

$$Q11 \quad dW_t = ((\pi_t(p-r)+r)W_t - c_t)dt + \pi_t \sigma W_t dz_t$$

$$\max \mathbb{E} \left\{ \int_t^T e^{-\rho(s-t)} \log(c_s) ds + e^{-\rho(T-t)} B(T) \log(W_t) \right\}$$

$$\Rightarrow V^*(t, W_t) = \max_{\pi, c} \mathbb{E} \left\{ \int_t^{t_1} e^{-\rho(s-t)} \log(c_s) ds + e^{-\rho(t_1-t)} V^*(t_1, W_{t_1}) \right\}$$

$$\Rightarrow e^{-\rho t} V^*(t, W_t) = \max_{\pi, c} \mathbb{E} \left\{ \int_t^{t_1} e^{-\rho s} \log(c_s) ds + e^{-\rho t_1} V^*(t_1, W_{t_1}) \right\}$$

$$\Rightarrow \max_{\pi, c} \mathbb{E} \left\{ d(e^{-\rho t} V^*(t, W_t)) + e^{-\rho t} \log c_t dt \right\} = 0$$

$$\Rightarrow \max_{\pi, c} \mathbb{E} \left\{ d(V^*(t, W_t)) + \log c_t dt = \rho V^*(t, W_t) dt \Rightarrow \right.$$

$$\max_{\pi, c} \frac{\partial V^*}{\partial t} + \frac{\partial V^*}{\partial W} ((\pi_t(p-r) + r)W_t - c_t) + \frac{\partial^2 V^*}{\partial W^2} \frac{\pi_t^2 \sigma^2 W_t^2}{2} + \log(c_t) = \rho V^*(t, W_t)$$

Take partial derivatives wrt  $\pi$  and  $c$  and equate to 0  $\Rightarrow$

$$\frac{\partial V^*}{\partial W_t} (p-r) + \frac{\partial^2 V^*}{\partial W_t^2} \pi_t \sigma^2 W_t = 0 \Rightarrow \boxed{\pi_t^* = \frac{-\frac{\partial V^*}{\partial W_t} (p-r)}{\frac{\partial^2 V^*}{\partial W_t^2} \sigma^2 W_t}}$$

$$-\frac{\partial V^*}{\partial W_t} + \frac{1}{c_t} = 0 \Rightarrow \boxed{c_t = \left( \frac{\partial V^*}{\partial W_t} \right)^{-1}}$$

Q3 States  $s_t = (e_t, v_t)$   $e_t \in \{0, 1\}$   $e_t = 0$  means unemployed,  $e_t = 1$  means employment

$v_t$  is the skill level at time (day)  $= t$ .

action  $= a_t \Rightarrow a_t = 0$  if we are unemployed at time  $t$ , namely  $e_t = 0$ .

$a_t = \alpha_t$  if we work  $\alpha_t$  portion of the time, so  $1 - \alpha_t$  becomes the portion for learning.

reward  $\Rightarrow R(s_t, a_t) = f(v_t) \cdot \alpha_t$ ;  $R(s_t, a_t) = 0$  if  $a_t = 0$  (unemployed)

State transitions:  $P(s_t, a_t, s_{t+1})$ :

If  $s_t = (0, v_t) \Rightarrow a_t = 0 \Rightarrow$  for  $s_{t+1} = (1, v_t e^{-\lambda \cdot p})$  where  $e^{-\lambda p}$  is the losing the skill in one day.  
 $\Rightarrow$  probability  $h(v_t)$ .

$$P((0, v_t), 0, (1, v_t e^{-\lambda p})) = h(v_t).$$

$$P((0, v_t), 0, (0, v_t e^{-\lambda p})) = 1 - h(v_t).$$

for  $s_t = (1, v_t) \Rightarrow$

$$P((1, v_t), \alpha_t, (0, v_t \cdot g(v_t)(1 - \alpha_t))) = p \text{ for all } \alpha_t.$$

$$P((1, v_t), \alpha_t, (1, v_t \cdot g(v_t)(1 - \alpha_t))) = 1 - p \text{ for all } \alpha_t.$$

our goal is to maximize  $\Rightarrow E(G_t) = R_t + \delta R_{t+1} + \delta^2 R_{t+2} + \dots$   
for infinite horizon.

For finite horizon  $\Rightarrow \max R_t + \delta R_{t+1} + \dots + \delta^{T-t} R_T.$

