

MATH 140: Mathematical Methods for Optimization
Assignment 4—Spring 2024

Due February 13, 2024

By:Ronald Nap

Note: Hessian's and Derivatives computed using Wolfram Alpha

1. (10 points) Consider the unconstrained optimization problem

$$\min f(x, y) \equiv -\cos x \cos(y/10).$$

- (a) Find and classify all stationary points in the region $-\pi/2 \leq x \leq \pi/2, -10\pi/2 \leq y \leq 10\pi/2$

Solution: The function given is $f(x, y) = -\cos(x) \cos(y/10)$. To find the stationary points, we first compute the gradient of $f(x, y)$:

$$\nabla f(x, y) = \begin{pmatrix} \frac{\partial f}{\partial x} \\ \frac{\partial f}{\partial y} \end{pmatrix}.$$

The partial derivatives are:

$$\frac{\partial f}{\partial x} = \sin(x) \cos\left(\frac{y}{10}\right),$$

$$\frac{\partial f}{\partial y} = \frac{1}{10} \cos(x) \sin\left(\frac{y}{10}\right).$$

To find the stationary points, we set each component of the gradient to zero within the region $-\frac{\pi}{2} \leq x \leq \frac{\pi}{2}, -\frac{10\pi}{2} \leq y \leq \frac{10\pi}{2}$.

$$\sin(x) \cos\left(\frac{y}{10}\right) = 0,$$

$$\frac{1}{10} \cos(x) \sin\left(\frac{y}{10}\right) = 0.$$

This results in the only solution being $x = 0$ and $y = 0$, as all other potential solutions do not satisfy both conditions simultaneously within the region.

To classify the stationary point, we examine the second derivatives and the Hessian matrix:

$$H(f) = \begin{bmatrix} \frac{\partial^2 f}{\partial x^2} & \frac{\partial^2 f}{\partial x \partial y} \\ \frac{\partial^2 f}{\partial x \partial y} & \frac{\partial^2 f}{\partial y^2} \end{bmatrix} = \begin{bmatrix} \cos(x) \cos\left(\frac{y}{10}\right) & -\frac{1}{10} \sin(x) \sin\left(\frac{y}{10}\right) \\ -\frac{1}{10} \sin(x) \sin\left(\frac{y}{10}\right) & \frac{1}{100} \cos(x) \cos\left(\frac{y}{10}\right) \end{bmatrix}.$$

At the point $(0, 0)$, the Hessian matrix simplifies to:

$$H(f)_{(0,0)} = \begin{bmatrix} 1 & 0 \\ 0 & \frac{1}{100} \end{bmatrix}.$$

The determinant of this Hessian matrix is positive, as $\det(H(f)_{(0,0)}) = 1 \times \frac{1}{100} - 0 = \frac{1}{100}$. Since both diagonal elements (which are also the eigenvalues in this case) are positive, it indicates that the stationary point at $(0, 0)$ is a local minimum.

- (b) There is a portion of the problem region within which the Hessian matrix of $f(x, y)$ is positive definite. Give expressions for this portion. You should be able to do this analytically but I recommend using Matlab/python.

Solution: Using 1a), the Hessian matrix $H(f)$ is

$$H(f) = \begin{bmatrix} \cos(x) \cos\left(\frac{y}{10}\right) & -\frac{1}{10} \sin(x) \sin\left(\frac{y}{10}\right) \\ -\frac{1}{10} \sin(x) \sin\left(\frac{y}{10}\right) & \frac{1}{100} \cos(x) \cos\left(\frac{y}{10}\right) \end{bmatrix}.$$

The determinant of $H(f)$ is:

$$\det(H(f)) = 0.005 \cos(2x) + 0.005 \cos\left(\frac{y}{5}\right).$$

For the Hessian matrix to be positive definite, the determinant must be greater than zero.

$$0.005 \cos(2x) + 0.005 \cos\left(\frac{y}{5}\right) > 0.$$

This condition is met within the domain where $\cos(x)$ and $\cos\left(\frac{y}{10}\right)$ are both positive or both negative. Given the specified domain $-\pi/2 \leq x \leq \pi/2, -10\pi/2 \leq y \leq 10\pi/2$, $\cos(x)$ is positive for $-\pi/2 < x < \pi/2$, and similarly, $\cos\left(\frac{y}{10}\right)$ is positive for $-10\pi/2 < y < 10\pi/2$. Therefore, within the given domain, the Hessian matrix can be positive definite where $\cos(x)$ and $\cos\left(\frac{y}{10}\right)$ maintain their positive values and satisfy the determinant condition.

- (c) Derive expressions for the search directions associated with the steepest descent method.

Solution: The steepest descent method moves from the current point in the direction of the most rapid decrease of the function. This direction is opposite to the gradient of the function at the current point. For $f(x, y)$, the gradient is

$$\nabla f(x, y) = \begin{pmatrix} \frac{\partial f}{\partial x} \\ \frac{\partial f}{\partial y} \end{pmatrix}.$$

The search direction at any point (x_k, y_k) is therefore

$$d_k = -\nabla f(x_k, y_k) = -\begin{pmatrix} \frac{\partial f}{\partial x}(x_k, y_k) \\ \frac{\partial f}{\partial y}(x_k, y_k) \end{pmatrix}.$$

For the function $f(x, y) = -\cos(x) \cos(y/10)$, the partial derivatives are

$$\frac{\partial f}{\partial x} = \sin(x) \cos\left(\frac{y}{10}\right),$$

$$\frac{\partial f}{\partial y} = -\frac{1}{10} \cos(x) \sin\left(\frac{y}{10}\right).$$

Hence, the search direction for steepest descent at (x_k, y_k) is

$$d_k = -\begin{pmatrix} \sin(x_k) \cos\left(\frac{y_k}{10}\right) \\ -\frac{1}{10} \cos(x_k) \sin\left(\frac{y_k}{10}\right) \end{pmatrix}.$$

This expression will be used to update the current point to the next point in steepest descent.

- (d) Write a program that performs the steepest descent iterations, without a line search, with an exact line search and with Armijo and backtracking (as discussed in class). Note that you will not be able to find the value of the optimal step length analytically; instead, determine it numerically. Suggestion: use a built-in one-dimensional minimization function such as FindMinimum or FindRoot in MATHEMATICA or fzero in MATLAB.

Solution: Refer to HW4.py for full code

```
def steepest_descent_no_line_search(x0, max_iter=100, tol=1e-6, step_size=0.01):
    x = x0
    grad_norm = np.linalg.norm(grad_f(x))
    for i in range(max_iter):
        grad = grad_f(x)
        x = x - step_size * grad
        grad_norm_reduction = np.linalg.norm(grad) / grad_norm
        print(f"Iter {i+1}: x = {x}, f(x) = {f(x)}, Grad Norm Reduction = {grad_norm_reduction}")
        if np.linalg.norm(grad) < tol:
            break
    print("Convergence achieved.")
    return x

def exact_line_search(f, x, p):
    func = lambda alpha: f(x + alpha * p)
    result = minimize_scalar(func)
    return result.x

def steepest_descent_exact_line_search(x0, max_iter=100, tol=1e-6):
    x = x0
    grad_norm = np.linalg.norm(grad_f(x))
    for i in range(max_iter):
        grad = grad_f(x)
        alpha = exact_line_search(f, x, -grad)
        x = x + alpha * grad
        grad_norm_reduction = np.linalg.norm(grad) / grad_norm
        print(f"Iter {i+1}: x = {x}, f(x) = {f(x)}, Grad Norm Reduction = {grad_norm_reduction}")
        if np.linalg.norm(grad) < tol:
            break
    print("Convergence achieved.")
    return x

def armijo_line_search(f, grad_f, x, p, alpha=1.0, beta=0.1):
    while (f(x + alpha * p) > f(x) + sigma * alpha * np.dot(grad_f(x), p)):
        alpha *= beta
    return alpha

def steepest_descent_armijo(x0, max_iter=100, tol=1e-6):
    x = x0
    grad_norm = np.linalg.norm(grad_f(x))
    for i in range(max_iter):
        grad = grad_f(x)
        p = -grad
        alpha = armijo_line_search(f, grad_f, x, p)
        x = x + alpha * p
        grad_norm_reduction = np.linalg.norm(grad) / grad_norm
        print(f"Iter {i+1}: x = {x}, f(x) = {f(x)}, Grad Norm Reduction = {grad_norm_reduction}")
        if np.linalg.norm(grad) < tol:
            break
    print("Convergence achieved.")
    return x
```

- (e) Run your program for various initial guesses within the region. At every iteration print out the iteration, the current point x_k , the value of the objective function $f(x_k)$, and the reduction in the norm of the gradient $\|\nabla f(x_k)\|_2 / \|\nabla f(x_0)\|_2$.

```
Steepest Descent without Line Search:
Iter 1: x = [-0.88047116  0.77985027], f(x) = -0.993734447207144, Grad Norm Reduction = 1.0
Iter 2: x = [-0.31133232e-04  7.2804878e-01], f(x) = -0.99702808389113, Grad Norm Reduction = 0.11421448527804574
Iter 3: x = [-0.27339994  0.78523857], f(x) = -0.99702808389113, Grad Norm Reduction = 0.8189149287408826
Iter 4: x = [-2.88043121e-09  7.56795422e-01], f(x) = -0.9971381236024943, Grad Norm Reduction = 0.81082328327785617
Iter 5: x = [-0.24343898e-12  7.49175288e-01], f(x) = -0.99744994261387, Grad Norm Reduction = 0.81072437245322261
Iter 6: x = [-2.42089128e-16  7.431690542e-01], f(x) = -0.9972509736389869, Grad Norm Reduction = 0.81084732592269141
Iter 7: x = [-0.35709237e-17  7.36289434e-01], f(x) = -0.997385372283786, Grad Norm Reduction = 0.810811553121905482
Iter 8: x = [-1.71299975e-19  7.26944227e-01], f(x) = -0.9973589238236013, Grad Norm Reduction = 0.81046072370465684
Iter 9: x = [-4.52416282e-22  7.19681185e-01], f(x) = -0.9974114125274229, Grad Norm Reduction = 0.81030293409893784
Iter 10: x = [-1.9121525e-24  7.12400546e-01], f(x) = -0.99742924287894822, Grad Norm Reduction = 0.81028047157838295
Iter 11: x = [-2.97129385e-27  7.05371785e-01], f(x) = -0.9975132850974737, Grad Norm Reduction = 0.81089834328462894
Iter 12: x = [-7.38670871e-30  6.98323836e-01], f(x) = -0.997562709892159, Grad Norm Reduction = 0.809977873511285476
Iter 13: x = [-1.80888846e-32  6.91427272e-01], f(x) = -0.9976113336056705, Grad Norm Reduction = 0.80898972523928579
Iter 14: x = [-4.38192736e-35  6.84438315e-01], f(x) = -0.997658532802141, Grad Norm Reduction = 0.80786792317579287
Iter 15: x = [-1.08724749e-37  6.77599274e-01], f(x) = -0.9977851743578582, Grad Norm Reduction = 0.80970147822118952
Iter 16: x = [-2.31457380e-40  6.70828466e-01], f(x) = -0.997587095171249, Grad Norm Reduction = 0.809468468999447852
Iter 17: x = [-0.7238919  0.78509011], f(x) = -0.73340867912235, Grad Norm Reduction = 0.8464629133275
Iter 18: x = [-1.14610999e-45  6.57488840e-01], f(x) = -0.997839286634243, Grad Norm Reduction = 0.80941397562694954
Iter 19: x = [-2.47637610e-48  6.58918688e-01], f(x) = -0.997882271935482, Grad Norm Reduction = 0.80932084133496913
Iter 20: x = [-0.6294943  0.78446251], f(x) = -0.7076972429789486, Grad Norm Reduction = 0.95746887032846371
Iter 21: x = [-1.08852028e-83  6.37974415e-01], f(x) = -0.99795653388125, Grad Norm Reduction = 0.80913976324843671
Iter 22: x = [-2.21444933e-86  6.31578977e-01], f(x) = -0.998086765878146, Grad Norm Reduction = 0.80943801433805934
Iter 23: x = [-0.4324225e-89  6.12527286e-01], f(x) = -0.9980457164208407, Grad Norm Reduction = 0.8085485675175287
Iter 24: x = [-0.62982684e-92  6.19838408e-01], f(x) = -0.998084569415844, Grad Norm Reduction = 0.80886418486473696
Iter 25: x = [-1.65283852e-94  6.12851976e-01], f(x) = -0.9981226499763658, Grad Norm Reduction = 0.80877516504554469

Steepest Descent with Exact Line Search:
Iter 1: x = [-0.14508817e-05  7.79216462e-01], f(x) = -0.9996564243836, Grad Norm Reduction = 1.0
Iter 2: x = [-0.80683374  0.80474875], f(x) = -0.9999816842796219, Grad Norm Reduction = 0.81184267751832842
Iter 3: x = [-0.71894327  0.7847759], f(x) = -0.999998849406676, Grad Norm Reduction = 0.8085933345828238
Iter 4: x = [-3.64283356e-02  8.26627836e-05], f(x) = -0.999999993323806, Grad Norm Reduction = 0.669146573192538e-05
Convergence achieved.

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