

Math 156 Project 1

Aatmun Baxi

Problem 1

Part 1

Let $k_a(\mathbf{x}_a, \mathbf{x}'_a) = \Phi_a(\mathbf{x}_a)^T \Phi_a(\mathbf{x}'_a)$, $k_b(\mathbf{x}_b, \mathbf{x}'_b) = \Phi_b(\mathbf{x}_b)^T \Phi_b(\mathbf{x}'_b)$ so that

$$k(\mathbf{x}, \mathbf{x}') = \Phi_a(\mathbf{x}_a)^T \Phi_a(\mathbf{x}'_a) + \Phi_b(\mathbf{x}_b)^T \Phi_b(\mathbf{x}'_b).$$

We claim that k is defined by a nonlinear feature space mapping

$$\psi(\mathbf{x}) = (\Phi_a(\mathbf{x}_a), \Phi_b(\mathbf{x}_b)).$$

where the subscripts a and b define the disjoint subsets of \mathbf{x} as in the problem statement. This feature space mapping is valid as all components of \mathbf{x} are present in the union of the sets $\mathbf{x}_a, \mathbf{x}_b$.

Evaluating an inner product as block matrices, we get that

$$\psi(\mathbf{x})^T \psi(\mathbf{x}') = (\Phi_a(\mathbf{x}_a), \Phi_b(\mathbf{x}_b))^T (\Phi_a(\mathbf{x}'_a), \Phi_b(\mathbf{x}'_b)).$$

Note here that inner product is valid since we can transpose the block vector components individually to get valid inner products in the expansion of the above expression. i.e.

$$\psi(\mathbf{x})^T \psi(\mathbf{x}') = (\Phi_a(\mathbf{x}_a), \Phi_b(\mathbf{x}_b))^T (\Phi_a(\mathbf{x}'_a), \Phi_b(\mathbf{x}'_b)) = \Phi_a(\mathbf{x}_a)^T \Phi_a(\mathbf{x}'_a) + \Phi_b(\mathbf{x}_b)^T \Phi_b(\mathbf{x}'_b),$$

which is exactly $k(\mathbf{x}, \mathbf{x}')$.

Part 2

Let $\mathbf{x} = (x_1, x_2)$, $\mathbf{y} = (y_1, y_2)$, so

$$k(\mathbf{x}, \mathbf{y}) = (x_1 y_1 + x_2 y_2)^2 = x_1^2 y_1^2 + 2x_1 x_2 y_1 y_2 + x_2^2 y_2^2.$$

From here it is clear that the mapping

$$\Phi(\mathbf{x}) = \left(x_1^2, \sqrt{2}x_1 x_2, x_2^2 \right)$$

produces the expression for k when taking $\Phi(\mathbf{x})^T \Phi(\mathbf{y})$.

Problem 2

The log likelihood of the model is

$$F(\mathbf{w}) = \frac{-\beta}{2} \sum_{n=1}^N [y(x_n, \mathbf{w}) - t_n]^2 + \frac{N}{2} \ln \beta - \frac{N}{2} \ln 2\pi.$$

To maximize we differentiate F with respect to each component of \mathbf{w} w_1, \dots, w_M . To compute this we compute the general partial derivatives of y with respect to each of the components w_1, \dots, w_M .

$$\frac{\partial y}{\partial w_i} = x^i \quad i = 0, \dots, M.$$

Therefore

$$\frac{\partial F}{\partial x} = -\beta \sum_{n=1}^N [y(x_n, \mathbf{w}) - t_n] x_n^i \quad i = 1, \dots, M.$$

Setting each of these partials equal to 0 we get

$$\begin{aligned} 0 &= -\beta \sum_{n=1}^N [y(x_n, \mathbf{w}) - t_n] x_n^i \quad i = 1, \dots, M \\ \sum_{n=1}^N t_n x_n^i &= \sum_{n=1}^N x_n^i y(x_n, \mathbf{w}) \quad i = 1, \dots, M \\ \sum_{n=1}^N t_n x_n^i &= \sum_{n=1}^N x_n^i \sum_{j=0}^M w_j x_n^j \quad i = 1, \dots, M \\ \sum_{n=1}^N t_n x_n^i &= \sum_{n=1}^N \sum_{j=0}^M w_j x_n^{i+j} \quad i = 1, \dots, M \\ \sum_{n=1}^N t_n x_n^i &= \sum_{j=0}^M \sum_{i=1}^M w_j x_n^{i+j} \quad i = 1, \dots, M \\ \iff T_i &= \sum_{j=0}^M A_{ij} w_j \end{aligned}$$

Problem 3

Let $A \in M_n(\mathbf{R})$. Suppose $v \in \text{Im}(A)$ so there exists $w \in \mathbf{R}^n$ such that $v = Aw$. Then

$$A(A^T A)^{-1} A^T v = A(A^T A)^{-1} A^T Aw = A \mathbf{1}_n w = Aw = v$$

so the claimed projection matrix leaves elements in the image of A alone. Now suppose $v \in \text{Im}(A)^\perp$. By rank nullity theorem this means that $v \in \text{Ker}(A^T)$. So

$$A(A^T A)^{-1} A^T w = 0,$$

which is consistent with the behavior of orthogonal projections of vectors onto orthogonal spaces.

Problem 4

We differentiate in \mathbf{w} and set equal to $\mathbf{0}$, solving for \mathbf{w} :

$$\begin{aligned}
E_D(\mathbf{w}) &= \frac{1}{2} \sum_{n=1}^N r_n \{t_n - \mathbf{w}^T \phi(\mathbf{x}_n)\} : \\
E'_D(\mathbf{w}) &= \left(\sum_{n=1}^N r_n \{t_n - \mathbf{w}^T \phi(\mathbf{x}_n)\} \right) (-2(t_n - \mathbf{w}^T \phi(\mathbf{x}_n)) \phi(\mathbf{x}_n)) \\
\mathbf{0} &= \left(\sum_{n=1}^N r_n \{t_n - \mathbf{w}^T \phi(\mathbf{x}_n)\} \right) (-2(t_n - \mathbf{w}^T \phi(\mathbf{x}_n)) \phi(\mathbf{x}_n)) \\
\mathbf{0} &= \left(\sum_{n=1}^N r_n \{t_n - \mathbf{w}^T \phi(\mathbf{x}_n)\} \right) (-2t_n + 2\mathbf{w}^T \phi(\mathbf{x}_n)) \phi(\mathbf{x}_n) \\
\mathbf{0} &= \left(\sum_{n=1}^N r_n \{t_n - \mathbf{w}^T \phi(\mathbf{x}_n)\} \right) \phi(\mathbf{x}_n) \\
\mathbf{0}^T &= \left(\sum_{n=1}^N r_n \{t_n - \mathbf{w}^T \phi(\mathbf{x}_n)\} \right) \phi(\mathbf{x}_n)^T \\
\mathbf{0}^T &= \sum_{n=1}^N r_n t_n \phi(\mathbf{x}_n)^T - \sum_{n=1}^N r_n \mathbf{w}^T \phi(\mathbf{x}_n) \phi(\mathbf{x}_n)^T \\
\sum_{n=1}^N r_n t_n \phi(\mathbf{x}_n)^T &= \sum_{n=1}^N r_n \mathbf{w}^T \phi(\mathbf{x}_n) \phi(\mathbf{x}_n)^T \\
\sum_{n=1}^N r_n t_n \phi(\mathbf{x}_n) &= \sum_{n=1}^N r_n \phi(\mathbf{x}_n) \phi(\mathbf{x}_n)^T \mathbf{w} \\
\mathbf{w} &= \left(\sum_{n=1}^N r_n \phi(\mathbf{x}_n) \phi(\mathbf{x}_n)^T \right)^{-1} \left(\sum_{n=1}^N r_n t_n \phi(\mathbf{x}_n) \right)
\end{aligned}$$

Problem 4

Final part

Using equation (1) we have

$$\begin{aligned}
\left(w_n^{(k+1)}\right)^T \mathbf{x}_n &= \left(\left(\mathbf{w}^{(k)}\right)^T + \frac{\left(t_n - \left(\mathbf{w}^{(k)}\right)^T \mathbf{x}_n\right)}{\|\mathbf{x}_n\|^2} \mathbf{x}_n^T \right) \mathbf{x}_n \\
\left(w_n^{(k+1)}\right)^T \mathbf{x}_n &= \left(\mathbf{w}^{(k)}\right)^T \mathbf{x}_n + \frac{\left(t_n - \left(\mathbf{w}^{(k)}\right)^T \mathbf{x}_n\right)}{\|\mathbf{x}_n\|^2} \mathbf{x}_n^T \mathbf{x}_n \\
\left(w_n^{(k+1)}\right)^T \mathbf{x}_n &= \left(\mathbf{w}^{(k)}\right)^T \mathbf{x}_n + \left(t_n - \left(\mathbf{w}^{(k)}\right)^T \mathbf{x}_n\right) \\
\left(w_n^{(k+1)}\right)^T \mathbf{x}_n &= t_n
\end{aligned}$$