

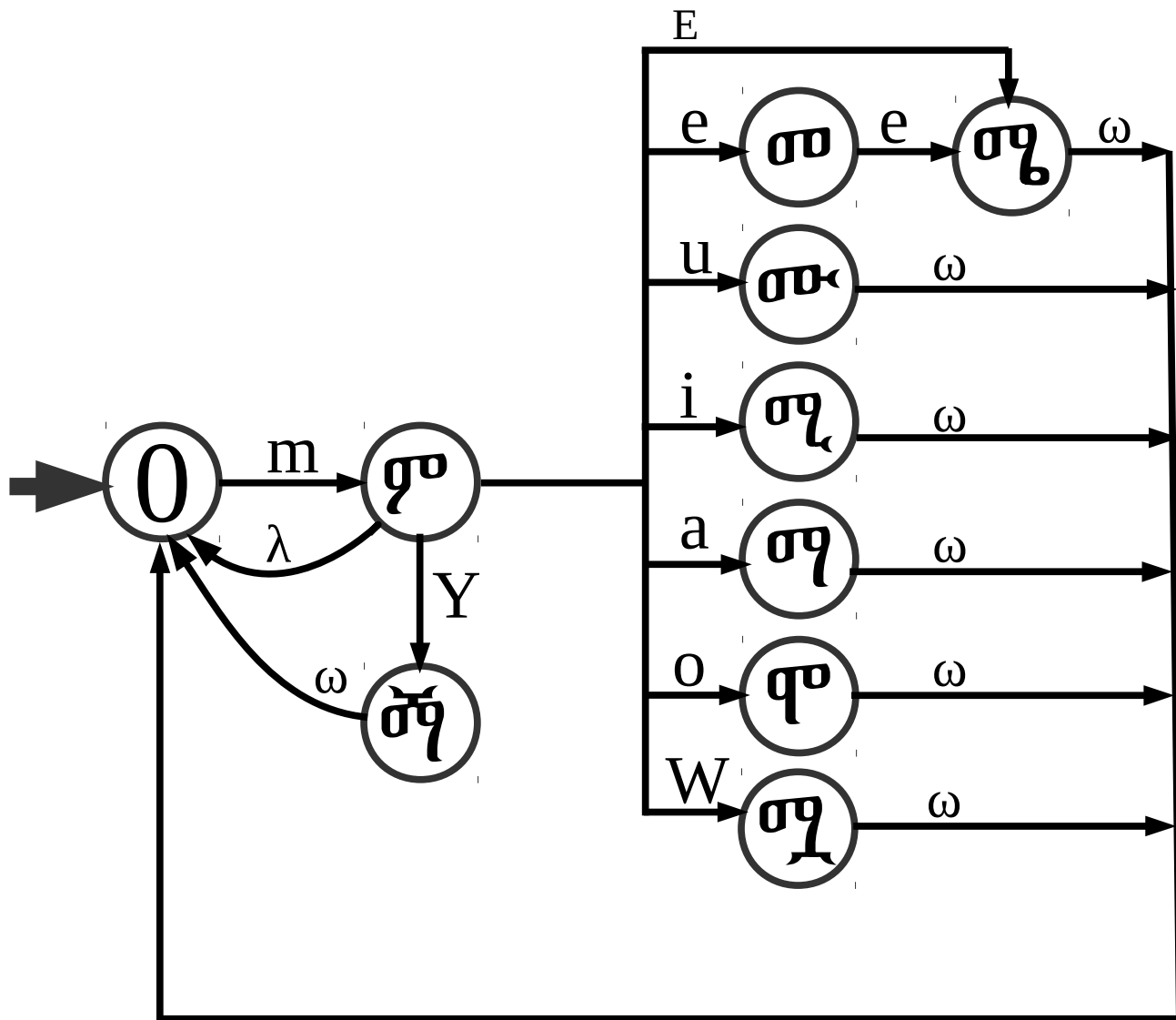
CASE INSENSITIVE:

$m \equiv \{b|B, f|F, j|J, l|L, m|M, r|R, v|V, w|W, x|X, y|Y\}$

$\lambda \equiv \text{any other key}$

$\omega \equiv \text{return to state 0 without input}$

$(f|F)Y \rightarrow \text{Z}$ AND $(m|M)Y \rightarrow \text{Y}$

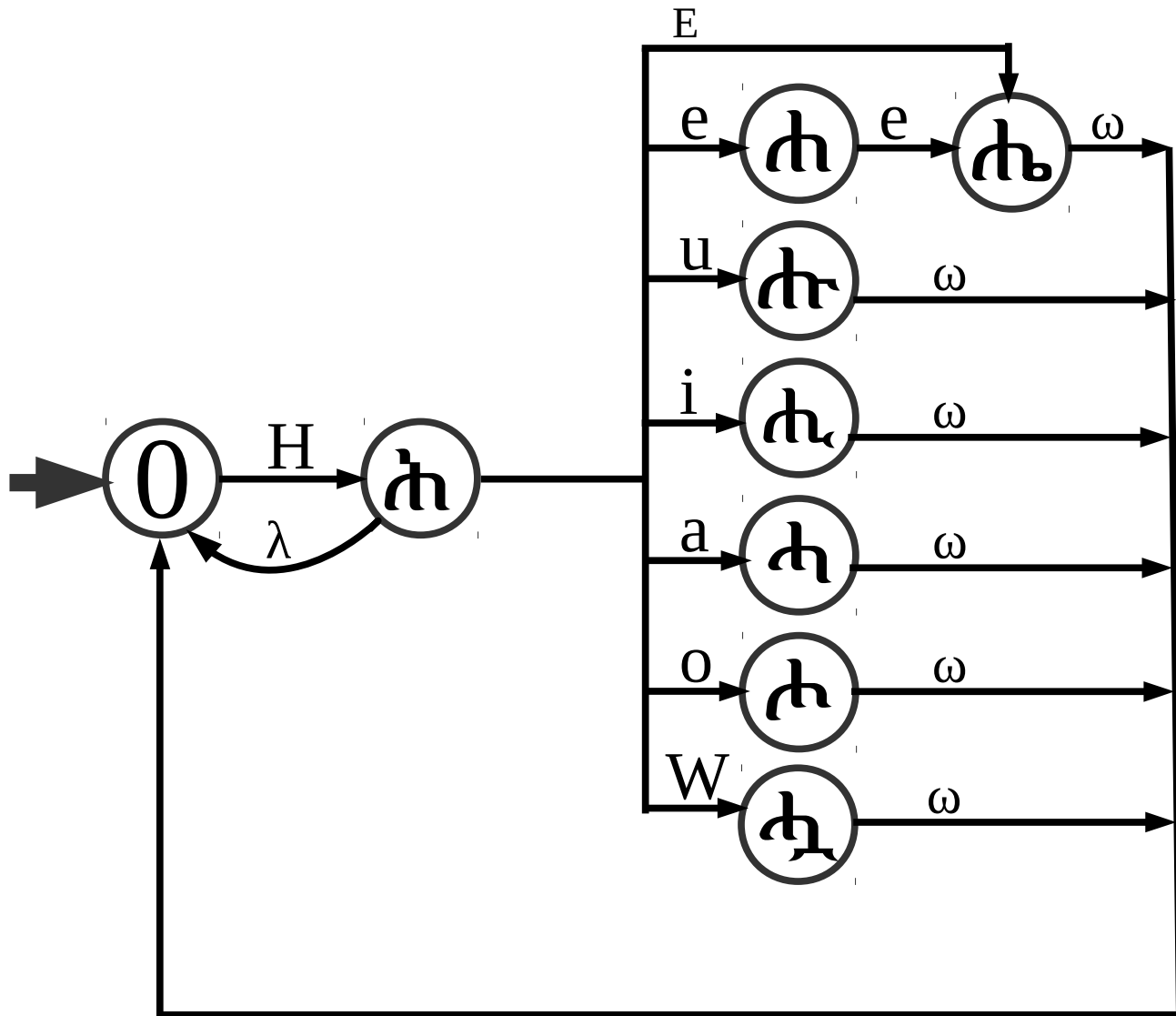


CASE SENSITIVE:

$m \equiv \{c, C, d, D, g, G, H, k, K, n, N, p, P, q, Q, t, T, z, Z\}$

$\lambda \equiv \text{any other key}$

$\omega \equiv \text{return to state 0 without input}$

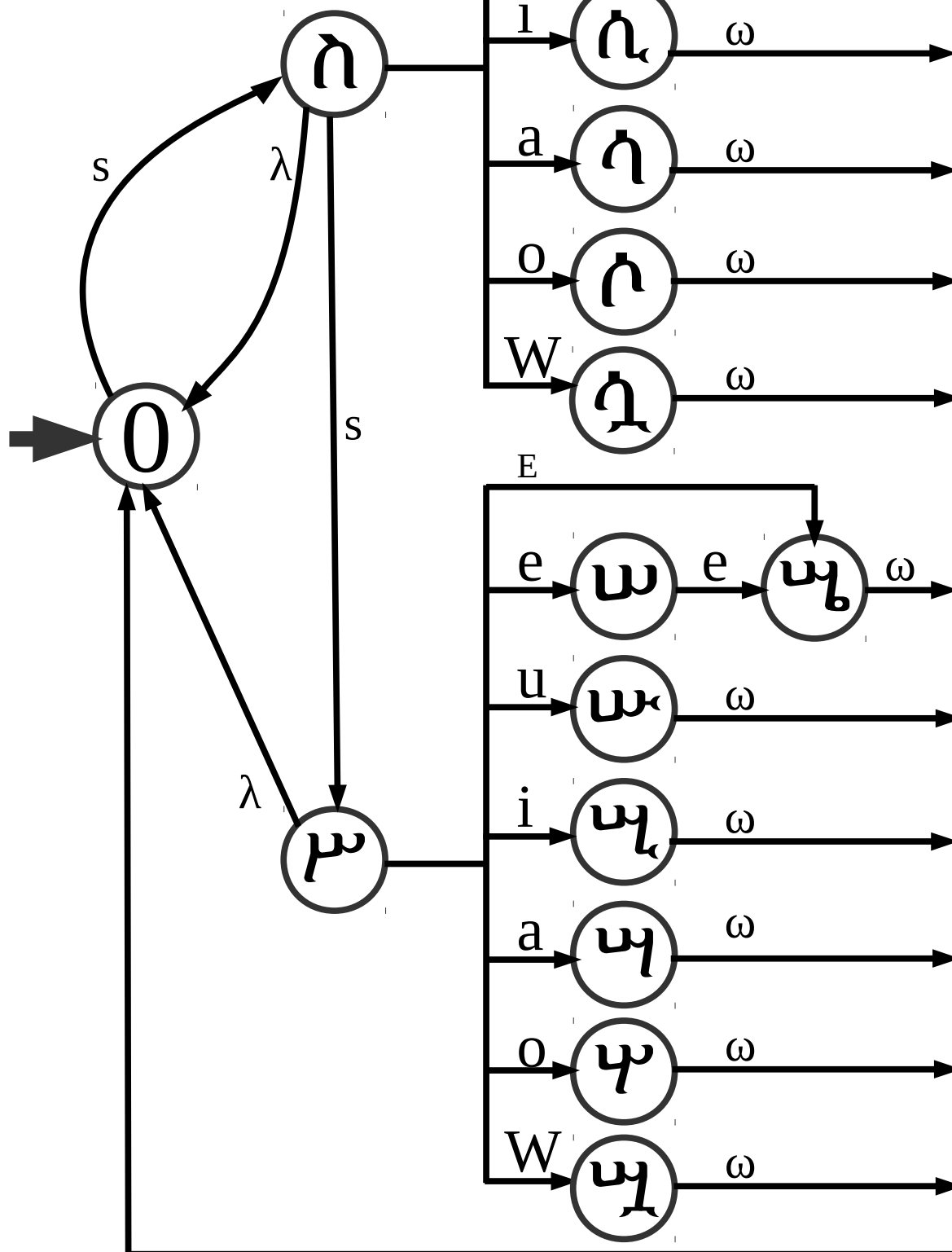


μ AND λ :

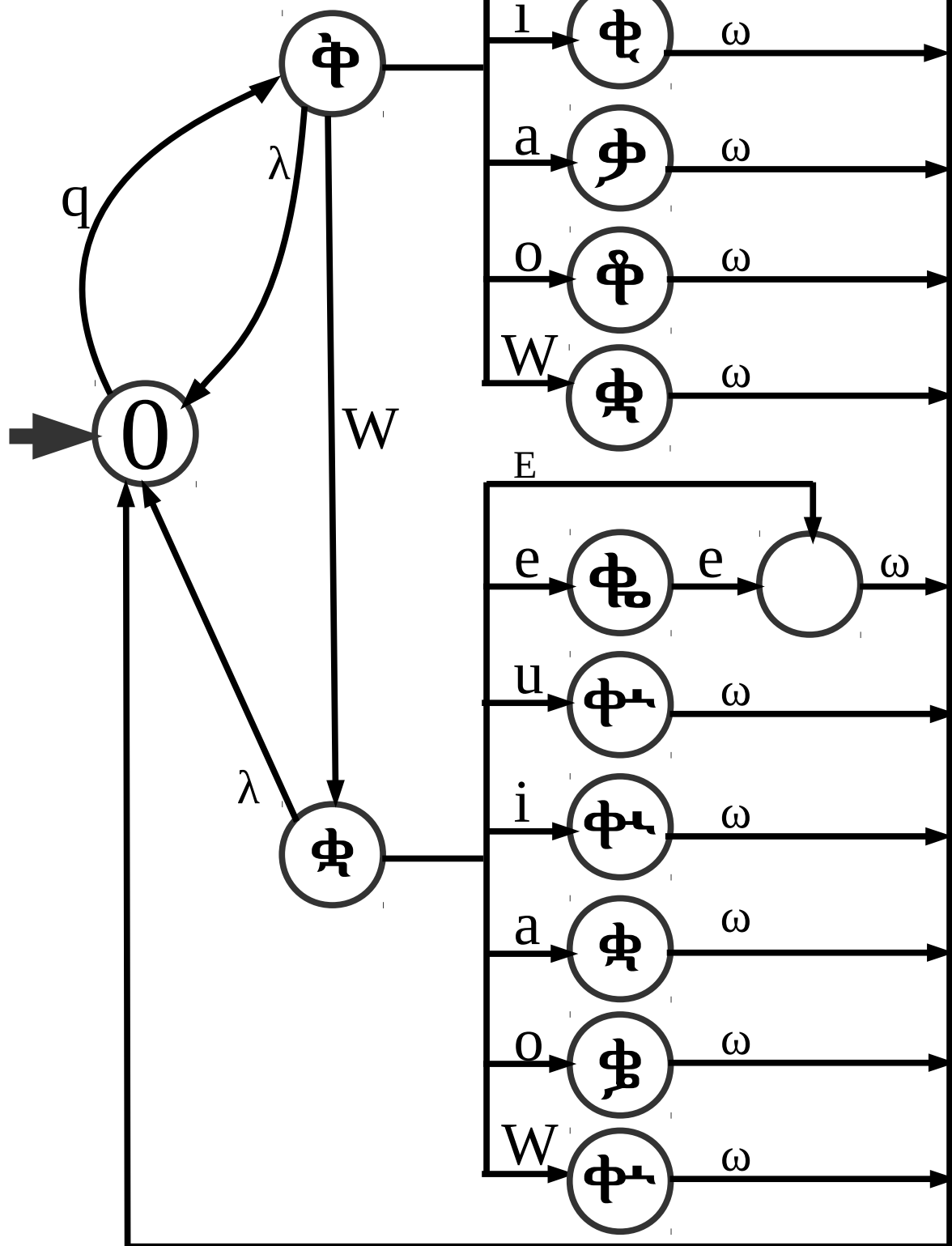
$s \equiv \{h, s, S\}$

$\lambda \equiv \text{any other key}$

$\omega \equiv$ return to state 0
without input



$\omega \equiv$ return to state 0
without input



CONSONANTS:

$\alpha \in A = \{b|B, f|F, j|J, l|L, m|M, r|R, v|V, w|W, x|X, y|Y\}$

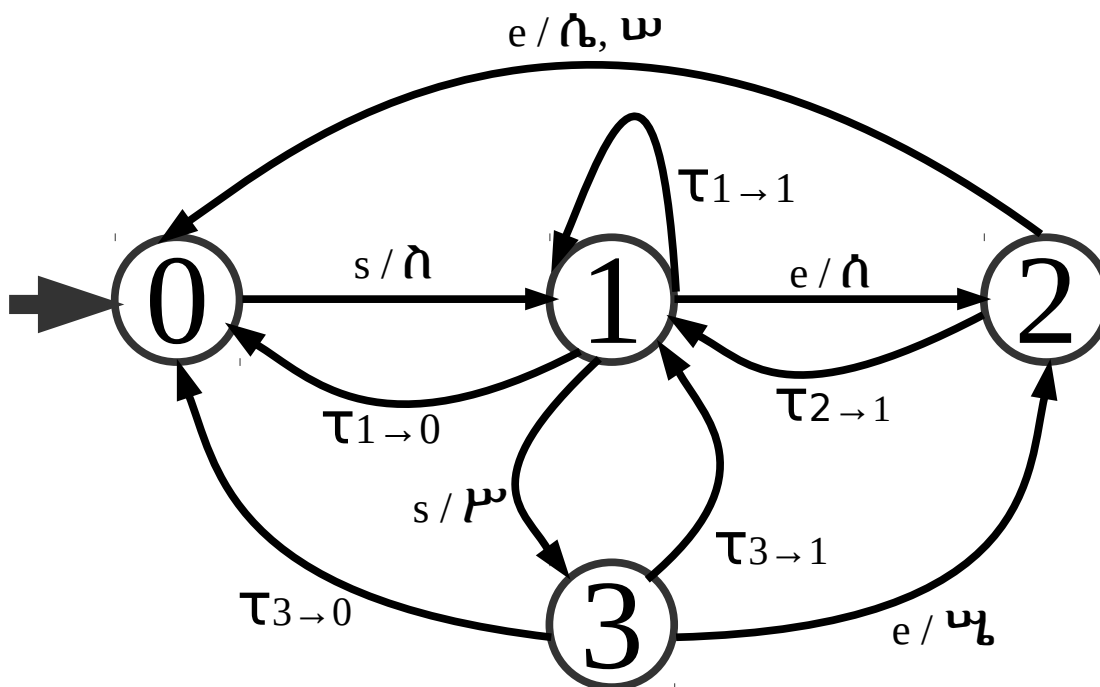
$\beta \in B = \{c, C, d, D, G, H, n, N, p, P, t, T, z, Z\}$

$\gamma \in C = \{g, k, K, q, Q\}$

$\delta \in D = \{h, s, S\}$

$\lambda \in A \cup B \cup C \cup D$

$\theta = \lambda - \delta \iff \theta \in A \cup B \cup C$



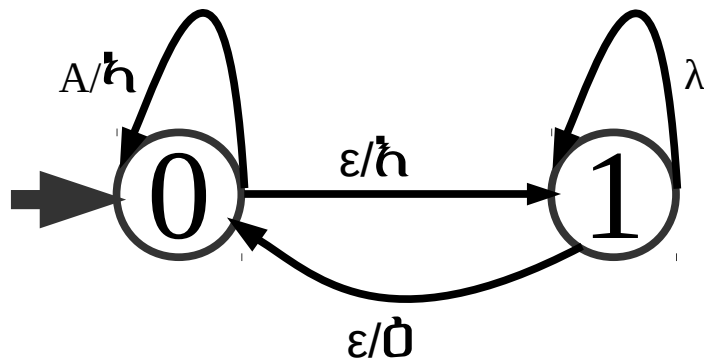
τ : STATE TRANSITIONS

$\tau(\text{current_state}, \text{temp_output}, \text{next_input}) \rightarrow (\text{output}, \text{next_state})$

$\tau_{0 \rightarrow 1} \quad \tau_{1 \rightarrow 0} \quad \tau_{1 \rightarrow 1} \quad \tau_{1 \rightarrow 2} \quad \tau_{1 \rightarrow 3}$

$\tau_{2 \rightarrow 0} \quad \tau_{2 \rightarrow 1}$

$\tau_{3 \rightarrow 0} \quad \tau_{3 \rightarrow 1} \quad \tau_{3 \rightarrow 2}$

VOWELS: $\varepsilon \in \{a, A, e, E, i, o, u\}$ 

Initial State	Temporary Output	Input	Next State	Output	Action on Output
0	null	a	1	$h = \text{anababi}(a)$	temp_out = a
0	null	e	1	$h = \text{anababi}(e)$	temp_out = e
0	null	i	1	$h = \text{anababi}(i)$	temp_out = i
0	null	o	1	$h = \text{anababi}(o)$	temp_out = o
0	null	u	1	$h = \text{anababi}(u)$	temp_out = u
0	null	A	0	$h = \text{anababi}(A)$	temp_out = null
0	null	E	1	$h = \text{anababi}(E)$	temp_out = E

Initial State	Temporary Output	Input	Next State	Output	Action on Output
1	anababi(a)	a	0	٩	temp_out = null
1	anababi(a)	e	0	0	temp_out = null
1	anababi(e)	a	0	٩	temp_out = null
	anababi(e)	e	0	0	temp_out = null
1	anababi(E)	E	0	٩	temp_out = null
1	anababi(i)	i	0	٩	temp_out = null
1	anababi(o)	o	0	٩	temp_out = null
1	anababi(u)	u	0	0	temp_out = null
1	anababi(ε)	λ	1	sadis(λ)	temp_out = sadis(λ)

Initial State	Temporary Output	Input	Next State	Output	Action on Output
0	null	λ	1	sadis(λ)	temp_out = out
1	sadis(λ)	a	0	rabee(λ)	temp_out = null
1	sadis(λ)	i	0	salis(λ)	temp_out = null
1	sadis(λ)	o	0	sabee(λ)	temp_out = null
1	sadis(λ)	u	0	kaeeb(λ)	temp_out = null
1	sadis(λ)	W	0	z_rabee(λ)	temp_out = null
1	sadis(λ)	Y	0	fia_mia(λ)	temp_out = null
1	sadis(λ)	E	0	hamis(λ)	temp_out = null
1	sadis(λ)	e	2	geez(λ)	temp_out = out
1	sadis(λ_1)	λ_2	1	sadis(λ_2)	temp_out = out
1	sadis(δ)	$\lambda \neq \delta$	1	sadis(λ)	temp_out = out
1	sadis(δ)	δ	3	sadis(δ^2)	temp_out = out
1	sadis(γ)	W	3	sadis(γW)	temp_out = out
2	geez(λ)	e	0	hamis(λ)	temp_out = null
2	geez(λ_1)	λ_2	1	sadis(λ_2)	temp_out = out

Initial State	Temporary Output	Input	Next State	Output	Action on Output
3	sadis(δ^2)	λ	1	sadis(λ)	temp_out = out
3	sadis(γW)	λ	1	sadis(λ)	temp_out = out
3	sadis(λ)	a	0	rabee(λ)	temp_out = null
3	sadis(λ)	i	0	salis(λ)	temp_out = null
3	sadis(λ)	o	0	sabee(λ)	temp_out = null
3	sadis(λ)	u	0	kaeeb(λ)	temp_out = null
3	sadis(λ)	W	0	z_rabee(λ)	temp_out = null
3	sadis(λ)	Y	0	fia_mia(λ)	temp_out = null
3	sadis(λ)	E	0	hamis(λ)	temp_out = null
3	sadis(λ)	e	2	geez(λ)	temp_out = out