

CEE 616: Probabilistic Machine Learning
M5 Unsupervised Learning:
5B: Factor Analysis and Autoencoders

Jimi Oke

UMass**Amherst**

College of Engineering

Dec 4, 2025

Outline

- ① Factor analysis
- ② FA Estimation
- ③ Autoencoders
- ④ AE variants
- ⑤ Outlook

Factor analysis model

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In PCA/FA, we learn a **linear mapping** from a high-dimensional observed space $\mathbf{x} \in \mathbb{R}^D$ to a low-dimensional latent space $\mathbf{z} \in \mathbb{R}^L$ and vice-versa.

- **Encoder** f_e : mapping from $\mathbf{x} \rightarrow \mathbf{z}$
- **Decoder** f_d : mapping from $\mathbf{z} \rightarrow \mathbf{x}$

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To introduce flexibility, we can specify f_e and f_d are nonlinear/more complex functions. This is best accomplished via neural network, resulting in an **autoencoder** (AE).

Reconstruction loss

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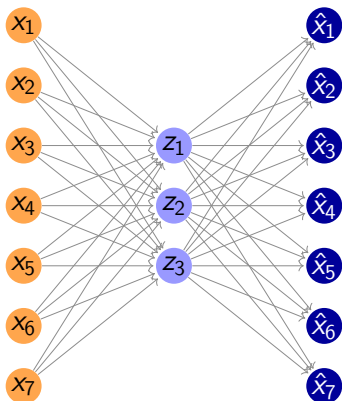
or equivalently, the negative log-likelihood:

$$\mathcal{L}(\boldsymbol{\theta}) = -\log p(\mathbf{x}|r(\mathbf{x})) \quad (22)$$

Basic autoencoder (AE) architecture

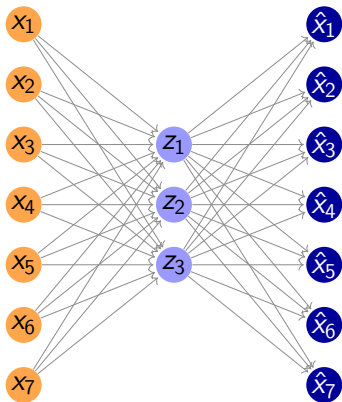
Basic autoencoder (AE) architecture

Autoencoder with 2 single-layer MLPS: input layer, hidden layer (latent representation) and output layer (reconstruction)



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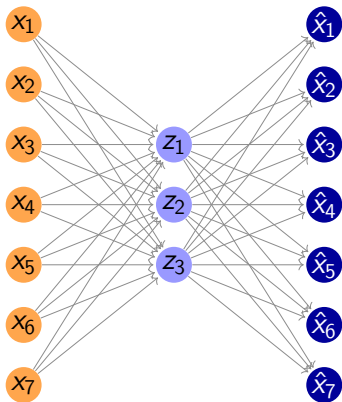
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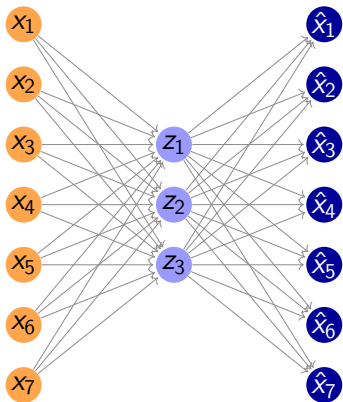
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- $L \gg D$: overcomplete representation (regularize to prevent identity learning)

Denoising autoencoders

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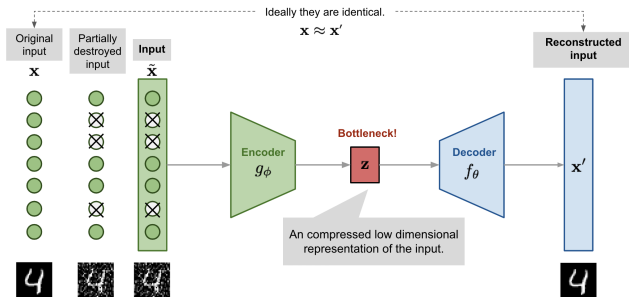
In denoising autoencoders (DAEs), the input is corrupted ($\tilde{\mathbf{x}}$) by:

- Gaussian noise: $p_c(\tilde{\mathbf{x}}|\mathbf{x}) = \mathcal{N}(\tilde{\mathbf{x}}|\mathbf{x}, \sigma^2 \mathbf{I})$

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- Gaussian noise: $p_c(\tilde{\mathbf{x}}|\mathbf{x}) = \mathcal{N}(\tilde{\mathbf{x}}|\mathbf{x}, \sigma^2 \mathbf{I})$
- Bernoulli dropout: randomly setting a proportion of input nodes to zero



Schematic of a DAE.

Source: <https://lilianweng.github.io/posts/2018-08-12-vae/>

The model is then trained to minimize the loss between the reconstructed input $r(\tilde{\mathbf{x}})$ and its uncorrupted version \mathbf{x}

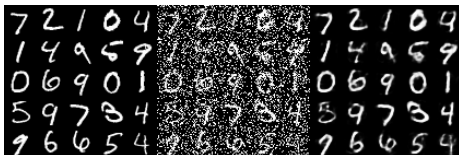
Uses of DAE

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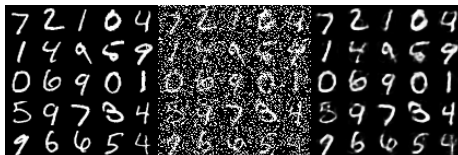
Original, corrupted and reconstructed images from MNIST dataset.

Source: <http://www.opendeep.org/v0.0.5/docs/tutorial-your-first-model>

- They can also learn vector fields of input data

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- They can also learn vector fields of input data
- Popular for their simplicity

Sparse autoencoder (SAE)

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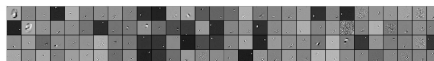
Sparse autoencoder (SAE): sparsity penalty on latent activations

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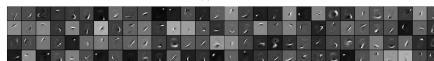
Sparse autoencoder (SAE): sparsity penalty on latent activations

$$\Omega(\mathbf{z}) = \lambda \|\mathbf{z}\|_1 \quad (23)$$

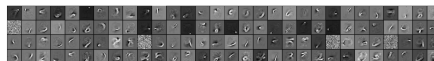
- k*-Sparse autoencoder:** use only *k* largest activations in training



(a) $k = 70$



(b) $k = 40$



(c) $k = 25$



(d) $k = 10$

Filters of the *k*-sparse autoencoder for different sparsity levels *k*, learnt from MNIST with 1000 hidden units.

Source: <https://arxiv.org/pdf/1312.5663.pdf>

Useful for interpretability

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- Variational autoencoder (VAE): probabilistic version of AE/generative model

Reading

- **PMLI 20.3**
- **DL 20**