# → Image Classification

# Naomi Zilber

The data set used is from this link. The target classes are the types of images, which are buildings, forest, glacier, mountain, sea, and street, each corresponding to a number 0-5, respectively. Therefore, the model should be able to predict the image type based on the image itself.

### ▼ Load Data

```
import numpy as np
import os
import cv2
from PIL import Image
import matplotlib.pyplot as plt
from sklearn.utils import shuffle
import tensorflow as tf
from sklearn.model_selection import train_test_split
```

The training data has 60K observations, but training will select batches of 128 examples at a time. The target, the image type, has 6 classes. The number of epochs is limited to 20, so training will stop after 20 forward and backward passes.

```
batch_size = 128
num_classes = 6
epochs = 20

from google.colab import drive
drive.mount('/content/drive')
    Drive already mounted at /content/drive; to attempt to forcibly remount, call drive.mount("/content/drive", force_remount=True).
!unzip /content/drive/MyDrive/ColabNotebooks/images.zip
```

```
intiating: seg_train/seg_train/street/פאיש.jpg
       inflating: seg_train/seg_train/street/9885.jpg
       inflating: seg_train/seg_train/street/9891.jpg
       inflating: seg_train/seg_train/street/9895.jpg
       inflating: seg_train/seg_train/street/9903.jpg
       inflating: seg_train/seg_train/street/9911.jpg
       inflating: seg_train/seg_train/street/992.jpg
       inflating: seg_train/seg_train/street/9926.jpg
       inflating: seg_train/seg_train/street/9931.jpg
       inflating: seg_train/seg_train/street/9934.jpg
       inflating: seg_train/seg_train/street/994.jpg
       inflating: seg_train/seg_train/street/9953.jpg
       inflating: seg_train/seg_train/street/9959.jpg
       inflating: seg_train/seg_train/street/9961.jpg
       inflating: seg_train/seg_train/street/9967.jpg
       inflating: seg_train/seg_train/street/9978.jpg
       inflating: seg_train/seg_train/street/9989.jpg
       inflating: seg_train/seg_train/street/999.jpg
# load the data
data = \{\}
X = []
train_path = "/content/seg_train/seg_train"
for folder in os.listdir(train_path):
    img_folder = train_path + "/" + folder
    images = os.listdir(img_folder)
    data[folder] = len(images)
    for img in images:
        img_path = img_folder + "/" + img
        temp = Image.open(img_path)
        temp = temp.convert("RGB")
        temp = np.array(temp)
        temp = cv2.resize(temp, (224, 224))
        X.append(temp)
# look at the amount of data
for key in data.keys():
    print("There are %s images of %s" % (data[key], key))
total = data['glacier'] + data['buildings'] + data['forest'] + data['street'] + data['mountain']
print("Total number of pictures:", total)
     There are 2512 images of mountain
     There are 2274 images of sea
     There are 2271 images of forest
     There are 2404 images of glacier
     There are 2191 images of buildings
     There are 2382 images of street
     Total number of pictures: 11760
X = np.array(X)
y = np.ones((14034,), dtype = "int32")
# assign each image type a number
# use the numbers found above to calculate each range
y[:2404] = 2
y[2404:4595] = 0
y[4595:7107] = 3
y[7107:9489] = 5
y[9489:11760] = 1
y[11760:] = 4
# shuffle the training data since it is too organized
X, y = shuffle(X, y, random_state=1234)
y = tf.keras.utils.to_categorical(y, num_classes)
# split into test and train data
x_train, x_test, y_train, y_test = train_test_split(X, y, test_size=0.2, random_state=1234)
\# print the dimensions of the train and test data
print('train size =', x_train.shape)
print('test size =', x_test.shape)
     train size = (11227, 224, 224, 3)
     test size = (2807, 224, 224, 3)
```

# ▼ Data Exploration

From the bar plot of the distribution of the target classes, it seems like the distribution is fairly even with all target classes having similar amount of images.

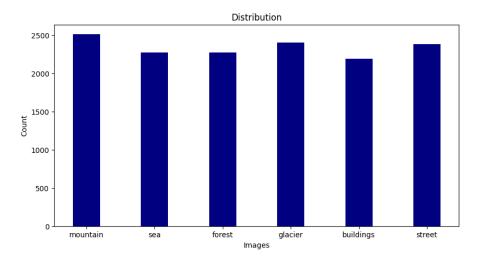
```
# graph of the distribution of the target classes

target = list(data.keys())
amount = list(data.values())

fig = plt.figure(figsize = (10, 5))

# creating the bar plot
plt.bar(target, amount, color ='navy', width = 0.4)

plt.title('Distribution')
plt.ylabel('Count')
plt.xlabel('Images')
plt.show()
```



# ▼ Sequential Model

Make a sequential model

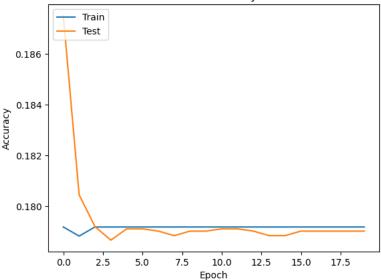
```
# create a sequential model
model = tf.keras.models.Sequential([
    tf.keras.layers.Flatten(input_shape=(224, 224, 3)),
    tf.keras.layers.Dense(512, activation='relu'),
    tf.keras.layers.Dropout(0.2),
    tf.keras.layers.Dense(256, activation='relu'),
    tf.keras.layers.Dropout(0.2),
    tf.keras.layers.Dense(num_classes, activation='softmax'),
])
model.summary()
```

Model: "sequential"

Layer (type)	Output Shape	Param #
flatten (Flatten)	(None, 150528)	0
dense (Dense)	(None, 512)	77070848
dropout (Dropout)	(None, 512)	0

```
dense_1 (Dense)
                  (None, 256)
                               131328
   dropout_1 (Dropout)
                  (None, 256)
   dense_2 (Dense)
                  (None, 6)
                               1542
  ______
  Total params: 77,203,718
  Trainable params: 77,203,718
  Non-trainable params: 0
model.compile(loss='categorical_crossentropy',
       optimizer='rmsprop',
       metrics=['accuracy'])
history = model.fit(x_train, y_train,
          batch_size=batch_size,
          epochs=epochs,
          verbose=1.
          validation_data=(x_test, y_test))
  Epoch 1/20
  Epoch 2/20
          88/88 [====
  Epoch 3/20
  Epoch 4/20
  88/88 [=============] - 183s 2s/step - loss: 71.8147 - accuracy: 0.1787 - val_loss: 1.9289 - val_accuracy: 0.1792
  Epoch 5/20
  Epoch 6/20
  Epoch 7/20
  88/88 [====
          ========== ] - 178s 2s/step - loss: 1.7908 - accuracy: 0.1790 - val_loss: 1.9266 - val_accuracy: 0.1792
  Epoch 8/20
  88/88 [============] - 177s 2s/step - loss: 1.7908 - accuracy: 0.1789 - val_loss: 1.9274 - val_accuracy: 0.1792
  Epoch 9/20
  88/88 [=========] - 169s 2s/step - loss: 1.7908 - accuracy: 0.1790 - val_loss: 1.9263 - val_accuracy: 0.1792
  Epoch 10/20
  Epoch 11/20
  Epoch 12/20
  Epoch 13/20
  Epoch 14/20
  88/88 [=========] - 180s 2s/step - loss: 1.7908 - accuracy: 0.1789 - val_loss: 1.9027 - val_accuracy: 0.1792
  Epoch 15/20
  88/88 [==========] - 180s 2s/step - loss: 1.7908 - accuracy: 0.1789 - val loss: 1.9050 - val accuracy: 0.1792
  Epoch 16/20
  88/88 [=========] - 170s 2s/step - loss: 1.7908 - accuracy: 0.1790 - val_loss: 1.9055 - val_accuracy: 0.1792
  Epoch 17/20
  Epoch 18/20
  88/88 [============] - 165s 2s/step - loss: 1.7908 - accuracy: 0.1790 - val_loss: 1.9081 - val_accuracy: 0.1792
  Epoch 19/20
  88/88 [======
           Epoch 20/20
  The accuracy is 0.1790 and the validation accuracy is 0.1792.
history.history.keys()
  dict_keys(['loss', 'accuracy', 'val_loss', 'val_accuracy'])
# plot training & validation accuracy values
plt.plot(history.history['val_accuracy'])
plt.plot(history.history['accuracy'])
plt.title('Model accuracy')
plt.ylabel('Accuracy')
plt.xlabel('Epoch')
plt.legend(['Train', 'Test'], loc='upper left')
plt.show()
```

# Model accuracy



```
# evaluation
score = model.evaluate(x_test, y_test, verbose=0)
print('Test loss:', score[0])
print('Test accuracy:', score[1])

Test loss: 1.9076663255691528
   Test accuracy: 0.1791948676109314
```

The accuracy of the sequential model is 0.1792, which is not very good.

# ▼ CNN Model

Make a convolutional neural network

Model: "sequential"

Layer (type)	Output Shape	Param #
conv2d (Conv2D)	(None, 222, 222, 32)	896
<pre>max_pooling2d (MaxPooling2D )</pre>	(None, 111, 111, 32)	0
conv2d_1 (Conv2D)	(None, 109, 109, 64)	18496
<pre>max_pooling2d_1 (MaxPooling 2D)</pre>	(None, 54, 54, 64)	0
flatten (Flatten)	(None, 186624)	0
dropout (Dropout)	(None, 186624)	0
dense (Dense)	(None, 6)	1119750

\_\_\_\_\_

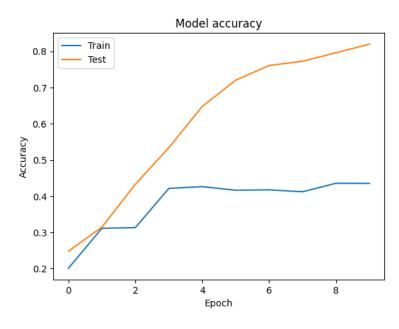
```
Total params: 1,139,142
Trainable params: 1,139,142
Non-trainable params: 0
```

```
model.compile(loss='categorical_crossentropy',
          optimizer='adam',
          metrics=['accuracy'])
history = model.fit(x_train[:5000], y_train[:5000],
              batch_size=batch_size,
              epochs=10,
              verbose=1.
              validation_data=(x_test[:5000], y_test[:5000]))
   Epoch 1/10
   Epoch 2/10
                   =========] - 511s 13s/step - loss: 1.6456 - accuracy: 0.3144 - val_loss: 1.6680 - val_accuracy: 0.3114
   40/40 [====
   Epoch 3/10
   40/40 [====
                  =========== ] - 525s 13s/step - loss: 1.4440 - accuracy: 0.4330 - val_loss: 1.7132 - val_accuracy: 0.3131
   Epoch 4/10
   40/40 [====
                  =========] - 495s 12s/step - loss: 1.2263 - accuracy: 0.5340 - val_loss: 1.8991 - val_accuracy: 0.4214
   Epoch 5/10
              :============] - 481s 12s/step - loss: 0.9599 - accuracy: 0.6478 - val_loss: 1.9909 - val_accuracy: 0.4264
   40/40 [======
   Epoch 6/10
                   =========] - 440s 11s/step - loss: 0.7727 - accuracy: 0.7204 - val_loss: 2.2133 - val_accuracy: 0.4165
   40/40 [====
   Epoch 7/10
   Epoch 8/10
                  :=========] - 465s 12s/step - loss: 0.6432 - accuracy: 0.7728 - val_loss: 2.3310 - val_accuracy: 0.4122
   40/40 [====
   Epoch 9/10
   40/40 [====
                   =========] - 464s 12s/step - loss: 0.6235 - accuracy: 0.7962 - val_loss: 2.9562 - val_accuracy: 0.4357
   Epoch 10/10
```

For the above code, I had to use only half of the datasets because the system wasn't able to handle more data. I also adjusted the number of epochs because it was taking a very long time for the model to train.

The accuracy ended up being 0.82 and the validation accuracy is 0.4353, which is much better than the sequential model and a big improvement.

```
# Plot training & validation accuracy values
plt.plot(history.history['val_accuracy'])
plt.plot(history.history['accuracy'])
plt.title('Model accuracy')
plt.ylabel('Accuracy')
plt.xlabel('Epoch')
plt.legend(['Train', 'Test'], loc='upper left')
plt.show()
```



```
# evaluation
score = model.evaluate(x_test[:5000], y_test[:5000], verbose=0)
print('Test loss:', score[0])
print('Test accuracy:', score[1])

Test loss: 3.0672171115875244
Test accuracy: 0.4353402256965637
```

The accuracy is 0.4353, which is an improvement on the previous model.

#### Pretrained Transfer Learning Model

### Creating the base model

```
# Use only a small subset of the original data because the system keeps crashing
train_x = x_train[:50]
train_y = y_train[:50]
test_x = x_{test}[:50]
test_y = y_test[:50]
# check that the distribution of the new dataset is relatively even
def evenDist(dataset):
 1b1 = 0
 1b2 = 0
 1h3 = 0
 1b4 = 0
 1b5 = 0
 1b6 = 0
  for i in range(50):
   if np.array_equal(dataset[i], [0,0,0,0,0,1], equal_nan=False):
     lb1 += 1
    elif np.array\_equal(dataset[i], \ [0,0,0,0,1,0], \ equal\_nan=False):
     1b2 += 1
    elif np.array_equal(dataset[i], [0,0,0,1,0,0], equal_nan=False):
     1b3 += 1
    elif np.array_equal(dataset[i], [0,0,1,0,0,0], equal_nan=False):
     lb4 += 1
    elif np.array_equal(dataset[i], [0,1,0,0,0,0], equal_nan=False):
     1b5 += 1
    else:
     1b6 += 1
  return (1b1, 1b2, 1b3, 1b4, 1b5, 1b6)
# the distribution looks relatively even among the target classes
lbs1 = evenDist(train_y)
print('lb1 =', lbs1[0])
print('lb2 =', lbs1[1])
print('lb3 =', lbs1[2])
print('lb4 =', lbs1[3])
print('lb5 =', lbs1[4])
print('lb6 =', lbs1[5])
lbs2 = evenDist(test_y)
print('\nlb1 =', lbs2[0])
print('lb2 =', lbs2[1])
print('lb3 =', lbs2[2])
print('lb4 =', lbs2[3])
print('lb5 =', lbs2[4])
print('lb6 =', lbs2[5])
     1b1 = 12
     1b2 = 10
     1b3 = 5
     lb4 = 11
     1b5 = 7
     1b6 = 5
     1b1 = 8
     1b2 = 8
     1b3 = 7
```

```
1b4 = 10
1b5 = 13
       1b6 = 4
  preprocess_input = tf.keras.applications.mobilenet_v2.preprocess_input
  # rescale pixel values
  rescale = tf.keras.layers.Rescaling(1./127.5, offset=-1)
  IMG\_SIZE = (224, 224)
  \# Create the base model from the pre-trained model MobileNet V2
  IMG_SHAPE = IMG_SIZE + (3,)
  base_model = tf.keras.applications.MobileNetV2(input_shape=IMG_SHAPE,
                                                  include_top=False,
                                                  weights='imagenet')
  Convert each 224x224x3 image into a 7x7x1280 block of features
  image\_batch = train\_x
  label_batch = train_y
  feature_batch = base_model(image_batch)
  print(feature_batch.shape)
       (50, 7, 7, 1280)
▼ Feature extraction
  # freeze the convolutional base model
```

```
base_model.trainable = False
base_model.summary()
```

```
DIOCK TO DLOJECT (COUAST)
                                  (None, /, /, 320)
                                                     30/200
                                                                [ DIOCK TO GEBLUMISE LEIN[A][A] ]
     block_16_project_BN (BatchNorm (None, 7, 7, 320)
                                                     1280
                                                                ['block_16_project[0][0]']
     alization)
                                  (None, 7, 7, 1280)
     Conv_1 (Conv2D)
                                                     409600
                                                                ['block_16_project_BN[0][0]']
     Conv_1_bn (BatchNormalization) (None, 7, 7, 1280) 5120
                                                                ['Conv_1[0][0]']
     out_relu (ReLU)
                                  (None, 7, 7, 1280)
                                                                ['Conv_1_bn[0][0]']
    _____
    Total params: 2,257,984
    Trainable params: 0
    Non-trainable params: 2,257,984
# convert the features to a single 1280-element vector per image
global_average_layer = tf.keras.layers.GlobalAveragePooling2D()
feature_batch_average = global_average_layer(feature_batch)
print(feature_batch_average.shape)
     (50, 1280)
# convert these features into a single prediction per image
prediction_layer = tf.keras.layers.Dense(num_classes)
prediction_batch = prediction_layer(feature_batch_average)
print(prediction_batch.shape)
     (50, 6)
inputs = tf.keras.Input(shape=(224, 224, 3))
x = preprocess_input(inputs)
x = base_model(x, training=False)
```

#### Build a model

```
x = global_average_layer(x)
x = tf.keras.layers.Dropout(0.2)(x)
outputs = prediction_layer(x)
model = tf.keras.Model(inputs, outputs)
```

#### Compile the model

```
base_learning_rate = 0.0001
model.compile(optimizer=tf.keras.optimizers.Adam(learning_rate=base_learning_rate),
             loss=tf.keras.losses.CategoricalCrossentropy(from_logits=True),
             metrics=['accuracy'])
```

model.summary()

Model: "model\_4"

Output Shape	Param #
[(None, 224, 224, 3)]	0
(None, 224, 224, 3)	0
(None, 224, 224, 3)	0
(None, 7, 7, 1280)	2257984
(None, 1280)	0
(None, 1280)	0
(None, 6)	7686
	[(None, 224, 224, 3)] (None, 224, 224, 3) (None, 224, 224, 3) (None, 7, 7, 1280) (None, 1280) (None, 1280)

\_\_\_\_\_ Total params: 2,265,670

Trainable params: 7,686

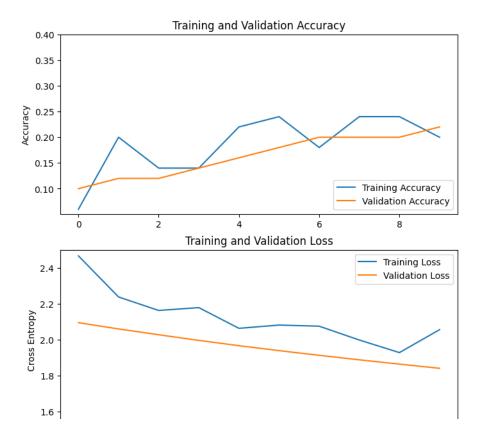
Train the model.

It looks like the initial accuracy of the model is very low

```
initial_epochs = 10
# evaluation
score = model.evaluate(test_x, test_y)
print('Test loss:', score[0])
print('Test accuracy:', score[1])
  2/2 [============ ] - 5s 1s/step - loss: 2.1301 - accuracy: 0.1000
  Test loss: 2.1301393508911133
  Test accuracy: 0.10000000149011612
history = model.fit(train_x, train_y,
         epochs=initial_epochs,
        validation_data=(test_x, test_y))
Epoch 1/10
  Epoch 2/10
  2/2 [===========] - 4s 3s/step - loss: 2.2372 - accuracy: 0.2000 - val_loss: 2.0592 - val_accuracy: 0.1200
  Epoch 3/10
  2/2 [============] - 5s 3s/step - loss: 2.1780 - accuracy: 0.1400 - val_loss: 1.9955 - val_accuracy: 0.1400
  Epoch 5/10
  Epoch 6/10
  Epoch 7/10
  2/2 [===========] - 5s 4s/step - loss: 2.0744 - accuracy: 0.1800 - val_loss: 1.9123 - val_accuracy: 0.2000
  Epoch 8/10
  Epoch 9/10
  Enoch 10/10
```

The accuracy has improved compared to the initial model accuracy.

```
acc = history.history['accuracy']
val_acc = history.history['val_accuracy']
loss = history.history['loss']
val_loss = history.history['val_loss']
plt.figure(figsize=(8, 8))
plt.subplot(2, 1, 1)
plt.plot(acc, label='Training Accuracy')
plt.plot(val_acc, label='Validation Accuracy')
plt.legend(loc='lower right')
plt.ylabel('Accuracy')
plt.ylim([min(plt.ylim()), 0.4])
plt.title('Training and Validation Accuracy')
plt.subplot(2, 1, 2)
plt.plot(loss, label='Training Loss')
plt.plot(val_loss, label='Validation Loss')
plt.legend(loc='upper right')
plt.ylabel('Cross Entropy')
plt.ylim([1.5, 2.5])
plt.title('Training and Validation Loss')
plt.xlabel('epoch')
plt.show()
```



# ▼ Fine tuning

```
# unfreeze the model
base_model.trainable = True

print("Number of layers in the base model: ", len(base_model.layers))
# Fine-tune from this layer onwards
fine_tune_at = 100
# Freeze all the layers before the `fine_tune_at` layer
for layer in base_model.layers[:fine_tune_at]:
    layer.trainable = False
    Number of layers in the base model: 154
```

# Compile the model

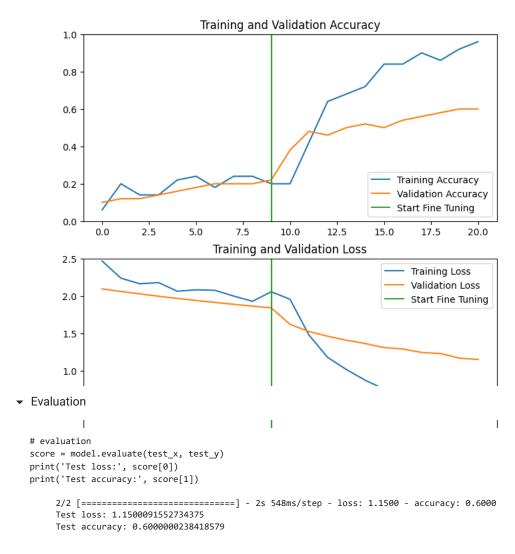
model.summary()

Model: "model\_4"

Layer (type)	Output Shape	Param #
input_9 (InputLayer)	[(None, 224, 224, 3)]	0
<pre>tf.math.truediv_4 (TFOpLamb da)</pre>	(None, 224, 224, 3)	0
<pre>tf.math.subtract_4 (TFOpLam bda)</pre>	(None, 224, 224, 3)	0
<pre>mobilenetv2_1.00_224 (Funct ional)</pre>	(None, 7, 7, 1280)	2257984
<pre>global_average_pooling2d_3 (GlobalAveragePooling2D)</pre>	(None, 1280)	0

```
dropout_4 (Dropout)
                      (None, 1280)
    dense_3 (Dense)
                      (None, 6)
                                        7686
   _____
   Total params: 2,265,670
   Trainable params: 1,869,126
   Non-trainable params: 396,544
fine_tune_epochs = 10
total_epochs = initial_epochs + fine_tune_epochs
history_fine = model.fit(train_x, train_y,
                epochs=total epochs,
                initial_epoch=history.epoch[-1],
                validation_data=(test_x, test_y))
   Epoch 10/20
   Epoch 11/20
   2/2 [===========] - 6s 4s/step - loss: 1.4775 - accuracy: 0.4200 - val_loss: 1.5232 - val_accuracy: 0.4800
   Epoch 12/20
   Epoch 13/20
   2/2 [===========] - 5s 4s/step - loss: 1.0145 - accuracy: 0.6800 - val loss: 1.4064 - val accuracy: 0.5000
   Epoch 14/20
   Epoch 15/20
   2/2 [==========] - 4s 3s/step - loss: 0.7549 - accuracy: 0.8400 - val_loss: 1.3084 - val_accuracy: 0.5000
   Epoch 16/20
   Enoch 17/20
   Epoch 18/20
   2/2 [===========] - 5s 4s/step - loss: 0.6058 - accuracy: 0.8600 - val loss: 1.2292 - val accuracy: 0.5800
   Epoch 19/20
   Epoch 20/20
   2/2 [===========] - 6s 4s/step - loss: 0.4342 - accuracy: 0.9600 - val loss: 1.1500 - val accuracy: 0.6000
After fine-tuning, the accuracy has improved
acc += history_fine.history['accuracy']
val_acc += history_fine.history['val_accuracy']
loss += history_fine.history['loss']
val_loss += history_fine.history['val_loss']
plt.figure(figsize = (8, 8))
plt.subplot(2, 1, 1)
plt.plot(acc, label='Training Accuracy')
plt.plot(val_acc, label='Validation Accuracy')
plt.ylim([0, 1])
plt.plot([initial_epochs-1,initial_epochs-1], plt.ylim(), label='Start Fine Tuning')
plt.legend(loc='lower right')
plt.title('Training and Validation Accuracy')
plt.subplot(2, 1, 2)
plt.plot(loss, label='Training Loss')
plt.plot(val_loss, label='Validation Loss')
plt.ylim([0, 2.5])
plt.plot([initial_epochs-1,initial_epochs-1], plt.ylim(), label='Start Fine Tuning')
plt.legend(loc='upper right')
plt.title('Training and Validation Loss')
plt.xlabel('epoch')
```

plt.show()



The accuracy is much better after fine tuning, with the accuracy being 0.60.

# Analysis

It looks like the sequential model did the worst out of all the other models, with accuracy of 0.1792. The CNN model did the second best, with an accuracy of 0.4353. The model that performed the best is the pretrained transfer learning model, which got an accuracy of 0.60 after fine tuning.

It took all models a lot of time to run, with the CNN model running the longest. The pretrained transfer learning model probably performed the best out of all the models because it learns from previous tasks, while sequential and CNN models are not trained on anything prior to the creating of the model.