

# Assignment 1

Sachinkumar Dubey

Download all python codes from

<https://github.com/sachinomdubey/Matrix-theory/codes>

and latex-tikz codes from

<https://github.com/sachinomdubey/Matrix-theory>

## 1 QUESTION No. 42

Find the coordinates of the foot of the perpendicular from the point  $\begin{pmatrix} -1 \\ 3 \end{pmatrix}$  to the line

$$(3 \quad -4)\mathbf{x} = 16. \quad (1.0.1)$$

## 2 EXPLANATION

The normal vector to the perpendicular drawn from point  $(-1 \ 3)$  is same as the direction vector of the given line:

$$\mathbf{n} = \begin{bmatrix} 4 \\ 3 \end{bmatrix}$$

The equation of the drawn perpendicular in terms of the normal vector is then obtained as

$$\mathbf{n}^T(\mathbf{x} - \mathbf{A}) = 0$$

$$(4 \quad 3)\mathbf{x} = 5$$

The above two line equations can be expressed as the matrix equation

$$\begin{bmatrix} 3 & -4 \\ 4 & 3 \end{bmatrix} \mathbf{x} = \begin{bmatrix} 16 \\ 5 \end{bmatrix}$$

The augmented matrix for the above equation is row reduced as follows

$$\begin{bmatrix} 3 & -4 & 16 \\ 4 & 3 & 5 \end{bmatrix}$$

$$\xleftrightarrow{R_1 \leftarrow R_1/3}$$

$$\begin{bmatrix} 1 & -4/3 & 16/3 \\ 4 & 3 & 5 \end{bmatrix}$$

$$\xleftrightarrow{R_2 \leftarrow R_2 - 4R_1}$$

$$\begin{bmatrix} 1 & -4/3 & 16/3 \\ 4 & 25/3 & -49/3 \end{bmatrix}$$

$$\xleftrightarrow{R_2 \leftarrow R_2 \times 3/25}$$

$$\begin{bmatrix} 1 & -4/3 & 16/3 \\ 0 & 1 & -49/25 \end{bmatrix}$$

$$\xleftrightarrow{R_1 \leftarrow R_1 + 4/3 \times R_2}$$

$$\begin{bmatrix} 1 & 0 & 68/25 \\ 0 & 1 & -49/25 \end{bmatrix}$$

Thus, The foot of the perpendicular is at point  $(68/25, -49/25)$  i.e.  $(2.72, -1.96)$