

# CPSC 5011: Object-Oriented Concepts

## Lecture 8: Inheritance and Polymorphism



# Inheritance

- Of Interface
  - Type extension (PUBLIC)
  - Child type IS-A (extension of) parent type
  - Child type retains, supports and, possibly extends parent interface
- Of Implementation
  - Code reuse (PRIVATE)
    - *Already defined, debugged, tested*
  - Child class inherits and uses parent code

- Child class has access to
  - All public data and functionality of parent
  - All protected data and functionality of parent
- Application programmer has access to
  - Parent class object
    - All public data and functionality of parent
  - Child class object
    - All public data and functionality of parent
    - All public data and functionality of child

# Java : Inheritance Example

```
class JParent {
    public      boolean  decideForAll() {...}
    protected   boolean  decideForDescendants() {...}
    private     boolean  decideForClassOnly() {...}
    protected   boolean  forDescendants;
    private     boolean  forClassOnly;
    // not accessible in Child class
    ...
}
class JChild extends JParent {
// only public extensibility for Java inheritance
    public JChild(int x) { super(x); }
    public void Childfn() { ... }
    public boolean  decideForAll() {
        if (super.forDescendants)
            return super.decideForAll();
        if (forDescendants)
            return decideForDescendants();
        if (forClassOnly)
            return false;
    }
    protected   boolean  forDescendants;
    private     boolean  forClassOnly;
    ...
}
```

```
JParent baseObj = new JParent();
baseObj.decideForAll();

JChild derivedObj = new JChild();
derivedObj.decideForAll();

baseObj = derivedObj;
// SUBSTITUTABILITY

baseObj.decideForAll();

baseObj = new JChild(22);

// constructor calls explicit;
// base constructor fires first
```

# C++ : Inheritance Example

```
class CParent {
public:          // accessible by all
    bool      decideForAll();
protected:    // accessible by Child class but not external world
    bool      forDescendants;
    bool      decideForDescendants();
private:       // not accessible in Child class
    bool      forClassOnly;
    bool      decideForClassOnly();
};

class CChild: public CParent {
// 3 types of extensibility for C++ inheritance
// inheritance access: private (default), protected, OR public (most common)
public:
    CChild(int  x): CParent(x) { ... }
    bool  decideForAll() {
        if (CParent::forDescendants)    return CParent::decideForAll();
        if (forDescendants)              return decideForDescendants();
        if (forClassOnly)              return false;
    }
protected:
    bool      forDescendants;
private:
    bool      forClassOnly;
};
```

# C++ : Private Inheritance

## PRIVATE INHERITANCE

- Default mechanism but not commonly used
- Suppresses all of inherited interface
  - No is-a relation => DESIGN CAREFULLY
  - Impacts use by application programmer
- Cuts off inheritance hierarchy
  - Impacts use by child class designer
- Code reuse (INTERNAL UTILITY ONLY)

```
class Child: Parent{ ... }; // default private inheritance
void passValue(Parent);      // parameter is parent object
passValue(pObj);             // ok
passValue(cObj);
```

# C++ : Protected Inheritance

## PROTECTED INHERITANCE

- Must use protected qualifier in definition
- **Public interface suppressed**
  - Impacts use by application programmer
- Protected interface passed onto descendants

```
class Child: protected Parent { ... };  
class Grand: Child { // private inheritance by default  
    ...  
    public:  
        void somefn() { parentFn(); ... }  
};  
cObj.parentFn();
```

## PUBLIC INHERITANCE

- Must use public qualifier in definition
- Most commonly used means of inheritance
- Access as defined in parent class preserved
  - Public remains public
  - Protected remains protected
- Child class may redefine access for specified functions
  - May curtail inherited functionality for future descendants
    - override protected function and declare it private
  - May suppress inherited functionality
    - override public function and declare it protected or private



# Java / C++ : Overloaded Constructors

```
// Java Example
class JParent {
    public JParent() { ... }
    public JParent(int x) { ... }
    private int old;
    ...
}

class JChild extends JParent {
    public JChild() { ... }
    public JChild(int x)
    { super(x); this(); ... }
    public JChild(int x, float y)
    { super(x); data = y; ... }
    private float data;
    ...
}
```

```
// C++ Example
class CParent {
    // default accessibility is private:
    // not accessible in Child class
public:           // accessible by all
    CParent();
    CParent(int);
private:
    int old;
};

class CChild: public CParent {
public:
    // default base constructor
    CChild();

    // specify to compiler which parent
    // constructor to invoke
    CChild(int x): CParent(x) { ... }

    CChild(int x, float y)
        : CParent(x), data(y) { ... }
private:
    float data;
};
```

# C++ : Is-A Relation

Every object of a publicly derived class is ALSO an object of the base class

- Utility restricted to base class interface
- C++ Child object assigned to parent: SLICED
- What about Java?
  - ASSIGNMENT COPIES REFERENCE  
=> no slicing

```
Parent pObj;  
Child cObj;  
pObj.parentFn();  
cObj.parentFn();  
cObj.childFn();  
pObj = cObj; // sliced: ONLY PARENT  
              // INTERFACE  
pObj.parentFn();
```

## Substitutability

- Derived class objects stands in for base class object
- Not a symmetric relation
  - Parent cannot stand in for child.  
Why?

```
Parent * pPtr;  
Child * cPtr;  
pPtr = new Parent;  
cPtr = new Child;  
pPtr->parentFn();  
delete pPtr;  
pPtr = cPtr;  
pPtr->parentFn();
```

# Inheritance : Language Differences

- Java supports only public inheritance
  - does not allow direct suppression of inherited functionality
- C++ offers public, protected, and private inheritance
  - only public inheritance is typically used
  - with protected inheritance, all inherited public functionality is demoted to protected accessibility
  - with private inheritance, all inherited public and protected functionality is demoted to private accessibility

=> application programmer has less accessibility via a derived object
- C++ allows class designers to directly suppress inherited functionality by changing the accessibility of inherited class methods on an individual basis

# C++ : Direct Is-A Suppression

## Purity of relation not guaranteed

- C++ may suppress directly by overriding with a private method

```
class Child: public Parent {  
public:  
    ...  
private:  
    // private is default accessibility  
    void parentFn() { // now private => suppressed }  
};
```

```
Parent pObj;
```

```
Child cObj;
```

```
pObj.parentFn();
```

```
cObj.parentFn();
```

# Inheritance : Advantages

- Code reuse
  - Reduce development cost (& time)
  - Usually better maintenance
    - Less cut & paste programming
  - Parent class presumed stable
    - Already designed, implemented, debugged and tested
- Type extension
  - Application Programmer familiar with parent
  - Substitutability
    - Polymorphism – run-time selection of functions
    - New type can be added without breaking application code

# Inheritance : Disadvantages

- Increased Coupling
  - Child tightly coupled to parent
- Decreased Cohesion
  - Type definition spread across inheritance hierarchy
- Fixed Relationship
- Overhead
  - Child absorbs overhead of parent component even if not used
- Maintenance
  - Cost highly dependent on design

# Has-A versus Is-A

- Has-a encapsulates and controls subObject(s)
  - Design variability in cardinality, association, lifetime and ownership
  - Interfaces may, but need not, be echoed
- Is-a implies a strong type dependency
  - Child object may stand in for parent object
  - Polymorphism, and heterogeneous collections, supported through inheritance and difficult to implement otherwise
- Is-a imperative to reuse functionality
  - Common interface
  - Extensibility promoted
  - Overhead is fixed as is cardinality, ownership, lifetime and association

## Use composition in preference to inheritance.

- Composite Principles states practitioners' preference for composition over inheritance – Why?
- Composition more flexible and offers more control over internal design than inheritance
- But remember, composition does NOT provide
  - Built-in subtype checking
  - Polymorphism
  - Support for heterogeneous collections
  - Type extensibility



# Principle of Least Knowledge

**Every object should assume the minimum possible about the structure and properties of other objects.**

- Promotes low coupling
- When classes interact, in any relationship
  - Class design should not be dependent on private implementation details of any other class
- With clear documentation, deliberate design identifies relationships and their consequential effects

# Open-Closed Principle (OCP)

**A class should be open for extension and closed for modification.**

- Inheritance is an attractive design option for
  - Class hierarchy that relies on implicit subtype selection to distinguish appropriate functionality
  - Substitutability
  - Heterogeneous collections
  - Type extensibility
- A good inheritance design adheres to OCP
  - Individual classes preserved
  - Type extensions are seamless
- OCP promotes software maintainability

# Three Forms of Polymorphism

- **Overloading aka Ad Hoc Polymorphism**
  - Allows multiple function definitions with same name
  - Compiler uses parameter type(s) to resolve function calls
- **Generics aka Parametric Polymorphism**
  - Supports 'type-less' definition of a class or a function
  - Application programmer can later supply type
  - Compiler generates version of generic class (or function) with that type
- **Subtyping aka Inclusion**
  - Describes design of class hierarchy where descendant classes (re)define, augment, or modify inherited functionality
  - Descendant classes are dependent on the base class interface
  - Dynamic binding expected

# C++ : Overloaded Functions

```
void reset() {  
    for (int k = 0; k < size; k++) A[k] = 0.0;  
}  
void reset(double value) {  
    for (int k = 0; k < size; k++) A[k] = value;  
}  
void reset(bool op, int factor) {  
    if (op)  
        for (int k = 0; k < size; k++) A[k] *= factor;  
    else  
        for (int k = 0; k < size; k++) A[k] += factor;  
}
```

# C++ : Generics

```
void swap(int &x, int &y) {  
    int hold = x;  
    x = y;  
    y = hold;  
}  
  
void swap(float &x, float &y) {  
    float hold = x;  
    x = y;  
    y = hold;  
}  
  
template <typename T>  
void swap(T &x, T &y) {  
    T hold = x;  
    x = y;  
    y = hold;  
}
```

# Third Form of Polymorphism

- Overloading
  - Allows multiple function definitions with same name
- Generics
  - 'type-less' definition of a class or a function
- **Subtyping depends on dynamic binding**
  - Associate function call resolution with subtype
  - POSTPONE function call resolution until run-time

# Static versus Dynamic Binding

- Static binding
  - compiler resolves function calls
  - translates each function invocation into a direct jump
  - efficient but rigid
- Dynamic binding
  - compiler does not resolve a function call at compile-time.
  - extra instructions generated
  - at run-time, the appropriate function address extracted from a jump table
  - flexible but costly

# Binding Design Choices

- Java
  - All functions dynamically bound (EXPENSIVE!)
- C++
  - Static binding by default (efficient!)
  - Dynamic binding with keyword 'virtual'
- Static binding
  - Reasonable when function choice will not vary
- Dynamic binding
  - Reasonable when subtype affects function choice
  - Heterogeneous collections



# C++ : Static Binding by Default

```
// How to select dynamic binding in C++?
```

```
// cannot use objects directly:
```

```
//      memory allocated => (sub)type fixed
```

```
//      access objects indirectly: pointers!
```

```
//      (sub)type of object addressed may vary
```

```
Parent * pPtr;      // stack allocated pointer
```

```
Child  * cPtr;      // stack allocated pointer
```

```
pPtr = new Child;   // pointer holds address of  
                  // heap-allocated Child object
```

```
pPtr->parentFn();   // parent class implementation  
// C++ -- static binding is default
```

```
// EXPLICIT DESIGN for C++ dynamic binding
```

```
//      #1 must define functions as virtual in base class
```

```
//      #2 object access must be indirect (via pointer)
```

# C++ : Dynamic Binding by Choice

```
// C++ : DYNAMIC BINDING by choice
// keyword virtual used to signal dynamic binding
class Parent
{
    ...
    public:
        virtual void parentFn();
};

class Child: public Parent
{
    ...
    public:
        void parentFn() override; // override inherited behavior
        void childFn();           // expanded interface
};

...
Parent * pPtr;    // stack allocated pointer
Child  * cPtr;    // stack allocated pointer

pPtr = new Child;    // pointer holds address of
                    // heap-allocated Child object
pPtr->parentFn();    // child class implementation
// C++ -- dynamic binding with virtual functions AND access via pointers
```

## Class design

- Add keyword 'virtual' to method in base class

## Application code

- Use base class pointers

# C++ : Dynamic Binding Issues

```
// Java only dynamic binding: consistent, readable
```

```
// consistency problem in C++  
//    increased SOFTWARE COMPLEXITY => confusion  
//    both static & dynamic binding
```

```
Parent * pPtr;    // stack allocated pointer  
Child  * cPtr;    // stack allocated pointer  
...  
pPtr = cPtr;      // okay to 'upcast'  
                  // parent pPtr holds address of Child object
```

```
// cannot easily discern effect of function invocation
```

```
pPtr->parentFn();
```

```
// #1 parent function if static binding (non-virtual)  
//    even if parentFn() overridden
```

```
// #2 child function if dynamic (virtual function)
```

```
// to get Parent behavior (even if virtual)
```

```
Parent  p = *pPtr; // object 'sliced'  
p.parentFn();      // static binding
```

# Static versus Dynamic Binding

- Static binding translates function calls directly into jump statements
  - ⇒ Function invoked at the point of call cannot vary
  - ⇒ No run-time overhead
  - ⇒ No run-time flexibility
- Dynamic binding postpones function call resolution until run-time
  - ⇒ Function invoke at the point of call can vary
  - ⇒ Run-time overhead
  - ⇒ Run-time flexibility
  - ⇒ Supports polymorphism and heterogeneous collections