

Stack. Representations

initEmpty

push

pop

isEmpty

$O(1)$

- over array (/ vector)
- over linked-list

Queue. Representations

initEmpty
enqueue
dequeue
isEmpty

$O(1)$

- over array (/ vector)
- over linked-list

Deque. Representations

initEmpty
push_back
push_front
pop_back
pop_front
isEmpty

$O(1)$

- over array (/ vector)
- over linked-list

STL: Stack, Queue. Issues

std::stack - container adaptor

```
template < class T, class Container = deque<T> > class queue;
```

- the underlying container
 - back()
 - push_back()
 - pop_back()

std::queue - container adaptor

```
template < class T, class Container = deque<T> > class queue;
```

- the underlying container
 - front()
 - back()
 - push_back()
 - pop_front()

STL: deque

Deque:

- Specific libraries may implement deque in different ways
 - generally as some form of dynamic array
- with efficient insertion and deletion of elements at the beginning and at its end.

Vector vs. deque

provide a very similar interface and can be used for similar purposes
internally can be quite different

Vector: use a single array

Deque: deques are not guaranteed to store all its elements in contiguous storage locations

can be scattered in different chunks of storage

ex.: implemented as a vector of vectors

Java: Stack, Queue, Deque. Issues

Java™ Platform
Standard Ed. 7

Interface :

Subinterface:

Implementing Classes:

Queue

Deque

ArrayDeque

LinkedList

Java: Stack, Queue, Deque. Issues

Java™ Platform
Standard Ed. 7

```
public class Stack<E>  
extends Vector<E>
```

- Use Deque instead of Stack

```
Deque<Integer> stack = new ArrayDeque<Integer>();
```

A more complete and consistent set of LIFO stack operations is provided by the Deque interface and its implementations,
which *should be used in preference* to this class.

Lists. Variations

- Multiple Values Per Node

ULNode = record

 next: Position

 elemCount: integer

 elemData: array[0..MAX-1] of TElement

end

Position = [^]**ULNode**

Terminology: **unrolled linked list**

Lists. Variations

- with multiple links from nodes

Node = *record*:

***info*: TElement**

***links*: List<Position> //array, record, linked**

end

Terminology: General Linked Lists

 Multiply Linked List

 Multi-Linked Lists

Multidimensional arrays

For example:

C++ : described as "arrays of arrays".

```
int matrix [3][5];  
    matrix[1][3]
```

the second element vertically and fourth horizontally

Using STL : Vector based multi-dim. array

```
vector<vector<double> > array2D  
// Put some values in  
array2D[1][2] = 6.0
```

Jagged arrays

many rows of varying lengths

For example:

```
int jagged_row0[] = {0,1};  
int jagged_row1[] = {1,2,3};  
int *jagged[] = { jagged_row0,  
                  jagged_row1 };
```

Lists. Variations. Application

Sparse Matrices

Sparse Matrix

- sparse ... many elements are zero
- dense ... few elements are zero

Structured sparse

- diagonal
- tridiagonal
- upper/lower triangular (?)

Unstructured sparse matrix. Example

- Web page matrix.
 - web pages are numbered 1 through n
 - $\text{web}(i,j)$ = number of links from page i to page j
- $n \sim 10^9$
- $n \times n$ array $\Rightarrow 10^{18}$ consecutive position
(linear representation)
- each page links to 10 (say) other pages on average
on average there are 10 nonzero entries per row
- space needed for non-*empty* elements is approximately
1 billion $\times 10 = 10^{10}$ consecutive elements

- **sparse matrix** is a matrix populated primarily with zeros
- How to store it will depend at least partly on exactly how sparse it is, and what you want to do.
 - For some applications, just treating it as a regular matrix is just fine (especially if the dimensions aren't very big). A 15x15 sparse matrix isn't a big memory hog.
 - suppose the sparse matrix has 10240x10240 elements, and you're using 8-byte floating point numbers: how much memory do you need?
- **Representation of sparse matrix** (idea)
 - list: keep information about non-zero cells
 - links: for fast access from one non-zero cell to the next, on the same row/column ← general linked list

sparse matrix

Unstructured Sparse Matrices. Representations

linear list in row-major order.

- nonzero elements of the sparse matrix
- each nonzero element is represented by a triple
(row, column, value)

→ the list of triples (linked , ...)

0 0 3 0 4

0 0 5 7 0

0 0 0 0 0

0 2 6 0 0

List:

row 1 1 2 2 4 4

column 3 5 3 4 2 3

value 3 4 5 7 2 6

One Linear List Per Row

0 0 3 0 4

0 0 5 7 0

0 0 0 0 0

0 2 6 0 0

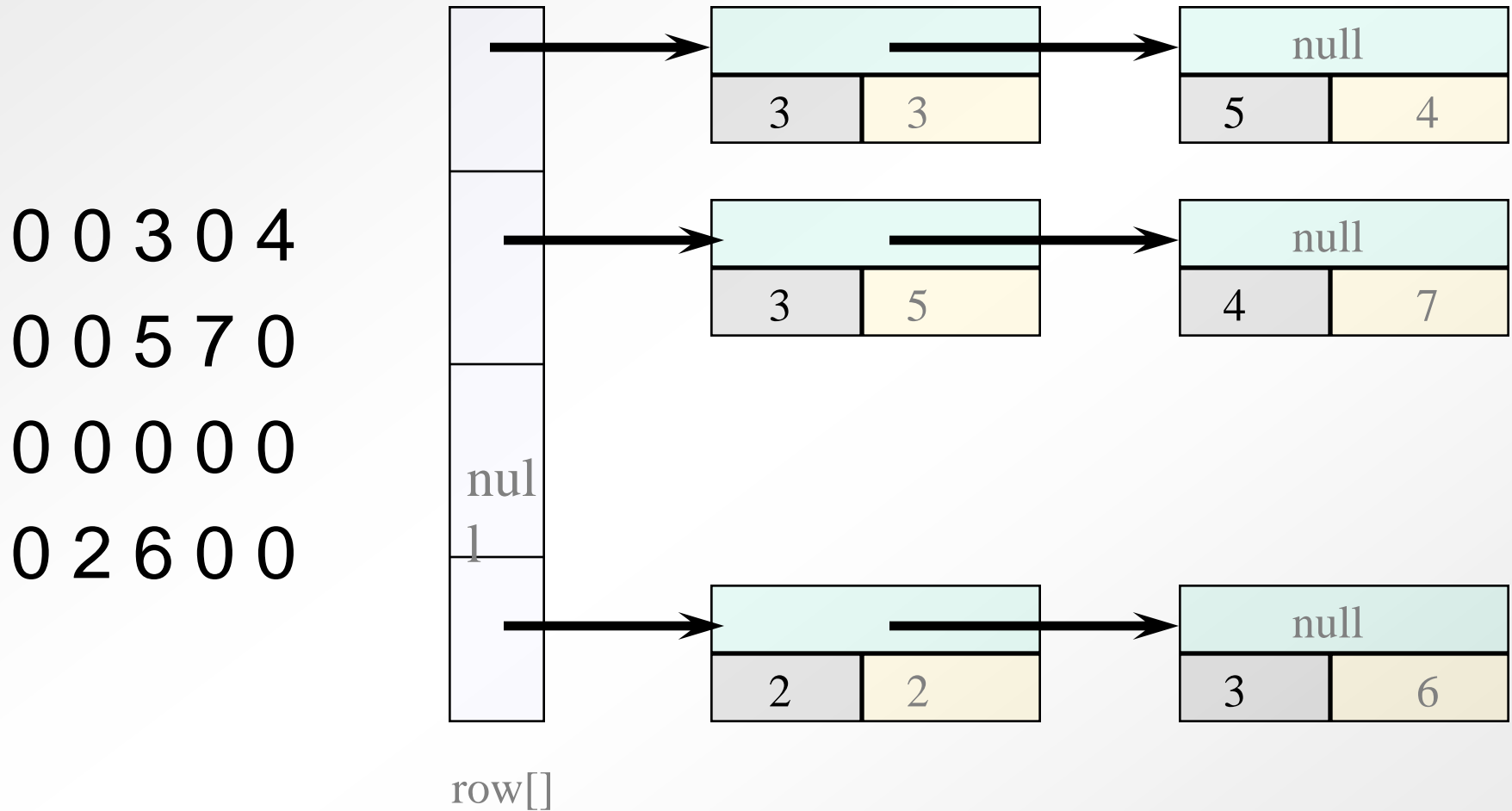
row1 = [(3, 3), (5,4)]

row2 = [(3,5), (4,7)]

row3 = []

row4 = [(2,2), (3,6)]

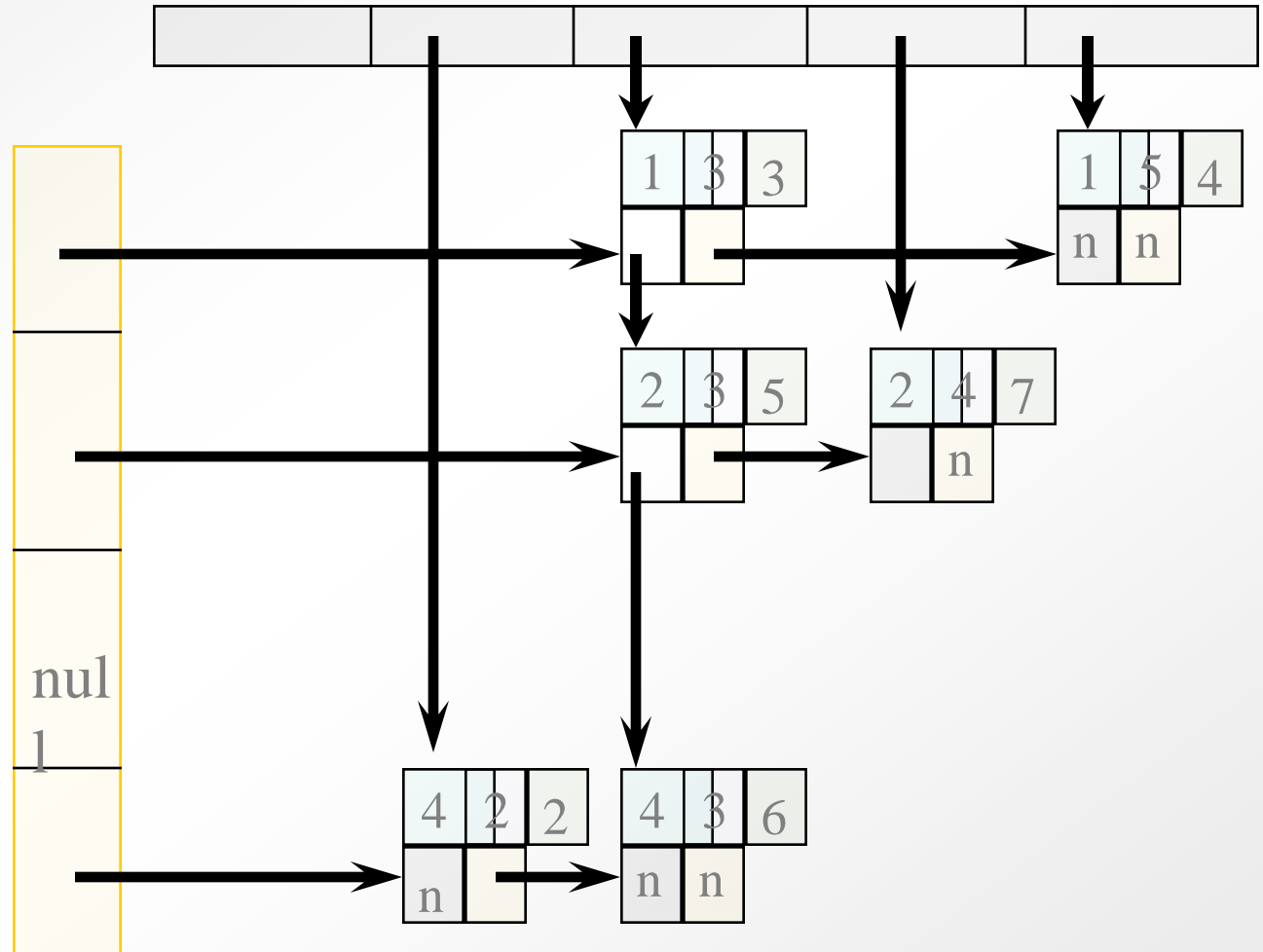
One Linear List Per Row (Linked)



Similar: one list per column

Orthogonal Lists

0 0 3 0 4
0 0 5 7 0
0 0 0 0 0
0 2 6 0 0



Variation: use circular lists

```

#include <iostream>
#include <string>

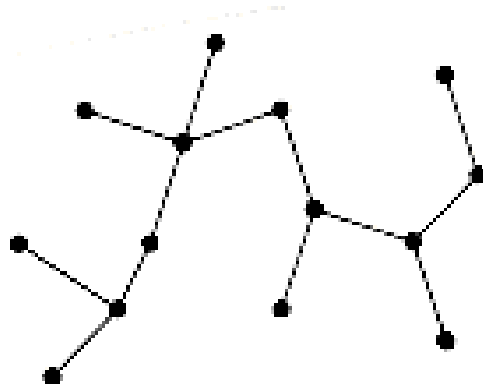
typedef char * CString;
typedef CString* TJaggedArray;
//typedef char** TJaggedArray;

void readStrings(TJaggedArray& str)
{
    int n;
    char myStr[200];
    std::cin >> n;
    str = new CString[n+1];
    str[n]=NULL;
    for(int i=0; i<n;i++){
        std::cin >> myStr;
        str[i]=new char[strlen(myStr)+1];
        strcpy(str[i],myStr);
    }
}

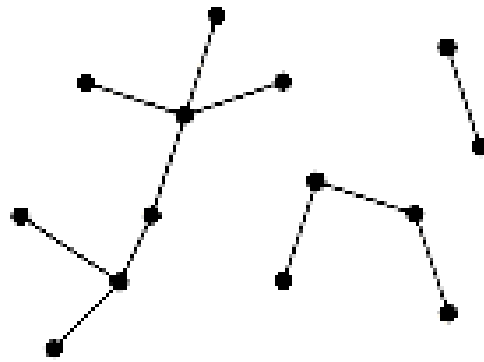
void printStrings(const TJaggedArray& str)
{
    for(int i = 0; str[i] != NULL ; i++) {
        std::cout << strlen(str[i]) <<" : " << str[i] << std::endl;
    }
}

```

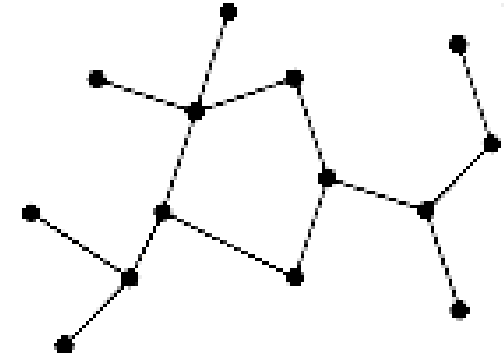
Tree



(a)



(b)



(c)

Tree

Free tree (graph theory)

- any two vertices are connected
- no cycles

Rooted tree

- **+ root** : one of the nodes is distinguished from the others

Ordered tree (most used in computer science)

- is a rooted tree in which the children of each node are ordered
if a node has k children, then there is a first child, a second child, . . . , and a k -th child

Data Structure → rooted, ordered tree
(for us, by default)

Tree

recursive definition

Tree:

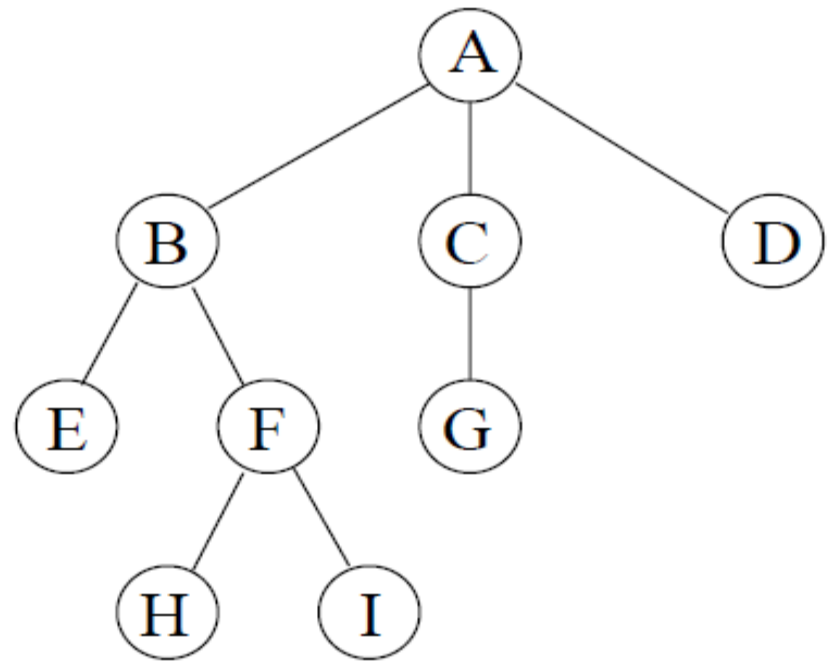
is empty
or it has a root **r** and 0 or more sub-trees

Properties:

- Each node has exactly one “*predecessor*” – its parent
- has exactly zero, one or more “*successors*” – its children

Trees

- root
- parent , children, sibling
- ancestor , descendants
- leaves , internal
- depth (level) , height
- degree



Tree

Node degree – the number of descendants

Node depth (level)

- the length of the path to the root
- root – depth 0

Node height:

- the longest path from that node to a leaf (of the tree)
- (equivalent) the height of the subtree having that node as root

If the last edge on the path from the root r of a tree T to a node x is (y, x) , then y is the **parent** of x , and x is a **child** of y .

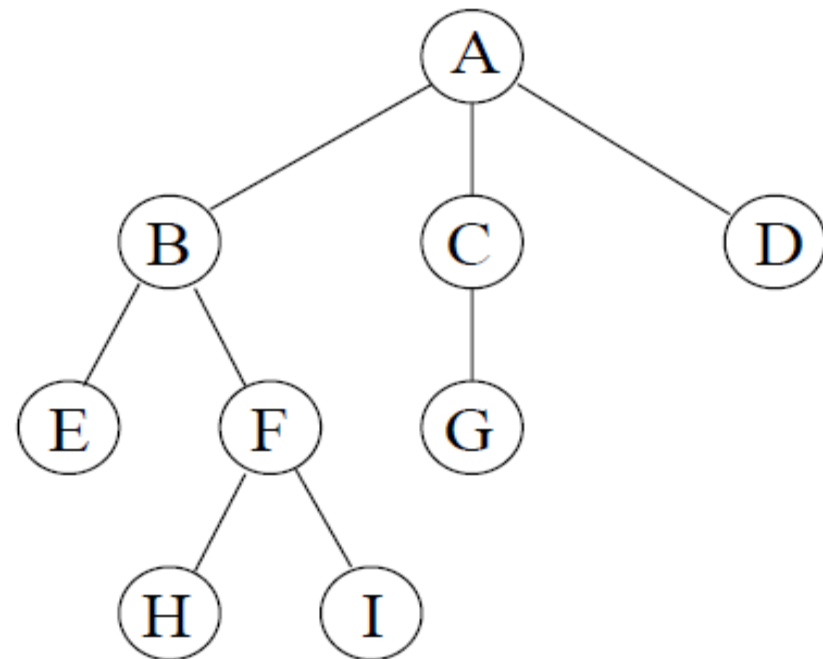
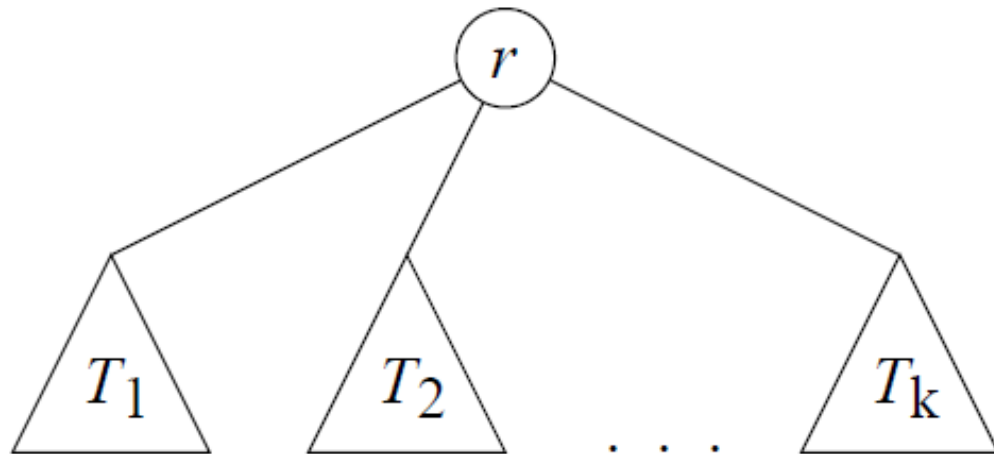
If two nodes have the same parent, they are **siblings**.

The root is the only node in T with no parent.

A node with no children is a **leaf**. A non-leaf node is an **internal node**.

k-ary tree

- A ***k*-ary tree** – each node have at most ***k*** descendants



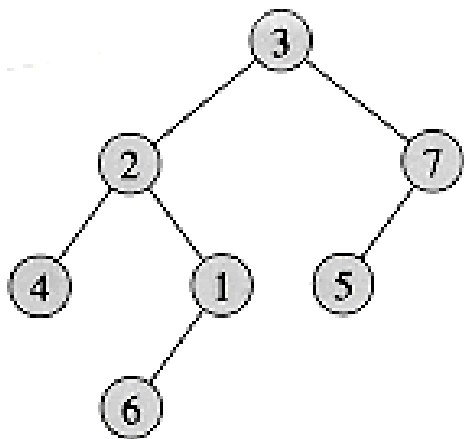
Binary trees

Rooted trees

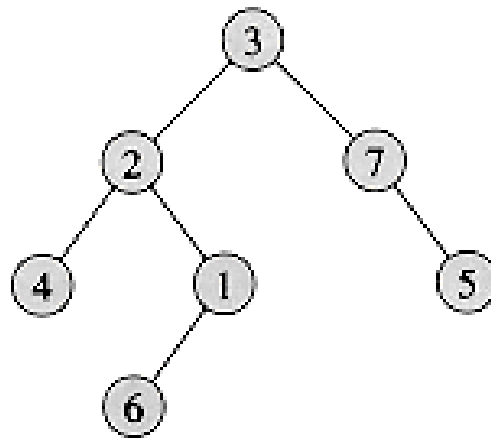
each node have at most two descendants.

- first descendant is the left descendant
- second descendant is the right descendant

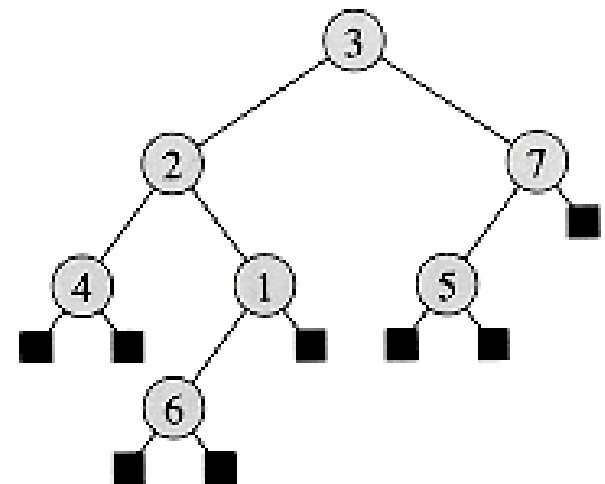
A tree with N nodes has $N-1$ edges



(a)



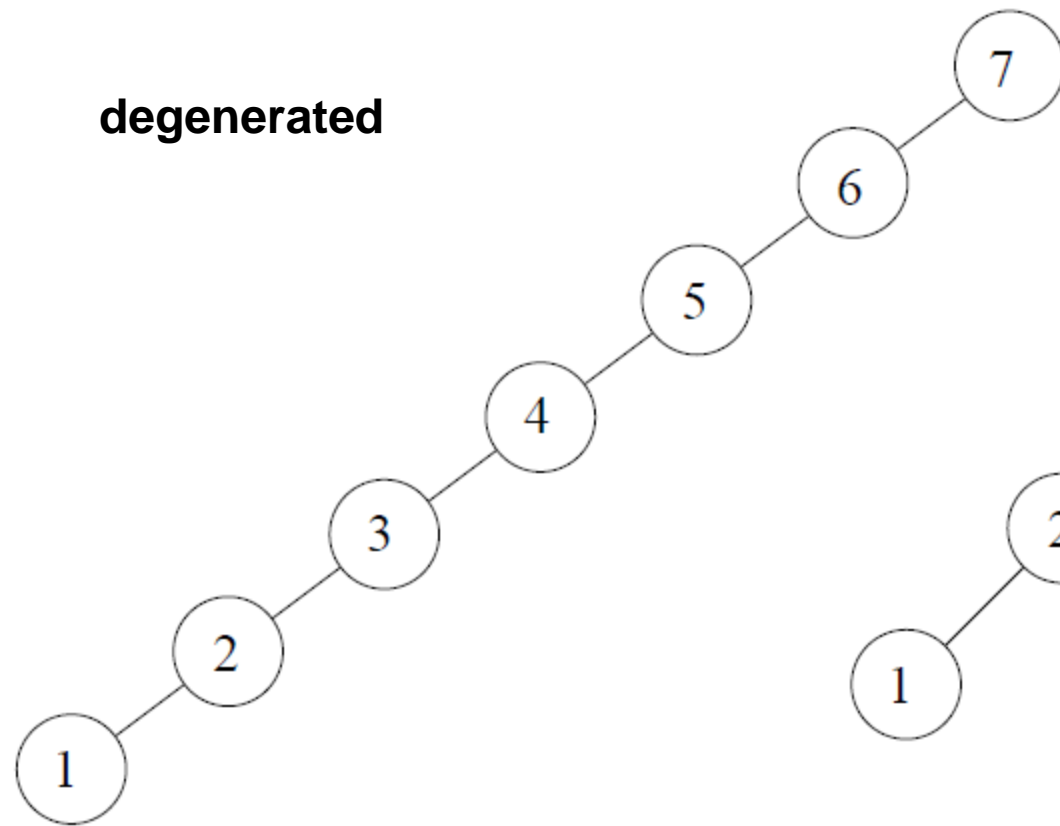
(b)



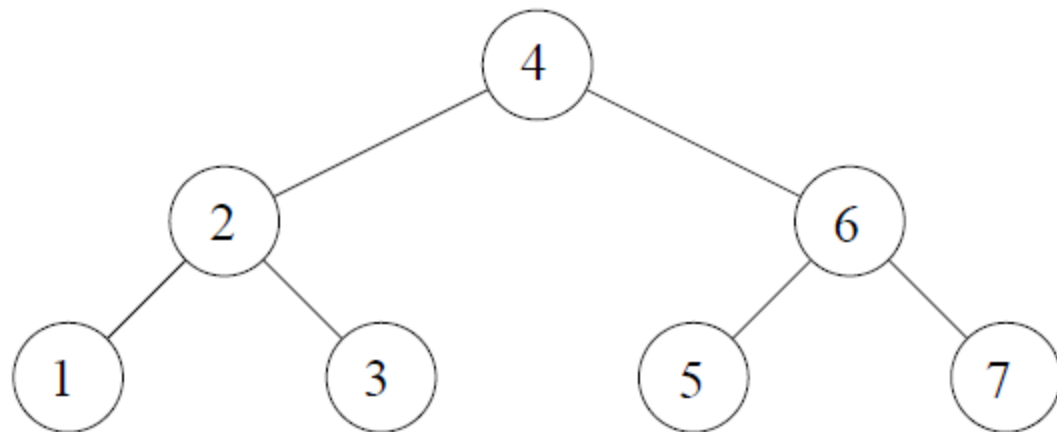
(c)

Binary trees

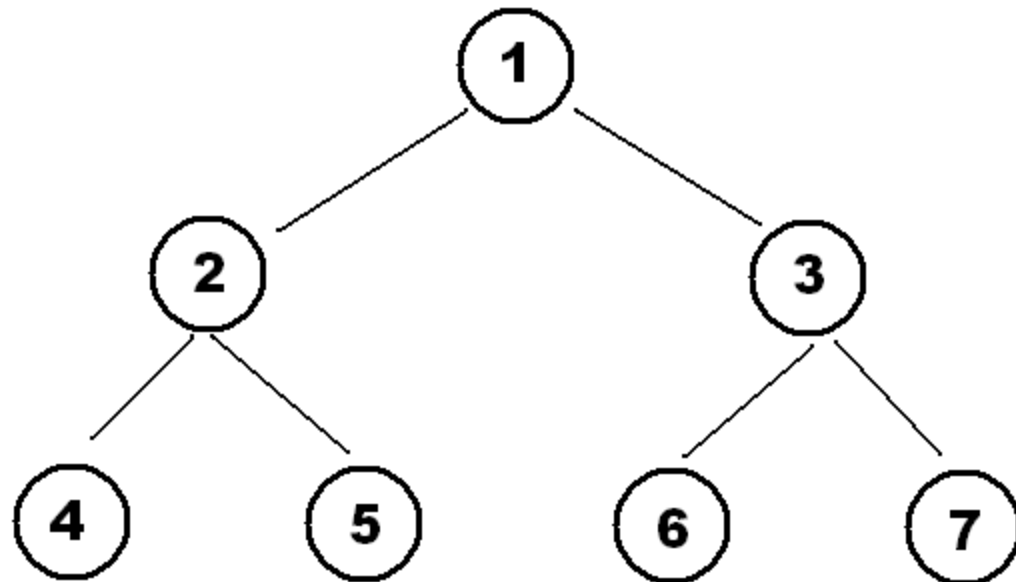
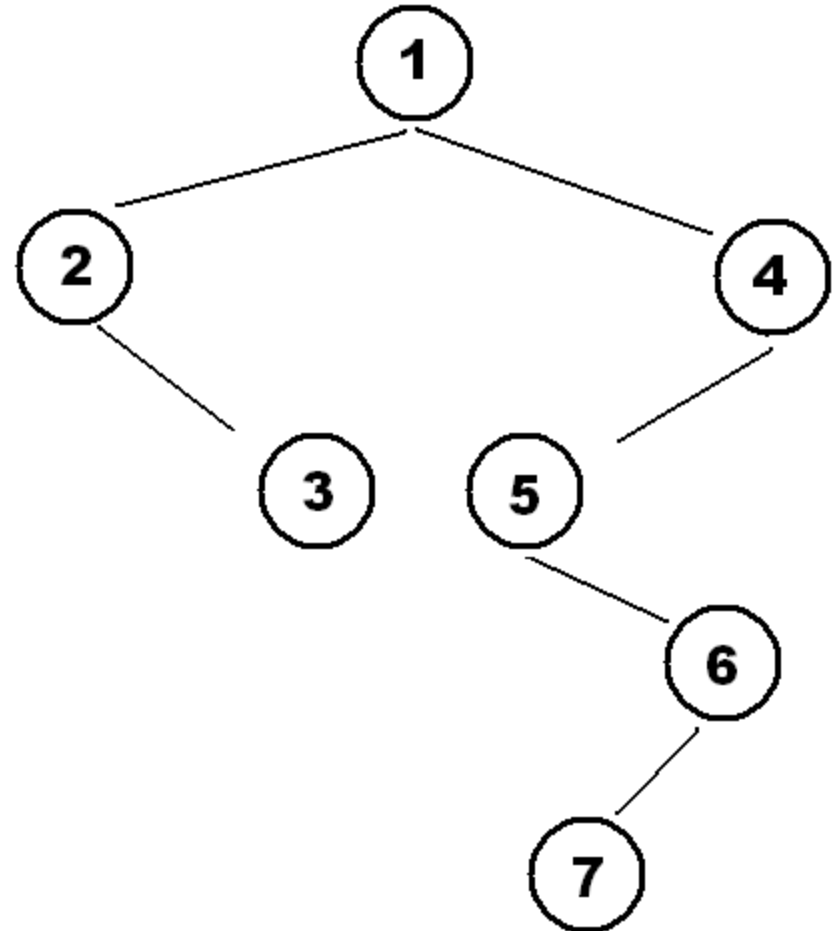
degenerated



perfect

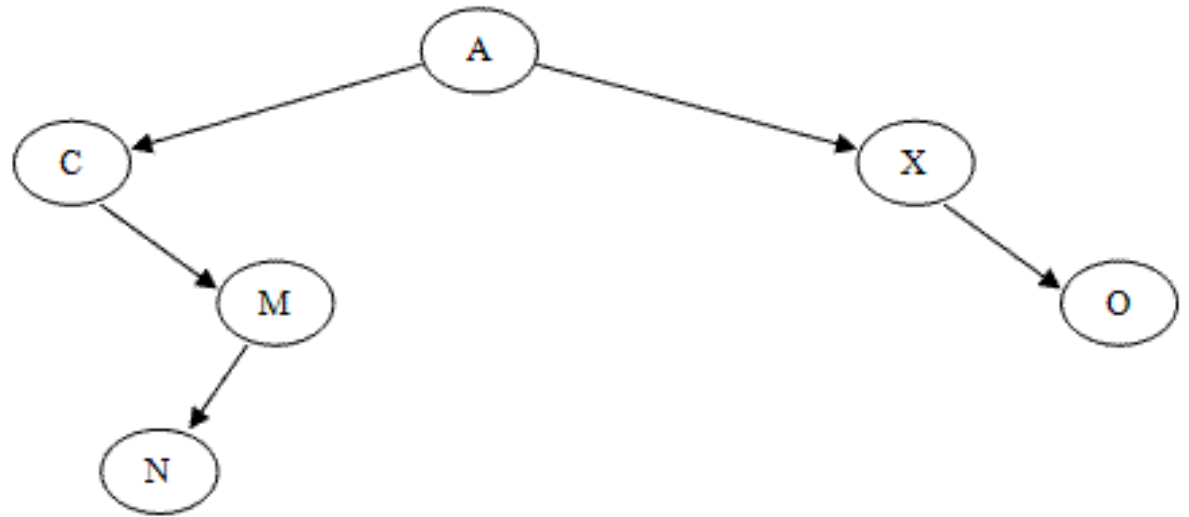


Binary trees

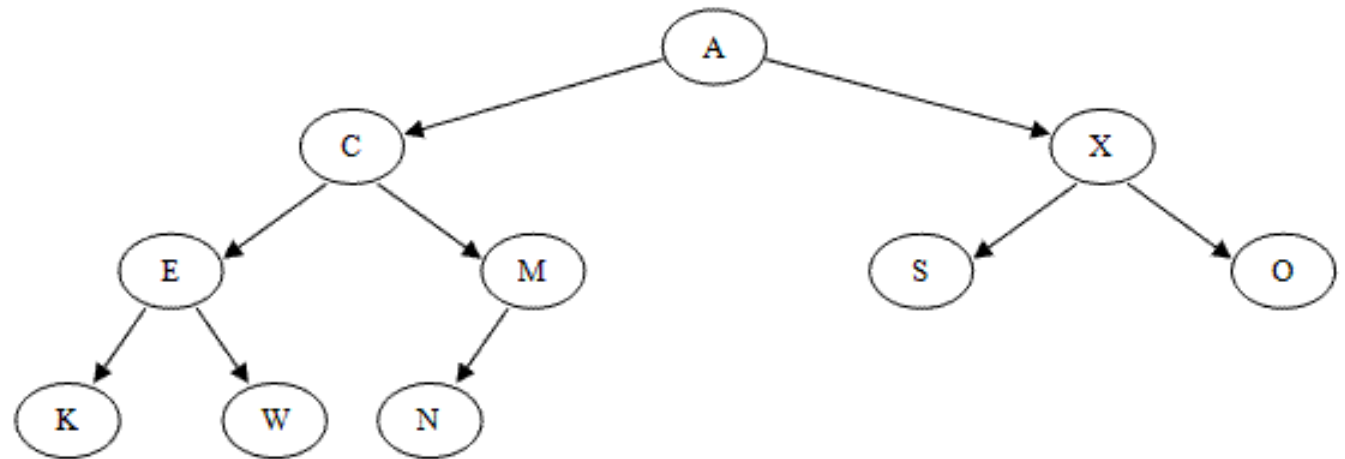


Binary trees

degenerated



**(almost)
complete**



Binary tree types

Perfect tree:

- all leaves have the same depth
- and all internal nodes have two children

(Almost) **complete** tree:

- for each level, except possibly the deepest, the nodes have 2 children
- in the deepest level, all nodes are as far left as possible

A **degenerate** tree

- each parent node has only one child
- ➔ the tree will essentially behave like a linked list data structure

A **balanced binary tree**

- no leaf is much farther away from the root than any other leaf
 - different balancing schemes allow different definitions of "much farther"

Binary tree types

(true or false ?)

Perfect tree:

A binary tree with all leaf nodes at the same depth.

All internal nodes have degree 2.

(Almost) **complete** tree:

A binary tree in which every level, except possibly the deepest, is completely filled.

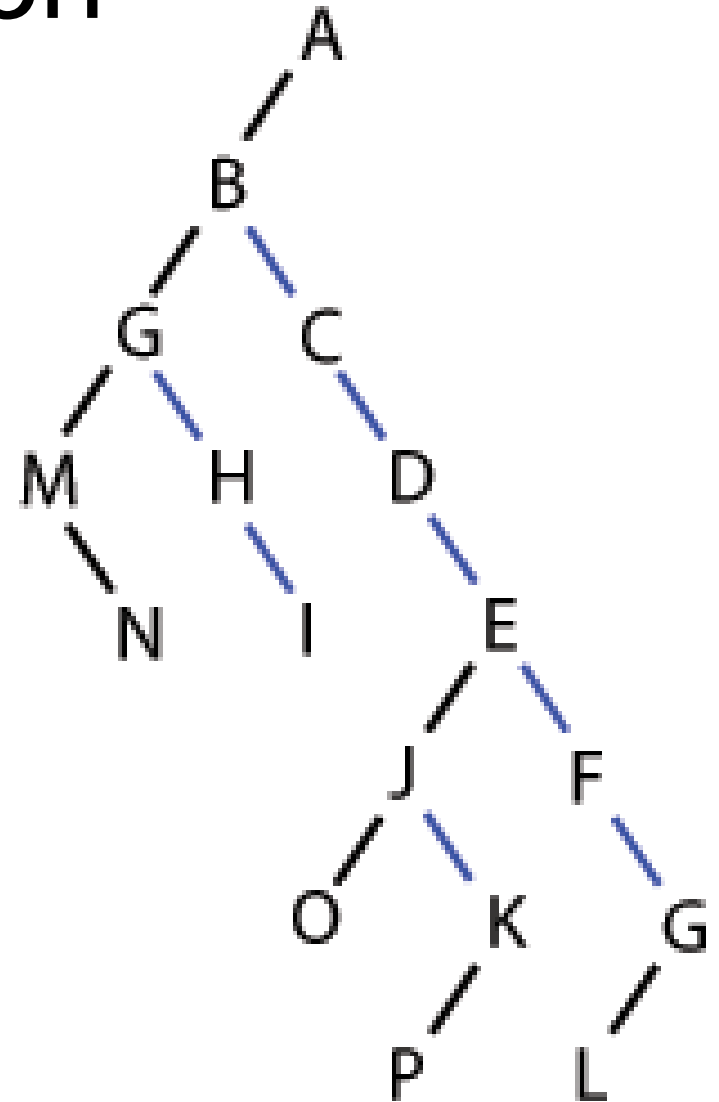
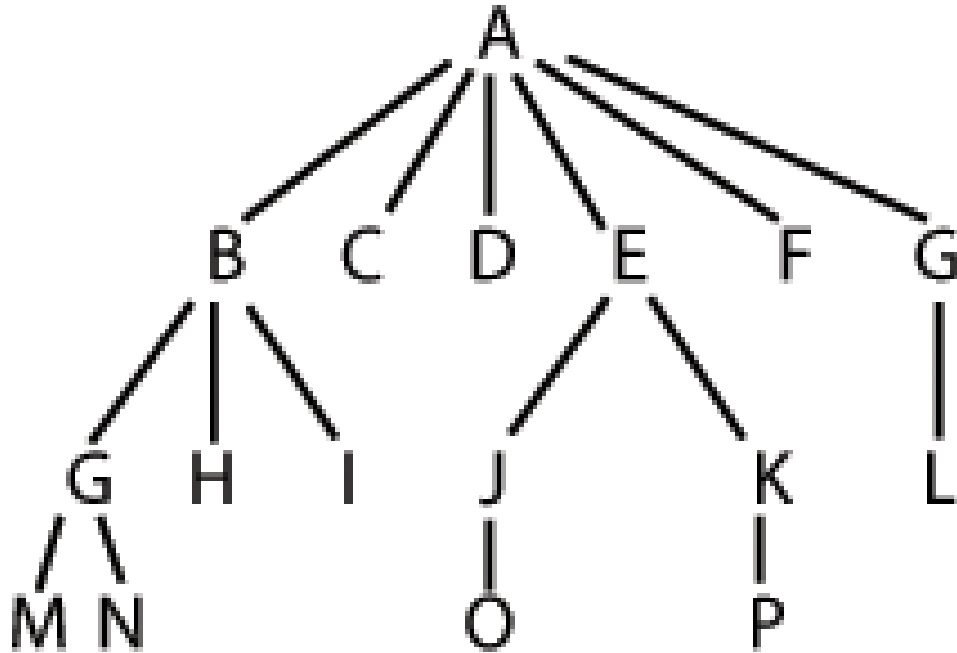
At depth n , the height of the tree, all nodes must be as far left as possible.

<http://xlinux.nist.gov/dads>
(equivalent definitions)

Binary tree properties

1. A tree with N nodes has $N-1$ edges
(true for any tree)
2. No of nodes in a perfect binary tree with height h is $2^{h+1}-1$
3. Maximum no of nodes in a binary tree with height h is $2^{h+1}-1$
4. A binary tree with n nodes has height at least $\lceil \log_2 n \rceil$

Tree representation



Tree representation

(A (B (E (K, L) , F) , C (G) , D (H, I, J)))

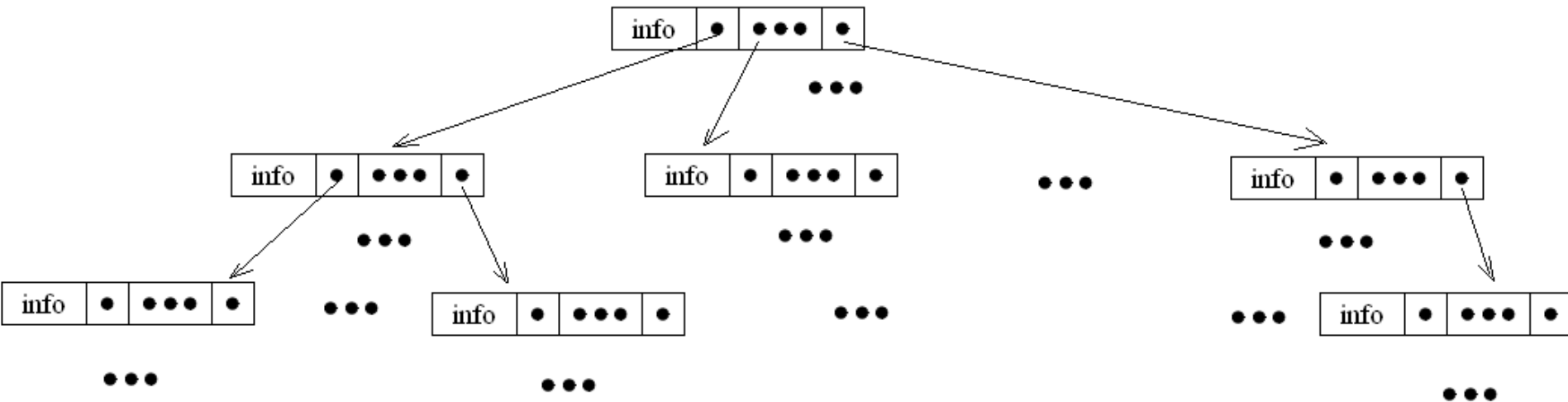
Tree representation (1)

Based on recursive definition

- Node root information
 list of subTrees

collection?

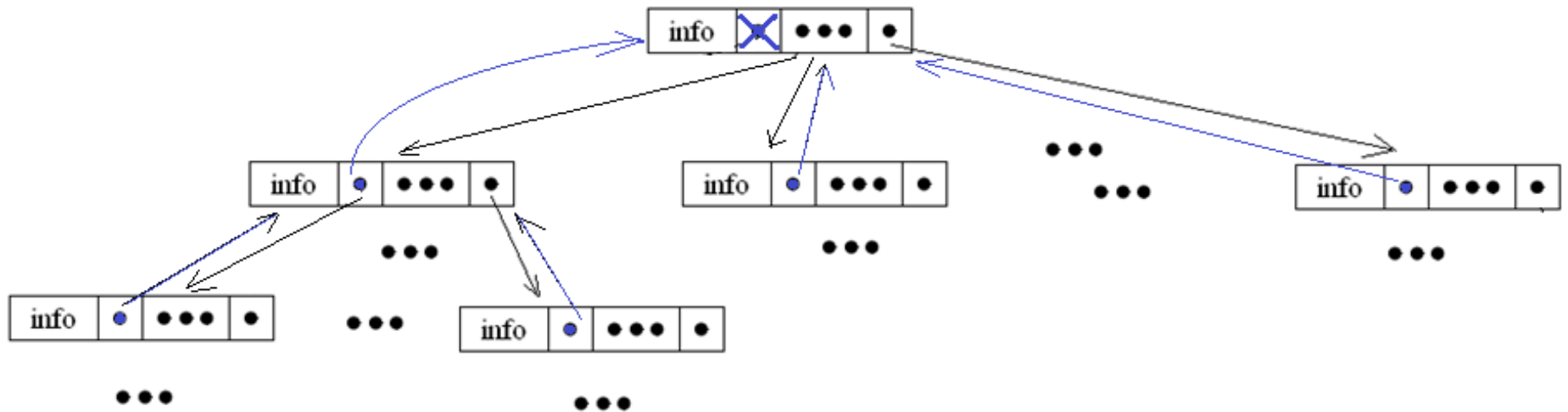
remark: a tree is known by knowing its root
(links to subtrees)



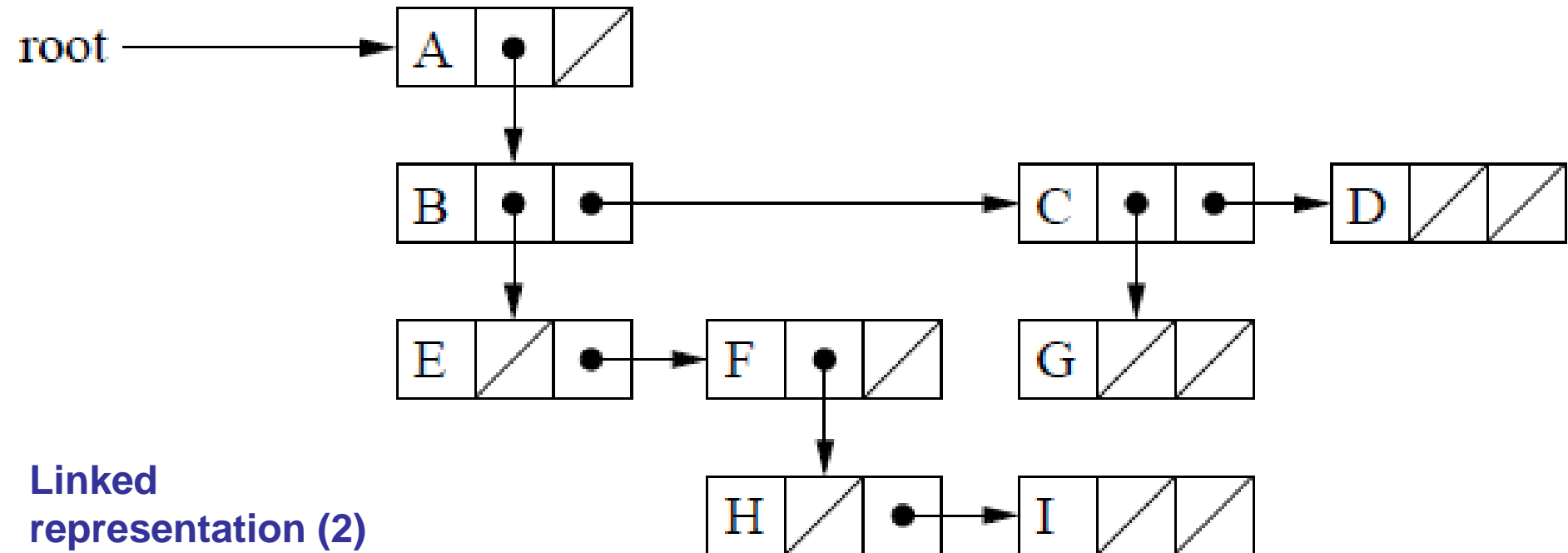
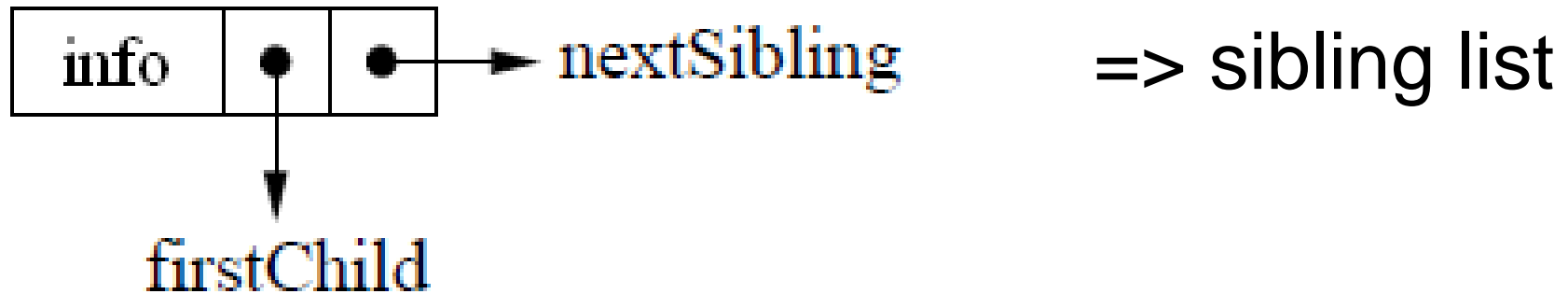
Linked representation (1)

Tree representation (1b)

- Sometimes, a link to the parent node is also kept



Tree Representation (2)



Tree traversal

can be traversed in many ways

- depth-first traversal
- breadth-first traversal
on levels

Representation (1) & dynamic allocation

TreeNode: record

info: TElement

left: Position

right: Position

end

Position: ^TreeNode

Tree: record

root: Position

end

Representation (1) & dynamic allocation

```
TreeNode: record  
    info: TElement  
    left: ^TreeNode  
    right: ^TreeNode  
end
```

```
Tree: record  
    root: ^TreeNode  
end
```

```
class TreeNode {  
    private:  
        TElement info;  
        TreeNode* left;  
        TreeNode* right;  
    public:  
        TreeNode(TElement value) {  
            this->info = value;  
            left = NULL;  
            right = NULL;  
        }  
        ...  
};  
class BinaryTree {  
    private:  
        TreeNode* root;  
    public:  
        ...  
};
```

Representation (1b) & dynamic allocation

TreeNode: record

info: TElement

left: ^TreeNode

right: ^TreeNode

end

Tree: ^TreeNode

This representation fits the recursive definition of binary tree.

For some recursive algorithms, we are going to use this representation.

Representation (1) & over arrays

```
TreeNode: record
    info: TElement
    left: Integer
    right: Integer
end
```

```
Tree: record
    root: Integer
    nodes: array [1..MAX] of TreeNode
    // ... information needed for freespace management
end
```

Variations:

- using 3 arrays: Infos, Lefts, Rights
- over a dynamic vector