Recorded at time: 1461977518.518 world Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 50.195 Hz Average rate: 50.195 Hz Most recent transform: 1461977518.518 (0.000 sec old) Most recent transform: 1461977518.518 (0.000 sec old) Buffer length: 4.981 sec Buffer length: 4.981 sec stand_alone_base_link base_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 38.554 Hz Average rate: 50.195 Hz Most recent transform: 1461977518.515 (0.003 sec old) Most recent transform: 1461977518.518 (0.000 sec old) Buffer length: 4.980 sec Buffer length: 4.981 sec shoulder_pan_link gantry_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 38.554 Hz Average rate: 50.195 Hz Most recent transform: 1461977518.515 (0.003 sec old) Most recent transform: 1461977518.518 (0.000 sec old) Buffer length: 4.980 sec Buffer length: 4.981 sec camera_link shoulder_lift_link Broadcaster: /robot_state_publisher Average rate: 38.554 Hz Most recent transform: 1461977518.515 (0.003 sec old) Buffer length: 4.980 sec upperarm_roll_link Broadcaster: /robot_state_publisher Average rate: 38.554 Hz Most recent transform: 1461977518.515 (0.003 sec old) Buffer length: 4.980 sec elbow_flex_link Broadcaster: /robot_state_publisher Average rate: 38.554 Hz Most recent transform: 1461977518.515 (0.003 sec old) Buffer length: 4.980 sec forearm_roll_link Broadcaster: /robot_state_publisher Average rate: 38.554 Hz Most recent transform: 1461977518.515 (0.003 sec old) Buffer length: 4.980 sec wrist_flex_link Broadcaster: /robot_state_publisher Average rate: 38.554 Hz Most recent transform: 1461977518.515 (0.003 sec old) Buffer length: 4.980 sec wrist_roll_link Broadcaster: /robot_state_publisher Average rate: 50.195 Hz Most recent transform: 1461977518.518 (0.000 sec old) Buffer length: 4.981 sec gripper_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 39.034 Hz Average rate: 39.034 Hz Most recent transform: 1461977518.508 (0.010 sec old) Most recent transform: 1461977518.508 (0.010 sec old) Buffer length: 4.970 sec Buffer length: 4.970 sec l_gripper_finger_link r_gripper_finger_link

view_frames Result