

G53FUZ

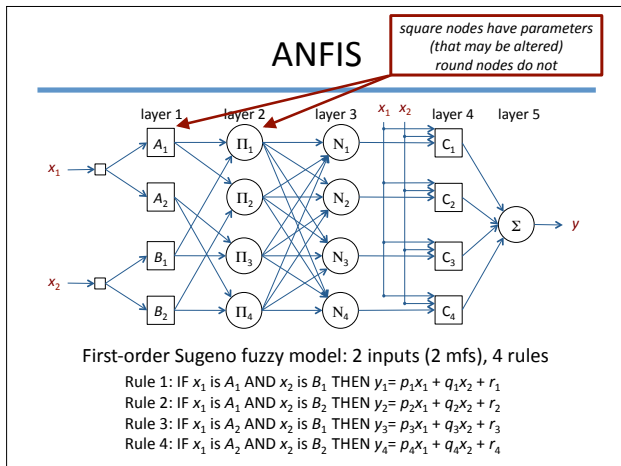
Fuzzy Sets and Systems

ANFIS
Adaptive Neuro-Fuzzy Inference System

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Background

- Introduced by J-S Roger Jang in 1993
 - “ANFIS: Adaptive-Neuro-Based Fuzzy Inference System”, *IEEE Transactions on Systems, Man and Cybernetics*, 23(3), 665-685, 1993
- Often (usually?) referred to as
 - Adaptive **Neuro**-Fuzzy Inference System
 - ANFIS
- TSK system viewed as a network of nodes
 - similar to a neural-network



Layer 1 – Inputs

- Premise parameters

$$O_{1,i} = \mu_{A_i}(x_1) \quad \text{for } i=1,2$$

$$O_{1,i} = \mu_{B_{i-2}}(x_2) \quad \text{for } i=3,4$$
- Often, m.f.s are Gaussians

$$\mu_{A_i}(x) = e^{-\frac{(x-c_i)^2}{a_i^2}}$$

Layer 2 – Rule Firing

- T-norm operator combining the separate antecedents into single rule firing strength
 - using the product t-norm

$$O_{2,i} = w_i = \mu_{A_i}(x_1)\mu_{B_i}(x_2) \quad i=1,2$$

- in general, for n inputs (each with m m.f.s), we have $R = m^n$ rules

$$O_{2,i} = \prod_{j=1}^n \mu(x_j) = \mu(x_1) \cdot \mu(x_2) \cdots \mu(x_n) \quad \text{for } i=1 \dots R$$

Layer 3 – Normalised Firing

- Outputs of layer 3 are the normalised rule firing strengths

$$O_{3,i} = \frac{w_i}{\sum_{j=1}^R w_j} \quad \text{for } i=1 \dots R$$

Layer 4 – Rule Consequents

- Consequent parameters (towards defuzzification)

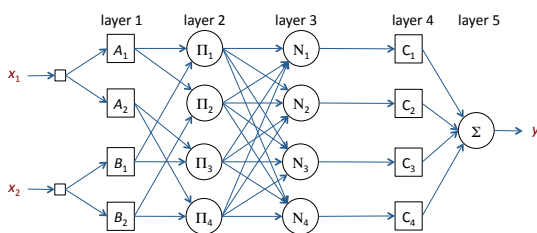
$$O_{4,i} = \bar{w}_i y_i = \bar{w}_i (p_i x_1 + q_i x_2 + r_i)$$

Layer 5 – Defuzzification

- Final crisp output
 - sums each normalised rule output

$$y = O_{5,j} = \sum_i \bar{w}_i y_i = \frac{\sum_i w_i y_i}{\sum_i w_i}$$

ANFIS – Zeroth Order



Zeroth-order Sugeno fuzzy model: 2 inputs (2 mfs), 4 rules

Rule 1: IF x_1 is A_1 AND x_2 is B_1 THEN $y_1 = r_1$
 Rule 2: IF x_1 is A_1 AND x_2 is B_2 THEN $y_2 = r_2$
 Rule 3: IF x_1 is A_2 AND x_2 is B_1 THEN $y_3 = r_3$
 Rule 4: IF x_1 is A_2 AND x_2 is B_2 THEN $y_4 = r_4$

Parameters

- ANFIS features two sets of parameters
 - S_1
 - the parameters that define the input m.f.s
 - non-linear
 - modified by using a gradient descent tuning algorithm in a backward pass (back-propagation of errors)
 - S_2
 - the parameters that define the consequent functions
 - linear
 - modified by using an iterative least squares estimation algorithm in a forward pass

ANFIS Learning

Two passes in the hybrid learning procedure

	Forward Pass	Backward Pass
Premise Parameters (nonlinear)	Fixed	Gradient descent
Consequent parameters (linear)	Least-square estimator	Fixed
Signals	Node outputs	Error signals

LSE Forward Pass

- LSE used to minimise the squared error

$$\|AX - B\|^2$$
 - where
 - A is a matrix of outputs produced by layer 3
 - B is a matrix of target outputs
 - X is a matrix of consequent parameters
- A sequential (iterative) estimation algorithm estimates X, essentially as per a Kalman filter
 - run over each of the P training instances

Back Propagation

- The overall error measure is

$$E = \sqrt{\frac{\sum_{p=1}^P (T_p - Y_p)^2}{P}}$$

– where Y_p are actual outputs and T_p are targets

- For each parameter α_i , the update formula is

$$\Delta\alpha_i = -\eta \frac{\partial E}{\partial \alpha_i}$$

– where η is the learning rate, $\eta = \frac{k}{\sqrt{\sum_i \left(\frac{\partial E}{\partial \alpha_i}\right)^2}}$

Example

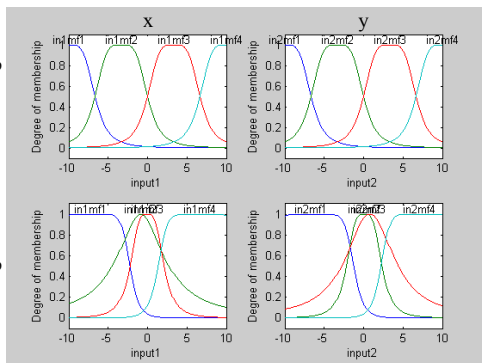
- Jang *et al.*, **Neuro-Fuzzy and Soft Computing**, Prentice Hall, 1997
- ANFIS is used to model a two-dimensional *sinc* equation defined by

$$z = \sin c(x, y) = \frac{\sin(x) \sin(y)}{xy}$$

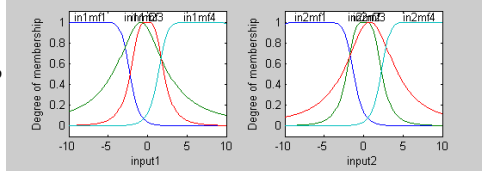
- x and y are in the range $[-10, 10]$
- number of m.f.s for each input: 4
- number of rules: 16

Result

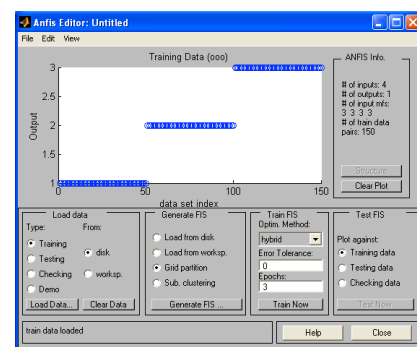
Initial membership functions



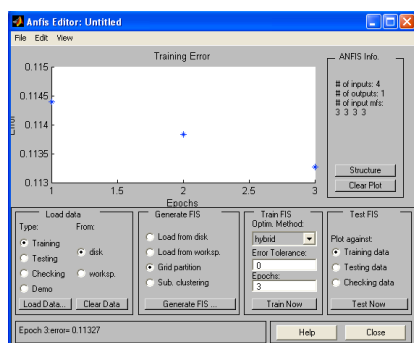
Final (trained) membership functions after 100 epochs



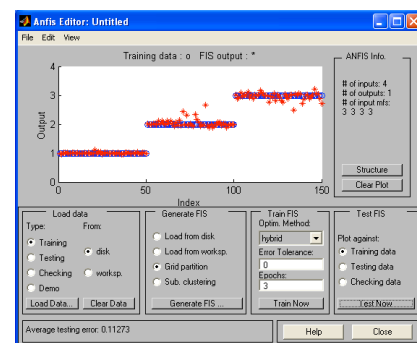
Iris Data (3 Species)



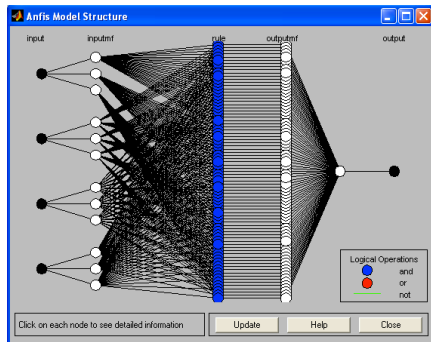
Grid Partition Train



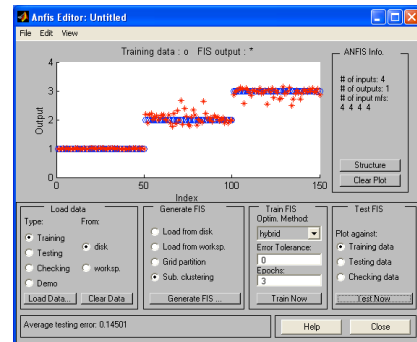
GP Test



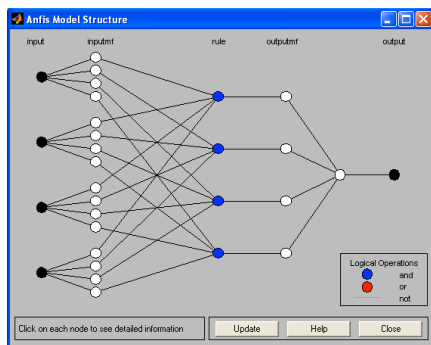
GP Structure!



Subtractive Clustering



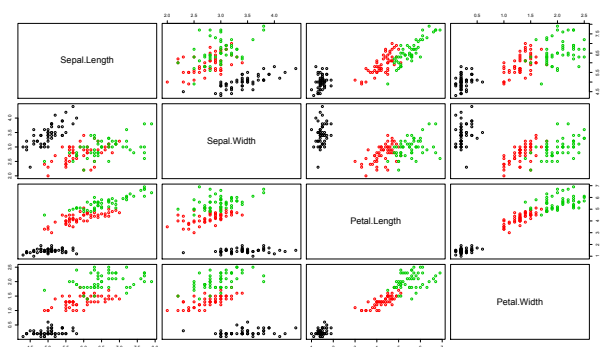
SC Structure



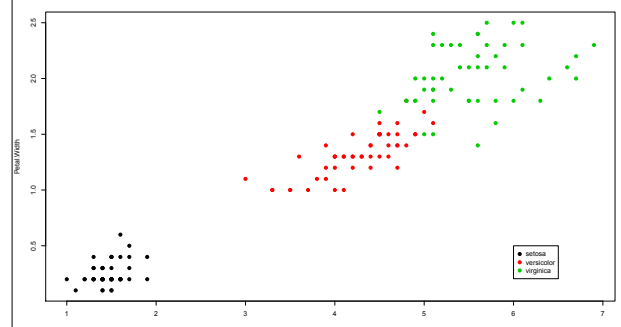
SC Structure Better?

- This is now 'only' a 4-rule 1st-order TSK FIS
 1. If in_1 is $i1mf1$ and in_2 is $i2mf1$ and in_3 is $i3mf1$ and in_4 is $i4mf1$ then out_1 is $o1mf1$
 2. If in_1 is $i1mf2$ and in_2 is $i2mf2$ and in_3 is $i3mf2$ and in_4 is $i4mf2$ then out_1 is $o1mf2$
 3. If in_1 is $i1mf3$ and in_2 is $i2mf3$ and in_3 is $i3mf3$ and in_4 is $i4mf3$ then out_1 is $o1mf3$
 4. If in_1 is $i1mf4$ and in_2 is $i2mf4$ and in_3 is $i3mf4$ and in_4 is $i4mf4$ then out_1 is $o1mf4$
- But each outmf is a linear combination, e.g.
 - $outmf4 = 0.851873in_1 + 1.659586in_2 + 1.352931in_3 - 5.703523in_4 - 8.063416$
- Still, far from comrehensible?

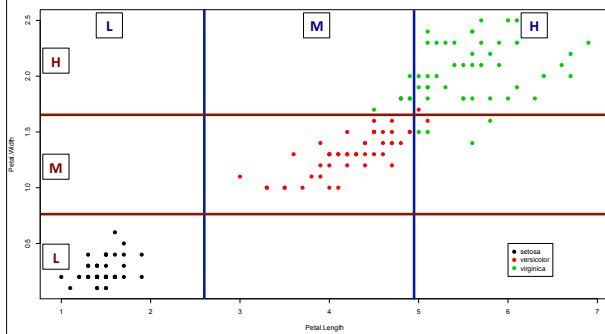
IRIS Pairs



Petal Length and Width



Petal Length and Width

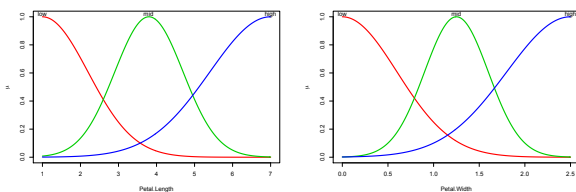


Classification Rules

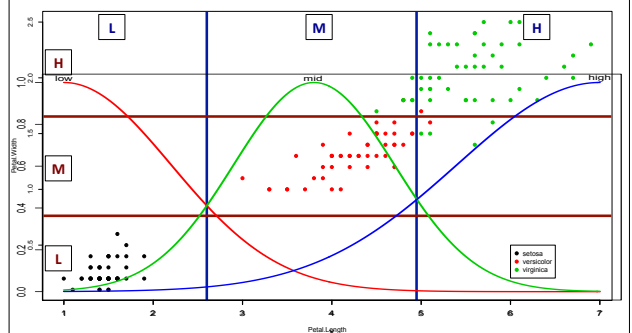
- IF *Petal.Length* is Low and *Petal.Width* is Low THEN *Species* is *setosa*
- IF *Petal.Length* is Mid and *Petal.Width* is Mid THEN *Species* is *versicolor*
- IF *Petal.Length* is High and *Petal.Width* is High THEN *Species* is *virginica*

Hand-Crafted FIS

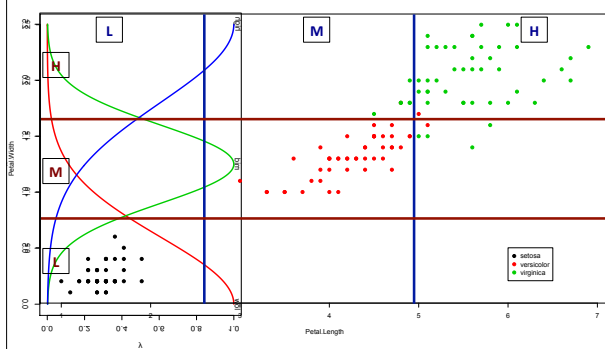
- Four input variables, one output
- only two inputs needed



Petal Length and Width



Petal Length and Width



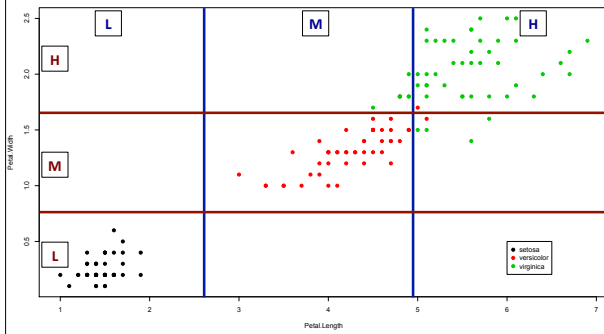
Hand-crafted FIS Performance

- Cross-tabulation

	1	2	3
setosa	50	0	0
versicolor	0	47	3
virginica	0	2	48

- RMSE
- 0.183

Petal Length and Width



Classification Rules

- IF *Petal.Length* is Low and *Petal.Width* is Low THEN *Species* is *setosa*
- IF *Petal.Length* is Mid and *Petal.Width* is Mid THEN *Species* is *versicolor*
- IF *Petal.Length* is High and *Petal.Width* is High THEN *Species* is *virginica*
- IF *Petal.Length* is Mid and *Petal.Width* is High THEN *Species* is *virginica*
- IF *Petal.Length* is High and *Petal.Width* is Mid THEN *Species* is *virginica*

5-Rule FIS Performance

- Cross-tabulation

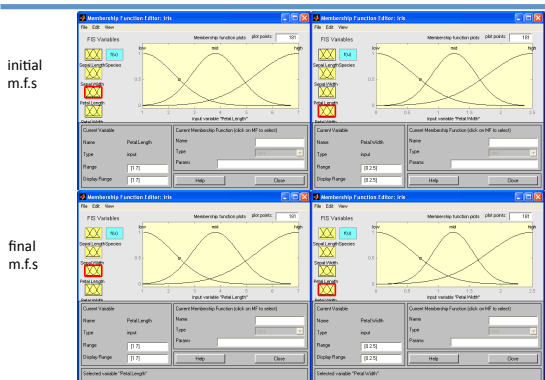
	1	2	3
setosa	50	0	0
versicolor	0	47	3
virginica	0	0	50

- RMSE
– 0.141

Process

- We can start with a manually created TSK structure and use ANFIS to tune mfs (only)
 - take the previous system and convert to 0th-order TSK with constant outputs (1, 2, 3)
- Process
 - load TSK FIS into ANFIS
 - load training/testing data
 - train and test!

Result



Summary

- Lecture summary
 - ANFIS provides a completely automated way of constructing and tuning fuzzy inference systems
 - often producing very good performance (RMSE)
 - automatic ANFIS models are not necessarily either parsimonious or easily interpretable
 - ANFIS can be used to tune a manual FIS
- Next lecture
 - beyond standard (type-1) fuzzy sets