

# Deep Learning Formulas and Examples

## ### 1. Perceptron Networks

### \*\*Formulas:\*\*

- \*\*Weighted Sum:\*\*  $z = \sum(w_i * x_i + b)$

-  $w_i$ : weights

-  $x_i$ : input features

-  $b$ : bias

- \*\*Activation Function (Step Function):\*\*

output = 1 if  $z > 0$  else 0

### \*\*Example:\*\*

- Inputs:  $x = [1, 0, 1]$

- Weights:  $w = [0.5, -0.6, 0.2]$

- Bias:  $b = 0.1$

-  $z = 0.5 * 1 + (-0.6) * 0 + 0.2 * 1 + 0.1 = 0.8$

- Output: 1 (since  $z > 0$ )

## ### 2. Backpropagation

### \*\*Formulas:\*\*

- \*\*Loss Function (Mean Squared Error):\*\*

$L = 1/2 \sum((y_i - \hat{y}_i)^2)$

- **Gradient of Loss w.r.t Weights:**

$$dL/dw_j = \sum((y_i - y_{\hat{i}}) * y_{\hat{i}} * (1 - y_{\hat{i}}) * x_{ij})$$

**Example:**

- Predicted output:  $y_{\hat{}} = [0.4, 0.6]$

- True output:  $y = [0.5, 0.5]$

$$L = 1/2 * [(0.5 - 0.4)^2 + (0.5 - 0.6)^2] = 0.01$$

### 3. Convolutional Neural Networks (CNNs)

**Formulas:**

- **Convolution Operation:**

$$(I * K)(i, j) = \sum(\sum(I(i+m, j+n) * K(m, n)))$$

- **Pooling Operation (Max Pooling):**

$$\text{output}(i, j) = \max(\text{region})$$

**Example:**

- Input Image:  $I = \begin{bmatrix} 1 & 2 & 0 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix}$

- Kernel:  $K = \begin{bmatrix} 1 & 0 \\ -1 & 1 \end{bmatrix}$

- Convolution Output:  $\begin{bmatrix} 2 & 3 \\ 5 & 6 \end{bmatrix}$

### 4. Recurrent Neural Networks (RNNs)

**Formulas:**

- **Hidden State:**

$$h_t = \text{sigma}(W_{xh} * x_t + W_{hh} * h_{t-1} + b_h)$$

- **Output:**

$$o_t = \text{sigma}(W_{ho} * h_t + b_o)$$

**Example:**

- Input:  $x_t = [1, 0.5]$

- Previous hidden state:  $h_{t-1} = [0.2, -0.1]$

- Weights:  $W_{xh} = [[0.1, 0.3], [0.2, -0.1]]$ ,  $W_{hh} = [[0.5, 0.4], [0.3, 0.2]]$

- Bias:  $b_h = [0.1, -0.1]$

-  $h_t = \tanh([ [0.1, 0.3], [0.2, -0.1] ] * [1, 0.5] + [ [0.5, 0.4], [0.3, 0.2] ] * [0.2, -0.1] + [0.1, -0.1] ) = \tanh([0.45, 0.2])$

### 5. Long Short-Term Memory (LSTM)

**Formulas:**

- **Forget Gate:**

$$f_t = \text{sigma}(W_f * [h_{t-1}, x_t] + b_f)$$

- **Input Gate:**

$$i_t = \text{sigma}(W_i * [h_{t-1}, x_t] + b_i)$$

$$\tilde{C}_t = \tanh(W_C * [h_{t-1}, x_t] + b_C)$$

- **Cell State:**

$$C_t = f_t * C_{t-1} + i_t * \tilde{C}_t$$

- **Output Gate:**

$$o_t = \text{sigma}(W_o * [h_{t-1}, x_t] + b_o)$$

$$h_t = o_t * \tanh(C_t)$$

**Example:**

- Input:  $x_t = [1, 0.5]$
- Previous hidden state:  $h_{t-1} = [0.2, -0.1]$
- Previous cell state:  $C_{t-1} = [0.5, 0.3]$
- Weights:  $W_f, W_i, W_C, W_o$  are weight matrices
- Biases:  $b_f, b_i, b_C, b_o$  are biases

### 6. Autoencoders

**Formulas:**

**Encoding:**

$$h = \text{sigma}(W_e * x + b_e)$$

**Decoding:**

$$x_{\text{hat}} = \text{sigma}(W_d * h + b_d)$$

**Example:**

- Input:  $x = [1, 0.5]$
- Weights:  $W_e = [[0.5, 0.4], [0.3, 0.2]]$ ,  $W_d = [[0.5, 0.3], [0.4, 0.2]]$
- Biases:  $b_e = [0.1, -0.1]$ ,  $b_d = [0.2, 0.1]$
- $h = \tanh([0.5, 0.4], [0.3, 0.2]) * [1, 0.5] + [0.1, -0.1] = \tanh([0.85, 0.4])$

### 7. Variational Autoencoders (VAE)

## **\*\*Formulas:\*\***

### - **\*\*Encoder:\*\***

$$\mu = f_{\mu}(x)$$

$$\log \sigma^2 = f_{\log \sigma^2}(x)$$

### - **\*\*Sampling:\*\***

$$z = \mu + \sigma * \epsilon$$

$$\epsilon \sim N(0, 1)$$

### - **\*\*Decoder:\*\***

$$\hat{x} = g(z)$$

### - **\*\*Loss:\*\***

$$L = E_{q(z|x)} [ \log p(x|z) ] - D_{KL}(q(z|x) || p(z))$$

## **\*\*Example:\*\***

- Input:  $x = [1, 0.5]$

- Encoder networks provide  $\mu$  and  $\log \sigma^2$

- Sample  $z$  from  $N(\mu, \sigma^2)$

- Decoder reconstructs  $\hat{x}$

## **### 8. Generative Adversarial Networks (GANs)**

## **\*\*Formulas:\*\***

### - **\*\*Generator Loss:\*\***

$$L_G = - E_{\{z \sim p_z(z)\}} [\log D(G(z))]$$

- **Discriminator Loss:**

$$L_D = - E_{\{x \sim p_{data}(x)\}} [\log D(x)] - E_{\{z \sim p_z(z)\}} [\log (1 - D(G(z)))]$$

**Example:**

- Random noise  $z$  is fed into the generator  $G$
- Generated sample  $G(z)$  is evaluated by the discriminator  $D$
- Discriminator updates its parameters to differentiate real data from generated data
- Generator updates its parameters to improve the realism of generated samples