CEE 697M: Big Data and Machine Learning for Engineers Lecture 1d: Decision and Information Theories

Jimi Oke

UMass Amherst

College of Engineering

September 11, 2025

Outline

Decision theory

2 Information theory

Outlook

The posterior expected loss/risk for an action a given a state of nature h is:

The posterior expected loss/risk for an action a given a state of nature h is:

$$R(a|\mathbf{x}) := \mathbb{E}_{p(h|\mathbf{x})}[\ell(h,a) = \sum_{h \in \mathcal{H}} \ell(h,a)p(h|\mathbf{x})$$
 (1)

The posterior expected loss/risk for an action a given a state of nature h is:

$$R(a|\mathbf{x}) := \mathbb{E}_{p(h|\mathbf{x})}[\ell(h,a) = \sum_{h \in \mathcal{H}} \ell(h,a)p(h|\mathbf{x})$$
 (1)

In making decisions, we want to find an optimal policy π^* by minimizing risk:

The posterior expected loss/risk for an action a given a state of nature h is:

$$R(a|\mathbf{x}) := \mathbb{E}_{p(h|\mathbf{x})}[\ell(h,a) = \sum_{h \in \mathcal{H}} \ell(h,a)p(h|\mathbf{x})$$
 (1)

In making decisions, we want to find an optimal policy π^* by minimizing risk:

$$\pi^*(\mathbf{x}) = \arg\min_{\mathbf{a} \in \mathcal{A}} \mathbb{E}_{p(h|\mathbf{x}}[\ell(h, \mathbf{a})]$$
 (2)

The posterior expected loss/risk for an action a given a state of nature h is:

$$R(a|\mathbf{x}) := \mathbb{E}_{p(h|\mathbf{x})}[\ell(h,a) = \sum_{h \in \mathcal{H}} \ell(h,a)p(h|\mathbf{x})$$
 (1)

In making decisions, we want to find an optimal policy π^* by minimizing risk:

$$\pi^*(\mathbf{x}) = \arg\min_{\mathbf{a} \in \mathcal{A}} \mathbb{E}_{p(h|\mathbf{x}}[\ell(h, \mathbf{a})]$$
 (2)

or maximizing expected utility $\mathbb{U}(h, a) = -\ell(h, a)$:

$$\pi^*(\mathbf{x}) = \arg\max_{\mathbf{a} \in \mathcal{A}} \mathbb{E}_h[U(h, \mathbf{a})] \tag{3}$$

To assign the optimal class label in a classification prediction, the **optimal policy** is:

To assign the optimal class label in a classification prediction, the **optimal policy** is:

$$\pi^*(\mathbf{x}) = \arg\max_{\mathbf{y} \in \mathcal{Y}} p(\mathbf{y}|\mathbf{x}) \tag{4}$$

To assign the optimal class label in a classification prediction, the **optimal policy** is:

$$\pi^*(\mathbf{x}) = \arg\max_{y \in \mathcal{Y}} p(y|\mathbf{x}) \tag{4}$$

that is, we assign the label to class that is most probable.

To assign the optimal class label in a classification prediction, the **optimal policy** is:

$$\pi^*(\mathbf{x}) = \arg\max_{\mathbf{y} \in \mathcal{Y}} p(\mathbf{y}|\mathbf{x}) \tag{4}$$

that is, we assign the label to class that is most probable.

- $y \in \{0, 1\}$: true label
- $\hat{y} \in \{0, 1\}$: predicted label
- x: input vector

To assign the optimal class label in a classification prediction, the **optimal policy** is:

$$\pi^*(\mathbf{x}) = \arg\max_{\mathbf{y} \in \mathcal{Y}} p(\mathbf{y}|\mathbf{x}) \tag{4}$$

that is, we assign the label to class that is most probable.

- $y \in \{0, 1\}$: true label
- $\hat{y} \in \{0, 1\}$: predicted label
- x: input vector

The posterior expected loss (if the loss function is the 0-1 loss) is:

To assign the optimal class label in a classification prediction, the **optimal policy** is:

$$\pi^*(\mathbf{x}) = \arg\max_{y \in \mathcal{Y}} p(y|\mathbf{x}) \tag{4}$$

that is, we assign the label to class that is most probable.

- $y \in \{0, 1\}$: true label
- $\hat{y} \in \{0, 1\}$: predicted label
- x: input vector

The posterior expected loss (if the loss function is the 0-1 loss) is:

$$R(\hat{y}|\mathbf{x}) = p(\hat{y} \neq y^*|\mathbf{x}) \tag{5}$$

To assign the optimal class label in a classification prediction, the **optimal policy** is:

$$\pi^*(\mathbf{x}) = \arg\max_{y \in \mathcal{Y}} p(y|\mathbf{x}) \tag{4}$$

that is, we assign the label to class that is most probable.

- $y \in \{0, 1\}$: true label
- $\hat{y} \in \{0, 1\}$: predicted label
- x: input vector

The posterior expected loss (if the loss function is the 0-1 loss) is:

$$R(\hat{y}|\mathbf{x}) = p(\hat{y} \neq y^*|\mathbf{x}) \tag{5}$$

(This is the error rate)

Decision rule for binary classification

Given a probability threshold τ , we can assign a class label in a binary setting using:

Decision rule for binary classification

Given a probability threshold τ , we can assign a class label in a binary setting using:

$$\hat{y}(\mathbf{x}) = \mathbb{I}(p(y=1|\mathbf{x}) \ge 1 - \tau) \tag{6}$$

Precision:

Precision:

$$\mathcal{P}(\tau) :=$$

Precision:

$$\mathcal{P}(\tau) := p(y = 1 | \hat{y} = 1, \tau)$$

• Precision:

$$\mathcal{P}(\tau) := p(y = 1|\hat{y} = 1, \tau) = \frac{TP_{\tau}}{TP_{\tau} + FP_{\tau}} \tag{7}$$

• Precision:

$$\mathcal{P}(\tau) := p(y = 1|\hat{y} = 1, \tau) = \frac{TP_{\tau}}{TP_{\tau} + FP_{\tau}} \tag{7}$$

Recall (sensitivity, hit rate, true positive rate (TPR):

Precision:

$$\mathcal{P}(\tau) := p(y = 1|\hat{y} = 1, \tau) = \frac{TP_{\tau}}{TP_{\tau} + FP_{\tau}} \tag{7}$$

Recall (sensitivity, hit rate, true positive rate (TPR):

$$\mathcal{R}(\tau) :=$$

Precision:

$$\mathcal{P}(\tau) := p(y = 1|\hat{y} = 1, \tau) = \frac{TP_{\tau}}{TP_{\tau} + FP_{\tau}} \tag{7}$$

Recall (sensitivity, hit rate, true positive rate (TPR):

$$\mathcal{R}(\tau) := p(\hat{y} = 1 | y = 1, \tau)$$

• Precision:

$$\mathcal{P}(\tau) := p(y = 1|\hat{y} = 1, \tau) = \frac{TP_{\tau}}{TP_{\tau} + FP_{\tau}} \tag{7}$$

• Recall (sensitivity, hit rate, true positive rate (TPR):

$$\mathcal{R}(\tau) := \rho(\hat{y} = 1|y = 1, \tau) = \frac{TP_{\tau}}{TP_{\tau} + FN_{\tau}} \tag{8}$$

• Precision:

$$\mathcal{P}(\tau) := p(y = 1|\hat{y} = 1, \tau) = \frac{TP_{\tau}}{TP_{\tau} + FP_{\tau}}$$
 (7)

• Recall (sensitivity, hit rate, true positive rate (TPR):

$$\mathcal{R}(\tau) := p(\hat{y} = 1|y = 1, \tau) = \frac{TP_{\tau}}{TP_{\tau} + FN_{\tau}} \tag{8}$$

• Precision:

$$\mathcal{P}(\tau) := p(y = 1|\hat{y} = 1, \tau) = \frac{TP_{\tau}}{TP_{\tau} + FP_{\tau}}$$
 (7)

• Recall (sensitivity, hit rate, true positive rate (TPR):

$$\mathcal{R}(\tau) := p(\hat{y} = 1|y = 1, \tau) = \frac{TP_{\tau}}{TP_{\tau} + FN_{\tau}} \tag{8}$$

$$FPR(\tau) = p(\hat{y} = 1|y = 0, \tau)$$

Precision:

$$\mathcal{P}(\tau) := p(y = 1|\hat{y} = 1, \tau) = \frac{TP_{\tau}}{TP_{\tau} + FP_{\tau}}$$
 (7)

• Recall (sensitivity, hit rate, true positive rate (TPR):

$$\mathcal{R}(\tau) := p(\hat{y} = 1|y = 1, \tau) = \frac{TP_{\tau}}{TP_{\tau} + FN_{\tau}} \tag{8}$$

$$FPR(au) = p(\hat{y} = 1|y = 0, au) = \frac{FP_{ au}}{FP_{ au} + TN_{ au}}$$

• Precision:

$$\mathcal{P}(\tau) := p(y = 1|\hat{y} = 1, \tau) = \frac{TP_{\tau}}{TP_{\tau} + FP_{\tau}}$$
 (7)

Recall (sensitivity, hit rate, true positive rate (TPR):

$$\mathcal{R}(\tau) := p(\hat{y} = 1|y = 1, \tau) = \frac{TP_{\tau}}{TP_{\tau} + FN_{\tau}} \tag{8}$$

$$FPR(\tau) = p(\hat{y} = 1|y = 0, \tau) = \frac{FP_{\tau}}{FP_{\tau} + TN_{\tau}} = \frac{FP_{\tau}}{N}$$
 (9)

• Precision:

$$\mathcal{P}(\tau) := p(y = 1|\hat{y} = 1, \tau) = \frac{TP_{\tau}}{TP_{\tau} + FP_{\tau}}$$
 (7)

• Recall (sensitivity, hit rate, true positive rate (TPR):

$$\mathcal{R}(\tau) := p(\hat{y} = 1|y = 1, \tau) = \frac{TP_{\tau}}{TP_{\tau} + FN_{\tau}} \tag{8}$$

False positive rate (FPR, false alarm rate, type I error rate):

$$FPR(\tau) = p(\hat{y} = 1|y = 0, \tau) = \frac{FP_{\tau}}{FP_{\tau} + TN_{\tau}} = \frac{FP_{\tau}}{N}$$
 (9)

*F*_β-score:

Precision:

$$\mathcal{P}(\tau) := p(y = 1|\hat{y} = 1, \tau) = \frac{TP_{\tau}}{TP_{\tau} + FP_{\tau}}$$
 (7)

Recall (sensitivity, hit rate, true positive rate (TPR):

$$\mathcal{R}(\tau) := p(\hat{y} = 1|y = 1, \tau) = \frac{TP_{\tau}}{TP_{\tau} + FN_{\tau}} \tag{8}$$

False positive rate (FPR, false alarm rate, type I error rate):

$$FPR(\tau) = p(\hat{y} = 1|y = 0, \tau) = \frac{FP_{\tau}}{FP_{\tau} + TN_{\tau}} = \frac{FP_{\tau}}{N}$$
 (9)

*F*_β-score:

$$F_{\beta} :=$$

Precision:

$$\mathcal{P}(\tau) := p(y = 1|\hat{y} = 1, \tau) = \frac{TP_{\tau}}{TP_{\tau} + FP_{\tau}}$$
 (7)

Recall (sensitivity, hit rate, true positive rate (TPR):

$$\mathcal{R}(\tau) := p(\hat{y} = 1|y = 1, \tau) = \frac{IP_{\tau}}{TP_{\tau} + FN_{\tau}}$$
(8)

False positive rate (FPR, false alarm rate, type I error rate):

$$FPR(\tau) = p(\hat{y} = 1|y = 0, \tau) = \frac{FP_{\tau}}{FP_{\tau} + TN_{\tau}} = \frac{FP_{\tau}}{N}$$
 (9)

*F*_β-score:

$$F_{\beta} := (1 + \beta^2) \frac{\mathcal{P} \cdot \mathcal{R}}{\beta^2 \mathcal{P} + \mathcal{R}} \tag{10}$$

Precision:

$$\mathcal{P}(\tau) := p(y = 1|\hat{y} = 1, \tau) = \frac{TP_{\tau}}{TP_{\tau} + FP_{\tau}} \tag{7}$$

• Recall (sensitivity, hit rate, true positive rate (TPR):

$$\mathcal{R}(\tau) := p(\hat{y} = 1|y = 1, \tau) = \frac{TP_{\tau}}{TP_{\tau} + FN_{\tau}} \tag{8}$$

False positive rate (FPR, false alarm rate, type I error rate):

$$FPR(\tau) = p(\hat{y} = 1|y = 0, \tau) = \frac{FP_{\tau}}{FP_{\tau} + TN_{\tau}} = \frac{FP_{\tau}}{N}$$
 (9)

• F_{β} -score:

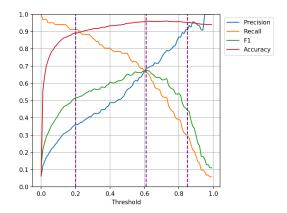
$$F_{\beta} := (1 + \beta^2) \frac{\mathcal{P} \cdot \mathcal{R}}{\beta^2 \mathcal{P} + \mathcal{R}} \tag{10}$$

Setting $\beta = 1$ gives the harmonic mean of precision and recall F_1 .

Comparing performance measures to select threshold

Comparing performance measures to select threshold

Here we choose τ to maximize \mathcal{P} , \mathcal{R} and F_1 :

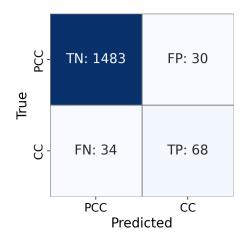


Activity: computing performance metrics

Given the confusion matrix, find P, R and F_1 :

Activity: computing performance metrics

Given the confusion matrix, find \mathcal{P} , \mathcal{R} and F_1 :

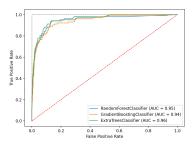


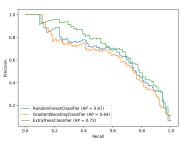
ullet ROC curves: TPR versus FPR for various au

- ullet ROC curves: TPR versus FPR for various au
- ullet Precision-recall curves: ${\cal P}$ versus ${\cal R}$ for various au

- ullet ROC curves: TPR versus FPR for various au
- Precision-recall curves: ${\cal P}$ versus ${\cal R}$ for various ${ au}$
- ROC and PRC of 3 candidate models:

- ROC curves: TPR versus FPR for various au
- Precision-recall curves: $\mathcal P$ versus $\mathcal R$ for various τ
- ROC and PRC of 3 candidate models:





We find optimal parameters by minimizing loss functions such as:

We find optimal parameters by minimizing loss functions such as:

• L2 loss: squared error: $\ell_2(h,a) = (h-a)^2$

We find optimal parameters by minimizing loss functions such as:

- L2 loss: squared error: $\ell_2(h, a) = (h a)^2$
- L1 loss: absolute value: $\ell_2(h, a) = |h a|$

We find optimal parameters by minimizing loss functions such as:

- L2 loss: squared error: $\ell_2(h, a) = (h a)^2$
- L1 loss: absolute value: $\ell_2(h, a) = |h a|$ (robust to outliers)

We find optimal parameters by minimizing loss functions such as:

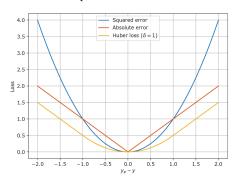
- L2 loss: squared error: $\ell_2(h, a) = (h a)^2$
- L1 loss: absolute value: $\ell_2(h, a) = |h a|$ (robust to outliers)
- Huber loss:

$$\ell_{\delta}(h,a) = \begin{cases} \frac{(h-a)^2}{2}, & |h-a| \le \delta\\ \delta|h-a| - \delta^2/2, & |h-a| > \delta \end{cases}$$
(11)

We find optimal parameters by minimizing loss functions such as:

- L2 loss: squared error: $\ell_2(h, a) = (h a)^2$
- L1 loss: absolute value: $\ell_2(h, a) = |h a|$ (robust to outliers)
- Huber loss:

$$\ell_{\delta}(h,a) = \begin{cases} \frac{(h-a)^2}{2}, & |h-a| \le \delta\\ \delta|h-a| - \delta^2/2, & |h-a| > \delta \end{cases}$$
(11)



Source: https://www.evergreeninnovations.co/blog-machine-learning-loss-functions/

Entropy \mathbb{H} is a measure of the lack of predictability (uncertainty) of a random variable X with distribution p over K states:

Entropy \mathbb{H} is a measure of the lack of predictability (uncertainty) of a random variable X with distribution p over K states:

 $\mathbb{H}(X)$

Entropy \mathbb{H} is a measure of the lack of predictability (uncertainty) of a random variable X with distribution p over K states:

$$\mathbb{H}(X) := -\sum_{k=1}^{K} p(X=k) \log_2 p(X=k)$$

Entropy \mathbb{H} is a measure of the lack of predictability (uncertainty) of a random variable X with distribution p over K states:

$$\mathbb{H}(X) := -\sum_{k=1}^{K} p(X = k) \log_2 p(X = k) = -\mathbb{E}_X[\log p(X)]$$
 (12)

Entropy \mathbb{H} is a measure of the lack of predictability (uncertainty) of a random variable X with distribution p over K states:

$$\mathbb{H}(X) := -\sum_{k=1}^{K} p(X = k) \log_2 p(X = k) = -\mathbb{E}_X[\log p(X)]$$
 (12)

Notes

Entropy is measured in bits

Entropy \mathbb{H} is a measure of the lack of predictability (uncertainty) of a random variable X with distribution p over K states:

$$\mathbb{H}(X) := -\sum_{k=1}^{K} p(X = k) \log_2 p(X = k) = -\mathbb{E}_X[\log p(X)]$$
 (12)

Notes

- Entropy is measured in bits
- For a K-ary r.v., entropy is maximized when $p(X = k) = \frac{1}{K}$

Binary r.v. $X \in \{0, 1\}$;

Binary r.v.
$$X \in \{0,1\}$$
; $p(X = 1) = \theta$;

Binary r.v.
$$X \in \{0, 1\}$$
; $p(X = 1) = \theta$; $p(X = 0) = 1 - \theta$.

Binary r.v.
$$X \in \{0,1\}$$
; $p(X = 1) = \theta$; $p(X = 0) = 1 - \theta$.

The binary entropy is given by:

Binary r.v.
$$X \in \{0,1\}$$
; $p(X = 1) = \theta$; $p(X = 0) = 1 - \theta$.

The binary entropy is given by:

$$\mathbb{H}(X) = -\sum_{k=1}^{K} p(X = k) \log_2 p(X = k)$$
 (13)

$$= -[p(X=1)\log_2 p(X=1) + p(X=0)\log_2 p(X=0)]$$
 (14)

$$= -[\theta \log_2 \theta + (1 - \theta) \log_2 (1 - \theta)] \tag{15}$$

Cross entropy between distribution p and q:

• Cross entropy between distribution *p* and *q*:

$$\mathbb{H}(p,q)$$

• Cross entropy between distribution *p* and *q*:

$$\mathbb{H}(p,q) := -\sum_{k=1}^{K} p_k \log q_k \tag{16}$$

• Cross entropy between distribution *p* and *q*:

$$\mathbb{H}(p,q) := -\sum_{k=1}^{K} p_k \log q_k \tag{16}$$

Joint entropy of two r.v.'s X and Y:

• Cross entropy between distribution *p* and *q*:

$$\mathbb{H}(p,q) := -\sum_{k=1}^{K} p_k \log q_k \tag{16}$$

Joint entropy of two r.v.'s X and Y:

$$\mathbb{H}(X,Y)$$

• Cross entropy between distribution *p* and *q*:

$$\mathbb{H}(p,q) := -\sum_{k=1}^{K} p_k \log q_k \tag{16}$$

Joint entropy of two r.v.'s X and Y:

$$\mathbb{H}(X,Y) := -\sum_{x,y} p(x,y) \log_2 p(x,y)$$
 (17)

Conditional entropy:

• Cross entropy between distribution p and q:

$$\mathbb{H}(p,q) := -\sum_{k=1}^{K} p_k \log q_k \tag{16}$$

Joint entropy of two r.v.'s X and Y:

$$\mathbb{H}(X,Y) := -\sum_{x,y} p(x,y) \log_2 p(x,y)$$
 (17)

Conditional entropy:

$$\mathbb{H}(Y|X)$$

• Cross entropy between distribution p and q:

$$\mathbb{H}(p,q) := -\sum_{k=1}^{K} p_k \log q_k \tag{16}$$

Joint entropy of two r.v.'s X and Y:

$$\mathbb{H}(X,Y) := -\sum_{x,y} p(x,y) \log_2 p(x,y)$$
 (17)

Conditional entropy:

$$\mathbb{H}(Y|X) := \mathbb{H}(X,Y) - \mathbb{H}(X) \tag{18}$$

Multivariate entropy functions

• Cross entropy between distribution p and q:

$$\mathbb{H}(p,q) := -\sum_{k=1}^{K} p_k \log q_k \tag{16}$$

Joint entropy of two r.v.'s X and Y:

$$\mathbb{H}(X,Y) := -\sum_{x,y} p(x,y) \log_2 p(x,y)$$
 (17)

Conditional entropy:

$$\mathbb{H}(Y|X) := \mathbb{H}(X,Y) - \mathbb{H}(X) \tag{18}$$

Chain rule for entropy:

Multivariate entropy functions

• Cross entropy between distribution *p* and *q*:

$$\mathbb{H}(p,q) := -\sum_{k=1}^{K} p_k \log q_k \tag{16}$$

Joint entropy of two r.v.'s X and Y:

$$\mathbb{H}(X,Y) := -\sum_{x,y} p(x,y) \log_2 p(x,y)$$
 (17)

Conditional entropy:

$$\mathbb{H}(Y|X) := \mathbb{H}(X,Y) - \mathbb{H}(X) \tag{18}$$

Chain rule for entropy:

$$\mathbb{H}(X_1, X_2, \dots, X_n) = \sum_{i=1}^n \mathbb{H}(X_i | X_1, \dots, X_{i-1})$$
 (19)

Also known as the Kullback-Leibler (KL) divergence or information gain.

Also known as the Kullback-Leibler (KL) divergence or information gain.

It measures the dissimilarity (distance) between two distributions p and q:

Also known as the Kullback-Leibler (KL) divergence or information gain.

It measures the dissimilarity (distance) between two distributions p and q:

$$\mathbb{KL}(p||q) := \sum_{k=1}^{K} p_k \log \frac{p_k}{q_k} \quad \text{(Discrete)}$$
 (20)

$$\mathbb{KL}(p||q) := \int p_k \log \frac{p_k}{q_k} dx$$
 (Continuous) (21)

In discrete case, we can show that:

$$\mathbb{KL}(p||q) = \mathbb{H}(p,q) - \mathbb{H}(p)$$
 (22)

i.e. cross entropy (between p and q minus entropy of p).

Also known as the Kullback-Leibler (KL) divergence or information gain.

It measures the dissimilarity (distance) between two distributions p and q:

$$\mathbb{KL}(p||q) := \sum_{k=1}^{K} p_k \log \frac{p_k}{q_k} \quad \text{(Discrete)}$$

$$\mathbb{KL}(p||q) := \int p_k \log \frac{p_k}{q_k} dx \quad \text{(Continuous)} \tag{21}$$

Also known as the Kullback-Leibler (KL) divergence or information gain.

It measures the dissimilarity (distance) between two distributions p and q:

$$\mathbb{KL}(p||q) := \sum_{k=1}^{K} p_k \log \frac{p_k}{q_k} \quad \text{(Discrete)}$$
 (20)

$$\mathbb{KL}(p||q) := \int p_k \log \frac{p_k}{q_k} dx \quad \text{(Continuous)} \tag{21}$$

In discrete case, we can show that:

Also known as the Kullback-Leibler (KL) divergence or information gain.

It measures the dissimilarity (distance) between two distributions p and q:

$$\mathbb{KL}(p||q) := \sum_{k=1}^{K} p_k \log \frac{p_k}{q_k} \quad \text{(Discrete)}$$
 (20)

$$\mathbb{KL}(p||q) := \int p_k \log \frac{p_k}{q_k} dx \quad \text{(Continuous)} \tag{21}$$

In discrete case, we can show that:

$$\mathbb{KL}(p||q) = \mathbb{H}(p,q) - \mathbb{H}(p)$$
 (22)

Also known as the Kullback-Leibler (KL) divergence or information gain.

It measures the dissimilarity (distance) between two distributions p and q:

$$\mathbb{KL}(p||q) := \sum_{k=1}^{K} p_k \log \frac{p_k}{q_k} \quad \text{(Discrete)}$$

$$\mathbb{KL}(p||q) := \int p_k \log \frac{p_k}{q_k} dx \quad \text{(Continuous)}$$
 (21)

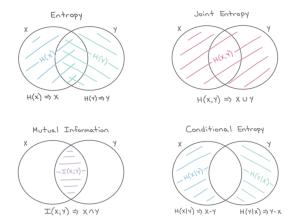
In discrete case, we can show that:

$$\mathbb{KL}(p||q) = \mathbb{H}(p,q) - \mathbb{H}(p)$$
 (22)

i.e. cross entropy (between p and q minus entropy of p).

Entropy Venn diagrams

Entropy Venn diagrams



Source: PMLI Figure 6.4, page 211

This measures the dependency between two r.v.'s (more robust than correlation):

This measures the dependency between two r.v.'s (more robust than correlation):

$$\mathbb{I}(X;Y) := \mathbb{KL}(p(x,y)||p(x)p(y))$$

This measures the dependency between two r.v.'s (more robust than correlation):

$$\mathbb{I}(X;Y) := \mathbb{KL}(p(x,y)||p(x)p(y)) = \sum_{y \in Y} \sum_{x \in X} p(x,y) \log \frac{p(x,y)}{p(x)p(y)}$$
(23)

This measures the dependency between two r.v.'s (more robust than correlation):

$$\mathbb{I}(X;Y) := \mathbb{KL}(p(x,y)||p(x)p(y)) = \sum_{y \in Y} \sum_{x \in X} p(x,y) \log \frac{p(x,y)}{p(x)p(y)}$$
(23)

• Can also be written as:

This measures the dependency between two r.v.'s (more robust than correlation):

$$\mathbb{I}(X;Y) := \mathbb{KL}(p(x,y)||p(x)p(y)) = \sum_{y \in Y} \sum_{x \in X} p(x,y) \log \frac{p(x,y)}{p(x)p(y)}$$
(23)

Can also be written as:

$$\mathbb{I}(X;Y) = \mathbb{H}(X) - \mathbb{H}(X|Y) = \mathbb{H}(Y) - \mathbb{H}(Y|X)$$
(24)

This measures the dependency between two r.v.'s (more robust than correlation):

$$\mathbb{I}(X;Y) := \mathbb{KL}(p(x,y)||p(x)p(y)) = \sum_{y \in Y} \sum_{x \in X} p(x,y) \log \frac{p(x,y)}{p(x)p(y)}$$
(23)

• Can also be written as:

$$\mathbb{I}(X;Y) = \mathbb{H}(X) - \mathbb{H}(X|Y) = \mathbb{H}(Y) - \mathbb{H}(Y|X)$$
 (24)

MI is always ≥ 0.

This measures the dependency between two r.v.'s (more robust than correlation):

$$\mathbb{I}(X;Y) := \mathbb{KL}(p(x,y)||p(x)p(y)) = \sum_{y \in Y} \sum_{x \in X} p(x,y) \log \frac{p(x,y)}{p(x)p(y)}$$
(23)

Can also be written as:

$$\mathbb{I}(X;Y) = \mathbb{H}(X) - \mathbb{H}(X|Y) = \mathbb{H}(Y) - \mathbb{H}(Y|X)$$
 (24)

- MI is always ≥ 0 .
- A normalized estimate of MI is the "maximal information coefficient" (MIC):

This measures the dependency between two r.v.'s (more robust than correlation):

$$\mathbb{I}(X;Y) := \mathbb{KL}(p(x,y)||p(x)p(y)) = \sum_{y \in Y} \sum_{x \in X} p(x,y) \log \frac{p(x,y)}{p(x)p(y)}$$
(23)

• Can also be written as:

$$\mathbb{I}(X;Y) = \mathbb{H}(X) - \mathbb{H}(X|Y) = \mathbb{H}(Y) - \mathbb{H}(Y|X)$$
 (24)

- MI is always ≥ 0.
- A normalized estimate of MI is the "maximal information coefficient" (MIC):

$$MIC(X,Y) = \max_{G} \frac{\mathbb{I}((X,Y)|_{G})}{\log||G||}$$
 (25)

where G is the set of 2d grids

Reading assignments

- **PMLI** 5.1–5.4; 6.1–6.3
- **ESL** 7.1–7.7, 7.10–12