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Assignment 9

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Download all python codes from

https://github.com/sachinomdubey/Matrix-theory/ Assignment9/codes

and latex-tikz codes from

https://github.com/sachinomdubey/Matrix-theory/ Assignment9

1 Problem

(Hoffman/Page27/12)

Prove that the given matrix is invertible and A^{-1} has integer values.

2 Solution 1

Proof that A is Invertible.

The elements of the given matrix is of the form:

$$A_{ij} = \frac{1}{i+j-1} = \int_0^1 t^{i+j-2} dt = \int_0^1 t^{i-1} t^{j-1} dt$$
(2.0.1)

We will prove that the matrix **A** is positive definite: **A** is Positive definite, if $\mathbf{X}\mathbf{A}\mathbf{X}^T > 0$

Let
$$\mathbf{X} = (x_i)_{1 \le i \le n} \in \mathbb{R}^N$$
 (2.0.2)

$$\mathbf{X}\mathbf{A}\mathbf{X}^{T} = \sum_{1 \le i, j \le n} \frac{x_{i}x_{j}}{i+j-1}$$
 (2.0.3)

From (2.0.1),

$$\mathbf{XAX}^{T} = \sum_{1 \le i, j \le n} x_{i} x_{j} \int_{0}^{1} t^{i+j-2} dt$$
 (2.0.4)

$$= \int_0^1 \left(\sum_{i=1}^n x_i t^{i-1} \right) \left(\sum_{j=1}^n x_j t^{j-1} \right) dt \qquad (2.0.5)$$

$$\implies \mathbf{X}\mathbf{A}\mathbf{X}^T = \int_0^1 \left(\sum_{i=1}^n x_i t^{i-1}\right)^2 dt > 0$$
 (2.0.6)

Thus, Matrix A is Positive definite.

Now, let's say λ is an eigen value of **A**. Then, for the corresponding eigen vector $\mathbf{X} = (x_1, x_2, ..., x_n)$, we can write:

$$\mathbf{X}\mathbf{A}\mathbf{X}^{T} = \mathbf{X}\lambda\mathbf{X}^{T} \quad [:: \mathbf{A}\mathbf{X}^{T} = \lambda\mathbf{X}^{T}] \quad (2.0.7)$$

$$= \|\mathbf{X}\|^2 \lambda \tag{2.0.8}$$

$$\implies \lambda = \frac{\mathbf{X}\mathbf{A}\mathbf{X}^T}{\|\mathbf{X}\|^2} > 0 \tag{2.0.9}$$

So, all of the eigenvalues belonging to **A** must be positive. The product of the eigenvalues of a matrix equals the determinant.

Thus, the given matrix **A** is non-singular and its inverse exist (Invertible).

Proof that A^{-1} has integer values.

Let us consider a set of shifted legendre polynomials as follow:

$$P_{i}(x) = \begin{cases} P_{1}(x) = P_{11} \\ P_{2}(x) = P_{21} + P_{22}x \\ P_{3}(x) = P_{31} + P_{32}x + p_{33}x^{2} \\ \vdots \\ P_{n}(x) = P_{n1} + P_{n2}x + P_{n3}x^{2} + \dots + P_{nn}x^{n-1} \\ (2.0.11) \end{cases}$$

Where, the coefficients P_{ij} are given as:

$$P_{ij} = (-1)^{i+j-1} {j-1 \choose i-1} {i+j-2 \choose i-1}$$
 (2.0.12)

The shifted legendre polynomials are analogous to legendre polynomials, but defined on the interval [0, 1] (whereas the interval is [-1, 1] for legendre polynomial).

A set of shifted legendre polynomials obey the written as: following orthogonal relationship:

$$\int_{0}^{1} P_{i}(x)P_{j}(x)dx = 0 \text{ for } i \neq j \qquad (2.0.13)$$

$$\int_{0}^{1} P_{i}(x)P_{j}(x)dx = \frac{1}{2i+1} \text{ for } i = j \qquad (2.0.14)$$

Forming a matrix **P** whose elements are the coefficients of polynomials in (2.0.11)

$$\mathbf{P} = \begin{pmatrix} P_{11} & 0 & \dots & 0 \\ P_{21} & P_{22} & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ P_{n1} & P_{n2} & \dots & P_{nn} \end{pmatrix}$$
 (2.0.15)

Forming a matrix PAP^T , the elements of the matrix $\mathbf{P}\mathbf{A}\mathbf{P}^T$ can be written as:

$$\mathbf{PAP}_{ij}^{T} = \sum_{s=1}^{N} \sum_{r=1}^{N} P_{ir} P_{js} A_{rs}$$
 (2.0.16)

From (2.0.1) with suitable change in variable notations, we can write:

$$A_{rs} = \int_0^1 x^{r-1} x^{s-1} dx \tag{2.0.17}$$

From (2.0.16) and (2.0.17),

$$\mathbf{PAP}_{ij}^{T} = \int_{0}^{1} \sum_{s=1}^{N} \sum_{r=1}^{N} P_{ir} P_{js} x^{r-1} x^{s-1} dx \qquad (2.0.18)$$

$$= \int_{0}^{1} \sum_{s=1}^{N} P_{ir} x^{r-1} \sum_{r=1}^{N} P_{js} x^{s-1} dx \qquad (2.0.19)$$

$$= \int_{0}^{1} P_{i}(x) P_{j}(x) dx \qquad (2.0.20)$$

From (2.0.14)

$$\mathbf{PAP}_{ij}^{T} = \begin{cases} 0 & i \neq j \\ \frac{1}{2i+1} & i = j \end{cases}$$
 (2.0.21)

Thus, Matrix PAP^T is diagonal matrix:

$$\mathbf{PAP}^{T} = \mathbf{D} = \begin{pmatrix} \frac{1}{3} & 0 & . & . & 0 \\ 0 & \frac{1}{5} & . & . & 0 \\ . & . & . & . & . \\ 0 & 0 & . & . & \frac{1}{2n+1} \end{pmatrix}$$
(2.0.22)
$$\xrightarrow{R_{3}=180R_{3}} \begin{pmatrix} 0 & 0 & 1 & 30 & -180 & 180 \\ \frac{R_{2}=R_{2}-R_{3}}{R_{1}=R_{1}-R_{3}} \begin{pmatrix} 1 & \frac{1}{2} & 0 & -9 & 60 & -60 \\ 0 & 1 & 0 & -36 & 192 & -180 \\ 0 & 0 & 1 & 30 & -180 & 180 \end{pmatrix}$$
From (2.0.22), the inverse of matrix \mathbf{A} can be
$$\xrightarrow{R_{1}=R_{1}-\frac{1}{2}R_{2}} \begin{pmatrix} 1 & 0 & 0 & 9 & -36 & 30 \\ 0 & 1 & 0 & -36 & 192 & -180 \\ 0 & 0 & 1 & 30 & -180 & 180 \end{pmatrix}$$

$$\mathbf{A} = \mathbf{P}^{-1}\mathbf{D}(\mathbf{P}^T)^{-1} \tag{2.0.23}$$

$$\implies \mathbf{A}^{-1} = \mathbf{P}^T \mathbf{D}^{-1} \mathbf{P} \tag{2.0.24}$$

From (2.0.12) and (2.0.22), It can be clearly observed that the elements of matrix \mathbf{P} , \mathbf{P}^T and \mathbf{D}^{-1} are all integers given as:

$$\mathbf{P}_{ij} = (-1)^{i+j-1} \binom{j-1}{i-1} \binom{i+j-2}{i-1}$$
 (2.0.25)

$$\mathbf{D}_{ij}^{-1} = \frac{1}{\mathbf{D}_{ij}} = \begin{cases} 0 & i \neq j \\ 2i+1 & i=j \end{cases}$$
 (2.0.26)

Since, matrix \mathbf{P} , \mathbf{P}^T and \mathbf{D}^{-1} are integer matrices, therefore A^{-1} is also an integer matrix. Hence proved.

3 Solution 2

https://github.com/Arko98/EE5609/blob/master/ Assignment 14

Let A_3 be 3×3 matrix i.e

$$\mathbf{A_3} = \begin{pmatrix} 1 & \frac{1}{2} & \frac{1}{3} \\ \frac{1}{2} & \frac{1}{3} & \frac{1}{4} \\ \frac{1}{3} & \frac{1}{4} & \frac{1}{5} \end{pmatrix}$$
 (3.0.1)

Now we find the inverse of the matrix A_3 as follows,

$$\begin{pmatrix}
1 & \frac{1}{2} & \frac{1}{3} & 1 & 0 & 0 \\
\frac{1}{2} & \frac{1}{3} & \frac{1}{4} & 0 & 1 & 0 \\
\frac{1}{3} & \frac{1}{4} & \frac{1}{5} & 0 & 0 & 1
\end{pmatrix} (3.0.2)$$

$$\stackrel{R_2=R_2-\frac{1}{2}R_1}{\underset{R_3=R_3-\frac{1}{3}R_1}{\longleftarrow}} \begin{pmatrix} 1 & \frac{1}{2} & \frac{1}{3} & 1 & 0 & 0 \\ 0 & \frac{1}{12} & \frac{1}{12} & -\frac{1}{2} & 1 & 0 \\ 0 & \frac{1}{12} & \frac{4}{45} & -\frac{1}{3} & 0 & 1 \end{pmatrix} (3.0.3)$$

$$\begin{pmatrix} 1 & \frac{1}{2} & \frac{1}{3} & 1 & 0 & 0 \\ \frac{1}{2} & \frac{1}{3} & \frac{1}{4} & 0 & 1 & 0 \\ \frac{1}{3} & \frac{1}{4} & \frac{1}{5} & 0 & 0 & 1 \end{pmatrix}$$
(3.0.2)
$$\stackrel{R_2 = R_2 - \frac{1}{2}R_1}{\longleftrightarrow} \begin{pmatrix} 1 & \frac{1}{2} & \frac{1}{3} & 1 & 0 & 0 \\ 0 & \frac{1}{12} & \frac{1}{12} & -\frac{1}{2} & 1 & 0 \\ 0 & \frac{1}{12} & \frac{4}{45} & -\frac{1}{3} & 0 & 1 \end{pmatrix}$$
(3.0.3)
$$\stackrel{R_3 = R_3 - R_2}{\longleftrightarrow} \begin{pmatrix} 1 & \frac{1}{2} & \frac{1}{3} & 1 & 0 & 0 \\ 0 & \frac{1}{12} & \frac{1}{12} & -\frac{1}{2} & 1 & 0 \\ 0 & 0 & \frac{1}{180} & \frac{1}{6} & -1 & 1 \end{pmatrix}$$
(3.0.4)

$$\stackrel{R_2=12R_2}{\longleftrightarrow} \stackrel{1}{\longleftrightarrow} \begin{pmatrix} 1 & \frac{1}{2} & \frac{1}{3} & 1 & 0 & 0\\ 0 & 1 & 1 & -6 & 12 & 0\\ 0 & 0 & 1 & 30 & -180 & 180 \end{pmatrix} (3.0.5)$$

$$\stackrel{R_2 = R_2 - R_3}{\underset{R_1 = R_1 - R_3}{\longleftrightarrow}} \begin{pmatrix}
1 & \frac{1}{2} & 0 & -9 & 60 & -60 \\
0 & 1 & 0 & -36 & 192 & -180 \\
0 & 0 & 1 & 30 & -180 & 180
\end{pmatrix} (3.0.6)$$

$$\stackrel{R_1 = R_1 - \frac{1}{2}R_2}{\longleftrightarrow} \begin{pmatrix} 1 & 0 & 0 & 9 & -36 & 30 \\ 0 & 1 & 0 & -36 & 192 & -180 \\ 0 & 0 & 1 & 30 & -180 & 180 \end{pmatrix} (3.0.7)$$

Hence we see that A_3 is invertible and the inverse as follows, contains integer entries and A_3^{-1} is given by,

$$\mathbf{A_3^{-1}} = \begin{pmatrix} 9 & -36 & 30 \\ -36 & 192 & -180 \\ 30 & -180 & 180 \end{pmatrix}$$
 (3.0.8)

Let, A_4 be 4×4 matrix as follows,

$$\mathbf{A_4} = \begin{pmatrix} 1 & \frac{1}{2} & \frac{1}{3} & \frac{1}{4} \\ \frac{1}{2} & \frac{1}{3} & \frac{1}{4} & \frac{1}{5} \\ \frac{1}{3} & \frac{1}{4} & \frac{1}{5} & \frac{1}{6} \\ \frac{1}{4} & \frac{1}{5} & \frac{1}{6} & \frac{1}{7} \end{pmatrix}$$
 (3.0.9) by,

Now, expressing A_4 using A_3 we get,

$$\mathbf{A_4} = \begin{pmatrix} \mathbf{A_3} & \mathbf{u} \\ \mathbf{u}^{\mathrm{T}} & d \end{pmatrix} \tag{3.0.10}$$

where,

$$\mathbf{u} = \begin{pmatrix} \frac{1}{4} \\ \frac{1}{5} \\ \frac{1}{6} \end{pmatrix}$$
 (3.0.11)
$$d = \frac{1}{-}$$
 (3.0.12)

Now assuming A_4 has an inverse, then from (3.0.10), the inverse of A_4 can be written using block matrix inversion,

Block matrix inversion

where, $x_4 = d - \mathbf{u}^{\mathrm{T}} \mathbf{A}_3^{-1} \mathbf{u}$

If a matrix is partitioned into four blocks, it can be inverted blockwise as follows:

If
$$\mathbf{M} = \begin{pmatrix} \mathbf{A} & \mathbf{B} \\ \mathbf{C} & \mathbf{D} \end{pmatrix}$$
 then,

$$\mathbf{M}^{-1} = \begin{pmatrix} \mathbf{A}^{-1} + \mathbf{A}^{-1} \mathbf{B} \begin{pmatrix} \mathbf{D} - \mathbf{C} \mathbf{A}^{-1} \mathbf{B} \end{pmatrix}^{-1} \mathbf{C} \mathbf{A}^{-1} & -\mathbf{A}^{-1} \mathbf{B} \begin{pmatrix} \mathbf{D} - \mathbf{C} \mathbf{A}^{-1} \mathbf{B} \end{pmatrix}^{-1} \\ - \begin{pmatrix} \mathbf{D} - \mathbf{C} \mathbf{A}^{-1} \mathbf{B} \end{pmatrix}^{-1} \mathbf{C} \mathbf{A}^{-1} & \begin{pmatrix} \mathbf{D} - \mathbf{C} \mathbf{A}^{-1} \mathbf{B} \end{pmatrix}^{-1} \end{pmatrix}$$
(3.0.13)

$$\therefore \mathbf{A}_{4}^{-1} = \begin{pmatrix} \mathbf{A}_{3}^{-1} + \mathbf{A}_{3}^{-1} \mathbf{u} x_{4}^{-1} \mathbf{u}^{\mathsf{T}} \mathbf{A}_{3}^{-1} & -\mathbf{A}_{3}^{-1} \mathbf{u} x_{4}^{-1} \\ -x_{4}^{-1} \mathbf{u}^{\mathsf{T}} \mathbf{A}_{3}^{-1} & x_{4}^{-1} \end{pmatrix}$$

$$= x_{4}^{-1} \begin{pmatrix} \mathbf{A}_{3}^{-1} x_{4} + \mathbf{A}_{3}^{-1} \mathbf{u} \mathbf{u}^{\mathsf{T}} \mathbf{A}_{3}^{-1} & -\mathbf{A}_{3}^{-1} \mathbf{u} \\ \mathbf{u}^{\mathsf{T}} \mathbf{A}_{3}^{-1} & 1 \end{pmatrix}$$

$$(3.0.15)$$

(3.0.16)

Now, the assumption of A_4 being invertible will hold if and only if A_3 is invertible, which has been proved in (3.0.8) and x_4 from (3.0.16) is invertible or x_4 is a nonzero scalar. We now prove that x_4 is invertible

$$x_4 = \frac{1}{7} - \begin{pmatrix} \frac{1}{4} & \frac{1}{5} & \frac{1}{6} \end{pmatrix} \begin{pmatrix} 9 & -36 & 30 \\ -36 & 192 & -180 \\ 30 & -180 & 180 \end{pmatrix} \begin{pmatrix} \frac{1}{4} \\ \frac{1}{5} \\ \frac{1}{6} \end{pmatrix}$$
(3.0.17)

$$\implies x_4 = \frac{1}{2800} \tag{3.0.18}$$

Hence, x_4 is a scalar, hence x_4^{-1} exists and is given

$$x_4^{-1} = 2800 (3.0.19)$$

Hence, A_4 is invertible. Now putting the values of A_3^{-1} , x_4^{-1} and **u** we get,

$$\mathbf{A_3^{-1}} + \mathbf{A_3^{-1}} \mathbf{u} x_4^{-1} \mathbf{u}^{\mathsf{T}} \mathbf{A_3^{-1}} = \begin{pmatrix} 16 & -120 & 240 \\ -120 & 1200 & -2700 \\ 240 & -2700 & 6480 \end{pmatrix}$$
(3.0.20)

$$-\mathbf{A}_{3}^{-1}\mathbf{u}x_{4}^{-1} = \begin{pmatrix} -140\\1680\\-4200 \end{pmatrix}$$
 (3.0.21)

$$x_4^{-1} \mathbf{u}^{\mathrm{T}} \mathbf{A}_3^{-1} = \begin{pmatrix} -140 & 1680 & -4200 \end{pmatrix}$$
(3.0.22)

$$x_4^{-1} = 2800 (3.0.23)$$

Putting values from (3.0.20), (3.0.21), (3.0.22) and (3.0.23) into (3.0.14) we get,

$$\mathbf{A_4^{-1}} = \begin{pmatrix} 16 & -120 & 240 & -140 \\ -120 & 1200 & -2700 & 1680 \\ 240 & -2700 & 6480 & -4200 \\ -140 & 1680 & -4200 & 2800 \end{pmatrix}$$
 (3.0.24)

Hence, from (3.0.24) we proved that, A_4 is invertible and has integer entries.

By successively repeating this method, we can prove that A_5 , A_6 , A_7 ,.... and so on, are invertible and have integer values. Thus, we can say, A_{n-1} will be invertible with integer entries. Then we can represent A_n as follows,

$$\mathbf{A}_{\mathbf{n}} = \begin{pmatrix} \mathbf{A}_{\mathbf{n}-1} & \mathbf{u} \\ \mathbf{u}^{\mathsf{T}} & d \end{pmatrix} \tag{3.0.25}$$

where,

$$\mathbf{u} = \begin{pmatrix} \frac{1}{4} \\ \frac{1}{5} \\ \vdots \\ \frac{1}{2n-2} \end{pmatrix}$$
 (3.0.26)
$$d = \frac{1}{2n-1}$$
 (3.0.27)

Now assuming A_n has an inverse, then from (3.0.32), the inverse of A_n can be written using block matrix inversion as follows,

$$\mathbf{A_{n}}^{-1} = \begin{pmatrix} \mathbf{A_{n-1}}^{-1} + \mathbf{A_{n-1}}^{-1} \mathbf{u} x_{n}^{-1} \mathbf{u}^{T} \mathbf{A_{n-1}}^{-1} & -\mathbf{A_{n-1}}^{-1} \mathbf{u} x_{n}^{-1} \\ -x_{n}^{-1} \mathbf{u}^{T} \mathbf{A_{n-1}}^{-1} & x_{n}^{-1} \end{pmatrix}$$

$$= x_{n}^{-1} \begin{pmatrix} x_{n} \mathbf{A_{n-1}}^{-1} + \mathbf{A_{n-1}}^{-1} \mathbf{u}^{T} \mathbf{A_{n-1}}^{-1} & -\mathbf{A_{n-1}}^{-1} \mathbf{u} \\ -\mathbf{u}^{T} \mathbf{A_{n-1}}^{-1} & 1 \end{pmatrix}$$

$$(3.0.29)$$

where,

$$x_n = d - \mathbf{u}^{\mathrm{T}} \mathbf{A}_{\mathbf{n}-1}^{-1} \mathbf{u} \tag{3.0.30}$$

Now, the assumption of A_n being invertible will hold if and only if A_{n-1} is invertible, which is intuitively proved and x from (3.0.37) is invertible or x_n is a nonzero scalar. We now prove that x_n is invertible as follows,

$$x_{n} = \frac{1}{2n-1} - \left(\frac{1}{4} \quad \frac{1}{5} \quad \dots \quad \frac{1}{2n-2}\right) \mathbf{A}_{\mathbf{n}-1}^{-1} \begin{pmatrix} \frac{1}{4} \\ \frac{1}{5} \\ \dots \\ \frac{1}{2n-2} \end{pmatrix}$$
(3.0.31)

In equation (3.0.38) **u** contains no negative or zero entries, again A_{n-1}^{-1} has non zero integer entries, hence $\mathbf{u}^{\mathrm{T}}\mathbf{A}_{\mathbf{n}-1}^{-1}\mathbf{u}$ is a non zero scalar. Moreover d is not equal to $\mathbf{u}^{\mathrm{T}}\mathbf{A}_{\mathbf{n-1}}^{-1}\mathbf{u}$ hence in (3.0.38) x is non-zero scalar and invertible and hence it has an inverse. Hence A_n is invertible, proved.

Proof for A $_{n+1}$:

Expressing A_{n+1} using A_n we get:

$$\mathbf{A}_{\mathbf{n}+1} = \begin{pmatrix} \mathbf{A}_{\mathbf{n}} & \mathbf{u} \\ \mathbf{u}^{\mathsf{T}} & d \end{pmatrix} \tag{3.0.32}$$

where,

$$\mathbf{u} = \begin{pmatrix} \frac{1}{4} \\ \frac{1}{5} \\ \vdots \\ \frac{1}{2n-1} \end{pmatrix}$$
 (3.0.33)
$$d = \frac{1}{2n}$$
 (3.0.34)

Now assuming A_{n+1} has an inverse, then from (3.0.32), the inverse of A_{n+1} can be written using block matrix inversion as follows,

$$\mathbf{A_{n}}^{-1} = \begin{pmatrix} \mathbf{A_{n-1}}^{-1} + \mathbf{A_{n-1}}^{-1} \mathbf{u} x_{n}^{-1} \mathbf{u}^{T} \mathbf{A_{n-1}}^{-1} & -\mathbf{A_{n-1}}^{-1} \mathbf{u} x_{n}^{-1} \\ -x_{n}^{-1} \mathbf{u}^{T} \mathbf{A_{n-1}}^{-1} & x_{n}^{-1} \end{pmatrix}$$

$$= x_{n}^{-1} \begin{pmatrix} x_{n} \mathbf{A_{n-1}}^{-1} + \mathbf{A_{n-1}}^{-1} \mathbf{u}^{T} \mathbf{A_{n-1}}^{-1} & -\mathbf{A_{n-1}}^{-1} \mathbf{u} \\ -\mathbf{u}^{T} \mathbf{A_{n-1}}^{-1} & 1 \end{pmatrix}$$

$$= x_{n}^{-1} \begin{pmatrix} x_{n} \mathbf{A_{n-1}}^{-1} + \mathbf{A_{n-1}}^{-1} \mathbf{u}^{T} \mathbf{A_{n-1}}^{-1} & -\mathbf{A_{n-1}}^{-1} \mathbf{u} \\ -\mathbf{u}^{T} \mathbf{A_{n-1}}^{-1} & 1 \end{pmatrix}$$

$$= x_{n+1}^{-1} \begin{pmatrix} x_{n+1} \mathbf{A_{n-1}}^{-1} + \mathbf{A_{n-1}}^{-1} \mathbf{u}^{T} \mathbf{A_{n-1}}^{-1} & -\mathbf{A_{n-1}}^{-1} \mathbf{u} \\ -\mathbf{u}^{T} \mathbf{A_{n-1}}^{-1} & 1 \end{pmatrix}$$

$$= x_{n+1}^{-1} \begin{pmatrix} x_{n+1} \mathbf{A_{n-1}}^{-1} + \mathbf{A_{n-1}}^{-1} \mathbf{u}^{T} \mathbf{A_{n-1}}^{-1} & -\mathbf{A_{n-1}}^{-1} \mathbf{u} \\ -\mathbf{u}^{T} \mathbf{A_{n-1}}^{-1} & 1 \end{pmatrix}$$

$$= x_{n+1}^{-1} \begin{pmatrix} x_{n+1} \mathbf{A_{n-1}}^{-1} + \mathbf{A_{n-1}}^{-1} \mathbf{u}^{T} \mathbf{A_{n-1}}^{-1} & -\mathbf{A_{n-1}}^{-1} \mathbf{u} \\ -\mathbf{u}^{T} \mathbf{A_{n-1}}^{-1} & 1 \end{pmatrix}$$

$$= x_{n+1}^{-1} \begin{pmatrix} x_{n+1} \mathbf{A_{n-1}}^{-1} + \mathbf{A_{n-1}}^{-1} \mathbf{u}^{T} \mathbf{A_{n-1}}^{-1} & -\mathbf{A_{n-1}}^{-1} \mathbf{u} \\ -\mathbf{u}^{T} \mathbf{A_{n-1}}^{-1} & 1 \end{pmatrix}$$

$$= x_{n+1}^{-1} \begin{pmatrix} x_{n+1} \mathbf{A_{n-1}}^{-1} + \mathbf{A_{n-1}}^{-1} \mathbf{u}^{T} \mathbf{A_{n-1}}^{-1} & -\mathbf{A_{n-1}}^{-1} \mathbf{u} \\ -\mathbf{u}^{T} \mathbf{A_{n-1}}^{-1} & 1 \end{pmatrix}$$

$$= x_{n+1}^{-1} \begin{pmatrix} x_{n+1} \mathbf{A_{n-1}}^{-1} + \mathbf{A_{n-1}}^{-1} \mathbf{u}^{T} \mathbf{A_{n-1}}^{-1} & -\mathbf{A_{n-1}}^{-1} \mathbf{u} \\ -\mathbf{u}^{T} \mathbf{A_{n-1}}^{-1} & 1 \end{pmatrix}$$

$$= x_{n+1}^{-1} \begin{pmatrix} x_{n+1} \mathbf{A_{n-1}}^{-1} + \mathbf{A_{n-1}}^{-1} \mathbf{u}^{T} \mathbf{A_{n-1}}^{-1} & -\mathbf{A_{n-1}}^{-1} \mathbf{u} \\ -\mathbf{u}^{T} \mathbf{A_{n-1}}^{-1} & 1 \end{pmatrix}$$

$$= x_{n+1}^{-1} \begin{pmatrix} x_{n+1} \mathbf{A_{n-1}}^{-1} + \mathbf{A_{n-1}}^{-1} \mathbf{u}^{T} \mathbf{A_{n-1}}^{-1} & -\mathbf{A_{n-1}}^{-1} \mathbf{u} \\ -\mathbf{u}^{T} \mathbf{A_{n-1}}^{-1} & -\mathbf{A_{n-1}}^{-1} \mathbf{u} \end{pmatrix}$$

$$= x_{n+1}^{-1} \begin{pmatrix} x_{n+1} \mathbf{A_{n-1}} + \mathbf{A_{n-1}}^{-1} \mathbf{u}^{T} \mathbf{A_{n-1}} & -\mathbf{A_{n-1}}^{-1} \mathbf{u} \\ -\mathbf{u}^{T} \mathbf{A_{n-1}}^{-1} & -\mathbf{A_{n-1}}^{-1} \mathbf{u} \end{pmatrix}$$

$$= x_{n+1}^{-1} \begin{pmatrix} x_{n+1} \mathbf{A_{n-1}} + \mathbf{A_{n-1}}^{-1} \mathbf{u}^{T} \mathbf{A_{n-1}} & -\mathbf{A_{n-1}}^{-1} \mathbf{u} \\ -\mathbf{u}^{T} \mathbf{A_{n-1}} & -\mathbf{A_{n-1}}^{-1} \mathbf{u} \end{pmatrix}$$

where,

$$x_{n+1} = d - \mathbf{u}^{\mathrm{T}} \mathbf{A}_{\mathbf{n}}^{-1} \mathbf{u} \tag{3.0.37}$$

Now, the assumption of A_{n+1} being invertible will hold if and only if A_n is invertible, which is proved and x from (3.0.37) is invertible or x_{n+1} is a nonzero scalar. We now prove that x_{n+1} is invertible as follows,

$$x_{n+1} = \frac{1}{2n} - \left(\frac{1}{4} \quad \frac{1}{5} \quad \dots \quad \frac{1}{2n-1}\right) \mathbf{A}_{\mathbf{n}}^{-1} \begin{pmatrix} \frac{1}{4} \\ \frac{1}{5} \\ \dots \\ \frac{1}{2n-1} \end{pmatrix}$$
 (3.0.38)

In equation (3.0.38) **u** contains no negative or zero entries, again A_n^{-1} has non zero integer entries, hence $\mathbf{u}^{\mathrm{T}}\mathbf{A}_{\mathbf{n}}^{-1}\mathbf{u}$ is a non zero scalar. Moreover d is not equal to $\mathbf{u}^{\mathrm{T}}\mathbf{A}_{\mathbf{n}}^{-1}\mathbf{u}$ hence in (3.0.38) x is non-zero scalar and invertible and hence it has an inverse. Hence A_{n+1} is also invertible.

4 Observations:

- 1) The given matrix is a $n \times n$ Hilbert matrix. Which is always invertible with its inverse having integer values.
- 2) The Hilbert matrix is symmetric and positive definite.