CURRENT LEADS ENERGIZED**, and **MAGNET QUENCH**.

Bit Definitions for the LED states

Bit Number	Decimal Value	Definition
0 SHIFT	1	If asserted, the SHIFT LED is lit.
1 FIELD AT TARGET	2	If asserted, the magnet field/current has reached the Target Setpoint and the associated front panel LED is lit.
2 MAGNET IN PERSISTENT MODE	4	If asserted, the last connected magnet is in persistent mode and the associated front panel LED is lit.
3 CURRENT LEADS ENERGIZED	8	If asserted, the current leads to the magnet are energized with at least 0.1% of the maximum configured Model 430 current and the associated front panel LED is lit.
4 MAGNET QUENCH	16	If asserted, the Model 430 has detected a magnet quench which must be cleared to continue operation and the associated front panel LED is lit.
5 Not Used	32	Always "0".
6 Not Used	64	Always "0".
7 Not Used	128	Always "0".

For example, the transaction:

Sent: *LED?

Returned: 10

indicates the **FIELD AT TARGET** and **CURRENT LEADS ENERGIZED** LEDs are energized.

- <Ctrl-C>

This clears the output buffers of the Model 430 Programmer and prepares the instrument for a new command. Status registers are unaffected. <Ctrl-C> corresponds to ASCII code 03.

- PRINT:SERIALnumber?

Returns the serial number.

- PRINT:PASSWORD?

Returns the presently set numerical password.

- SETTINGS?

Returns a multi-line ASCII text dump of *all* the Model 430 settings. The output of this query is terminated with two contiguous pairs of <CR><LF> characters (i.e. double terminators).

- SYSTem:LOCAL

Enables all front panel controls. All front panels controls are enabled by default after a power-up or *RST command.

- SYSTem:REMote

NOTE The SYSTem:REMote command only disables the front panel controls for purposes of preventing accidental operation of a front panel feature. It is not necessary for this command to be sent prior to using a remote interface. Send the SYSTem:LOCAL command, send the *RST command, press **SHIFT** followed by **MENU**, or cycle Model 430 Programmer power to re-enable the front panel controls.

Disables all front panel controls. If the Model 430 Programmer is in the remote mode, an asterisk (*) will appear in the front panel display in the position just below the ramping character as shown below.



+50.00 kG ↑ Mode: Ramping
+1.50 Vs * PSwitch Heater: ON

Asterisk Indicating the Model 430 is in Remote Mode

- SYSTem:TIME?

Returns the date and time of the Model 430 Programmer in the format *mm/dd/yyyy hh:mm:ss*. Time is always reported in 24-hour format. Example output: 05/02/2017 21:13:50

- SYSTem:TIME:SET <*date(mm/dd/yyyy) time(hh:mm:ss)*>

Sets the date and time of the Model 430 Programmer using the format *mm/dd/yyyy hh:mm:ss*. Time is always set in 24-hour format.

- SYSTem:ERRor?

Queries the error buffer of the Model 430 Programmer. Up to 10 errors are stored in the error buffer. Errors are retrieved in first-in-first-out (FIFO) order. The error buffer is cleared by the *CLS (clear status) command or when the power is cycled. Errors are also cleared as they are read. See page 183 for a complete description of the error buffer and messages.

- SYSTem:ERRor:COUNT?

Returns the number of errors stored in the error buffer. The error buffer and count is cleared by the *CLS (clear status) command or when the power is cycled. Errors are also cleared as they are read and the count reduces by one for each error read.

- SYSTem:IPaddr?

Returns the presently active IPv4 address of the Model 430 in dotted-decimal notation (e.g. “192.168.1.20”). If no address is currently assigned, the query returns “0.0.0.0”. This can be useful command for querying the IPv4 address using the serial port in order to automatically establish an Ethernet-based connection.

STATUS SYSTEM COMMANDS

The status system register groups and commands are illustrated the figure on page 142.

- *STB?

Returns the contents of the Status Byte register. The *STB? command does not clear the “Summary Bit” (bit 6) of the Status Byte register.

- *SRE <enable_value>

Enables bits in the Status Byte register to be reported in the “Summary Bit” (bit 6) of the Status Byte register. To enable bits, you must write a decimal <enable_value> which corresponds to the binary-weighted sum of the bits you wish to enable. Refer to page 143 for more information. For example, to enable quench detections only in the “Summary Bit” of the Status Byte register, send the command: *SRE 4.

- *SRE?

The *SRE? query returns a decimal sum which corresponds to the binary-weighted sum of the bits enabled by the last *SRE command.

- *CLS

Clears the Standard Event register and the error buffer.

- *ESR?

Returns a decimal sum which corresponds to the binary-weighted sum of the contents of the Standard Event register.

- *ESE <enable_value>

Enables bits in the Standard Event register to be reported in the “Standard Event” bit (bit 5) of the Status Byte register. To enable bits, you must write a decimal <enable_value> which corresponds to the binary-weighted sum of the bits you wish to enable. Refer to page 145 for more information. For example, to enable *all* categories of error messages to be reported in bit 5 of the Status Byte register, send: *ESE 60.

- *ESE?

The *ESE? query returns a decimal sum which corresponds to the binary-weighted sum of the bits enabled by the last *ESE command.

- *PSC {0|1}

Power-On Status Clear. If *PSC 1 is in effect, the Standard Event enable register and the Status Byte enable register are cleared at power on. If *PSC 0 is in effect, the enable registers are not cleared at power on. The default setting is “1”.

- *PSC?

Returns the *Power-On Status Clear* setting currently in effect. A value of “0” indicates the enable registers are not cleared at power on; a value of “1” indicates the enable registers are cleared at power on.

- *OPC

Sets the “Operation Complete” bit (bit 0) of the Standard Event register when executed. See page 145 for a complete discussion.

- *OPC?

Returns “1” to the requesting interface when executed. See page 146 for more information.

SUPPLY SETUP CONFIGURATION QUERIES

The Supply Setup Configuration Queries provide read-only access to the setup functions available for the Supply Setup submenu (page 74).

- SUPPLY:TYPE?

Returns the index according to the table below for the selected power supply type according to the table below. This value can be configured only via front panel operation of the SUPPLY setup menu.

Return Values and Meanings for SUPPLY:TYPE? Query

Return Value	Meaning
0	AMI 12100PS
1	AMI 12200PS
2	AMI 4Q05100PS
3	AMI 4Q06125PS
4	AMI 4Q06250PS
5	AMI 4Q12125PS
6	AMI 10100PS
7	AMI 10200PS
8	HP 6260B
9	Kepco BOP 20-5M
10	Kepco BOP 20-10M
11	Xantrex XFR 7.5-140
12	Custom
13	AMI 08150PS
14	AMI 05120PS
15	AMI 05240PS
16	AMI 05360PS
17	AMI 05600PS
18	AMI 03300PS
19	Accel Instruments TS250-8

- SUPPLY:VOLTage:MINimum?

Returns the minimum *power supply* compliance setting in volts. This value can be configured only via front panel operation using the Supply submenu and is set automatically when a preset supply type is selected.

- SUPPLY:VOLTage:MAXimum?

Returns the maximum *power supply* compliance in volts. This value can be configured only via front panel operation using the Supply submenu and is set automatically when a preset supply type is selected.

- SUPPLY:CURRent:MINimum?

Returns the minimum output current capacity of the *power supply* in amperes. This value can be configured only via front panel operation using the Supply submenu and is set automatically when a preset supply type is selected.

- SUPPLY:CURRent:MAXimum?

Returns the maximum output current capacity of the *power supply* in amperes. This value can be configured only via front panel operation using the Supply submenu and is set automatically when a preset supply type is selected.

- SUPPLY:MODE?

Returns an integer value corresponding to the voltage output mode according to the table below:

Return Values and Meanings for SUPPLY:MODE? Query

Return Value	Meaning
0	+0.000 to +5.000
1	+0.000 to +10.000
2	-5.000 to +5.000
3	-10.000 to +10.000
4	-5.000 to +0.000
5	+0.000 to +8.000

This value can be configured only via front panel operation using the Supply submenu and is set automatically when a preset supply type is selected.

LOAD SETUP CONFIGURATION COMMANDS AND QUERIES

The Load Setup Configuration Commands and Queries provide read/write access to the setup functions available for the Load Setup submenu (page 80).

- **CONFigure:STABility:MODE { 0 | 1 | 2 }**

“0” configures the stability mode as “Auto”, “1” is “Manual”, and “2” is “Test”. If “Auto” mode is selected and an inductance value is not specified (i.e. the inductance entry is zero), the Model 430 will beep once, generate an error, and revert to “Manual” stability mode. Manual mode is the default value.

In “Auto” stability mode, the stability setting is automatically adjust per the presence or absence of a persistent switch, the presence or absence of a stabilizing resistor, and the estimated or measured magnet inductance.

- **STABility:MODE?**

Returns “0” for “Auto” stability mode, “1” for “Manual”, and “2” for “Test”.

- **CONFigure:STABility <percent>**

Sets the stability setting in percent. Valid range is 0.0 to 100.0%.

- **STABility?**

Returns the stability setting in percent.

- **CONFigure:STABility:RESistor { 0 | 1 }**

An argument of “0” specifies no stabilizing resistor is installed. “1” indicates a stabilizing resistor is installed. “0” is the default value.

- **STABility:RESistor?**

Returns “0” for no stabilizing resistor and “1” for an installed stabilizing resistor.

- **CONFigure:COILconst <value (kG/A, T/A)>**

Sets the coil constant (also referred to as the field-to-current ratio) per the selected field units. The coil constant must be set to a non-zero, positive value in order to command or query the Model 430 Programmer in units of field.

- COILconst?

Returns the coil constant setting in kG/A or T/A per the selected field units.

- CONFigure:INDuctance <inductance (H)>

Sets the currently-connected magnet inductance in Henries.

- INDuctance:SENSe?

Initiates a direct measurement of the currently connected magnet. The measurement requires the magnet to be ramping up or down while not passing through a ramp segment change during the measurement. If these conditions are not met, the Model 430 will beep once, generate an error, and exit the measurement. Otherwise, this will return a measurement of the magnet inductance in Henries. The measured value will automatically be stored as the currently-connected inductance.

NOTE The inductance measurement *requires* the magnet voltage input to the rear panel Magnet Station connector as described on page 211. Please note that some magnet system manufacturers do not provide magnet voltage taps.

NOTE This remote command blocks communication for several seconds on all ports until the measurement process completes or is interrupted.

- INDuctance?

Returns the currently-connected magnet inductance in Henries.

- CONFigure:ABsorber {0|1}

Sending “0” indicates that an energy absorber is not present in the system. A “1” indicates that an energy absorber is present. “0” is the default value.

- ABsorber?

Returns “0” indicating that an energy absorber is not present in the system, or “1” indicating that an energy absorber is present.

SWITCH SETUP CONFIGURATION COMMANDS AND QUERIES

The Switch Setup Configuration Commands and Queries provide read/write access to the setup functions available for the Switch Setup submenu (page 86).

- CONFigure:PSwitch {0|1}
- PSwitch:INSTalled?

“0” indicates that a persistent switch is not installed on the connected superconducting magnet. “1” indicates that a persistent switch is installed. The default value is “1”. If a persistent switch is installed, the persistent switch heated current should be specified. Heating/cooling times should also be specified for timer-based switch transitions.

- CONFigure:PSwitch:CURRent <current (mA)>

Sets the persistent switch heater current in mA.

- PSwitch:CURRent?

Returns the persistent switch heater current setting in mA.

- PSwitch:AUTODetect?

Executes the auto-detection algorithm (refer to page 87) and returns the appropriate persistent switch heater current in mA. Note that after this value is returned, it can be entered into the Model 430 Programmer using the CONFigure:PSwitch:CURRent command.

NOTE This remote command blocks communication on all ports until the auto-detection process completes or is interrupted.

- CONFigure:PSwitch:TRANSition {0|1}

Sending a value of “0” selects the timer-based switch transition detection. Sending “1” selects the magnet voltage-based transition detection. Timer-based transition detection is the default.

- PSwitch:TRANSition?

“0” return value indicates timer-based switch transitions. “1” indicates magnet voltage-based transitions.

- CONFigure:PSwitch:HeatTIME <time (sec)>

Sets the time required in seconds for the persistent switch to become resistive after the persistent switch heater has been activated.

- PSwitch:HeatTIME?

Returns the persistent switch heated time in seconds.

- CONFigure:PSwitch:CoolTIME <time (sec)>

Sets the time required in seconds for the persistent switch to become superconducting after the persistent switch heater has been deactivated.

- PSwitch:CoolTIME?

Returns the persistent switch cooled time in seconds.

- CONFigure:PSwitch:PowerSupplyRampRate <rate (A/s)>

Sets the ramp rate that will be used by the power supply to ramp the current⁴ during the **PERSIST. SWITCH CONTROL** operation when the switch is in a cooled state. This ramp rate can be much higher than when the switch is heated and the magnet is in the circuit. For more information as to how this function operates, refer to page 58.

- PSwitch:PowerSupplyRampRate?

Returns the power supply ramp rate used to change the power supply output when the magnet persistent switch is cool. The units are A/sec.

- CONFigure:PSwitch:CoolingGAIN <percent>

Sets the persistent switch cooling gain in percent.

- PSwitch:CoolingGAIN?

Returns the persistent switch cooling gain in percent.

PROTECTION SETUP CONFIGURATION COMMANDS AND QUERIES

The Protection Setup Configuration Commands and Queries provide read/write access to the setup functions available for the Protection Setup submenu (page 92).

- CONFigure:CURREnt:LIMit <current (A)>

Sets the Current Limit in amperes. The Current Limit is the largest magnitude operating current allowed during *any* ramping mode. For four-quadrant power supplies, the Current Limit functions as both a positive and negative current limit. This value is typically provided by the magnet

4. While the magnet is in persistent mode.

manufacturer as the maximum safe limit of magnet operation (for AMI magnets it is the Magnet Rated Current, see page 112).

- CURRent:LIMit?

Returns the Current Limit in amperes.

- CONFigure:QUench:DETect {0|1|2|3}

Sending “0” disables the automatic quench detection function of the Model 430 Programmer. “1” enables the current-mismatch quench detection function of the Model 430. “2” enables the temperature-limit quench detection function. “3” enables both the current-mismatch and temperature-limit methods of quench detection with either able to trigger a quench. See page 127 for more information. “1” is the default value.

- QUench:DETect?

Returns “0” indicating automatic quench detection is disabled, or “1” indicating that the current-mismatch automatic quench detection is enabled. “2” indicates temperature-limit quench detection is enabled. “3” indicates *both* current-mismatch and temperature-limit quench detection methods are enabled.

- CONFigure:QUench:RATE {1|2|3|4|5}

Sets the value of the quench detect sensitivity. The range is from 1 to 5 in integer increments. “1” indicates the most sensitivity. “5” is the least sensitivity. “3” (normal) is the default value.

- QUench:RATE?

Returns the value of the quench detect sensitivity from 1 to 5 in integer increments where “1” is the most sensitivity and “5” is the least.

- OPLimit:IC?

Returns the present value of the temperature-based maximum (i.e. critical) current limit, **Ic**, specified by the equation documented on page 95.

- OPLimit:TEMP?

Returns the temperature in units of Kelvin read from the Auxiliary Input 3 (see page 220).

- CONFigure:OPLimit:MODE {0|1|2}

Sets the Protection Mode for the Operational Limits submenu (refer to section on page 95). Sending “0” sets the mode is Off. Sending “1” sets

the mode to “On Entry”. Sending “2” sets the mode to “Cont f(T)”. “0” is the default value.

- OPLimit:MODE?

Returns “0” indicating the Protection Mode for the Operational Limits submenu is Off. Returns “1” indicating the mode is “On Entry”. Returns “2” indicating the mode is “Cont f(T)”.

- CONFigure:OPLimit:ICSLOPE <value (A/K)>

Sets the *Ic Slope* value in the Operational Limits submenu. The units are amperes/Kelvin.

- OPLimit:ICSLOPE?

Returns the present *Ic Slope* value from the Operational Limits submenu in units of amperes/Kelvin.

- CONFigure:OPLimit:ICOFFSET <value (A)>

Sets the *Ic Offset* value in the Operational Limits submenu. The units are amperes.

- OPLimit:ICOFFSET?

Returns the present *Ic Offset* value from the Operational Limits submenu in units of amperes.

- CONFigure:OPLimit:TMAX <value (K)>

Sets the *T_{max}* value in the Operational Limits submenu. The units are Kelvin.

- OPLimit:TMAX?

Returns the present *T_{max}* value from the Operational Limits submenu in units of Kelvin.

- CONFigure:OPLimit:TSCALE <value (K/V)>

Sets the scale value in Kelvin/volts for the voltage-to-temperature conversion for the voltage value read from Auxiliary Input 3 (see page 220).

- OPLimit:TSCALE?

Returns the scale value in Kelvin/volts for the Auxiliary Input 3 voltage-to-temperature conversion.

- CONFfigure:OPLimit:TOFFSET <value (K)>

Sets the offset value in Kelvin for the voltage-to-temperature conversion for the voltage value read from Auxiliary Input 3 (see page 220).

- OPLimit:TOFFSET?

Returns the offset value in Kelvin for the Auxiliary Input 3 voltage-to-temperature conversion.

- CONFfigure:RAMPDown:ENABLE {0|1}

Enables the external rampdown function. “1” enables while “0” disables. “0” is the default value.

- RAMPDown:ENABLE?

Queries whether the external rampdown function is enabled. Returns “1” for enabled while “0” for disabled. “0” is the default value.

MISC SETUP CONFIGURATION COMMANDS AND QUERIES

The Misc Setup Configuration Commands and Queries provide read/write access to the setup functions available for the Misc Setup submenu (page 99).

- CONFfigure:RAMP:RATE:SEGments <value>

Sets the number of ramp segments from 1 to 10. 1 is the default. See page 99 for details of the use of ramp segments.

- RAMP:RATE:SEGments?

Returns the number of ramp segments from 1 to 10.

- CONFfigure:RAMP:RATE:UNITS {0|1}

Sets the preferred ramp rate time units. Sending “0” selects seconds. A “1” selects minutes. “0” is the default value. The selected units are applied to both the Model 430 Programmer display and the appropriate remote commands.

- RAMP:RATE:UNITS?

Returns “0” for ramp rates displayed/specifyed in terms of seconds, or “1” for minutes.

- CONFigure:FIELD:UNITS {0|1}

Sets the preferred field units. Sending “0” selects kilogauss. A “1” selects tesla. “0” is the default value. The selected field units are applied to both the Model 430 Programmer display and the applicable remote commands.

- FIELD:UNITS?

Returns “0” for field values displayed/specify in terms of kilogauss, or “1” for tesla.

LOCK COMMANDS AND QUERIES

The Lock Commands and Queries provide read/write access to all lock settings which can be accessed under the Settings Protection portion of the Misc Setup submenu. See page 100 for more information regarding the settings protection features of the Model 430 Programmer.

- CONFigure:LOCK:PSwitch:CONTROL {0|1}

Specifies whether use of the **PERSIST. SWITCH CONTROL** key is locked or unlocked. Sending “0” unlocks. A “1” locks. “0” is the default value.

- LOCK:PSwitch:CONTROL?

Returns “0” for use of the **PERSIST. SWITCH CONTROL** key unlocked, or “1” for locked.

- CONFigure:LOCK:TARGet {0|1}

Specifies whether use of the **TARGET FIELD SETPOINT** key is locked or unlocked. Sending “0” unlocks. A “1” locks. “0” is the default value.

- LOCK:TARGet?

Returns “0” for use of the **TARGET FIELD SETPOINT** key unlocked, or “1” for locked.

- CONFigure:LOCK:RAMP-PAUSE {0|1}

Specifies whether use of the **RAMP / PAUSE** key is locked or unlocked. Sending “0” unlocks. A “1” locks. “0” is the default value.

- LOCK:RAMP-PAUSE?

Returns “0” for use of the **RAMP / PAUSE** key unlocked, or “1” for locked.

- CONFigure:LOCK:ZEROfield {0|1}

Specifies whether use of the **RAMP TO ZERO** key is locked or unlocked. Sending “0” unlocks. A “1” locks. “0” is the default value.

- LOCK:ZEROfield?

Returns “0” for use of the **RAMP TO ZERO** key unlocked, or “1” for locked.

- CONFigure:LOCK:RAMPrate {0|1}

Specifies whether ramp rate settings are locked or unlocked. Ramp rate settings protected by this setting are: use of the **RAMP RATE** (SHIFT+1) menu, editing of the Ramp Segments value (under the Misc submenu) and editing of the Ramp Time Units value (under the Misc submenu). Sending “0” unlocks. A “1” locks. “0” is the default value.

- LOCK:RAMPrate?

Returns “0” for ramp rate settings unlocked, or “1” for locked.

- CONFigure:LOCK:SUPPLY {0|1}

Specifies whether the Select Supply picklist value is locked or unlocked. If the Select Supply value is Custom..., then setting Power Supply Lock to Locked also prevents the custom power supply parameters (Min Output Voltage, Max Output Voltage, Min Output Current, Max Output Current and V-V Mode Input Range) from being edited. Sending “0” unlocks. A “1” locks. “0” is the default value.

- LOCK:SUPPLY?

Returns “0” for Select Supply picklist value unlocked, or “1” for locked.

- CONFigure:LOCK:VOLTage:LIMit {0|1}

Specifies whether use of the **VOLTAGE LIMIT** (SHIFT+2) menu is locked or unlocked. Sending “0” unlocks. A “1” locks. “0” is the default value.

- LOCK:VOLTage:LIMit?

Returns “0” for use of the **VOLTAGE LIMIT** (SHIFT+2) menu unlocked, or “1” for locked.

- CONFigure:LOCK:QUench:RESet {0|1}

Specifies whether use of the **RESET QUENCH** (SHIFT+3) command is locked or unlocked. Sending “0” unlocks. A “1” locks. “0” is the default value.

- LOCK:QUench:RESet?

Returns “0” for use of the **RESET QUENCH** (SHIFT+3) command unlocked, or “1” for locked.

- CONFigure:LOCK:INCR-DECR {0|1}

Specifies whether use of the **INCR. FIELD** (SHIFT+4) and **DECR. FIELD** (SHIFT+6) commands are locked or unlocked. Sending “0” unlocks. A “1” locks. “0” is the default value.

- LOCK:INCR-DECR?

Returns “0” for use of the **INCR. FIELD** (SHIFT+4) and **DECR. FIELD** (SHIFT+6) commands unlocked, or “1” for locked.

- CONFigure:LOCK:FIELD-CURRent {0|1}

Specifies whether use of the **FIELD <> CURRENT** (SHIFT+5) command is locked or unlocked. Sending “0” unlocks. A “1” locks. “0” is the default value.

- LOCK:FIELD-CURRent?

Returns “0” for use of the **FIELD <> CURRENT** (SHIFT+5) command unlocked, or “1” for locked.

- CONFigure:LOCK:FIELD:UNITS {0|1}

Specifies whether the Field Units value is locked or unlocked (whether accessed through the **FIELD UNITS** (SHIFT+7) menu or under the Misc Setup submenu). Sending “0” unlocks. A “1” locks. “0” is the default value.

- LOCK:FIELD:UNITS?

Returns “0” for Field Units value unlocked, or “1” for locked.

- CONFigure:LOCK:STABility {0|1}

Specifies whether the Stability Mode and Stability Setting values are locked or unlocked (whether accessed through the **STAB.** (SHIFT+8) menu or under the Load submenu). Sending “0” unlocks. A “1” locks. “0” is the default value.

- **LOCK:STABility?**

Returns “0” for Stability Mode and Stability Setting values unlocked, or “1” for locked.

- **CONFigure:LOCK:INDuctance {0|1}**

Specifies whether the Inductance and Sense Inductance? functions are located or unlocked under the Load Setup submenu. Sending “0” unlocks. A “1” locks. “0” is the default value.

- **LOCK:INDuctance?**

Returns “0” for Inductance and Sense Inductance? functions unlocked, or “1” for locked.

- **CONFigure:LOCK:VOLTage:VS-VM {0|1}**

Specifies whether use of the **Vs <> Vm** (SHIFT+0) command is locked or unlocked. Sending “0” unlocks. A “1” locks. “0” is the default value.

- **LOCK:VOLTage:VS-VM?**

Returns “0” for use of the **Vs <> Vm** (SHIFT+0) command unlocked, or “1” for locked.

- **CONFigure:LOCK:VOLTMeter {0|1}**

Specifies whether use of the **VOLT METER** (SHIFT+.) command is locked or unlocked. Sending “0” unlocks. A “1” locks. “0” is the default value.

- **LOCK:VOLTage:VOLTMeter?**

Returns “0” for use of the **VOLT METER** (SHIFT+.) command unlocked, or “1” for locked.

- **CONFigure:LOCK:FINEadjust {0|1}**

Specifies whether use of the **FINE ADJUST** (SHIFT +/-) command is locked or unlocked. Sending “0” unlocks. A “1” locks. “0” is the default value.

- **LOCK:VOLTage:FINEadjust?**

Returns “0” for use of the **FINE ADJUST** (SHIFT +/-) command unlocked, or “1” for locked.

- CONFigure:LOCK:COILconst {0|1}

Specifies whether the Coil Constant value (under the Load submenu) is locked or unlocked. Sending “0” unlocks. A “1” locks. “0” is the default value.

- LOCK:VOLTage:COILconst?

Returns “0” for Coil Constant value (under the Load submenu) unlocked, or “1” for locked.

- CONFigure:LOCK:CURREnt:LIMit {0|1}

Specifies whether the Current Limit value (under the Load submenu) is locked or unlocked. Sending “0” unlocks. A “1” locks. “0” is the default value.

- LOCK:CURREnt:LIMit?

Returns “0” for Current Limit value (under the Load submenu) unlocked, or “1” for locked.

- CONFigure:LOCK:PSwitch:SETtings {0|1}

Specifies whether persistent switch settings are locked or unlocked. Persistent switch settings protected by this setting (all under the Switch Setup submenu) are: PSwitch Installed, PSwitch Current, PSwitch Transition, PSwitch Heated Time, PSwitch Current Detect, PSwitch Cooled, PSw P/S Ramp Rate, and PSwitch Cooling Gain. Sending “0” unlocks. A “1” locks. “0” is the default value.

- LOCK:PSwitch:SETtings?

Returns “0” for persistent switch settings unlocked, or “1” for locked.

- CONFigure:LOCK:QUench:DETect {0|1}

Specifies whether the Enable Quench Detect picklist value (under the Protection Setup submenu) is locked or unlocked. Sending “0” unlocks. A “1” locks. “0” is the default value.

- LOCK:QUench:DETect?

Returns “0” for Enable Quench Detect picklist value (under the Protection Setup submenu) unlocked, or “1” for locked.

- CONFigure:LOCK:QUench:RATE {0|1}

Specifies whether use of the quench sensitivity (rate) command is locked or unlocked. Sending “0” unlocks. A “1” locks. “0” is the default value.

- **LOCK:QUench:RATE?**

Returns “0” for use of the quench sensitivity (rate) command unlocked, or “1” for locked.

- **CONFigure:LOCK:ABsorber {0|1}**

Specifies whether the Energy Absorber Present picklist value (under the Load submenu) is locked or unlocked. Sending “0” unlocks. A “1” locks. “0” is the default value.

- **LOCK:ABsorber?**

Returns “0” for Energy Absorber Present picklist value (under the Load submenu) unlocked, or “1” for locked.

- **CONFigure:LOCK:BRIGHTness {0|1}**

Specifies whether the Display Brightness picklist value (under the Misc submenu) is locked or unlocked. Sending “0” unlocks. A “1” locks. “0” is the default value.

- **LOCK:BRIGHTness?**

Returns “0” for Display Brightness picklist value (under the Misc submenu) unlocked, or “1” for locked.

- **CONFigure:LOCK:NETsetup {0|1}**

Specifies whether the Net Setup submenu is locked or unlocked. Sending “0” unlocks. A “1” locks. “0” is the default value.

- **LOCK:NETsetup?**

Returns “0” for Net Setup submenu unlocked, or “1” for locked.

- **CONFigure:LOCK:OPLimit {0|1}**

Specifies whether the Operational Limits submenu (under the Protection Setup submenu) is locked or unlocked. Sending “0” unlocks. A “1” locks. “0” is the default value.

- **LOCK:OPLimit?**

Returns “0” for Operational Limits submenu (see section on page 95) unlocked, or “1” for locked.

- CONFigure:LOCK:RAMPDown {0|1}

Specifies whether the External Rampdown Enabled picklist value (under the Protection Setup submenu) is locked or unlocked. Sending “0” unlocks. A “1” locks. “0” is the default value.

- LOCK:RAMPDown?

Returns “0” for External Rampdown Enabled picklist value (under the Protection Setup submenu) unlocked, or “1” for locked.

NET SETUP CONFIGURATION COMMANDS AND QUERIES

The Net Setup Configuration Commands and Queries provide read/write access to the IPNAME setting available in the Net Setup submenu (page 110).

- CONFigure:IPNAME <system name>

Sets the system name (also known as *host name* or *computer name*), the *name* by which the Model 430 Programmer is identified on a network.

NOTE If the system name value is changed, the Model 430 Programmer power must be cycled off for at least 5 seconds and then back on to complete the change. The new value will be used internally immediately (even before cycling power off and back on), but the IPNAME? query will return the previous system name until the Model 430 Programmer is restarted.

- IPNAME?

Returns the system name (also known as *host name* or *computer name*).

RAMP TARGET/RATE CONFIGURATION COMMANDS AND QUERIES

The ramp configuration commands set the various parameters required for defining and limiting piecewise-linear ramp segments.

- CONFigure:VOLTage:LIMit <voltage (V)>

Sets the ramping Voltage Limit in volts. The limit may not exceed the maximum output voltage of the power supply.

- VOLtage:LIMit?

Returns the ramping Voltage Limit in volts.

- CONFigure:CURRent:TARGet <current (A)>

Sets the target setpoint current in amperes.

- CURRent:TARGet?

Returns the target current setting in amperes.

- CONFigure:FIELD:TARGet <field (kG, T)>

Sets the target field in units of kilogauss or tesla, per the selected field units. This command requires that a coil constant be defined, otherwise an error is generated.

- FIELD:TARGet?

Returns the target field setting in units of kilogauss or tesla, per the selected field units. This query requires that a coil constant be defined, otherwise an error is generated.

- CONFigure:RAMP:RATE:CURRent <segment>,<rate (A/s, A/min)>,<upper bound (A)>

Sets the ramp rate for the specified segment (values of 1 through the defined number of ramp segments are valid) in units of A/sec or A/min (per the selected ramp rate units), and defines the current upper bound for that segment in amperes (see page 99 for details of the use of ramp segments).

NOTE The number of ramp rate segments (1-10) is set by the Ramp Segments menu as part of the Misc Setup submenu (see page 165 and page 99).

- RAMP:RATE:CURRent:<segment>?

Returns the ramp rate setting for the specified segment (values of 1 through the defined number of ramp segments are valid) in units of A/sec or A/min (per the selected ramp rate units) and the current upper bound for that range in amperes. The two return values are separated by a comma. For example:

Sent: RAMP:RATE:CURRENT:1?
Returned: 0.1000,50.0000

- CONFigure:RAMP:RATE:FIELD <segment>,<rate (kG/s, kG/min, T/s, T/min)>,<upper bound (kG, T)>

Sets the ramp rate for the specified segment (values of 1 through the defined number of ramp segments are valid) in units of kilogauss/second or minute, or tesla/second or minute (per the selected field units and ramp rate units), and defines the field upper bound for that segment in kilogauss or tesla (see page 99 for details of the use of ramp segments). This command requires that a coil constant be defined; otherwise, an error is generated.

- RAMP:RATE:FIELD:<segment>?

Returns the ramp rate setting for the specified segment (values of 1 through the defined number of ramp segments are valid) in units of kilogauss/second or minute, or tesla/second or minute (per the selected field units and ramp rate units) and the current upper bound for that range in kilogauss or tesla (per the selected field units). This command requires that a coil constant be defined; otherwise, an error is generated. The two return values are separated by a comma. For example:

Sent: RAMP:RATE:FIELD:1?
Returned: 0.0100,5.0000

MEASUREMENT COMMANDS AND QUERIES

Included are queries for collecting the present supply current/voltage, magnet field, magnet current, and magnet voltage.

- VOLTage:MAGnet?

Returns the magnet voltage in volts. Requires voltage taps to be installed across the magnet terminals and connected to a Magnet Station rear connector.

- VOLTage:SUPPLY?

Returns the power supply voltage commanded by the Model 430 Programmer in volts.

- CURRent:MAGnet?

Returns the current flowing in the magnet in amperes, expressed as a number with a variable number of significant digits past the decimal point (dependent on operating range), such as 5.2320. If the magnet is in persistent mode, the command returns the current that was flowing in the magnet when persistent mode was last entered.

- CURRent:SUPPLY?

Returns the measured power supply current in amperes.

- CURRent:REFerence?

The Model 430 maintains an internal, noise-less, digital current ramp reference as the control reference for the magnet. This command returns the ramp reference current in amperes.

NOTE This command requires firmware version 3.14, or legacy firmware version 2.64, or later.

- FIELD:MAGnet?

Returns the calculated field in kilogauss or tesla, per the selected field units. This query requires that a coil constant be defined; otherwise, an error is generated. The field value is calculated by multiplying the *measured* magnet current by the coil constant. If the magnet is in persistent mode, the command returns the field that was present when persistent mode was last entered.

- FIELD:REFerence?

The Model 430 maintains an internal, noise-less, digital ramp reference current as the control reference for the magnet. This command returns the ramp reference in units of kilogauss or tesla, per the selected field units. This query requires that a coil constant be defined; otherwise, an error is generated. The field value is calculated by multiplying the *reference* magnet current by the coil constant. If the magnet is in persistent mode, the command returns the field that was present when persistent mode was last entered.

NOTE This command requires firmware version 3.14, or legacy firmware version 2.64, or later.

RAMPING STATE COMMANDS AND QUERIES

The ramping state commands control and query the ramping state of the Model 430 Programmer. For more information regarding each state, see page 114.

If the ramping state is commanded remotely, the front panel display and LED indicators will update and accurately reflect the commanded ramping state.

- RAMP

Places the Model 430 Programmer in automatic ramping mode. The Model 430 will continue to ramp at the configured ramp rate(s) until the target field/current is achieved.

- PAUSE

Pauses the Model 430 Programmer at the present operating field/current.

- INCR

Places the Model 430 Programmer in the MANUAL UP ramping mode. Ramping continues at the ramp rate until the Current Limit is achieved.

- DECR

Places the Model 430 Programmer in the MANUAL DOWN ramping mode. Ramping continues at the ramp rate until the Current Limit is achieved (or zero current is achieved for unipolar power supplies).

- ZERO

Places the Model 430 Programmer in ZEROING CURRENT mode. Ramping automatically initiates and continues at the ramp rate until the power supply output current is less than 0.1% of I_{max} , at which point the AT ZERO status becomes active.

- STATE?

Returns an integer value corresponding to the ramping state according to the table below:

Return Values and Meanings for STATE? Query

Return Value	Meaning
1	RAMPING to target field/current
2	HOLDING at the target field/current
3	PAUSED
4	Ramping in MANUAL UP mode
5	Ramping in MANUAL DOWN mode
6	ZEROING CURRENT (in progress)
7	Quench detected
8	At ZERO current
9	Heating persistent switch
10	Cooling persistent switch
11	External Rampdown active

SWITCH HEATER COMMAND AND QUERY

The PSwitch commands control and query the state of the persistent switch heater. For further information regarding the persistent switch heater, see section on page 117.

- PSwitch {0|1}

Turns the persistent switch heater OFF and ON. Sending “0” turns the switch heater OFF. Sending a “1” turns the switch heater ON. The default value is “0”.

- PSwitch?

Returns a “0” indicating the switch heater is OFF, or a “1” indicating the persistent switch heater is ON.

- PERSISTENT?

Returns the state of the **MAGNET IN PERSISTENT MODE** LED on the front panel of the Model 430: “0” if the LED is OFF; “1” if the LED is ON.

QUENCH STATE COMMANDS AND QUERIES

The quench commands control and query the quench state of the Model 430 Programmer. For further information regarding the quench detection functions, see page 127.

- QUench {0|1}

Clears or sets the quenched state. Sending a “0” clears any quench condition (equivalent to using the **RESET QUENCH** front panel SHIFT+3). Sending a “1” sets a quench condition. Setting the quench state to “1” is equivalent to a quench detection by the Model 430 Programmer — the power supply output is forced to 0 V, the quench output of the rear panel Quench I/O connector is asserted, and all ramping functions are disabled.

- QUench?

Queries the quench state. If a “0” is returned, no quench condition exists. If a “1” is returned, a quench detect has occurred and is still in effect.

- QUench:COUNT?

Queries the number of recorded quench events in the non-backup quench event file.

- QUenchFile?

Formats and sends the contents of the recorded quench events file as a formatted ASCII text stream which can exceed 255 characters. This allows the user to view the state of both the magnet and Model 430 Programmer at each recorded quench event. The output of this query is terminated with two contiguous pairs of <CR><LF> characters (i.e. double terminators).

- QUenchBackup?

Formats and sends the contents of the quench events backup file as a formatted ASCII text stream which can exceed 255 characters. When the number of recorded quench events reaches 100, the standard quench events file becomes the backup file, and a new (empty) standard quench events file is created. The standard quench events file contains data from the most recent quench events, and the backup file (if it exists) contains data from the 100 quench events preceding the oldest record in the standard quench events file.

The output of this query is terminated with two contiguous pairs of <CR><LF> characters (i.e. double terminators).

NOTE The **QUenchFile?** and **QUenchBackup?** queries can return thousands of ASCII characters. Ensure your input communication buffers are setup to handle a large amount of text.

RAMPDOWN STATE COMMANDS AND QUERIES

The external rampdown function also has ramp segmenting capability—the function operates in a manner similar to the normal ramp as described on page 63, but the parameters *can only be edited via the remote interface*.

- **CONFigure:RAMPDown:RATE:SEGments <# segments>**

Sets the number of external rampdown segments.

- **RAMPDown:RATE:SEGments?**

Returns the number of external rampdown segments.

- **CONFigure:RAMPDown:RATE:CURRent <segment>, <rate (A/s, A/min)>, <upper bound (A)>**

Sets the external rampdown rate for the specified segment (values of 1 through the defined number of rampdown segments are valid) in units of A/sec or A/min (per the selected rampdown rate units), and defines the current upper bound for that segment in amperes.

- **RAMPDown:RATE:CURRENT: <segment>?**

Returns the external rampdown rate setting for the specified segment (values of 1 through the defined number of rampdown segments are valid) in units of A/sec or A/min (per the selected rampdown rate units) and the current upper bound for that range in amperes. The two return values are separated by a comma. For example:

Sent: RAMPDown:RATE:CURRENT:1?
Returned: 0.1000,50.0000

- **CONFigure:RAMPDown:RATE:FIELD <segment>, <rate (kG/s, kG/min, T/s, T/min)>, <upper bound (Kg, T)>**

Sets the external rampdown rate for the specified segment (values of 1 through the defined number of rampdown segments are valid) in units of kilogauss/second or minute, or tesla/second or minute (per the selected field units and rampdown rate units), and defines the field upper bound for that segment in kilogauss or tesla. This command requires that a coil constant be defined; otherwise, an error is generated.

- RAMPDown:RATE:FIELD: <segment>?

Returns the external rampdown rate setting for the specified segment (values of 1 through the defined number of rampdown segments are valid) in units of kilogauss/second or minute, or tesla/second or minute (per the selected field units and rampdown rate units) and the current upper bound for that range in kilogauss or tesla (per the selected field units). This command requires that a coil constant has been defined; otherwise, an error is generated. The two return values are separated by a comma. For example:

Sent: RAMPDown:RATE:FIELD:1?
Returned: 0.0100,5.0000

- RAMPDown:COUNT?

Queries the number of recorded rampdown events in the non-backup rampdown event file.

- RAMPDownFile?

Formats and sends the contents of the standard rampdown file as a formatted ASCII text stream which can exceed 255 characters. This allows the user to view the state of both the magnet and Model 430 Programmer during each recorded rampdown event. The output of this query is terminated with two contiguous pairs of <CR><LF> characters (i.e. double terminators).

- RAMPDownBackup?

Formats and sends the contents of the rampdown backup file as a formatted ASCII text stream which can exceed 255 characters. When the number of recorded rampdown events reaches 100, the standard rampdown file becomes the backup file, and a new (empty) standard rampdown file is created. The standard rampdown file contains data from the most recent rampdown events, and the backup file (if it exists) contains data from the 100 rampdown events preceding the oldest record in the standard rampdown file.

The output of this query is terminated with two contiguous pairs of <CR><LF> characters (i.e. double terminators).

NOTE The **RAMPDownFile?** and **RAMPDownBackup?** queries can return thousands of ASCII characters. Ensure your input communicaton buffers are setup to handle a large amount of text.

TRIGGER FUNCTIONS

The Model 430 Programmer provides trigger functions which provide a means of collecting operational data with a minimum of commands and directing the output to either or both remote interfaces.

DESCRIPTION OF THE TRIGGER FUNCTIONS

The Model 430 Programmer defines a *trigger enable register*, very similar to the enable registers of the status system, which controls which data is output and the interface to which the data is presented. The trigger enable register is defined as shown in the following table:

Model 430 Programmer Trigger Function Bit Definitions

Bit Number	Bit Name	Decimal Value	Definition
0	Magnet Voltage	1	Magnet voltage in volts is included in trigger output.
1	Magnet Current	2	Magnet current in amperes is included in the trigger output.
2	Magnet Field	4	Magnet field in kilogauss or tesla (per the selected field units) is included in the trigger output.
3	Date and Time	8	The trigger date and time is included in the trigger output in the form <i>mm/dd/yyyy hh:mm:ss</i>
4	Supply Current & Voltage	16	Supply current in amperes and supply voltage in volts are included in the trigger output.
5	Formatted Output	32	The trigger output data is formatted.
6	Serial Interface	64	Trigger output data is placed in the serial interface output buffer and transmitted immediately.
7	Ethernet Interface	128	Trigger output data is placed in the Ethernet output buffer.

To enable the trigger functions, the `*ETE <enable_value>` command is written with a decimal value corresponding to the binary-weighted sum of the desired output. Upon receipt of the `*TRG` command, the Model 430 Programmer places the return data in the appropriate output buffer(s). Data placed in the serial or Ethernet output buffers is transmitted immediately. Note that trigger output data may be placed in both the serial *and* the Ethernet output buffers if desired, but the formatting and output selections are common to both.

NOTE Since trigger data is output immediately to the serial interface, it is possible to use the trigger functions to drive a terminal, modem, or a line printer (if a serial-to-parallel or serial-to-USB converter is available) connected to the serial interface.

TRIGGER OUTPUT DATA ORDER

If the trigger output data is not formatted, the data will be comma delimited (i.e. CSV compatible format) and returned in the order of *time*, *magnet field*, *magnet current*, *magnet voltage*, and *supply current and voltage*. Only the data enabled for output will appear in the trigger output string.

TRIGGER COMMANDS AND QUERIES

- *ETE <enable_value>

Enables trigger functions according to the definitions in the table on page 181. To enable the trigger functions, you must write a decimal <enable_value> which corresponds to the binary-weighted sum of the functions you wish to enable. For example, to enable *formatted* output of the *time*, *magnet field*, and the *magnet voltage* to the serial interface, send the command:

```
*ETE 109;
```

The return data in the serial output buffer would appear as (with the field units selected as tesla):

```
10/23/2007 13:03:14, FIELD= 20.002 T, VOLTAGE= 2.05 V
```

- *ETE?

The *ETE? query returns a decimal sum which corresponds to the binary-weighted sum of the trigger functions enabled by the last *ETE command.

- *TRG

Initiates trigger output to the enabled interfaces for trigger functions.

ERROR MESSAGES

If an error occurs, the Model 430 Programmer will beep, load the internal error buffer with the error code and description, and set the appropriate bits in the standard event and status byte registers if enabled by the user. Error codes are returned with a negative 3 digit integer, then a comma, and then a text description enclosed in double quotes.

NOTE If the Model 430 is emitting error beeps while under remote control, the interface is *not* being used properly and the user risks unintended consequences of failed or ignored commands/queries. Please contact an authorized AMI Technical Support Representative for assistance if you cannot resolve the issue.

A typical error is not handling the “hello” message in stateless communication code on port 7180. Use port 7185 instead (see page 148) which does not provide a “hello” message upon connect which makes VISA-based communication easier to manage.

Use the SYSTem:ERRor? query to retrieve the errors in first-in-first-out (FIFO) order. Errors are removed from the internal error buffer as they are read. The Model 430 Programmer can store up to 10 errors.

If more than 10 errors have occurred, the last error stored in the internal error buffer is replaced with -304, “Error buffer overflow”. No additional errors are stored until you have cleared at least one error from the buffer. If no errors have occurred and the SYSTem:ERRor? query is sent to the Model 430 Programmer, the instrument will return:

0, “No errors”

Error strings may contain up to 80 characters. Errors are classified in the following categories: *command errors*, *query errors*, *execution errors*, and *device errors*. Each category corresponds to the identically named bit in the standard event register (see page 144). If an error occurs in any one of the categories, the corresponding bit in the standard event register is set and remains set until cleared by the user.

COMMAND ERRORS

- -101, “Unrecognized command”

The command string sent was not identified as valid. Check the command string for invalid characters or separators, syntax errors, or for errors in the mnemonics. Spaces are not allowed before or after colon separators, and at least one space must separate a command string from the parameter(s).

- -102, "Invalid argument"

The argument provided as a parameter for the command was invalid. *Value* arguments must be of the following form:

- an optional plus or minus sign,
- a sequence of decimal digits, possibly containing a single decimal point, and
- an optional exponent part, consisting of the letter e or E, an optional sign, and a sequence of decimal digits.

Enable_value arguments must be within the inclusive range of 0 to 255.

- -103, "Non-boolean argument"

The command required a parameter in the form of 0 or 1. No other form of the parameter is allowed.

- -104, "Missing parameter"

The command required at least one argument which was not found before the termination character(s).

- -105, "Out of range"

At least one of the parameter values received was out of the valid range. Refer to the summary of valid ranges for the Model 430 Programmer settings on page 132. Be sure to note the field units and ramp units settings and check any unit conversions.

If an Operational Limits Protection Mode is enabled (see section on page 95), ensure the value is below any limits such as **lc**.

- -106, "Undefined coil const"

The user attempted to invoke a command with units of field without first setting a value for the coil constant. The coil constant must be a non-zero, positive value.

- -107, "No switch installed"

The user attempted to activate the persistent switch heater when no switch is installed. Before activating the persistent switch heater, the user must indicate a switch is installed and set the switch current and heating time (see page 86).

- -108, "Not ramping"

The command that was issued requires the Model 430 Programmer to be ramping for the duration of command processing, and the Model 430

Programmer was either not ramping when the command was issued, or stopped ramping before the command processing was completed.

- -109, "N/A in present mode"

The command or query is not applicable to the present operational mode. For example, in Short Sample Mode the commands or queries associated with operation of the Persistent Switch do not apply.

- -110, "Zero inductance"

The command or query is not available due to a zero inductance value in the Load Setup submenu.

- -111, "Custom supply required"

The command sent requires a "Custom" power supply selection in order to execute.

QUERY ERRORS

- -201, "Unrecognized query"

The query string sent (identified as a query by a ?) was not identified as valid. Check the query string for invalid characters or separators, syntax errors, or for errors in the mnemonics. Spaces are not allowed before or after colon separators.

- -202, "Undefined coil const"

The user attempted to invoke a query with units of field without first setting a value for the coil constant. The coil constant must be a non-zero, positive value.

- -203, "Query interrupted"

A new query was processed before the return string of a previous query had been completely transmitted to the host. The new query clears the remaining data and replaces it with the new return string.

- -204, "No recorded events"

There are no events in the request for output of the quench or rampdown standard or backup event files.

EXECUTION ERRORS

- -301, "Heating(Cooling) switch"

The user attempted to initiate a disallowed function during the persistent switch heating or cooling transition period. Ramping functions, for example, are disallowed during the transition period.

- -302, "Quench condition"

The user attempted to change the ramping state while a quench condition was active. A quench condition must be cleared via the **RESET QUENCH** SHIFT-key or by remote command before the ramping state can be modified.

- -303, "Input overflow"

The four input buffers are all occupied with unprocessed commands or queries. The command or query is lost. Review the handshaking on page 145 for directions for avoiding input overflow errors.

- -304, "Error buffer overflow"

More than 10 errors have occurred. For further errors to be recorded in the internal buffer, at least one error must be cleared.

- -305, "Supply is off"

A command was attempted while the "Turn on power supply/Press ENTER to continue" banner is displayed. Commands are disallowed until the banner has been acknowledged.

- -306, "Rampdown is active"

No commands are allowed during an active rampdown. All user input is blocked until the rampdown process completes.

- -307, "Cooled switch @ 0A required"

A persistent switch current auto-detect cycle requires an initially cooled switch at zero current before initiation.

- -308, "N/A when persistent"

Attempted to execute a function that is not available if the magnet is presently in persistent mode.

- -309, "Zero current required"

Attempted to execute a function that is not allowed unless the prevailing power supply current is at zero. The Stability Mode = TEST, for example, requires a zero power supply current in order to activate.

DEVICE ERRORS

- -401, "Checksum failed"

The non-volatile memory which stores the calibration data for the Model 430 Programmer is corrupted. Contact an Authorized AMI Technical Representative for further instructions. Do not continue to use the Model 430 Programmer to operate a superconducting magnet.

- -402, "Serial framing error"

The baud rate of the Model 430 Programmer and host device are not identical. The host device must be set to the same baud rate as the Model 430 Programmer (115200).

- -403, "Serial parity error"

The number of data bits and/or the parity of the Model 430 Programmer and the host device are not identical. The host device must be set for the same number of data bits, stop bits and parity as the Model 430 Programmer (8 data bits, 1 stop bit and no parity).

- -404, "Serial data overrun"

The received buffer of the Model 430 Programmer was overrun. Verify that the host device has hardware handshaking (RTS/CTS) enabled.

- -405, "File not found"

The quench or rampdown standard or backup event file was not found.

- -406, "Corrupted file"

The quench or rampdown standard or backup even file appears to be corrupted and cannot be read.

- -407, "Output stream corrupted"

The quench or rampdown standard or backup event file encountered an error while parsing to ASCII text.

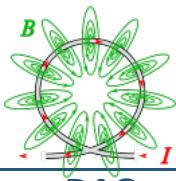
- -408, "Unknown file format"

The quench or rampdown standard or backup event file contained an unknown memory format.

NOTE In the event the quench and/or rampdown event files continue to present an error when queried for output, it is possible to clear the stored history to begin anew.

For the quench event history this can be done with the *RQC command. The command clears the quench event count and deletes any existing standard and backup quench event files.

The rampdown event history is cleared by the *CRD command. The command clears the rampdown event count and deletes any existing standard and backup rampdown event files.



MAGNET-DAQ: COMPREHENSIVE MODEL 430 REMOTE CONTROL

REMOTE APPLICATIONS AND EXAMPLES

The Model 430 can be accessed via a network connection⁵ with fully functional control.⁶ This is accomplished through the Ethernet connection on the rear panel using TCP/IP protocol via a host computer. The connection and control can be established through a locally connected computer or remotely through a network or even the Internet; the actual control is accomplished through the SCPI remote commands as documented in this chapter.

The free, open-source⁷ Magnet-DAQ application⁸ is provided to manage the remote control with a familiar graphical interface. The source code and latest binary (i.e. pre-compiled and ready-to-use) downloads for the application are available at:

<https://bitbucket.org/americanmagneticsinc/magnet-daq>

To utilize the Magnet-DAQ application, the Model 430 Programmer RJ-45 Ethernet port must be connected either directly to a host computer or through a computer network on which the host computer resides or can directly access:

1. For a host computer on a network, connect a standard Ethernet cable between the Model 430 and the network.
2. For a direct hardwired connection between the Model 430 and a host computer, use a “null-modem” or “crossover” Ethernet cable connected from the Model 430 to the host computer.

NOTE Most modern computers will negotiate the direct connection cross-over automatically with a standard Ethernet cable.

3. Once connected, plug in and power up the Model 430.
4. Press <**ENTER**> after responding to the “Turn on power supply . . .” prompt.

NOTE Allow up to 90-seconds (from power-up) for the TCP/IP link between the Model 430 and host computer to be established.

In order to access the Model 430 using the Magnet-DAQ application, the Model 430 IP Address must be known. The IP Address can be determined

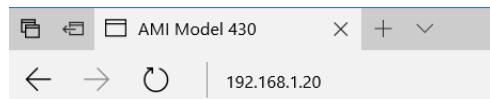
5. Third-party remote software, such as National Instruments LabVIEW, can also be used.
6. With the exception of the Power ON/OFF switch.
7. Subject to the [GPL version 3.0 license](#).
8. Requires Model 430 version 2.55 or later firmware.

after Model 430 power-up. The following example illustrates how the *IP Address* may be determined using the Model 430 menu system:

5. *IP Address: Menu > Net Settings > IP Address (Present).*

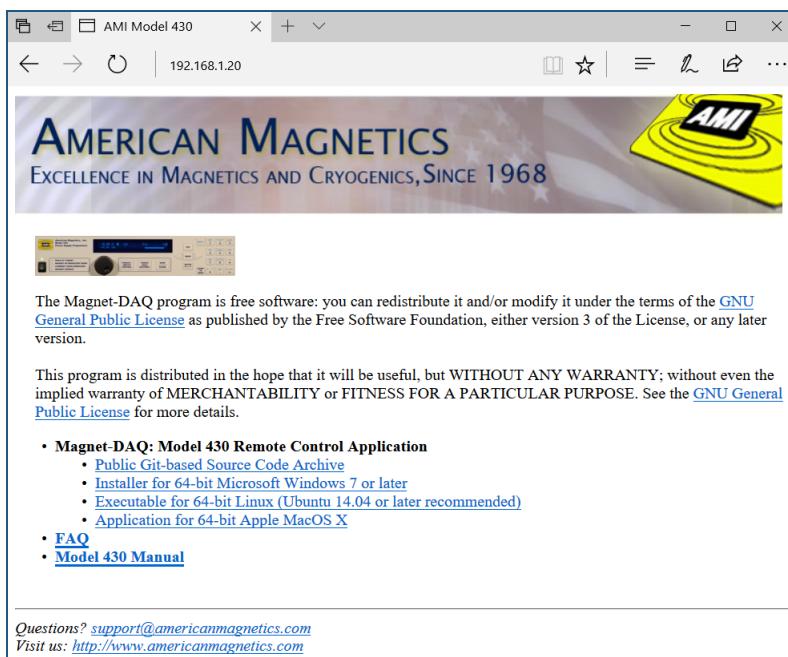
0.00 A -	IP Address (Present)
0.00 Vs	192.168.1.20 (DHCP)

Open a web browser on the host computer. In the address field, type the *IP Address*, and press <**ENTER**>. For example:



IP Address Entry in Browser Address Field

The following initial (home) screen should appear:



Initial Screen for Browser Access of the Model 430

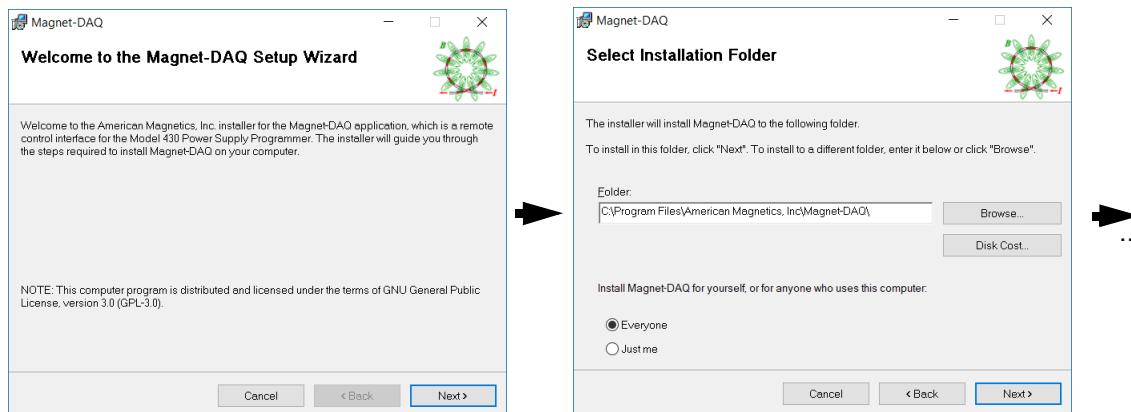
The *Magnet-DAQ: Model 430 Remote Control Application* section is the primary feature of this HTML page. In addition to the URL shown on the prior page, the integrated web page offers download links for the pre-compiled installers or executables for various computing platforms.

NOTE Please note that the version provided was current at the time the Model 430 was shipped. Check the AMI website, or the on-line Git-based Source Code Archive, for updated versions of the Magnet-DAQ application. Updated versions of the Magnet-DAQ may also require updating the Model 430 firmware.

The initial screen also includes links to the *Model 430 Manual* in Adobe PDF form along with the *FAQ (Frequently Asked Questions)* related to the Magnet-DAQ application (all stored in the Model 430 firmware). There are also links to the AMI website and an e-mail form for contacting AMI Customer Support.

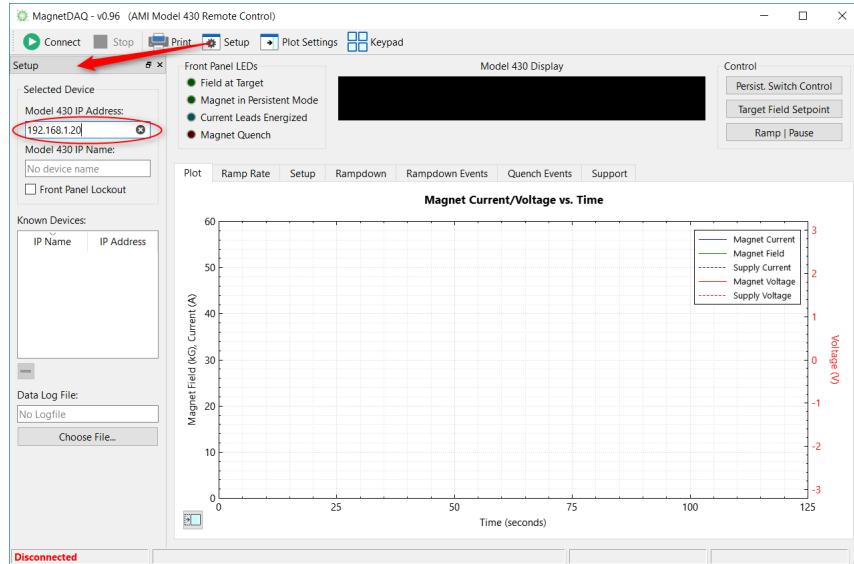
6. Choose the desired Magnet-DAQ version for the appropriate operating system and follow the installation instructions for each.

The Windows version installation will be illustrated herein which is provided in the form of an installer. After the installer download is complete, simply launch the installer and follow the familiar installation wizard (using the Next button) to complete the process:



Windows-version Installation Wizard for the Magnet-DAQ Application

7. Launch the Magnet-DAQ application, choose the Setup panel, and enter the IP address discovered in Step 5 above:

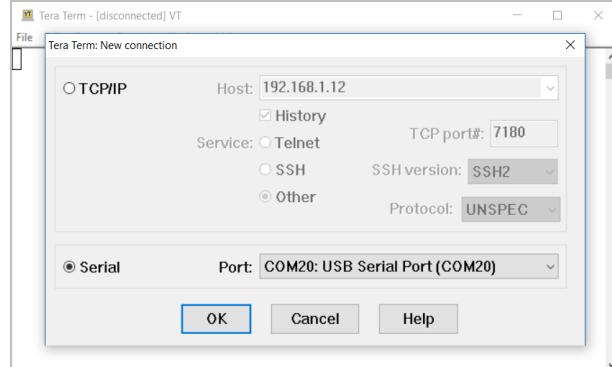


8. Press the Connect toolbar button to start communication.

Use the provided Magnet-DAQ interface to remotely control the Model 430. The Keypad panel provides a remote keypad function. For more details, refer to the integrated Help provided in the Magnet-DAQ application.

SCPI-BASED COMMUNICATION VIA RS-232

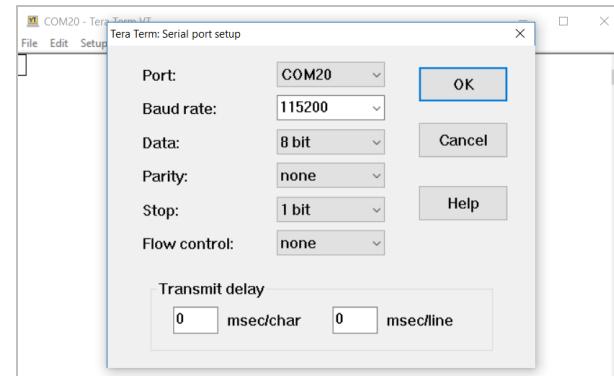
1. Using serial null modem adapter (and possibly a gender changer)⁹, connect the DB9 RS-232 connector on the rear of the Model 430 Programmer to a standard USB-to-serial cable¹⁰ connected to a computer.
2. Start a terminal emulator program on the remote computer. As an example, this procedure will use the open-sourced Tera Term program¹¹ running on a Windows machine. You are greeted immediately with the *Tera Term New Connection* dialog.



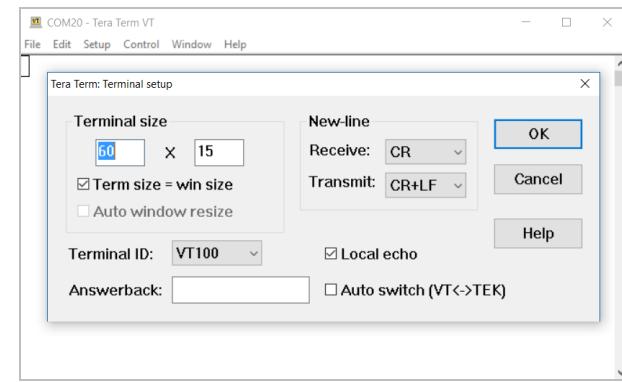
9. Mouser Electronics offers a compact null-model/gender changer: see part # 515-140-448-R.
10. AMI recommends FTDI USB-to-serial cables. See DigiKey part # 768-1084-ND.
11. The Tera Term application is open-sourced and is available at <https://ttssh2.osdn.jp/index.html.en>. A Windows installer is also linked on the internal Model 430 web page, see page 189.

3. Choose the *Serial* option and then the *Port* to which the Model 430 is connected. This example illustrates *COM20: USB Serial Port (COM20)*, which in this example is the port assigned by Windows to a USB-to-serial adapter cable. Press *OK*.

4. Use the *Setup | Serial Port...* menu command in Tera Term to show the serial parameters dialog. Set the parameters as shown at right per page 147 (*Port* selection is specific to your setup).

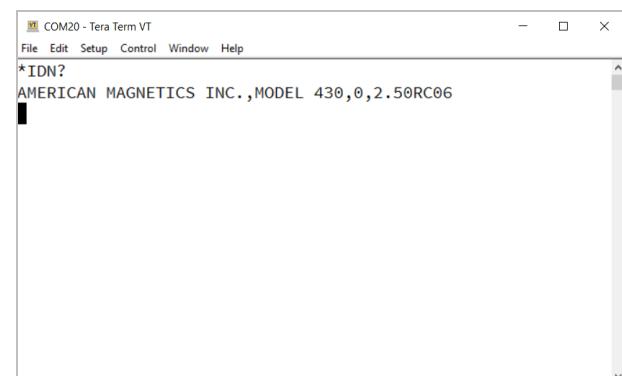


5. Use the *Setup | Terminal...* command in Tera Term to show the terminal setup parameters. Set the parameters as shown at right. You may choose the *Terminal size* per your preference and screen size.



6. Optionally choose the *Setup | Save Setup...* menu selection in Tera Term to save these settings as the default for new sessions. Depending on where you install Tera Term, you may need to specify a different *Setup directory* depending on your account privileges.

7. Type *IDN? followed by *Enter* to test the connection. The Model 430 Programmer should respond with "AMERICAN MAGNETICS, INC., MODEL 430,X,Y.Y" where X is the serial number and Y.Y is the firmware version.



8. Issue commands or queries as desired. See “Remote Interface Reference” on page 133.

The screenshot shows a terminal window titled "COM20 - Tera Term VT". The menu bar includes File, Edit, Setup, Control, Window, and Help. The main window displays a command-line interface with the following text:
*IDN?
AMERICAN MAGNETICS INC., MODEL 430, 0, 2.50RC06
SYST:TIME?
05/10/2017 18:59:27
CURR:LIMIT?
67.000
PS:CURR?
20.9

SCPI-BASED COMMUNICATION VIA ETHERNET

1. Connect the Model 430 Programmer RJ-45 Ethernet port either directly to a host computer or through a computer network on which the host computer resides:
 - c. For a host computer on a network, connect a standard Ethernet cable between the Model 430 and the network.
 - d. For a direct hardwired connection between the Model 430 and a host computer, use a “null-modem” or “crossover” Ethernet cable connected from the Model 430 directly to the host computer.

NOTE Most modern computers will negotiate the direct connection cross-over automatically with a standard Ethernet cable.

2. Turn on the Model 430 and press **ENTER** at the “Turn on power supply . . .” prompt.
3. Press **MENU** to enter the menu system.
4. Use <◀>/◀▶> to navigate to the *Net Settings* submenu and press **ENTER**.
5. Use <◀>/◀▶> as necessary to navigate to *Addr Assignment (Present)*.

NOTE The *Addr Assignment (Present)* must show “DHCP” as originally set by AMI unless a static IP address has been assigned by your local network administrator.

If you are using the direct PC-to-Model 430 connection, you may be required to assign a static IP addresses for the Model 430 on the same subnet as the PC interface (typically 169.254.xxx.xxx for Windows) with a compatible mask setting (see page 110).

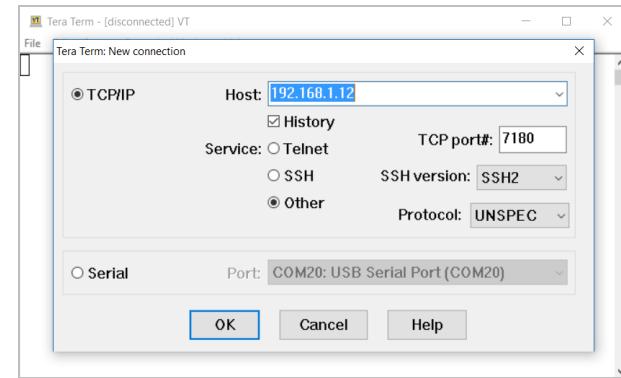
NOTE In the following step, the IP Address is the four part number separated by periods (.) and will change with each Ethernet connection.

6. Use <◀>/<▶> to locate *IP Address (Present)*, similar to that shown below:

0.00 A -	IP Address (Present)
0.00 Vs	192.168.1.12 (DHCP)

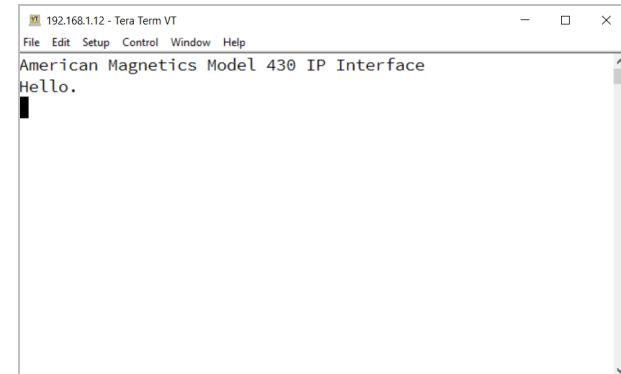
7. Make note of the *IP Address (Present)*.

8. Start a terminal emulator program on the remote computer. As an example, this procedure will use the open-sourced Tera Term program¹² running on a Windows machine. You are greeted immediately with the *Tera Term New Connection* dialog.



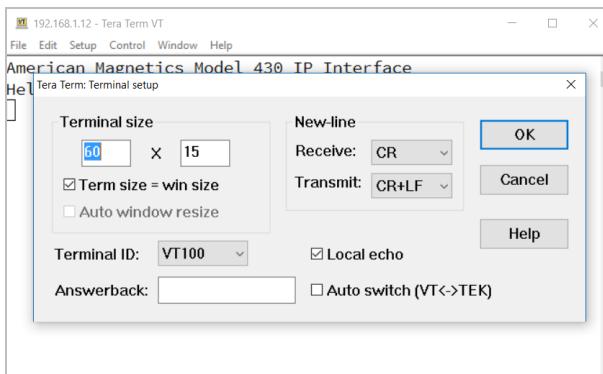
9. Choose the *TCP/IP* option and then the *Host* address for the Model 430 that was determined from the previous Step 7. This example illustrates 192.168.1.12. Choose the *Service | Other* and enter *TCP port #* 7180 (use port 7185 to avoid the "Hello" message, see page 148). Press *OK*.

10. The computer will connect with the Model 430 Programmer and display the welcome message.



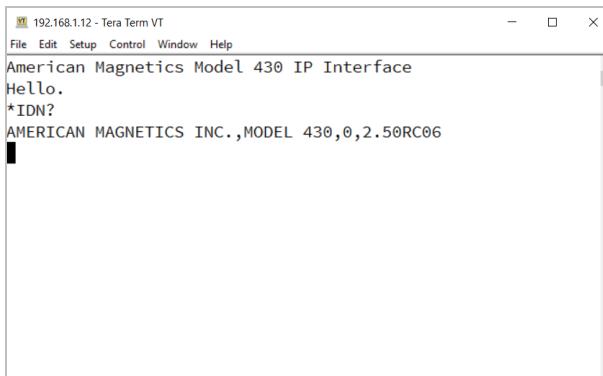
12. The Tera Term application is open-sourced and is available at <https://ttssh2.osdn.jp/index.html.en>. A Windows installer for a *recent* version (not guaranteed to be the latest) is also included on the internal Model 430 web page, see page 189.

11. Use the *Setup | Terminal...* command in Tera Term to show the terminal setup parameters. Set the parameters as shown at right. You may choose the *Terminal size* per your preference and screen size.

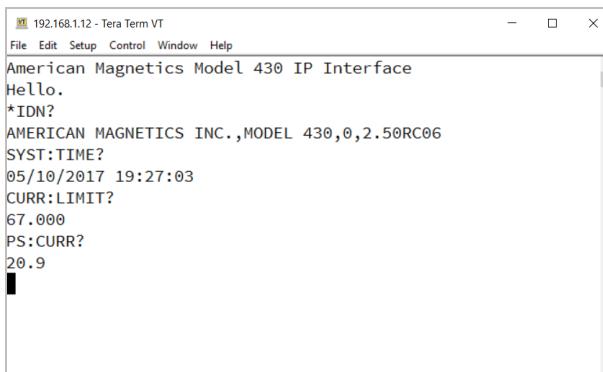


12. Optionally choose the *Setup | Save Setup...* menu selection in Tera Term to save these settings as the default for new sessions. Depending on where you install Tera Term, you may need to specify a different *Setup directory* depending on your account privileges.

13. Type *IDN? followed by *Enter* to test the connection. The Model 430 Programmer should respond with "AMERICAN MAGNETICS, INC., MODEL 430,X,Y.Y" where X is the serial number and Y.Y is the firmware version.



14. Issue commands or queries as desired. See "Remote Interface Reference" on page 133.



Service

SYSTEM COMPONENT ROUTINE MAINTENANCE

CAUTION

Electronic devices are sensitive to electrostatic-discharge (ESD) damage when opened (cover removed). Observe all standard ESD precautions when handling opened power supplies and instruments. Refer to information on page 201.

The Model 430 Programmer was designed and manufactured to give years of reliable service. The only routine maintenance required is to keep the exterior surfaces of the Model 430 Programmer clean by gently wiping with a damp cloth moistened with a mild detergent.

MODEL 430 FIRMWARE UPGRADES

Model 430 firmware upgrades are most easily accomplished using the free, open-source Magnet-DAQ application distributed by AMI for all major, non-mobile computing platforms (see page 189). Please note that there are presently two branches of firmware with the base version separated by 0.5 in the revision value, e.g. 2.62 and 3.12. *Magnet-DAQ is intelligent in this regard and will offer the correct firmware upgrade.*

The latest branch firmware is 3.0+ and requires a Rev 9 or later PCB internally in the Model 430. This can be *externally verified* by observing if the RS-232 connector is a female DB-9 (which functions with COTS USB-to-serial cables). If so, then the PCB is Rev 9 or later.

The “legacy” branch is firmware 2.5+ and will never cross the 3.0 boundary. That indicates an internal PCB *prior* to Rev 9. This is

externally verifiable by virtue of a male DB-9 connector for the RS-232 which requires a gender changer and null modem adapter to work with modern computers and COTS USB-to-serial cables.

CAUTION

Do not attempt to manually upgrade a legacy device to firmware version 3.0+, or downgrade a 3.0+ device to 2.x firmware. Attempting to do so may render the device non-bootable or result in operational errors, and require assistance from an Authorized AMI Technical Representative to recover.

The goal of AMI is to continue supporting legacy devices with all bug fixes and new features where the hardware supports it. Features specific to newer branch firmware (3.0+) are noted in this manual.

**MANUALLY
UPGRADING THE
FIRMWARE VIA FTP**

If for whatever reason it is not possible to use the free Magnet-DAQ application and its easy-to-use integrated Firmware Upgrade Wizard, the following instructions can be used to upgrade the Model 430 firmware manually via a command-line FTP client available on all major computing platforms including Microsoft Windows, Linux, and macOS.

HARDWARE AND SOFTWARE REQUIREMENTS

1. Personal Computer (PC) networked by Ethernet to the system on which the target Model 430 resides,

or

PC connected directly to the target Model 430 via a “null-modem” or “cross-over” Ethernet cable.

NOTE **Most modern computers will negotiate the direct connection cross-over automatically with a standard Ethernet cable.**

2. The Model430.exe upgrade file extracted from the zip file (typically of the same name) provided by an Authorized AMI Technical Representative.
3. The command-line interface of a built-in FTP client that requires no software installation.

PREPARATION

1. The AMI Model 430 can be upgraded through a local facility network, or via direct Ethernet connection to the PC:
 - a. Via Facility Network:
 - (i.) Make a new “Upgrade” folder located in an appropriate location on your local computer or file server.

- (ii.) Extract and save the AMI-supplied upgrade-file, Model430.exe, to the new folder.
- (iii.) Ensure that the PC is connected to the network.
- (iv.) Ensure the Model 430 is connected to the network via a standard Ethernet cable.

b. Direct PC-to-Model 430:

- (i.) Make a new “Upgrade” folder located in an appropriate location on the PC.
 - (ii.) Extract and save the AMI-supplied upgrade-file, Model430.exe, to the new folder.
 - (iii.) Connect the PC to the Model 430 using a “null-modem” Ethernet cable (also referred to as an Ethernet “cross-over” cable). *Modern computer equipment may not require a crossover cable as the Ethernet ports can automatically sense the necessary configuration.*
2. Turn on the Model 430 and press **ENTER** at the “Turn on power supply . . .” prompt.
 3. Press **MENU** to enter the menu system.
 4. Use <◀>/◀▶> to navigate to *Net Settings* submenu and press **ENTER**.
 5. Use <◀>/◀▶> as necessary to navigate to *Addr Assignment (Present)*.

NOTE The Addr Assignment (Present) must show “DHCP” as originally set by AMI unless a static IP address has been assigned by your local network administrator.

If you are using the direct PC-to-Model 430 connection, you may be required to assign a static IP addresses for the Model 430 on the same subnet as the PC interface with a compatible mask setting (see page 110).

NOTE In the following step, the IP Address is the four part number separated by periods (.), and will change with each Ethernet connection.

6. Use <◀>/◀▶> to locate IP Address (Present), similar to that shown in Figure 1.

0.00 A -	IP Address (Present)
0.00 Us	169.254.34.203 (DHCP)

7. Make note of the IP Address (Present).

UPLOAD PROCEDURE USING WINDOWS FTP

Modern versions of Microsoft Windows (and other operating systems such as Linux and macOS) include a command line-based client version of FTP as a standard feature. There is no *requirement* to install a GUI FTP Client to perform the Model 430 firmware upgrade.

First, perform steps described in the *Requirements* and *Preparation* section above to obtain the firmware upgrade file and the IP address of the Model 430.

To actually perform the FTP upload to the Model 430, do the following steps:

1. Open a Windows Command Line (or Terminal window on Linux and macOS) instance and navigate to the local computer folder where you stored the firmware upgrade during the preparation steps.
2. FTP to the instrument address on the network as identified during the preparation (the example below uses 192.168.1.12). The entire command line process is illustrated below with required operator input marked in red:

```
C:\Model430\IoT-Firmware\Model430\X86Rel>ftp 192.168.1.12
Connected to 192.168.1.12.
220 Service ready for new user.
500 Syntax error, command unrecognized.
User (192.168.1.12:(none)): model430admin
331 User name okay, need password.
Password: [REDACTED]
230 User logged in, proceed.
ftp> bin
200 Command okay.
ftp> cd Upgrade
250 Requested file action okay, completed.
ftp> put Model430.exe
200 Command okay.
150 File status okay; about to open data connection.
226 Closing data connection.
ftp: 213504 bytes sent in 1.66Seconds 128.93Kbytes/sec.
ftp> quit
221 Service closing control connection.

C:\Model430\IoT-Firmware\Model430\X86Rel>
```

3. Login with user name “model430admin” and password “supermagnets” (do not include the quotes, the password will be hidden during typing).
4. Type “bin” and press Enter to ensure a binary mode transfer.
5. Type “cd Upgrade” and Enter to change to the target folder for the firmware upload.
6. Type “put Model430.exe” and Enter.
7. Type “quit” and Enter to exit.
8. Cycle power on the Model 430 and observe the firmware version banner during boot.

TROUBLESHOOTING HINTS

The following paragraphs serve as an aid to assist the user in troubleshooting a potential problem with the Model 430 Programmer within a superconducting magnet system. If the user is not comfortable in troubleshooting the system, contact an AMI Technical Support Representative for assistance. Refer to "Additional Technical Support" on page 208.

ELECTROSTATIC DISCHARGE PRECAUTIONS

The Model 430 Programmer system contains components which are susceptible to damage by Electrostatic Discharge (ESD). Take the following precautions whenever the cover of electronic equipment is removed.

1. Disassemble the Model 430 Programmer only in a static-free work area.
2. Use a conductive workstation or work area to dissipate static charge.
3. Use a high resistance grounding wrist strap to reduce static charge accumulation.
4. Ensure all plastic, paper, vinyl, Styrofoam® and other static generating materials are kept away from the work area.
5. Minimize the handling of the Model 430 Programmer system and all static sensitive components.
6. Keep replacement parts in static-free packaging.
7. Do not slide static-sensitive devices over any surface.
8. Use only antistatic type desoldering tools.
9. Use only grounded-tip soldering irons.
10. Use only static-dissipative hand tools (pliers, cutters, etc.).

HINTS FOR COMMONLY ENCOUNTERED ERRORS

The following paragraphs provide hints for specific error conditions. Please review the steps for each before beginning a troubleshooting session or contacting an Authorized AMI Technical Support Representative.

THE MODEL 430 DOES NOT APPEAR TO BE ENERGIZED

1. Ensure that the Model 430 Programmer is energized from a power source of proper voltage.

WARNING

If the Model 430 Programmer is found to have been connected to an incorrect power source, return the instrument to AMI for evaluation to determine the extent of the damage. Frequently, damage of this kind is not visible and must be determined using test equipment.

2. Verify continuity of all line fuses (F1, F2, F3, F4, F5, F6 and F7) located on the Model 430 Programmer printed circuit board.

WARNING

This procedure is to be performed only when the Model 430 Programmer is completely de-energized by removing the power-cord from the power receptacle. Failure to do so could result in personnel coming in contact with high voltages capable of producing life-threatening electrical shock.

- a. Ensure the Model 430 Programmer and all connected components are de-energized by first shutting down the system and then disconnecting the power cord from the power source. Disconnect the power cord from the connector located on the rear panel of the instrument.
- b. Remove the Model 430 Programmer top cover and check all fuses for continuity.
- c. If a fuse is bad, replace with a fuse of identical rating:

V-V Mode Input Range Picklist Values

Fuse Identification	Fuse Rating	Fuse Size
F1	T 800 mA	
F2	T 250 mA	
F3		
F4		5 x 20 mm
F5		
F6		
F7		

CAUTION

Installing fuses of incorrect values and ratings could result in damage to the Model 430 Programmer in the event of component failure.

- d. Replace the fuse and securely fasten the Model 430 Programmer top cover. Reconnect the power-cord.
3. Verify the input voltage selector switch on the Model 430 Programmer printed circuit board is in the proper position for the available input power.

Checking the input voltage selector requires removal of the top cover of the Model 430 Programmer. Observe the same safety procedures as presented in step 2, above.

"FAILURE TO LOAD" MESSAGE DISPLAYED AFTER POWER-UP

1. Power the Model 430 Programmer off using the front panel power switch.
2. Wait at least 15 seconds.
3. Power the Model 430 Programmer on using the front panel switch.

POWER SUPPLY UNSTABLE - MAGNET VOLTAGE OSCILLATES

NOTE If the size of the voltage oscillation is small (approximately 0.1 volt or smaller), see step 1, below. If the voltage oscillation is larger than approximately 0.1 volt, see steps 1 through 4, below.

1. Adjust the persistent switch heater current to a value 10 mA larger than the present value. If the oscillation stops, adjust the heater current to as small a value as possible that maintains magnet voltage stability.
2. Verify the power supply controlled by the Model 430 Programmer is configured for remote programming, voltage-to-voltage mode. Consult the manufacturer's operations manual for the necessary power supply configuration.
3. Verify that the persistent switch heater is operating. Also, verify that the actual persistent switch in the magnet is correctly installed and connected.

NOTE If the persistent switch heater is activated without an inductive load present at the supply outputs, oscillating current will result. The Model 430 Programmer is designed to operate large inductive loads with only relatively small resistive characteristics (i.e. superconducting magnets). The Model 430 Programmer is not designed for use as a general purpose power supply controller for resistive loads.

4. If the magnet has no persistent switch installed, or has a small inductance (typically less than 3 H), then adjust the stability setting for the Model 430 Programmer. As this setting is increased, the system should become more stable. For best results, minimize the amount that this value is adjusted from 0.0%. Refer to page 81 for more details about the Stability Setting.

THE POWER SUPPLY SYSTEM WILL NOT CHARGE THE MAGNET

1. Verify system interconnecting wiring. If the Model 430 Programmer shows "+0.00 A ↑ Status: Ramping" with the supply voltage, Vs, increasing or at the programmed Voltage Limit (as indicated by the reverse video "V" status indicator), there may be a problem with the power supply. Verify the power supply is on and the program out connection from the Model 430 Programmer to the program voltage input to the power supply is intact.
2. Verify the power leads are properly connected to the magnet.

3. Verify the power supply is configured for remote programming, voltage-to-voltage mode.
4. If the system incorporates the Model 601 Energy Absorber, check the system wiring and verify that the current flow direction through the Model 601 is from the positive (+) to the negative (-) lug.
5. If the system incorporates the Model 601 Energy Absorber, verify that the supplied external DC power converter is connected to the rear of the Model 601, and the AC power cord is also connected to the appropriate power receptacle.
6. If the system incorporates the Model 601 Energy Absorber, check the Voltage Limit settings of the Model 430 Power Supply Programmer and verify the limits are set to a value greater than 5 volts plus the charging voltage and any power lead voltage drops.

CANNOT CHARGE THE MAGNET AT THE SELECTED RAMP RATE

1. Ensure the Model 430 Programmer is properly configured for the connected power supply. See page 74.
2. Ensure that the persistent switch heater is on and the switch heated time has expired. Ramping is disabled during the switch heating period.
3. Check the value of the Voltage Limit. Refer to page 66.

NOTE If an energy absorber is present in the system, the Model 430 Programmer must command enough power supply voltage to overcome any forward voltage drop due to the energy absorber. Increase the Voltage Limit to account for the +5 VDC energy absorber voltage drop.

4. Check for excessive wiring resistances in the magnet-power supply loop which may prevent proper charge/discharge voltages at the magnet. Use the local voltmeter on the power supply to see if the proper voltages exist across the various components in the magnet power loop. Loose or oxidized interconnections often exhibit excessive resistances.

CANNOT DISCHARGE THE MAGNET AT THE SELECTED RAMP RATE

NOTE Rapid discharging of the magnet requires either an energy absorbing component or a four-quadrant power supply. If a unipolar supply is used without an energy absorbing component, only the resistance of the power leads is available as a mechanism for discharging the magnet.

1. Ensure that the persistent switch heater is on and the switch heated time has expired. Ramping is disabled during the switch heating period.
2. Check the value of the Voltage Limit. Refer to page 66.
3. For *unipolar power supply systems*, an energy absorber is usually required to ramp a magnet down in a reasonable amount of time. When ramping the system down at the fastest rate achievable, observe the voltage appearing at

the power supply output terminals either by a voltmeter on the front of the supply or by a DVM measurement. If the supply output voltage is approximately zero, the resistance of the power leads (not the Model 430 Programmer) is dictating the maximum ramp down rate. An energy absorber is necessary to increase the rampdown rate.

CANNOT CHARGE THE MAGNET TO DESIRED FIELD

1. For *unipolar power supply systems*, if the power supply ramps to full output current after the supply output voltage exceeds approximately 0.7 V, verify the polarity of the power supply protective diode. **Ensure the protective diode remains installed** across the output terminals of the power supply with the anode at the negative terminal and the cathode at the positive terminal.
2. Ensure any voltage or current adjust controls on the front of the power supplies that may override remote programming are in their fully clockwise position.
3. Ensure that the Model 430 Programmer supply setup submenu is configured to match the connected power supply, e.g. check that the Model 430 Programmer is configured for the proper voltage-to-voltage programming range according to page 79.
4. If the connected magnet has a persistent switch, verify the switch heater output is properly connected to the Magnet Station connector (see page 211) and the appropriate connector on the cryostat.

CANNOT PLACE THE MAGNET IN PERSISTENT MODE

1. Ensure there is adequate LHe level in the cryostat to allow the persistent switch to cool to the superconducting state.
2. Ensure the persistent switch cooldown time is adequate (see page 90). Conduction-cooled systems may have much longer switch cooldown periods than wet magnet systems. Optionally use the magnet voltage-based switch transition detection method if the shortest possible cooldown time is an important consideration (see page 88).

CANNOT BRING THE MAGNET OUT OF PERSISTENT MODE

1. If a PSwitch Error was indicated when the **PERSIST. SWITCH CONTROL** key was used to turn on the persistent switch heater current, then there is a problem with the wiring to the persistent switch heater. Check the continuity between the persistent switch heater power supply output pins at the rear panel **MAGNET STATION CONNECTORS** and the connectors on the magnet support stand top plate. Refer to page 212.
2. Verify that the output of the persistent switch heater is set to the appropriate value. Refer to page 112.
3. Ensure that there is sufficient time for the switch to warm before the power supply current is changed. Increase the persistent switch heating time if needed. Refer to page 89.

THE MAGNET QUENCHES FOR NO APPARENT REASON

1. Ensure the magnet is not being charged at a ramp rate exceeding the capabilities of the magnet. Exceeding the designed rate for ramping the magnet may cause a quench or it may turn on protective diodes on the magnet which may appear very similar to a quench.
2. Ensure there is adequate LHe level in the cryostat. For systems operating at less than 4.2K, ensure the magnet is cooled to the temperature specified by the magnet manufacturer.
3. For conduction-cooled magnets, ensure the magnet temperature is proper and in accordance with the magnet manufacturer's specifications.
4. Disable the Model 430 Programmer quench detection feature (see page 128) if you suspect the Model 430 Programmer is falsely indicating a quench condition.

CANNOT LOWER THE MAGNET FIELD

1. Ensure the magnet is not in the persistent mode. Refer to page 121 for the procedure to remove a magnet from the persistent mode of operation.
2. If a PSwitch Error was indicated when the **PERSIST. SWITCH CONTROL** key was used to turn on the persistent switch heater current, then there is a problem with the wiring to the persistent switch heater. Check the continuity between the persistent switch heater power supply output pins at the rear panel **MAGNET STATION CONNECTORS** and the connectors on the magnet support stand top plate. Refer to page 212.

THE SYSTEM CURRENT RAMPS SLOWLY FROM ZERO

With the Model 601 Energy Absorber in the system, an initial charging delay will be observed when operating without an inductive load (e.g. a persistent switch is not heated on a connected magnet).

1. To decrease the amount of time delay, increase the ramp rate to 1 A/sec or greater value. Remember to decrease the ramp rate, if necessary, before heating the persistent switch of the connected magnet and attempting to ramp the current.
2. The charging delay will not be observed when operating with an inductive load.

THE MODEL 601 FAULT LED ENERGIZED WITH AUDIBLE ALARM

1. Verify that the supplied external DC power converter is connected to the rear of the Model 601, and the AC power cord is also connected to the appropriate power receptacle.
2. If the DC power converter is connected properly, observe if an internal green LED is energized by looking through the Model 601 rear-panel grating. If the green LED is energized, then the DC power converter is operating correctly.

If the internal green LED is not energized, then the DC power converter has

failed, or AC power to the DC power converter has been lost. Contact an Authorized AMI Technical Support Representative for a replacement.

3. If the DC power converter is connected and the internal green LED is energized, then the FAULT LED indicates the failure of an internal energy absorbing element. Do not continue to operate the unit and contact an Authorized AMI Technical Support Representative for further instructions.

THERE IS EXCESSIVE LHe BOIL-OFF DURING OPERATION

Excessive LHe consumption is usually attributable to one or both of the following: thermal energy being conducted into the cryostat or electrical energy being converted into thermal energy within the cryostat. Analyzing the circumstances under which the high boil-off occurs will help determine what is causing the problem.

1. For magnets equipped with switches for persistent operation, verify that the persistent switch heater power supply is operating at the proper current for the installed switch. Excessive currents cause excessive boiloffs. The typical switch requires approximately 45 mA to function correctly. Refer to the documentation provided with the magnet for proper operating current. See page 112.
2. Verify that the protective diodes on the magnet are not turning on. Damaged diodes may short causing current to flow through them whenever magnet current flows and cause excessive heating. This can be identified by observing a change in the apparent field-to-current ratio since some of the current is bypassing the coil. If the boil off rate returns to normal with the magnet de-energized, this may indicate a defective diode.
3. Ensure that there are no inadvertent thermal paths between the cryogenic environment and the 300K environment. Ensure all transfer lines are removed from the cryostat; check the position of break-away vapor-cooled current leads.
4. Ensure the LHe level sensor is not continuously energized if continuous level indication is not necessary.
5. Ensure the vacuum in vacuum-jacketed dewars is of sufficiently low pressure.

CANNOT DISPLAY THE MAGNETIC FIELD STRENGTH, ONLY CURRENT

Enter a coil constant in accordance with directions on page 83.

NOTE Setup menu limits are always required in terms of current.

CANNOT USE REMOTE COMMUNICATIONS COMMANDS

1. Verify your communications cable integrity and wiring. Refer to page 221 and page 222 for wiring of remote communications connectors.
2. Check to make sure you are sending the correct termination to the Model 430 Programmer. If you are using RS-232, make sure the baud rate, number of stop bits, and data bits/parity settings of the host device are matched to

those of the Model 430 Programmer (see page 147). If you are using Ethernet communications, check all Model 430 Programmer network settings (see page 108).

3. Check your host communications software and make sure it is recognizing the return termination characters from the Model 430 Programmer. The return termination characters are <CR><LF>.
4. If the Model 430 Programmer is responding repeatedly with errors, try a device clear command (DCL) or powering the Model 430 Programmer off and then back on. Be sure you are sending valid commands.

MAGNET CURRENT DRIFTS UNACCEPTABLY WHILE COOLING PSWITCH

1. Set the PSwitch Cooling Gain to 25% (see page 91) and cool the switch. Observe the current on the front of the Model 430 Programmer while the persistent switch is cooling
2. If the switch will not lock (cool to superconducting), resulting in a PSW lock error, reduce the PSwitch Cooling Gain by several percent and attempt cooling the switch again.
3. If the switch cools but the magnet current has excessive drift during cooling, increase the PSwitch Cooling Gain value by several percent.

MODEL 430 APPEARS TO LOCK UP WHEN CONNECTING TO NETWORK

NOTE If the IP Address Assignment value is changed, the Model 430 Programmer power must be cycled off and then back on to complete the change.

On power-up, when connecting via Ethernet (Internet Protocol), the Model 430 will display the firmware version screen until an IP address has been obtained. On busy or slow networks, IP address assignment may take several seconds (even as much as a minute or so on very slow networks). The additional time required may give the temporary false appearance of Model 430 "lockup".

ADDITIONAL TECHNICAL SUPPORT

If the cause of the problem cannot be located, contact an AMI Technical Support Representative at (865) 482-1056 for assistance. The AMI technical support group may also be reached by internet e-mail at **support@americanmagnetics.com**. Additional technical information, latest software releases, etc. are available at the AMI web site at:

<http://www.americanmagnetics.com>

Do not return the Model 430 Programmer or other magnet system components to AMI without prior return authorization.

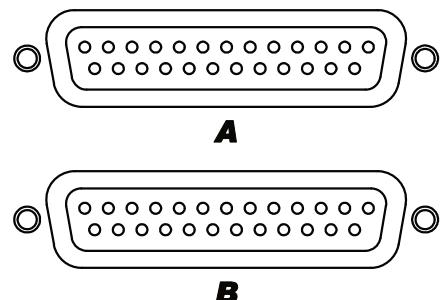
RETURN AUTHORIZATION

Items to be returned to AMI for repair (warranty or otherwise) require a return authorization number to ensure your order will receive proper attention. Please call an AMI representative at (865) 482-1056 for a return authorization number before shipping any item back to the factory.

Appendix

MAGNET STATION CONNECTORS

**MAGNET
STATION**



The two 25-pin D-sub female Magnet Station Connectors are identically wired and connected pin-for-pin internally. Spare connections may be used for custom coil taps or other signals.

NOTE For maximum noise immunity, use shielded cabling and connect one end of the shield to the Magnet Station Connector shell.

The connectors provide an interface for connecting a *single* integrated instrumentation cable from the magnet support stand to the Model 430 Programmer. The Model 430 Programmer can then be used to distribute the signals to the appropriate instruments or data acquisition systems. The LHe level and temperature sensor signals are also internally routed to the LHe Level / Temp Connectors.

If the Model 430 Programmer is purchased as part of a magnet system, a Magnet Station Connector instrumentation cable will be provided with the system.

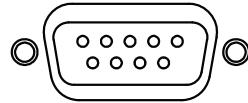
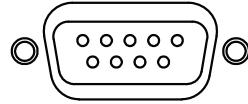
Magnet Station Connectors Pin Definitions

Pin	Function	Pin	Function
1	LHe Sensor I+ (Red)	14	spare
2	LHe Sensor I- (Black)	15	spare
3	LHe Sensor V- (Yellow)	16	spare
4	LHe Sensor V+ (Blue)	17	spare
5	Temperature Sensor I+ (Red)	18	spare
6	Temperature Sensor I- (Black)	19	spare
7	Temperature Sensor V- (Yellow)	20	spare
8	Temperature Sensor V+ (Blue)	21	spare
9	Persistent Switch Heater I+ (Red)	22	spare
10	Persistent Switch Heater I- (Black)	23	spare
11	Magnet Voltage Tap V+ (Yellow)	24	spare
12	Magnet Voltage Tap V- (Blue)	25	spare
13	spare		

NOTE The spare pins in the Magnet Station cable can be used for additional temperature sensors or other functions in various magnet system configurations. These custom pin functions will be documented with a specific magnet.

LHe LEVEL / TEMP CONNECTORS

LHe LEVEL / TEMP SENSORS

**A****B**

LHe Level / Temp Connectors Pin Definitions

Pin	Function
1	LHe Sensor I+ (Red)
2	Temperature Sensor I+ (Red)
3	Temperature Sensor V- (Yellow)
4	Temperature Sensor I- (Black)
5	Temperature Sensor V+ (Blue)
6	LHe Sensor V- (Yellow)
7	LHe Sensor I- (Black)
8	LHe Sensor V+ (Blue)
9	not used

The two 9-pin D-sub male LHe Level / Temp Connectors are identically wired and connected pin-for-pin internally.

WARNING

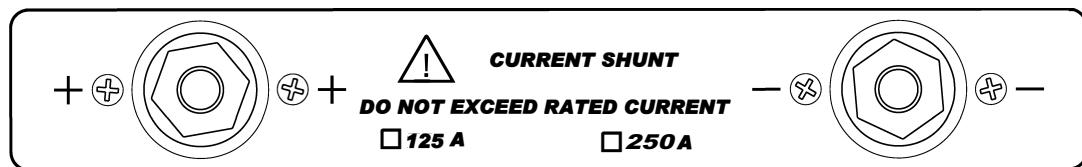


Although the LHe level sensor connector terminals are isolated from earth ground and therefore touching one terminal is not hazardous, the voltage between terminals is at a hazardous potential if an AMI Liquid Helium Level Instrument is connected and energized. The LHe level sensor pins are designed for use with an AMI LHe sensor and the wiring for the sensor is to have no live parts which are accessible. Conductors connected to its terminals must be insulated from user contact by basic insulation rated for 150 VAC (Category I).

The connectors route the incoming signals from the Magnet Station Connectors to external level and/or temperature instruments. If an AMI Liquid Level Instrument is purchased (with LHe measurement option) with the Model 430 Programmer and magnet system, an LHe level cable will be provided.

NOTE For maximum noise immunity, use shielded cabling and connect one end of the shield to the LHe Level / Temp Connector shell.

PROGRAMMER SHUNT TERMINALS



The shunt terminals should be connected so that positive conventional current flows from the + terminal to the - terminal. Refer to the Installation section beginning on page 13 for a detailed description of the system interconnections for a specific system configuration.

WARNING



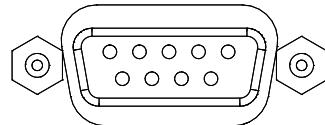
Exercise caution near the shunt terminals when operating a magnet. Metallic objects shorted across the shunt terminals may conduct large DC currents which are capable of melting the object and causing severe burns.

CAUTION

Do not overtighten the nuts on the shunt terminals of the Model 430 Programmer (refer to specifications in the table on page 8). Overtightening can result in damage to the terminals.

CURRENT TRANSDUCER CONNECTOR

CURRENT TRANSDUCER

**CAUTION**

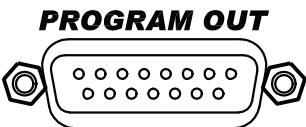
Operating the system without the connection between the Model 430 and the current transducer (CT) can result in loss of control, and may damage the CT.

The current transducer connector, which is only present for the High-Stability Option or systems with a maximum current greater than 250 A, provides pins for connection of the external current transducer (CT) to the Model 430 Programmer. Power to the CT is also provided via this connector. The connector is a 9-pin D-sub female connector with the shell lugs connected to the Model 430 Programmer chassis ground.

Current Transducer Connector Pin Definitions

Pin	Function
1	Sense Out –
2	not used
3	READY/NOT READY Status Sense
4	Power Input: 0 VDC (common)
5	Power Input: -15 VDC
6	Sense Out +
7	not used
8	READY/NOT READY Status Sense
9	Power Input: +15 VDC

PROGRAM OUT CONNECTOR



Program Out Connector Pin Definitions

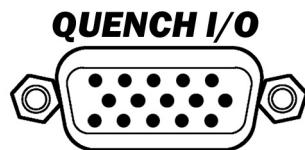
Pin	Function	Pin	Function
1	not used	9	not used
2	not used	10	not used
3	not used	11	Program Out Voltage
4	Program Out Common	12	not used
5	not used	13	not used
6	not used	14	not used
7	not used	15	not used
8	not used		

The Program Out 15-pin D-sub male connector provides up to a -10 VDC to +10 VDC output designed to drive the remote *voltage-to-voltage* programming input of a connected power supply.¹ Refer to “Installation” on page 13 for a detailed description of the system interconnections. Pin 11 of the Program Out connector is the program out voltage. Pin 4 of the Program Out connector is the output return. All other pins of the Program Out connector are unused.

NOTE For maximum noise immunity, the Model 430 Programmer chassis and the chassis of any connected power supply should be tightly electrically coupled. This can be accomplished through the rack mounting or by using a grounding strap between the chassis.

1. The *optional* Short-Sample Mode operates the connected power supply in voltage-to-current mode. See page 226.

QUENCH I/O CONNECTOR



The Quench I/O connector provides pins for external quench detection input, external rampdown input, quench detection output, and several other Model 430 status output signals (refer to the table below). The Quench I/O connector is a high density 15-pin D-sub male connector. The shell lugs of the connector are connected to the Model 430 Programmer chassis ground.

Quench I/O Connector Pin Definitions

Pin	Polarity	Function
1	n/a	Quench Output (Model 430 Programmer NO ^a dry contacts)
2		
3	n/a	Relay K3 Output (Model 430 Programmer NO dry contact - see Pin 8)
4	circuit common	Quench Input (customer-supplied external NO dry contacts) NOTE: The Model 430 has a 1K Ohm pull-up resistor for this input.
5	+	
6	circuit common	External Rampdown Input (customer-supplied external NO dry contact) NOTE: The Model 430 has a 1K Ohm pull-up resistor for this input.
7	+	
8	n/a	Relay K3 Output (see Pin 3)
9	n/a	Magnet Energized Relay (K2) Output (Model 430 Programmer NO dry contacts)
10		
11	n/a	At Target Relay (K4) Output (Model 430 Programmer NO dry contacts)
12		
13	n/a	Leads Energized Relay (K5) Output (Model 430 Programmer NO dry contacts)
14		
15	n/a	Future input (not used)

a. NO in this context means "Normally Open".

EXTERNAL QUENCH DETECTION INPUT

The external quench detection input allows the user to facilitate his own quench detection circuitry, the output of which is wired to the Model 430 Programmer. The external input overrides the internal quench detection function of the Model 430 Programmer and cannot be disabled.

CAUTION **The external quench detection input is a dry contact input, not galvanically isolated from the Model 430 Programmer internal circuitry. To avoid noise problems and potential damage to the Model 430 Programmer, it is very important that the dry contacts to which the input is connected be galvanically isolated from any external circuitry.**

It is recommended that the external quench detection input be driven by the contacts of a low level dry contact relay, which will galvanically isolate the input from all other circuitry.

When the external quench detection input pins (pins 4 and 5 of the Quench I/O connector) are shorted together, it is the same as if an Model 430 Programmer internal quench detection occurred. Refer to page 127 for details.

NOTE **The Model 430 Programmer takes approximately 600 microseconds from the time it detects the external quench input to execute the quench condition process. Refer to page 128 for more information.**

EXTERNAL RAMPDOWN INPUT

When enabled², the external rampdown input initiates a rampdown of the magnetic field of the magnet when triggered.

CAUTION **The external rampdown input is a dry contact input, not galvanically isolated from the Model 430 Programmer internal circuitry. To avoid noise problems and potential damage to the Model 430 Programmer, it is very important that the dry contacts to which the input is connected be galvanically isolated from any external circuitry.**

It is recommended that the external rampdown input be driven by the contacts of a low level dry contact relay, which will galvanically isolate the input from all other circuitry.

When the external rampdown input pins (pins 6 and 7 of the Quench I/O connector) are shorted together for more than 10 milliseconds, the Model 430 Programmer enters external rampdown mode. If the magnet

2. Refer to "Enable External Rampdown" on page 98.

is in driven mode, the Model 430 Programmer ramps the magnet field/current to zero. If the magnet is in persistent mode, the Model 430 Programmer ramps the power supply to match the last known persistent magnet current, turns on the persistent switch heater, waits the specified heated time (or detects the transition using the magnet voltage per the *Pswitch Transition* setting³) and then ramps the magnet field/current to zero.

This function may be used with the AMI Model 1700 Liquid Level Instrument⁴. The level instrument has a NO relay associated with the low level condition and this contact closure can be connected to the External Rampdown Input so that when a low helium level occurs in a system, the magnet is safely and automatically ramped down, preventing a magnet quench. AMI offers a cable for this purpose or the user can make a suitable cable to connect pins 5 and 6 of the Aux I/O connector of the Model 1700 instrument to pins 6 and 7 of the 430 Programmer, Quench I/O connector.

CAUTION The separate external segmented-rampdown option described below ignores the Voltage Limit during the rampdown process.

NOTE If the number of external-rampdown ramp segments is set to zero, the modified rampdown is not used and the standard ramp rate table will be effective during external rampdown. The Model 430 Programmer defaults to an empty rampdown table (number of segments equal zero).

A separate, optional segmented-ramp-rate table is available for external rampdown. This option is accessible only via the external interface commands (see page 172).

EXTERNAL QUENCH DETECTION OUTPUT

The external quench detection output is a set of dry contacts (pins 1 and 2 of the Quench I/O connector) which close when the Model 430 Programmer internal circuitry detects a quench condition. Note that the Model 430 Programmer internal quench detection must be enabled to assure that the Model 430 Programmer will indicate a detected quench (see page 93).

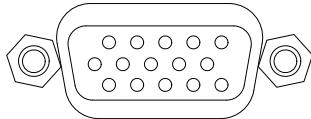
The contacts remain shorted (when a quench has been detected) until the **RESET QUENCH** SHIFT-key is used to clear the quench condition.

3. See page 88.

4. Or the Model 13x series of Liquid Helium Level Instruments for legacy systems.

AUXILIARY INPUTS CONNECTOR

AUX INPUTS



The Aux Inputs connector provides pins for external voltage inputs, reserved for future use. The shell lugs of the connector are connected to the Model 430 Programmer chassis ground. The Aux Inputs connector is a high density 15-pin D-sub female connector.

Aux Inputs Connector Pin Definitions

Pin	Function	Pin	Function
1	Aux Input 1 + (Vm +) ^a	9	Aux Input 4 –
2	Aux Input 1 – (Vm –)	10	not used
3	Aux Input 2 + (Vss +) ^b	11	Aux Input 5 +
4	Aux Input 2 – (Vss –)	12	Aux Input 5 –
5	not used	13	Aux Input 6 +
6	Aux Input 3 + (Tmax +) ^c	14	Aux Input 6 –
7	Aux Input 3 – (Tmax –)	15	not used
8	Aux Input 4 +		

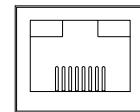
a. Auxiliary Input 1 is consumed by the magnet voltage input internally connected to the Magnet Station connector (pins 11+ and 12–) for *Model 430 units that ship with version 3.00 firmware or later*. It is used for the magnet voltage-based switch transition detection logic and is not available for general use. See page 88 for more information.

b. Auxiliary Input 2 is used for the sample voltage taps (Vss) for the optional Short-Sample operational mode. See page 226 for more information.

c. Auxiliary Input 3 is optionally used for the Tmax 0 to 10VDC signal from an external temperature monitor. See page 97 for more information.

Each input pin has a 1 megohm resistor to analog circuit common. The inputs are differential inputs. Aux Input 1 and Aux Input 2 have a ± 1 V nominal input voltage range. Aux Input 3, Aux Input 4, Aux Input 5 and Aux Input 6 have a ±10 V nominal input voltage range.

ETHERNET CONNECTOR

ETHERNET

The Ethernet connector provides visual (LED) indications of the status:

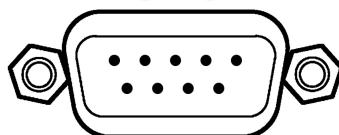
1. Steady green when a link is established.
2. Blinking amber for network activity as network packets are received or transmitted.

Ethernet RJ-45 Connector Pin Definitions

Pin	Mnemonic	Function
1	TXD+	Transmit differential output +
2	TXD-	Transmit differential output -
3	RXD+	Transmit differential input +
4		not used
5		
6	RXD-	Transmit differential input -
7		not used
8		

RS-232 CONNECTOR

RS-232



The RS-232 connector for legacy devices (pre-Rev 9 internal PCB with firmware prior to version 3.0, see page 197) is a standard **DTE** 9-pin D-sub male connector. This connector requires a gender changer *and* null modem adapter to connect with COTS USB-to-serial cables.

The RS-232 connector for the latest Model 430 revision is a standard **DCE** 9-pin D-sub female connector. The female connector *is compatible* with COTS USB-to-serial cables available in the general marketplace. It should be plug-and-play with no other required adapters.

The detailed pinout function for both forms of the connector are detailed in the graphic below:

DB9 Male
Legacy (Firmware earlier than 3.x)

A schematic diagram of a DB9 male connector. The pins are numbered 1 through 9. Pin 1 is at the top, followed by 2, 3, 4, 5 in the top row. In the middle row, 6 is on the left, 7 is in the middle, and 8 is on the right. In the bottom row, 9 is at the bottom. Arrows point from the pin numbers to their respective positions in the connector.

Pin	Signal Direction	Signal Name	Signal Function
1	→	CD	Carrier Detect
2	→	RxD	Receive Data
3	→	TxD	Transmit Data
4	→	DTR	Data Terminal Ready
5	—	GND	Ground
6	→	DSR	Data Set Ready
7	→	RTS	Request To Send
8	→	CTS	Clear To Send
9	→	RI	Ring Indicator

→ Transmitted from DTE Device
← Received by DTE Device

DB9 Female
Firmware 3.x or Later

A schematic diagram of a DB9 female connector. The pins are numbered 1 through 9. Pin 1 is at the top, followed by 2, 3, 4, 5 in the top row. In the middle row, 6 is on the left, 7 is in the middle, and 8 is on the right. In the bottom row, 9 is at the bottom. Arrows point from the pin numbers to their respective positions in the connector.

Pin	Signal Direction	Signal Name	Signal Function
1	←	CD	Carrier Detect
2	→	TxD	Transmit Data
3	→	RxD	Receive Data
4	→	DTR	Data Terminal Ready
5	—	GND	Ground
6	→	DSR	Data Set Ready
7	→	CTS	Clear To Send
8	→	RTS	Request To Send
9	→	RI	Ring Indicator

→ Transmitted from DCE Device
← Received by DCE Device

ABBREVIATIONS AND ACRONYMS USED IN THIS MANUAL

Abbreviations and Acronyms

Term	Meaning
AC; ac	Alternating Current; strictly, electrical <i>current</i> that periodically reverses direction. Typically used also to describe an electrical power source in terms of the <i>voltage</i> . For example, 240 VAC.
ASCII	American Standard Code for Information Interchange; numerical representation of characters such as 'a' or '@' or an action (such as line-feed); 'plain' raw text with no formatting such as tabs, bold or underscoring
COTS	Commercial Off-the-Shelf
<CR>	Text carriage-return (\r) character
CT	Current Transducer
CTS	DTE clear-to-send signal
DB9	Type of electrical connector containing 9 pins arranged in two parallel rows of 4 pins and 5 pins each)
DB15	Type of electrical connector containing 15 pins arranged in two parallel rows of 7 pins and 8 pins each
D-Sub	Term referring to the family of connectors containing an odd number of pins in two parallel rows with a 1-pin difference in pins-per-row (DB9, DB15, and DB25 are most common)
DC; dc	Direct Current; strictly, electrical <i>current</i> that flows in only one direction. Typically used also to describe an electrical power source in terms of the <i>voltage</i> . For example, 12 VDC.
DCE	Data Communication Equipment: The devices of a communications network, such as modems, that connect the communication circuit between the data source and destination (DTE's).
DHCP	Dynamic Host Configuration Protocol; a computer networking protocol which dynamically distributes the IP address to networked devices
di/dt	Current flow rate of change
DSP	Digital Signal Processing; digital representation and processing of signals typically converted to/from analog signals external to the processor.
DTE	Data Terminal Equipment: the source or destination of data in a communication connection. DTE's are connected to DCE which in turn is connected to the communication channel.
EFT	Electrical Fast Transient
EMC	Electromagnetic Compatibility

Abbreviations and Acronyms (Continued)

Term	Meaning
E_o	Power supply output voltage
ESD	Electrostatic Discharge
FIFO	First-in / First-out
FTP	File Transfer Protocol
i, I	Electrical current flow
I_c, I_c	Critical current, the maximum recommended current for at a given superconductor temperature
I_o	Power supply output current
IEC	International Electrotechnical Commission
IEEE	Institute of Electrical and Electronics Engineers
I/O	Input/Output; The hardware and associated protocol that implement communication between information processing systems and/or devices. Inputs are the signals or data received by the system or device, and outputs are the signals or data sent from it.
IP	Internet Protocol; when used with "address", refers to a numerical internet address
IR	The product $I \times R$: the voltage developed by electrical current flow (I) through a resistance (R)
kG	kilogauss: a magnetic field unit of measurement
L	Electrical circuit inductance measured in henries; superconducting magnets act as nearly perfect inductors when at superconducting temperatures.
LED	Light-Emitting Diode; a semiconductor device that emits light when energized - used for visual status indication
<LF>	Text line-feed (\n) character
LHe	Liquid helium
LN2	Liquid nitrogen
Max	Maximum
Min	Minimum
ms, msec	Milli-seconds
NC	Normally Closed used in the context of relay contacts
NO	Normally Open used in the context of relay contacts
nom	Nominal

Abbreviations and Acronyms (Continued)

Term	Meaning
P/S	Persistent switch; a switch which, if perfectly realized, has zero resistance when at superconducting temperatures. An integrated heater element allows the switch to be heated for purposes of charging or discharging a superconducting magnet.
pk	Peak
PSw	Persistent switch
PSwitch	Persistent switch
RF	Electromagnetic radiation in the radio frequency spectrum
R _{lead}	Electrical circuit lead or wiring resistance
RTS	DTE ready-to-send signal
RS-232	RS-232 is a long-established standard and protocol for relatively low speed serial data communication between computers and related devices; originally established for teletypewriter communication.
SCPI	Standard Commands for Programmable Instruments
STP	Standard Temperature and Pressure
T	Tesla: a magnetic field unit of measurement = 10 kilogauss
Temp	Temperature
USB	Universal Serial Bus
V	Volts
V-I	Voltage-controls-Current; the power supply mode in which the Program Out voltage is in direct ratio to the output current of a connected power supply; used for Short-Sample mode by the Model 430 Programmer.
V-V	Voltage-controls-Voltage; the power supply mode in which the Program Out voltage is in direct ratio to the output voltage of a connected power supply; used by the Model 430 Programmer for superconducting magnet operation.
VA	Volt-amperes ($V \times I$); a unit of electrical reactive power
VFD	Vacuum Fluorescent Display; an electronic display device which, unlike liquid crystal displays, can emit very bright, high contrast light in various colors.
V _{lead}	Voltage ($i \times R$) developed across circuit lead or wiring resistance due to high current flow
V _m	Magnet voltage
V _s	Power supply voltage
V _{ss}	Short-sample voltage

SHORT-SAMPLE MODE⁵

The Model 430 also features the ability to operate as a short-sample controller. *Short-sample* refers to samples of superconducting wires of relatively short length as compared to lengths required for a wound magnet, typically tested in the presence of various background magnetic field levels. The short-sample test is designed to determine critical current density limits for various field levels for the wire sample.

In the Short-Sample Mode, the Model 430 commands a connected power supply in voltage-controls-current mode, i.e. the Program Out connector (see page 216) outputs a voltage that corresponds to the current output limit of a connected power supply. *The connected power supply must support remote current limit programming by external analog voltage.*

CAUTION

The Short-Sample Mode includes a sample quench detection feature. It is recommended that the sample quench detection always be ON and that voltage taps across the sample be connected to Auxiliary Input 2. It is possible to destroy a sample (via overheating) if the Model 430 is allowed to continue ramping or hold a current for a sample that has quenched. Samples should not be left unattended when actively ramping the sample current.

If the sample has quenched, the Model 430 will indicate the sample current at which the quench was detected and immediately command and hold the supply output current at 0 A until the sample quench detection state is cleared.

The typical system setup for short-sample testing will require a data acquisition computer to query and record the sample voltage vs. sample current and an application to plot the real-time result.

In Short-Sample Mode several features of the Model 430 applicable only to operation with a magnet are disabled. The changes include:

- All menu items associated with the Persistent Switch operation are removed.
- The Voltage Limit function is removed.
- The units display for current is always amperes since *there is no magnet connected to the 430* with an associated coil constant (only the short-sample).
- The sample voltage is measured via Auxiliary Input 2 (see page 220) and is reported in the default display as V_{SS} in microvolts. An external gain factor of

5. Contact an AMI Technical Support Representative for details on how the Short-Sample Mode can be enabled and the latest data acquisition options for microvolt sampling.

10,000 is required for the sample voltage signal connected to Auxiliary Input 2 in Short-Sample Mode.⁶

+50.00 A	-	Status: Holding
+24.53 Vss		Short-Sample Mode

NOTE The sample voltage must be connected to the Auxiliary Input 2 for the sample quench detection feature to function. Sample quench detection is defined as a sample voltage magnitude greater than 90 microvolts. The quench threshold of 90 microvolts is a fixed internal parameter.

- The custom Supply parameter “V-V Mode Input Range” is changed to “V-I Mode Input Range” to reflect voltage-commands-current operation of a connected power supply.
- The Load submenu of the Setup menu is limited to four parameters: Stability Setting, Current Limit, Sample Voltage Null, and Sample Quench Detect.

A Stability Setting of 0% is recommended for Short-Sample Mode unless otherwise directed by an AMI Technical Support Representative.

The Current Limit in this context refers to the maximum allowable current through the short-sample under test.

The Sample Voltage Null feature when exercised will quickly average several sample voltage (Vss) measurements and determine an offset to apply to the sample voltage to report 0 Volts for the Vss display and remote query. *This offset is not saved between power cycles* of the Model 430 and may be exercised as many times as desired to null out sample voltage offsets.

+50.00 A	-	Sample Voltage (Vss) Null
+24.53 Vss		►Press ENTER to Zero Vss

- The following remote commands and queries generate the error:

-109, "N/A in present mode"

when the Model 430 is operating in Short-Sample Mode:

```

CONFigure:VOLTage:LIMit
CONFigure:COILconst
CONFigure:RAMPDown (all subcommands)
CONFigure:RAMP:RATE:FIELD
CONFigure:FIELD:UNITS
CONFigure:PSwitch (all subcommands)

```

6. AMI offers an external low-noise amplifier to scale microvolt sample voltages to a range that can be read by AUX Input 2.

```
CONFigure:LOCK:PSwitch:CONTRoL
CONFigure:LOCK:PSwitch:SETtings
CONFigure:LOCK:VOLTage:LIMit
CONFigure:LOCK:VOLTage:VS-VM
CONFigure:LOCK:QUench:RATE
CONFigure:LOCK:FIELD-CURRent
CONFigure:LOCK:FIELD:UNITS
CONFigure:LOCK:COILconst
CONFigure:LOCK:ABsorber
CONFigure:LOCK:RAMPDown
CONFigure:QUench:RATE
CONFigure:ABsorber
INDuctance?
VOLTage:SUPPLY?
VOLTage:LIMit?
VOLTage:MAGnet?
CURRent:MAGnet?
COILconst?
PSwitch? (all subcommands)
PERSistent?
LOCK:PSwitch:CONTRoL?
LOCK:PSwitch:SETtings?
LOCK:CURRent:RATING?
LOCK:VOLTage:LIMit?
LOCK:VOLTage:VS-VM?
LOCK:QUench:RATE?
LOCK:FIELD-CURRent?
LOCK:FIELD:UNITS?
LOCK:COILconst?
LOCK:ABsorber?
LOCK:RAMPDown?
QUench:RATE?
ABsorber?
RAMP:RATE:FIELD?
FIELD:MAGnet?
FIELD:TARGet?
FIELD:UNITS?
FIELD:PRESent?
```

- The following remote queries are available only in Short-Sample Mode:

CURRent:SAMple?
Returns the sample current in amperes.

VOLTage:SAMple?
Returns the sample voltage in microvolts.

A

abbreviations and acronyms 223
 absolute limits 132
 AMI internet e-mail address 208
 AMI web address 208
 applicable hardware x

B

beep
 editing PSw P/S ramp rate 64
 editing ramp rate 64
 error messages 183
 incorrect password 101, 108
 locked command 101
 mismatch between pswitch and power supply currents 123
 on initiate ramping 61
 on select supply 77
 on setting Current Limit below TARGET FIELD SETPOINT 92
 on setting TARGET FIELD SETPOINT above Ic 95
 parameter outside range 55, 132
 pswitch 59
 pswitch did not properly transition to the superconducting state 120
 brightness 99

C

cable interconnections. See interconnects
 canceling entry 55
 cleaning - see routine maintenance
 coil constant
 acceptable values 83
 calculate 83
 defined 83
 lock 105
 command
 error messages 183
 device errors 187
 query errors 185
 overview 141
 command handshaking 145
 condition register 142
 event register 142
 SCPI introduction 141
 standard event register 144
 status byte 143
 status system 141
 status system diagram 142
 reference
 locking 166

protection commands 166
 quench control 178, 179
 ramping commands 172
 ramping states 175
 status commands 155
 switch heater control 177
 system commands 152
 trigger commands 182
 trigger functions 181
 summary
 conventions 133
 protection commands 137
 protection configuration queries 137
 quench state 139, 140
 ramp configuration 138
 ramping state 139
 setup configuration queries 135
 switch heater 139
 system-related commands 134
 trigger control 140

compatible power supplies x, 83

configuration

system
 bipolar high-stability supply 24
 bipolar supply 21
 four-quadrant high-current high-stability supply 31
 four-quadrant high-current supply 28
 four-quadrant low-current supply 34
 general 16
 non-standard 43
 power lead size 16
 standard configurations 7
 third-party supplies 43
 unipolar supply 18

connectors

analog I/O 18, 23, 26, 28, 31
 aux inputs 220
 current transducer signal 215
 Ethernet communication 20, 23, 27, 30, 33, 36, 221
 LHe level/temp 17, 20, 23, 26, 28, 31, 34, 213
 magnet station 17, 20, 23, 26, 28, 31, 34, 211
 program out 16, 18, 23, 26, 28, 31, 34, 216
 quench I/O 20, 23, 26, 30, 33, 36, 217
 RJ-45 - see Ethernet
 RS-232 serial communication 20, 23, 27, 30, 33, 36, 222
 shunt terminals 214
 system interconnect 16

current limit 47, 61, 64, 65, 66, 68, 74, 101, 114, 116, 162, 176

current limit symmetry 92

current transducer

connector 215
 current direction 24, 31

- power 50
D
 data logging 181
 de-energizing the system 50
 default display modes 51
 default password 101
 default settings 132
 DHCP 110, 111, 194, 199
 diode
 light emitting - see LED
 protective - see protective diode
 display
 asterisk 54, 57
 brightness 99
 current 47
 field / current 51
 field units 52
 magnet quench indicator 53
 mode status indicators 53
 up/down arrow 55
 voltage 52, 69
 display brightness 99
 dual-quadrant operation 10, 24

E
 encoder - see fine adjust knob
 energizing the system 49
 energy absorber
 fault 206
 lock 106
 operation 44, 46
 present 86
 entering values 54
 error messages 183
 ESD precautions 197, 201
 Ethernet
 cable 189, 194
 configuration
 connector 148, 194, 221
 termination characters 148
 null-modem/crossover cable 189, 194, 198
 port 148, 189, 194
 slow connection 208
 stateless connection 148
 Telnet broadcast 148
 VISA 148
 Ethernet link status
 blinking amber 221
 steady green 221
example
 Ethernet communication setup 194
 magnet specification sheet 112
 Model 430 remote control application 189
 ramp rate menus 64
 ramping functions 125
 RS-232 communication setup 192
 setup 112
 system setup 112
 external quench detect 93, 99
 external rampdown 98, 99, 106, 129, 130, 131, 175, 179, 180
 external rampdown input 218

F
 FAILURE TO LOAD message 203
 field display 52
 field units 100
 fine adjust knob
 coil constant 83
 current limit 92
 custom ps
 max output current 79
 max output voltage 78
 min output current 78
 min output voltage 78
 displayed up/down arrow 55
 enter key vs. esc. key 56
 immediate affect on the system 56
 lock/unlock 105
 pswitch cooled time 90
 pswitch cooling gain 91
 pswitch current 88
 pswitch heated time 89
 pswitch power supply ramp rate 91
 ramp rate 64
 shift key 69
 slow/very fine resolution 56
 stability setting 81
 target current in HOLDING mode 116
 to adjust numeric values 55
 velocity sensitive 56
 voltage limit 66
 firmware upgrade
 via FTP 198
 firmware upgrades 197
 firmware version screen 208
 four-quadrant operation 11, 77
 fuses 202

I**Ic**

equation 95
how to display value 97
offset 97
slope 97

inductance, calculate 85

installation

cabinet feet 14
earth ground 13
magnet system characteristics 16
mounting 14
power 15
power supply and Programmer ground 16
unpacking 14

interconnects

multi-axis 37

IP Address 108, 110, 111, 147, 148, 194, 199, 208, 223

K**keys**

arrows 57
enter 54, 73
esc 55, 73
ESCAPE 58
fine adjust 55
manual control 115
menu 57
persistent switch control 58
ramp / pause 62
ramp rate 63
ramp to zero 62
ramp/pause 114
shift 55
shift persistent switch control 59
target field setpoint 61
voltage limit 66

L**LED**

current leads energized 72
definition 224
field at target 46, 71, 130
magnet in persistent mode 59, 72, 117, 119, 124, 130, 177
magnet quench 72, 127
Model 601 fault 206, 207
Model 601 internal indicator 206
power-on 71
shift 62

load submenu

calculate inductance 85
coil constant 83
enable external rampdown 98

enable quench detect 93, 99
pswitch cooling gain 91
pswitch cooling time 90
pswitch current 88
pswitch current detect 87
pswitch heated time 89
pswitch installed 86
pswitch ramp rate 90
stability setting 81

locked 100, 107

long discharge time 10

loop gain 82

M**magnet current**

drifts while PSwitch cooling 208
oscillating 203
viewing established persistent current 61, 121

magnet specs 112

Magnet-DAQ application 189
download links 190
Windows installation 191

menu

cursor 57
navigation 57, 73
structure diagram 74

menus

load submenu 80
misc submenu 99
net settings submenu 108
net setup submenu 110
supply submenu 74

misc submenu

coil constant lock 105
current limit lock 105
display brightness 99
display brightness lock 107
external rampdown lock 106
field / current lock 103
field units 100
field units lock 104
fine adjust lock 105
increment / decrement field lock 103
net setup lock 107
operational constants 95
persistent switch settings lock 105
power supply lock 102
pswitch control lock 101
quench detect lock 106
quench rate 94
quench rate lock 106
ramp / pause lock 102
ramp rate time units 100
ramp segments 99

- ramp settings lock 102
 reset quench lock 103
 settings password lock 107
 settings protection 100
 stability settings lock 104
 target field setpoint lock 102
 voltage limit lock 103
 voltmeter lock 105
 Vs / Vm lock 104
- Model 430**
 appears to lock up 208
 remote control application 189
- Model 601 Energy Absorber** 21, 24, 206
- Multi-Axis Systems** 37
- N**
- net settings submenu**
 address assignment 108
 gateway address 110
 IP address 109
 subnet mask 109
 system name 109
- net setup submenu**
 gateway IP address 111
 IP address assignment 110
 subnet mask 111
 system IP address 111
- null-modem/crossover adapter**
 RS-232 192
- null-modem/crossover cable**
 Ethernet 189, 194, 198
 RS-232 147
- O**
- operating modes**
 bipolar 10
 dual-quadrant 10
 four-quadrant 11
 single-quadrant 9
- operating voltage, changing** 15
- operation** 49
- operational constants**
 aux-in 3 offset value 98
 aux-in 3 scale factor 98
 example graph 96
 how to display Ic 96
 Ic offset 97
 Ic slope 97
 protection mode 95
 remote commands 136, 163, 171
 submenu description 95
 temperature display 52, 97
- tmax 97
- P**
- password** 101, 107
- pause** 62
- persistent mode**
 entering 118
 exiting 121
 viewing established magnet current 61, 121
- persistent switch**
 abbreviations 225
 beep 59
 control 117
 cooled time 55, 58, 59, 87, 90, 119, 126, 132
 cooling 53, 60, 90, 91, 115, 119, 124, 208
 cooling gain 55, 59, 60, 87, 91, 132, 208
 current 88
 current detect 87
 defaults
 cooling gain 60
 cooling period 60
 heating period 59
 heated time 55, 59, 87, 89, 118, 122, 132
 heating 16, 53, 60, 71, 89, 115, 117, 124, 130, 131
 heating current 55, 59, 87, 88
 installed? 86, 135, 161
 not installed on magnet 43, 81
 ramp rate 55, 58, 59, 64, 87, 90, 119, 122, 162
 settings lock 105, 170
- power supply**
 4-quadrant 28, 34
 4-quadrant high-stability 31
 applicable x
 bipolar 21
 bipolar high-stability 24
 compatibility 76
 displayed current 47
 displayed voltage 52
 operating characteristics 9
 system integral components 1
 system interconnects 16, 37
 system terminology 223
 system troubleshooting 201
 third-party 43
 unipolar system 18
- power up/down sequence** 49
- powering system off** 50
- powering system on** 49
- power-up test** 45
- programmed current** 61
- protection password** 100, 107
- protective diode**

magnet 206, 207
 power supply 18, 21, 24, 205
pswitch - see persistent switch

Q

quench detection 94, 127
 disabling 93, 128
 enabling 93
 external in/out 128, 217
 indicator 53
 switch failure 129
quench rate 94
quench, magnet xiii

R

ramp modes 115
ramp rate time units 100
ramp segments 99
rampdown, external - see external rampdown
ramping
 automatic ramping 115
 basic relationships 114
 direct current manipulation 116
 example 125
 manual increment or decrement 115
 mode symbols 53
 ramp to zero 116
 segmented 63, 64, 65, 66, 99, 102, 114, 116, 136, 140,
 165, 167, 172, 174, 179, 180, 219
 states 114, 177
remote control application
 frequently asked questions 191
 IP address 190
 links 191
 Magnet-DAQ 189
remote interface reference - see command
return authorization 209
RJ-45 connector - see Ethernet
routine maintenance 197
RS-232 configuration
 connector 192, 222
 null-modem/crossover adapter 192
 parameters 147
 termination characters 147

S

safety
 cryogens xi
 equipment xiv

legend xv
 quenches xiii
segmented ramping 99
 see ramping, segmented
settings 100
settings password 107
settings protection 100
setup
 example 112
 load submenu 80
 misc submenu 99
 supply submenu 74
setup lock 107
Shift Key Commands
 Decrement Field 68
 Field <> Current 68
 Field Units 68
 Fine Adjust 69
 Increment Field 67
 Persist. Switch Control 59
 Persistent Switch Heater Current 69
 Ramp Rate 63
 Reset Quench 67
 Voltage Limit 66
short-circuit operation 44
short-circuit stability setting 82
short-sample mode 226
shunt accuracy 47
shunt current measurement 7
shunt terminals 214
Single-key Commands
 Persistent Switch Control 58
 Ramp / Pause 62
 Ramp To Zero 62
 Target Field Setpoint 61
single-quadrant operation 9
slow networks 208
stability setting ??–45, 69, 81–82, 203
stabilizing resistor 43
stateless communication 148
status indicator 53
 current-limited 53
 temperature-limited 53, 97
 voltage-limited 53
submenus 74
supply submenu
 max output current 79

max output voltage 78
min output current 78
min output voltage 78
select power supply 75
v-v mode range 79

system configuration - see configuration

system features 1

system interconnects

- multi-axis 37
- single-axis 16

T

TeraTerm 192, 195

terminal torque limits 8

test procedure 45

torque limit on terminals 8

troubleshooting

- cannot enter persistent mode 205, 206
- cannot exit persistent mode 205
- charges slowly 204
- communication failures 207
- contacting AMI support 208
- excessive LHe losses 207
- magnet current drifts while PSwitch cooling 208
- Model 601 alarm 206
- no field display 207
- no power 201
- operating voltage 15
- oscillation 203
- quenches 206
- ramps slowly from zero 206
- replacing the battery 203
- replacing the Model 430 fuse 202
- voltage limits 204
- voltage selector 202
- will not charge 203, 205
- will not discharge 204, 206

troubleshooting hints 201

U

unstable power supply 203

V

velocity sensitivity of fine adjust knob 56

ventilation 14

voltage limit 66

Z

zero flux current measurement 2, 7, 31, 50