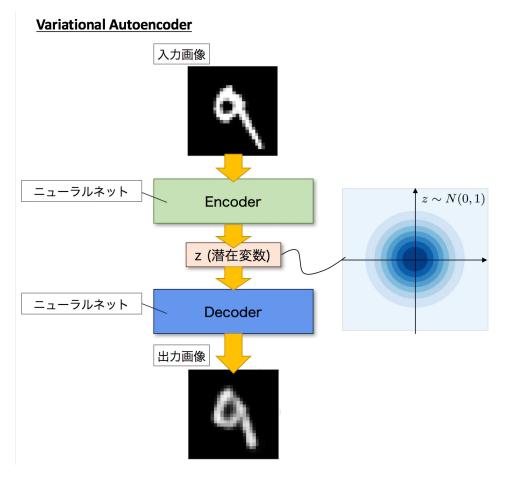
深層生成モデル(VAE・GAN)

• どんなことができるのか、手を動かしてみてみましょう

VAE (Variational Auto Encoder)

- VAEは深層生成モデルの一種で、与えられたデータと似たようなデータを幅広く生成することができます。
 - VAE全体はエンコードして小さい次元のベクトルに圧縮した後にデコードするような、入力を再構成するNNモデルとなっています。
 - エンコード先はが正規分布に近づくようなlossを入れることで、コンパクトに圧縮されたベクトルzにエンコードすることができ、またzを少し変化させると様々な画像をデコードすることができます。



- 出典: Variational Autoencoder徹底解説
- 目的関数

Loss = 再構成誤差 +zのはみだし具合(KLダイバージェンス)

• 時間がかかるのでepoch数を減らして実行してみます

```
In [1]:
         import argparse
         import torch
         import torch.utils.data
         from torch import nn, optim
         from torch.nn import functional as F
         from torchvision import datasets, transforms
         from torchvision.utils import save_image
         parser = argparse. ArgumentParser(description='VAE MNIST Example')
         parser.add_argument('--batch-size', type=int, default=128, metavar='N'
                            help='input batch size for training (default: 128)')
         parser add_argument('--epochs', type=int, default=8, metavar='N'
                             help='number of epochs to train (default: 10)')
         parser.add_argument('--no-cuda', action='store_true', default=False,
                            help='disables CUDA training')
         parser.add_argument('--seed', type=int, default=1, metavar='S',
                            help='random seed (default: 1)')
```

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parser.\ add\_argument('--log-interval',\ type=int,\ default=10,\ metavar='N',
                     help='how many batches to wait before logging training status')
args = parser.parse args("".split())
args. cuda = not args. no_cuda and torch. cuda. is_available()
torch. manual_seed (args. seed)
device = torch. device("cuda" if args. cuda else "cpu")
kwargs = {'num_workers': 1, 'pin_memory': True} if args.cuda else {}
train_loader = torch.utils.data.DataLoader(
    {\tt datasets.\;MNIST('\ldots/data',\;train=True,\;download=True,}
                   transform=transforms. ToTensor()),
    batch_size=args.batch_size, shuffle=True, **kwargs)
test_loader = torch. utils. data. DataLoader(
    datasets. MNIST('.../data', train=False, transform=transforms. ToTensor()),
    batch\_size=args.\ batch\_size,\ \ shuffle=True,\ \ **kwargs)
class VAE(nn. Module):
    def __init__(self):
        super(VAE, self). __init__()
        self. fc1 = nn. Linear (784, 400)
        self. fc21 = nn. Linear (400, 20)
        self. fc22 = nn. Linear (400, 20)
        self. fc3 = nn. Linear(20, 400)
        self. fc4 = nn. Linear(400, 784)
    def encode(self, x):
        h1 = F. relu(self. fc1(x))
        return\ self.\ fc21\,(h1)\,,\ self.\ fc22\,(h1)
    def reparameterize(self, mu, logvar):
        std = torch. exp(0.5*logvar)
        eps = torch.randn_like(std)
        return mu + eps*std
    def decode(self, z):
        h3 = F. relu(self. fc3(z))
        return torch.sigmoid(self.fc4(h3))
    def forward(self, x):
        mu, logvar = self. encode(x. view(-1, 784))
        z = self.reparameterize(mu, logvar)
        return self. decode(z), mu, logvar
model = VAE().to(device)
optimizer = optim. Adam (model. parameters (), Ir=1e-3)
# Reconstruction + KL divergence losses summed over all elements and batch
def loss_function(recon_x, x, mu, logvar):
    BCE = F. binary_cross_entropy(recon_x, x. view(-1, 784), reduction='sum')
    KLD = -0.5 * torch. sum(1 + logvar - mu. pow(2) - logvar. exp())
return BCE + KLD
def train(epoch):
    model.train()
    train_loss = 0
    for batch_idx, (data, _) in enumerate(train_loader):
        data = data. to(device)
        optimizer.zero_grad()
        recon_batch, mu, logvar = model(data)
        loss = loss_function(recon_batch, data, mu, logvar)
        loss.backward()
        train loss += loss.item()
        optimizer.step()
        if batch_idx % args.log_interval == 0:
            print('Train Epoch: {} [ {} /{} ({:.0f}%)]*tLoss: {:.6f}'.format(
    epoch, batch_idx * len(data), len(train_loader.dataset),
    100. * batch_idx / len(train_loader),
                 loss.item() / len(data)))
    print('===> Epoch: {} Average loss: {:.4f}'.format(
          epoch, train_loss / len(train_loader.dataset)))
def test(epoch):
    model.eval()
    test_loss = 0
    with torch no_grad():
        for i, (data, _) in enumerate(test_loader):
           data = data.to(device)
```

```
recon_batch, mu, logvar = model(data)
                              test_loss += loss_function(recon_batch, data, mu, logvar).item()
                                       n = min(data.size(0), 8)
                                       comparison = torch.cat([data[:n],
                                                                                        recon_batch.view(args.batch_size, 1, 28, 28)[:n]])
                                       save_image(comparison.cpu(),
                                                            'reconstruction_' + str(epoch) + '.png', nrow=n)
           test_loss /= len(test_loader.dataset)
           print('====> Test set loss: {:.4f}'.format(test_loss))
 for epoch in range(1, args. epochs + 1):
          train(epoch)
           test (epoch)
           with torch.no_grad():
                    sample = torch. randn (64, 20). to (device) sample = model. decode (sample). cpu ()
                    save_image(sample.view(64, 1, 28, 28),
                                                 'sample_' + str(epoch) +
                                                                                                              . png')
                                  [0/60000 (0%)] Loss: 550.595764

[1280/60000 (2%)] Loss: 287.982056

[2560/60000 (4%)] Loss: 242.801651

[3840/60000 (6%)] Loss: 213.623199

[5120/60000 (9%)] Loss: 216.030853

[6400/60000 (11%)] Loss: 216.303207

[7680/60000 (13%)] Loss: 203.971207

[8960/60000 (15%)] Loss: 197.527985

[10240/60000 (17%)] Loss: 199.671753

[11520/60000 (19%)] Loss: 199.269043

[12800/60000 (21%)] Loss: 186.938980
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Loss: 149.537003

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Loss: 118, 756752

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105. 103088
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107. 780846
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 Train
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                                                                                        108.373764
       => Epoch:
                             Average loss:
                                                        108 5484
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loss: 107.3431
[0/60000 (0%)]
[1280/60000 (2
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Train Epoch: 7
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Loss: 107.465958
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109. 174400
102. 631935
107. 866821
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====> Epoch: 7
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                            Average loss:
loss: 106.7860
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====> Epoch: 8 Average loss:
===> Test set loss: 106.3582
                                                     (98%)
                                                                            Loss: 104.415237
                                                       107 0709
```

In [2]:

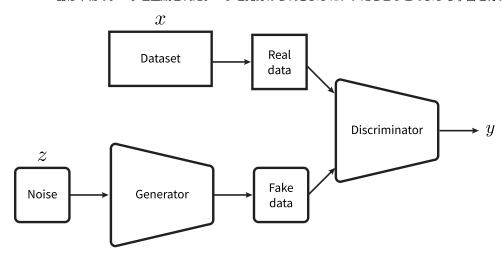
N = 5data, _ = iter(test_loader).next() data = data[:N].to(device)

```
In [3]: import matplotlib.pyplot as plt
          data np = data. detach(). cpu(). numpy()
          plt. figure (figsize= (18, 18))
          for i in range(N):
           plt. subplot(1, N, i+1); plt. imshow(data_np[i]. squeeze(), "gray")
         plt. show()
         0
         10
                                   10
         15
                                   15
         20
         25
In [4]:
          recon_batch, mu, logvar = model(data)
          recon\_batch = recon\_batch. view(N, 28, 28). detach().cpu().numpy()
         plt. figure (figsize= (18, 18))
          for i in range (N):
           plt. subplot(1, N, i+1); plt. imshow(recon_batch[i], "gray")
          plt. show()
         0 -
                                   10
                                                             10
                                                                                        10
                                                                                                                  10 -
         10
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                                                             15
                                                                                        15
                                                                                                                  15
         15
         20
                                   20
                                                             20
                                                                                       20
         25
In [5]:
          sample = torch.randn(N, 20).to(device)
          sample = model.decode(sample)
          sample = sample. view(N, 28, 28). detach().cpu().numpy()
          plt. figure (figsize= (18, 18))
          for i in range(N):
           plt. subplot(1, N, i+1); plt. imshow(sample[i], "gray")
         plt. show()
         0
         10
                                   10
         15
                                   15
                                                             15
         20
         25
                          20
In [6]:
          a = torch. randn(20). to(device)
         b = torch. randn(20). to(device)
          sample = torch. stack([r*a/float(N) + (1.-r)*b/float(N) for r in range(N)])
          sample = model.decode(sample)
          sample = sample. view(N, 28, 28). detach().cpu().numpy()
         plt. figure (figsize= (18, 18))
          for i in range(N):
           plt. subplot(1, N, i+1); plt. imshow(sample[i], "gray")
          plt. show()
```

In []:	
In []:	

GAN (Generative Adversarial Networks)

- GANは深層生成モデルの一種で、与えられたデータと遜色ない本物のような画像を作ることができます。
 - GANの全体は生成器(G:Generator)と識別器(D:Disctiminator)の二つからなっており、生成器は識別器をだませるように、識別器は本物のデータと生成されたデータを見分けられるように、いたちごっこのような学習を行います。



出典: https://www.bigdata-navi.com/aidrops/2519/

- 目的関数
 - 1つの式に表すと以下のようになります(ミニマックス問題)

$$\min_{G} \max_{D} V(D,G) = \mathbb{E}_{\boldsymbol{x} \sim p_{\text{data}}(\boldsymbol{x})}[\log D(\boldsymbol{x})] + \mathbb{E}_{\boldsymbol{z} \sim p_{\boldsymbol{z}}(\boldsymbol{z})}[\log(1 - D(G(\boldsymbol{z})))].$$

■ 識別器の目的関数 (D=1: 本物と判断, D=0: 偽物と判断)

$$\max_{\phi} E_{pd(x)}[\ln D(\phi; x)] + E_{p(z)}[\ln(1 - D(\phi; G(\theta; z))]$$

。 識別器は本物は本物、偽物は偽物と識別できるようにする

$$\min_{\theta} E_{p(z)}[\ln(1-D(\phi;G(\theta;z))]$$

- 生成器の目的関数
 - 。 生成器は、本物だと識別されるようにする
- ref: http://aidiary.hatenablog.com/entry/20180304/1520172429
- 時間がかかるのでepoch数を減らして実行してみます

In [7]:
import os
import pickle
import numpy as np

```
from tqdm import tqdm
import torch
import torch.nn as nn
import torch.optim as optim
from torch.utils.data import DataLoader
from torchvision import datasets, transforms
from torchvision.utils import save_image, make_grid
import matplotlib.pyplot as plt
device = torch. device("cuda" if torch. cuda. is_available() else "cpu")
print(device)
def initialize_weights(model):
    for m in model. modules():
       if isinstance(m, nn. Conv2d):
            m. weight. data. normal_(0, 0.02)
            m. bias. data. zero_()
        elif isinstance(m, nn.ConvTranspose2d):
            m. weight. data. normal_(0, 0.02)
            m. bias. data. zero_()
        elif isinstance(m, nn.Linear):
            m. weight. data. normal_{-}(0, 0.02)
            m. bias. data. zero_()
class Generator (nn. Module):
    def __init__(self):
        super(Generator, self).__init__()
        self. fc = nn. Sequential(
            nn. Linear (62, 1024)
            nn. BatchNorm1d(1024),
            nn. ReLU(),
            nn. Linear (1024, 128 * 7 * 7),
            nn. BatchNorm1d(128 * 7 * 7),
            nn. ReLU(),
        self. deconv = nn. Sequential(
            nn. ConvTranspose2d(128, 64, kernel_size=4, stride=2, padding=1),
            nn. BatchNorm2d(64),
            nn. ReLU(),
            nn.ConvTranspose2d(64, 1, kernel_size=4, stride=2, padding=1),
            nn. Sigmoid(),
        initialize_weights(self)
    def forward(self, input):
        x = self. fc(input)
        x = x. view(-1, 128, 7, 7)
        x = self. deconv(x)
        return x
class Discriminator(nn. Module):
    def __init__(self):
        super(Discriminator, self). __init__()
        self. conv = nn. Sequential (
            nn. Conv2d(1, 64, kernel_size=4, stride=2, padding=1),
            nn. LeakyReLU(0.2),
            nn. Conv2d(64, 128, kernel_size=4, stride=2, padding=1),
            nn. BatchNorm2d(128),
            nn. LeakyReLU (0.2),
        self. fc = nn. Sequential(
            nn. Linear (128 * 7 * 7, 1024),
            nn. BatchNorm1d(1024),
            nn. LeakyReLU (0.2),
            nn. Linear (1024, 1),
            nn. Sigmoid().
        initialize_weights(self)
    def forward(self, input):
        x = self. conv(input)
        x = x. view(-1, 128 * 7 * 7)
        x = self. fc(x)
        return x
# Generatorのサイズテスト
G = Generator()
```

```
input = torch. rand ((32, 62))
out = G(input)
print(out. size())
torch. Size([32, 1, 28, 28])
# Discriminatorのサイズテスト
D = Discriminator()
input = torch. rand ((32, 1, 28, 28))
out = D(input)
print(out. size())
torch. Size([32, 1])
# hyperparameters
batch size = 128
Ir = 0.0002
z_dim = 62
num_epochs = 10 # 25
sample_num = 16 log_dir = './'
# initialize network
G = Generator().to(device)
D = Discriminator().to(device)
# optimizer
G_{optimizer} = optim. Adam(G. parameters(), Ir=Ir, betas=(0.5, 0.999))
D_optimizer = optim. Adam (D. parameters (), | Ir=Ir, | betas= (0.5, 0.999))
criterion = nn. BCELoss()
# load dataset
transform = transforms. Compose([
    transforms. ToTensor ()
dataset = datasets. MNIST('.../data', train=True, download=True, transform=transform)
data\_loader = DataLoader(dataset, \ batch\_size=batch\_size, \ shuffle=True, \ drop\_last=True)
def train(D, G, criterion, D_optimizer, G_optimizer, data_loader):
   # 訓練モー
   D. train()
   G. train()
   # 本物のラベルは1
   y_real = torch. ones(batch_size, 1)
    # 偽物のラベルは0
   y_fake = torch. zeros(batch_size, 1)
   y_real = y_real. to (device)
   y_fake = y_fake. to(device)
   D_running_loss = 0
    G_running_loss = 0
    for batch_idx, (real_images, _) in enumerate(tqdm(data_loader)):
       z = torch.rand((batch_size, z_dim))
       real_images, z = real_images. to(device), z. to(device)
       # Discriminatorの更新
       D_optimizer.zero_grad()
       # Discriminatorにとって本物画像の認識結果は1 (本物) に近いほどよい
       \# E[log(D(x))]
       D_{real} = D(real_{images})
       D real loss = criterion(D real, y real)
       # DiscriminatorにとってGeneratorが生成した偽物画像の認識結果は0(偽物)に近いほどよい
       \# E[log(1 - D(G(z)))]
       # fake_imagesを通じて勾配がGに伝わらないようにdetach()して止める
       fake_images = G(z)
       D_fake = D(fake_images.detach())
       D_fake_loss = criterion(D_fake, y_fake)
       #2つのlossの和を最小化する
       D_loss = D_real_loss + D_fake_loss
       D_loss.backward()
       D_optimizer.step()
       D_running_loss += D_loss.item()
       # Generatorの更新
       z = torch.rand((batch_size, z_dim))
       z = z. to(device)
       G_optimizer.zero_grad()
       # GeneratorにとってGeneratorが生成した画像の認識結果は1(本物)に近いほどよい
       # E[log(D(G(z)))
```

```
fake_images = G(z)
                        D_fake = D(fake_images)
                        G_loss = criterion(D_fake, y_real)
                        G loss. backward()
                        G_optimizer.step()
                        G_running_loss += G_loss.item()
                  D_running_loss /= len(data_loader)
G_running_loss /= len(data_loader)
                  return D_running_loss, G_running_loss
            def generate(epoch, G, log_dir='logs'):
                  G. eval()
                  os.makedirs(log_dir, exist_ok=True)
                  # 生成のもとになる乱数を生成
                  sample_z = torch. rand((64, z_dim))
                  sample_z = sample_z. to (device)
                  # Generatorでサンプル生成
                  with torch no_grad():
                        samples = G(sample_z). to ('cpu')
                  save_image(samples, os.path.join(log_dir, 'epoch_%03d.png' % (epoch)))
            history = {}
            history['D_loss'] = []
            history['G_loss'] = []
            for epoch in range(num_epochs):
                  D_loss, G_loss = train(D, G, criterion, D_optimizer, G_optimizer, data_loader)
                  print('epoch~\%d,~D\_loss:~\%.~4f~G\_loss:~\%.~4f'~\%~(epoch~+~1,~D\_loss,~G\_loss))
                  history['D_loss'].append(D_loss)
                  history['G_loss'].append(G_loss)
                  # 特定のエポックでGeneratorから画像を生成してモデルも保存
                  if epoch == 0 or epoch == 9 or epoch == 24:
generate(epoch + 1, G, log_dir)
                        torch. save(G. state_dict(), os. path. join(log_dir, 'G_\%03d. pth' % (epoch + 1))) torch. save(D. state_dict(), os. path. join(log_dir, 'D_\%03d. pth' % (epoch + 1)))
            # 学習履歴を保存
            with open(os.path.join(log_dir, 'history.pkl'), 'wb') as f:
                  pickle.dump(history, f)
           cuda
           torch.Size([32, 1, 28, 28])
torch.Size([32, 1])
           100% | 468/468 [00:13<00:00, 34.07it/s] | 4/468 [00:00<00:14, 32.97it/s] | epoch 2, D_loss: 1.0237 G_loss: 1.1171
           100% | 468/468 [00:13<00:00, 33.71it/s] | 4/468 [00:00<00:13, 33.16it/s] | epoch 3, D_loss: 1.0485 G_loss: 1.0855
           100% | 468/468 [00:13<00:00, 33.63it/s]
           4/468 [00:00<00:13, 33.36it/s]
epoch 4, D_loss: 1.0479 G_loss: 1.0947

100% 468 [00:013<00:00, 33.62it/s]
4/468 [00:00<00:14, 32.89it/s]
epoch 5, D_loss: 1.0379 G_loss: 1.1054
           100% 468/468 [00:13<00:00, 33.71it/s] 4/468 [00:00<00:13, 34.56it/s] epoch 6, D_loss: 1.0215 G_loss: 1.1376 100% 4/468 [00:00<00:13, 34.56it/s] 4/468 [00:00<00:13, 33.80it/s] 4/468 [00:00<00:13, 33.80it/s] epoch 7, D_loss: 0.9936 G_loss: 1.1692
           100% | 468/468 [00:13<00:00, 33.69it/s] | 4/468 [00:00<00:13, 33.27it/s] | epoch 8, D_loss: 0.9674 G_loss: 1.2082
           100% | 468/468 [00:13<00:00, 33.70it/s] | 4/468 [00:00<00:14, 33.02it/s] | epoch 9, D_loss: 0.9452 G_loss: 1.2532
           100%| 468/468 [00:13<00:00, 33.63it/s] epoch 10, D_loss: 0.9130 G_loss: 1.2955
In [8]:
            sample_z = torch. rand((64, z_dim))
            sample_z = sample_z. to(device)
            # Generatorでサンプル生成
            with torch no_grad():
                  samples = G(sample z), to ('cpu')
            samples = samples. view(64, 28, 28). detach(). cpu(). numpy()
```