

New algorithms for approximating massive datasets

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TTIC

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This talk – geometrically summarizing massive datasets

Introduction

Streaming ellipsoidal approximations

Motivation and problem statement

Our results

Monotone algorithm for the symmetric case

Application – Coreset for convex hull

Conclusion

Approximating matrix block norms

Block norm sparsification – introduction

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Sparsification via importance sampling

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Guiding questions/motivations

Can we:

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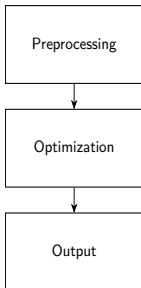
- ▶ quickly summarize a massive dataset in a geometrically meaningful way?



Guiding questions/motivations

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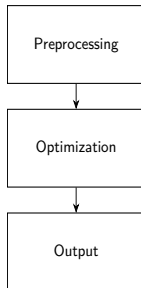
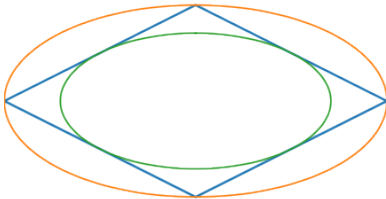
- ▶ quickly summarize a massive dataset in a geometrically meaningful way?
- ▶ use our summaries as optimization primitives or preprocessing routines?



Guiding questions/motivations

Can we:

- ▶ quickly summarize a massive dataset in a geometrically meaningful way?
- ▶ use our summaries as optimization primitives or preprocessing routines?
- ▶ gain a better understanding of high-dimensional convex geometry?



Streaming algorithms for ellipsoidal approximation of convex polytopes – symmetric and asymmetric

<https://arxiv.org/abs/2206.07250> (COLT 2022) and
<https://arxiv.org/abs/2311.09460> (STOC 2024, to appear)

Yury Makarychev, *NSM*, Max Ovsiankin

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Ellipsoidal approximations

Basic problem

Given a convex body $X \subset \mathbb{R}^n$, find an ellipsoid \mathcal{E} and a center $\mathbf{c} \in \mathbb{R}^n$ such that $\mathbf{c} + \mathcal{E}/\alpha \subseteq X \subseteq \mathbf{c} + \mathcal{E}$.

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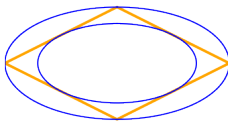


Figure: $\mathcal{E}/\sqrt{2} \subseteq X \subseteq \mathcal{E}$

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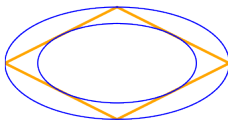


Figure: $\mathcal{E}/\sqrt{2} \subseteq X \subseteq \mathcal{E}$

Such an \mathcal{E} allows us to succinctly represent a convex body (n^2 floats).

Offline solution

Ellipsoidal approximation – offline

Given a convex body $X \subseteq \mathbb{R}^n$, compute a center $\mathbf{c} \in \mathbb{R}^n$ and an ellipsoid \mathcal{E} with $\mathbf{c} + \mathcal{E}/\alpha \subseteq X \subseteq \mathbf{c} + \mathcal{E}$ that minimizes α . Let α be \mathcal{E} 's *approximation factor*.

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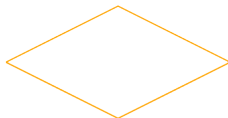
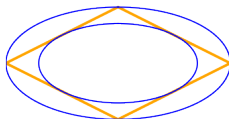


Figure: X

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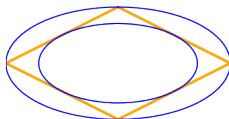


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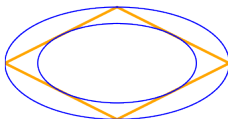
Theorem (John [Joh48])

If \mathcal{E} is the minimum volume ellipsoid covering X , then we can always achieve $\alpha \leq n$.

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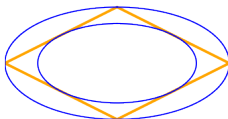
If \mathcal{E} is the minimum volume ellipsoid covering X , then we can always achieve $\alpha \leq n$. If X is origin-symmetric, then we can always achieve $\alpha \leq \sqrt{n}$.

There exists X for which *any* ellipsoidal approximation for X must achieve $\alpha = n$ (e.g. simplex).

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There exists X for which *any* ellipsoidal approximation for X must achieve $\alpha = n$ (e.g. simplex). For symmetric polyhedrons with m linear constraints, John's Ellipsoid can be approximated in time $\tilde{O}(mn^2)$ [CCLY19].

Streaming/online ellipsoidal approximations

Problem

Given a convex body $X = \text{conv}(\mathbf{x}_1, \dots, \mathbf{x}_m)$ **as a stream of points**, find a center $\mathbf{c} \in \mathbb{R}^n$ and ellipsoid \mathcal{E} with $\mathbf{c} + \mathcal{E}/\alpha \subseteq X \subseteq \mathbf{c} + \mathcal{E}$ that minimizes α .

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Motivation – Suppose we want to summarize a dataset in a resource-constrained environment.

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- ▶ Cannot store too many points at once;
- ▶ Update time in each iteration must be fast.

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Aspect ratio of convex body

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Let R be the smallest value and r be the largest value such that:

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The *aspect ratio* of X is $\kappa(X) := R/r$.

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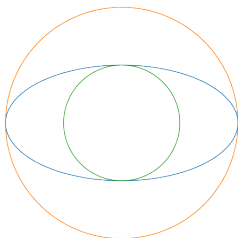


Figure: $1 \cdot B_2^n \subseteq \mathcal{E} \subseteq 2 \cdot B_2^n \Rightarrow \kappa(\mathcal{E}) = 2/1$

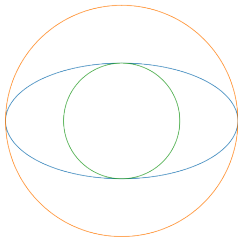
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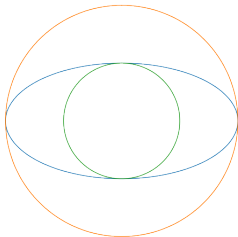
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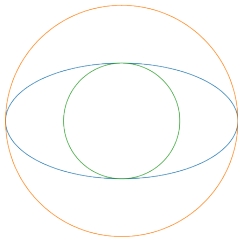


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Results for streaming ellipsoidal approximations

Approximation result

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Runtime: $\tilde{O}(mn^2)$. **Space complexity:** $O(n^2)$ floating point numbers.

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- ▶ If X is asymmetric, then for all "monotone" algorithms, there exists an example stream for which

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- ▶ If we assume the points \mathbf{x}_i have integer coordinates in $[-N, \dots, N]$, then we can replace $\log(R/r)$ with $\log n + \log N$.

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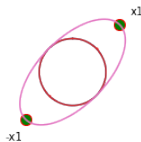
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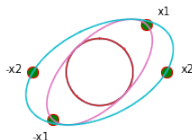
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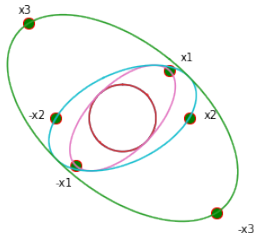
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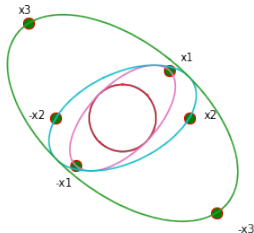
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Formally, if $\mathcal{E}_t = \{\mathbf{x} : \|\mathbf{A}_t \mathbf{x}\|_2 \leq 1\}$ for invertible \mathbf{A}_t , then:

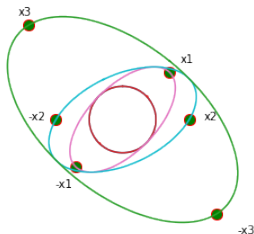
Greedy algorithm, symmetric case

Assumption

The algorithm is told a value of r_0 such that $r_0 \cdot B_2^n \subseteq X$.

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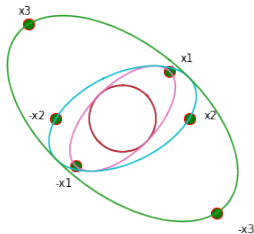
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Convex hull coresets

Desired approximation guarantee

Find a subset S of $\mathbf{x}_1, \dots, \mathbf{x}_m$ such that there exists a center $\mathbf{c}_m \in \mathbb{R}^n$ for which

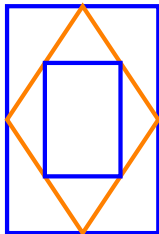
$$\begin{aligned} & \mathbf{c}_m + \text{conv}(X_S) \\ & \subseteq \text{conv}(\mathbf{x}_1, \dots, \mathbf{x}_m) \\ & \subseteq \mathbf{c}_m + \alpha_m \cdot (\text{conv}(X_S) - \mathbf{c}_m) \end{aligned}$$

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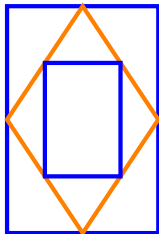


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From ellipsoids to convex hull coresets (informal)

There exists an algorithm that calls the ellipsoidal approximation algorithm as a subroutine and chooses S in an online fashion such that:

$$\alpha_m \leq Cn \log(n\kappa^{\text{OL}}(X)) \quad (\text{asymmetric})$$

$$\alpha_m \leq C\sqrt{n \log(n\kappa^{\text{OL}}(X))} \quad (\text{symmetric})$$

and $|S| \leq Cn \log(n\kappa^{\text{OL}}(X))$.

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4. Papers – <https://arxiv.org/abs/2206.07250> (symmetric) and <https://arxiv.org/abs/2311.09460> (asymmetric).

Approximating matrix block norms

<https://arxiv.org/abs/2311.10013> (in progress)

NSM, Max Ovsiankin

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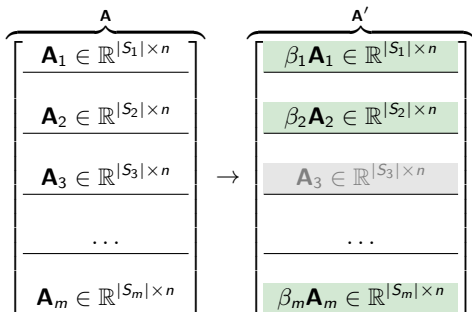
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Applications – subroutine to speed up regression, dataset summarization, etc

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Approximate leverage scores $(\mathbf{a}_i^T (\mathbf{A}^T \mathbf{D} \mathbf{A})^{-1} \mathbf{a}_i$ for nonnegative diagonal \mathbf{D}) can be found in time $\tilde{O}(\text{nnz}(\mathbf{A}) + n^\omega)$.

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1. (Existence) If p and p_i belong to at least one of the regimes above, then there exists a weight vector $\beta \in \mathbb{R}_{\geq 0}^m$ such that

$$\tilde{m} := \|\beta\|_0 = C(p, p_1, \dots, p_m) \cdot \frac{n^{\max(1, p/2)} \log(n/\varepsilon) (\log n)^2}{\varepsilon^2}.$$

2. (Computation) If $p = p_1 = \dots = p_m$, or $p_1 = \dots = p_m = 2$ and $p > 0$, or $p = 2$ and $p_1, \dots, p_m \geq 2$, then β can be found in polylogarithmically many leverage score computations.

Approximate leverage scores $(\mathbf{a}_i^T (\mathbf{A}^T \mathbf{D} \mathbf{A})^{-1} \mathbf{a}_i$ for nonnegative diagonal \mathbf{D}) can be found in time $\tilde{O}(\text{nnz}(\mathbf{A}) + n^\omega)$.

Dependence on n is essentially optimal (we need $\tilde{m} \gtrsim n^{\max(1, p/2)}$ [LWW19]).

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Our task: Find \mathcal{D} such that for a “small” \tilde{m} , w.h.p, for all $\mathbf{x} \in \mathbb{R}^n$:

$$(1 - \varepsilon) \cdot \frac{f(\mathbf{x})}{\tilde{m}} \leq \|\mathbf{Ax}\|_{\mathcal{G}_p}^p \leq (1 + \varepsilon) \cdot \frac{f(\mathbf{x})}{\tilde{m}}.$$

Conclusion – approximating matrix block norms

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4. Paper – <https://arxiv.org/abs/2311.10013>.

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The input in a data science problem instance isn't always clean or accessible.

Untrustworthy and unexpected data

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Questions?

Thank you!!

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