Introduction to VLBI Time Delay (VTD) package.

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Abstract:

This document provides an outlines of the package of subroutines for computation of VLBI Time Delay and the Doppler frequency shift for observations of objects in the Solar system.

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1 General remarks

VTD is a set of subroutines for computation of VLBI Time Delay, Doppler frequency shift for observations of objects in the Solar system and its partial derivatives. It does not have a built-in database handler, so it is adaptive enough to be incorporated in existing software packages. The options of the model are specified in the control file. At the high level, there are only five calls:

VTD_INIT -- for initialization of the internal data structures;

VTD_CONF -- for parsing configuration file;

VTD_LOAD -- for loading input catalogues, planetary ephemerides, Earth orientation parameter series and other apriori parameters of

the model as well as the range of dates for which VLBI time

delay is to be computed.

VTD_METEO -- for loading meteorological information. NB: meteorological information is not needed, if the path delay through the

atmosphere is interpolated from the external time series

of slanted path delays.

VTD_DELAY -- for computation of VLBI time delay and its partial derivatives.

VTD_READ_NZO -- read coordinates of the near zone object

VTD_LOAD_NZO -- compute coefficients of the B-spline expansion of coordinates

of the near zone object and load them in the VTD object.

VTD_LT_ORB -- for computation of light time from the ground station to

the orbiting station

 $\label{thm:computation} \mbox{\sc VTD_REL_ORB} \ \mbox{\sc -- for computation of time dilation integral for a case when}$

one of the stations is on the orbit.

VTD_QUIT -- for deallocation dynamic memory used by VTD

Internal data structures are defined in one object called VTD which is passed from one routine to another. All routines have integer universal error handler parameter IUER. If the input value of IUER = -1, and the error is detected, the routine which detected the error prints the error message and returns non-zero output value of IUER. If the routine which has detected the error was called from the routine of upper level, the routine of the upper level prints its error message as well and returns non-zero value. Input value of IUER suppresses the error message. In the case of successful completion the output value of IUER = 0.

Inside VTD only SI units are allowed, except the date. Dates are specified in a pair of \mbox{MJD}, \mbox{TAI} .

VTD is written in Fortran90 was tested under Linux, HP-UX and Sun operating systems. VTD depends on petools library and optionally on cfitsio library.

2 Strategy of computation

Computation of time delay and/or Doppler frequency shift is highly parameterized. Apriori data, names of variants of the algorithms for astronomical reductions are specified in the control file.

After parsing control file VTD needs apriori files to be loaded in the slots of internal data structures. VTD_LOAD loads station description file, station coordinate file, station velocity file, site eccentricity file. During this step it transforms units. It computes for each station longitude, geocentric and geodetic latitude, matrix of transformation from crust-fixed terrestrial reference system to Up(vertical)-East-North topocentric reference system, local gravity acceleration and the height above the reference ellipsoid. Then it loads source coordinates catalogue. Then it load series of pole coordinates and UT1 angles and computes coefficients of cubic spline for interpolation. Then it reads the file with DE403 ephemerides and parses it. Then it computes time-independent intermediate variables for solid Earth tides computation. These parameters depends only on station coordinates. Then it parses files with position variation models. In the case of harmonic site position variations model it loads parameters of the models into slots of internal data structure. In the case if time series of position variations it computes interpolating polynomials for these variations.

Reading all these input files and making some computations which are time-independent is done only once. All remaining work is done by VTD_DELAY or $VTD_DOPPLER$.

VTD first checks whether the time epochs passed to as an argument is the same as in the previous call. If not, then it calls VTD_MOMENT which computes site-independent intermediate variables. It computes positions of the celestial bodies: the Moon and the Sun and all planets, except the Pluto using

DE403 ephemerides. It computes pole coordinates and UT1-TAI using interpolation polynomials created by VTD_LOAD. It computes site-independent sums over constituents of the tide-generating potential for solid Earth's tides displacements computations. Then VTD_MOMENT computes the matrix of transformation from the terrestrial reference system to the celestial reference system. It may use either the Newcomb-Andoyer formalism for precession, nutation and stellar angle (Greenwich true stellar time) or the Empirical Earth rotation model formalism. In addition to nutation expansion, it applies the small perturbation to the transformation matrix specified in the external file in for form of harmonic expansion with cross terms (t* sin (omega*t _phase), t* cos (omega*t _phase))

Then VTD_DELAY checks whether site-dependent parameters for this particular epoch have been computed for the first and the second station of the baseline. If not, then it computes for each site station-specific parameters. This includes computation of the contribution due to antenna axis offset, solid Earth tides, pole tide, position variation models specified in the external files, troposphere/axis offset coupling. It applies site eccentricity, transforms coordinates from the crust fixed terrestrial reference frame to the celestial reference frame. Then it computes elevation and azimuth of the observing source at each station and computes atmospheric zenith path delay and the mapping function. Using these quantities VTD_DELAY computes apriori path delay at each station.

After calculation of site- and time- specific intermediate variables VTD_DELAY computes geometric path delay and VTD_DOPPLER computes the Doppler frequency shift parameter. VTD_DELAY computes small troposphere-geometric coupling contribution. VTD_DELAY computes (not implemented on 2007.01.01) the contribution to delay due to source structure and ionosphere.

3 Interface to the subroutines

The program which calls VTD should have definition of the object VTD which are kept in the include block vtd.i , i.e. should have a statement

INCLUDE 'vtd.i'

3.1 VTD_INIT

SUBROUTINE VTD_INIT (VTD, IUER)

!	*	Routine VTD_INIT initializes object VTD. It should be called	*
!	*	before first used of package VLBI Time Delay (VTD).	*
!	*		*
!	* _	Modified parameters:	*
!	*	·	*
!	*	VTD (RECORD) Object which keeps configuration and data	*
!	*	related to VLBI Theoretical Delay (VTD)	*
!	*	package.	*
!	*	<pre>IUER (INTEGER*4, OPT) Universal error handler.</pre>	*
!	*	<pre>Input: IUER=0 no error message will be</pre>	*
!	*	printed even in the case	*
!	*	of error.	*
!	*	IUER=-1,-2,-3 in the case of error	*
!	*	the message will be put on	*
!	*	stdout.	*

3.2 VTD_CONF

```
Routine VTD_CONF parses configuration file of the package for
      computation of VLBI Time Delay (VTD) and stores results of parsing
! *
      in the internal fields of the object VTD.
! *
! *
                           ___ Input parameters: ___
!
   CONFIG_FILE ( CHARACTER ) -- Full path name of the configuration
! *
!
                              Modified parameters: ___
! *
! *
                        ) -- Object which keeps configuration and data
        VTD ( RECORD
! *
                             related to VLBI Theoretical Delay (VTD)
! *
                             package.
       IUER ( INTEGER*4 ) -- Universal error handler argument.
                             Input: switch IUER=0 -- no error messages
! *
                                     will be generated even in the case
                                     of error. IUER=-1 -- in the case of
                                     error the message will be put on
                                     stdout.
                             Output: 0 in the case of successful
                                     completion and non-zero in the
                                     case of error.
extern void vtd_conf (
               char * vtd_config_file,
               char * vtd,
               int * iuer,
                      sizeof_vtd_config_file
               int
            ) ;
```

3.3 VTD_LOAD

```
! * Routine VTD_LOAD loads lists of stations participated in the
! * observing session, list of observed sources, time of the first and *
! * the last observation. It puts station and sources list in the
! * internal field of VTD. VTD reads the catalogue specified in the
! * control file, reads the Earth orientation parameters file, reads
! * planetary ephemerides, computes time-independent quantities needed *
! * for solid Earth tide computations, loads position variations
! * modes, computes interpolating coefficients of site displacements
```

```
if needed. VTD_LOAD should be called before computation of time
      delay for the first observation.
! *
! *
                           _ Input parameters: _
! *
! *
        L\_STA ( INTEGER*4 ) -- The number of stations participating in
! *
                               the experiment.
! *
        C_STA ( CHARACTER ) -- List of statation names participating in
! *
                               the experiment. Dimenstion: L_STA.
        L_SOU ( INTEGER*4 ) -- The number of observed sources.
! *
! *
        C_SOU ( CHARACTER ) -- List of source names participating in
! *
                               the experiment. Dimenstion: L_SOU.
! *
      MJD\_BEG ( INTEGER*4 ) -- Modified Julian data on the midnight of
! *
                               the first observation. Units: days.
! *
                          ) -- Moment of time of the first observation.
      TAI_BEG ( REAL*8
                               Units: sec.
! *
      MJD_END ( INTEGER*4 ) -- Modified Julian data on the midnight of
! *
                               the last observation. Units: days.
! *
      TAI_END ( REAL*8
                          ) -- Moment of time of the last observation.
! *
                               Units: sec.
 *
!
!
                            _ Modified parameters: ___
!
! *
        VTD ( RECORD
                        ) -- Object which keeps configuration and data
! *
                             related to VLBI Theoretical Delay (VTD)
! *
                             package.
       IUER ( INTEGER*4, OPT ) -- Universal error handler.
                         Input: IUER=0 -- no error message will be
                                          printed even in the case
                                          of error.
                                IUER=-1,-2,-3 -- in the case of error
                                          the message will be put on
                                          stdout.
                                IUER=-3 -- in the case of error after
                                            printing the error message
                                            the program will terminate.
                          Output:
                                if input value of IUER =-2,-3 -- IUER
! *
                                           is not modified.
! *
                                otherwise, the output value of IUER is 0 *
! *
                                in the case of successful and
! *
                                positive non-zero in the vase of errors. *
extern void vtd_load (
                     * vtd,
               char
                      * 1_sta,
               int
                     * c_sta,
               char
                      * 1_sou,
               int
               char
                      * c_sou,
                      * mjd_beg,
               int
               double * tai_beg,
               int
                     * mjd_end,
               double * tai_end,
                     * iuer,
               int
                        sizeof_c_sta_element,
               int
               int
                        sizeof_c_sou_element
            ) ;
```

```
Routine VTD_METEO_IN inserts atmospheric pressure and air
      temperature for station STANAM in the object VTD.
! *
! *
                            _ Input parameters: _
! *
! *
      STANAM ( CHARACTER ) -- Name of the station of the baseline.
                              The station should be in the input
                              catalogue defined in the control file.
                         ) -- Atmospheric pressure at the station in
! * ATM_PRES ( REAL*8
! *
                              Pascals.
! * AIR_TEMP ( REAL*8
                       ) -- Air temperature at the station in Kelvins.
! * AIR_TEMP_EFF ( REAL*8 ) -- Effective air temperature for taking
                                into account thermal expansion of the
! *
                                antenna (in Kelvins). It is up to the
                                analyst to descide which effective
                                temperature is the best. It was found
                                that the station air temperature lagged
1
                                2-3 hours gives the best agreement with
                                the in situ measuremenets.
1
1
                              Modified parameters: __
!
!
! *
        VTD ( RECORD
                        ) -- Object which keeps configuration and data
! *
                             related to VLBI Theoretical Delay (VTD)
! *
                             package.
! *
       IUER ( INTEGER*4, OPT ) -- Universal error handler.
! *
                         Input: IUER=0 -- no error message will be
                                          printed even in the case
                                          of error.
                                IUER=-1,-2,-3 -- in the case of error
                                          the message will be put on
                                          stdout.
                                IUER=-3 -- in the case of error after
                                           printing the error message
                                           the program will terminate.
                          Output:
                                if input value of IUER =-2,-3 -- IUER
                                           is not modified.
! *
                                otherwise, the output value of IUER is 0 *
! *
                                in the case of successful and
! *
                                positive non-zero in the vase of errors. *
extern void vtd_meteo_in (
               char * vtd,
               char * sta_nam,
               double * pres,
               double * temp,
               double * humid,
               int
                      * iuer,
               int
                        sizeof_sta_nam
            ) ;
```

3.5 VTD_DELAY

```
! * Routine VTD_DELAY is the main routine of the package for
! * computation of the VLBI Time Delay (VTD). It computes group delay
! * and phase delay as well as partial derivatives of group delay and
! * delay rate with respect to parameters of the model at the
! * specified moment of time, for the specified pair of stations and
! * for the specified source using the model specified from the
```

control file previously loaded into the data structure VTD. It is assumed that routines VTD_INIT, VTD_CONF and VTD_LOAD were called before the call of VTD_DELAY.

! * ! * ! * ! *

! *

! *

! *

! *

1

VLBI Time delay is defined as the difference of two intervals of proper time: 1) the interval of proper time of station #2 between events: coming the wave front to the reference point on the moving axis and clock synchronization; 2) the interval of proper time of station #1 between events: coming the wave front to the reference point on the moving axis and clock synchronization. The time delay is referred to the moment of coming the wave front to the reference point on the moving axis of the first antenna at time measured by the time scale TAI. The reference point of the station $\dot{}$ for which modeling is done is defined as the point on the moving axes which has the minimal distance to the fixed axis. In the case if axes intersect, this is the point of intersection.

! * ! * ! *

! *

Precision of computation of VLBI time delay is deemed to be no worse than 1.D-12 seconds, precision of computation of delay rate is no worse than 1.D-15 . Accuracy of computation of time delay is limited by accuracy of a priori information. It can be as good as 1.0D-10 .

! !

!

! *

1 *

! *

! *

1

!

!

1

1

1

1

___ Input parameters: __

SOU_NAM (CHARACTER) -- Name of the source. The source should be in the input catalogue defined in the control file.

* STA1_NAM (CHARACTER) -- Name of the first station of the baseline. The station should be in the input catalogue defined in the control file.

! * STA2_NAM (CHARACTER) -- Name of the second station of the baseline.* The station should be in the input catalogue defined in the control file.

MJD (INTEGER*4) -- Modified Julian date of the midnight of the observation.

TAI (INTEGER*4) -- Time of the observations in seconds at time scale TAI elapsed from the midnight.

OBS_TYP (VTD__OBS_TYPE) -- The object with information about observation type, polarization and frequency setup of the experiment. It is used for

- 1) computing source structure contribution;
- computing ionospheric contribution;
- 3) computing contribution to phase caused by delay parallactic angle rotation.

Fields of VTD__OBS_TYPE:

! * ! * ! * ! *

1

1

۱ *

! *

INTEGER*4 %L_FRQ ! The number of frequency channels within the

CHARACTER*2 %PLRZ ! Polarization at each band: RR, LL, RL or LR

'RR' -- both antennas observed right circular polarization;

'LL' -- both antennas observed right circular polarization;

'LR' -- Reference antenna observed left circular polarization and another antenna observed right circular polarization.

'RL' -- Reference antenna observed left circular polarization and another

! *

! *

```
antenna observed right circular
                                     polarization.
                             'NO' -- Contribution due to parallactic
! *
                                     angle correction is not computed.
! *
                  %STATUS ! Status: VTD__UNDF, VTD__BND, VTD__CHN
       TNTFGFR*4
                            VTD__UNDF -- ! Frequency setup is undefined.
 *
                                           This indicates that no
                                           information about frequencies *
1
                                           and polarization is available.*
1
                            VTD__BND -- ! Frequency channel setup is
                                           undefined, but the reference
                                           frequency, effective
1
                                           ionospheric frequencies and
                                           polarization are known.
                            VTD__CHN -- ! Frequency channel setup is
                                           known. Effective ionospheric
                                           frequencies are computed on
! *
                                           the fly.
! *
       TNTFGFR*4
                   %N_BND ! Number of either bands or channel depending
! *
                            on the status.
! *
       INTEGER*4
                   %DELAY_TYPE ! Delay type. Delay type depends on
! *
                                 band: low or high and on observable for
! *
                                 each band: phase delay, multi-band
! *
                                 delay, narrow-band delay. The list of
! *
                                 supported combination is defined in
! *
                                 vtd.i
       CHARACTER
                   %EXP_NAME
                                ! Experiment name. Experiment name may
! *
                                ! be used for gaining access to external '
! *
                                ! calibration files.
! *
       CHARACTER
                   %SCAN_NAME
                                ! Scan name. Scan name may be used for
! *
                                ! gaining access to external calibration
! *
                                ! files.
! *
       REAL*8
                   %FRQ ! Array of cyclic frequencies. Dimension %L_FRQ.
! *
       REAL*8
                   %WEI ! Array of channel weights. Dimension %L_FRQ.
! *
       REAL*8
                   %FRQ_REF ! Reference frequency per band.
! *
       REAL*8
                   %FRQ_ION_EFF ! Effective cyclic ionosphere
! *
                                ! frequency for this type of delay
! *
                                ! contribution. Units: Herz.
! *
! *
       If no information about frequencies and polarization is
! *
       available, set OBS_TYP%STATUS to VTD__UNDF. Then contents
! *
       of OBS_TYP will be ignored and contribution to delay caused
! *
       by the ionosphere, source structure and parallactic anlge
! *
       rotation will be set to zero.
! *
! *
                            __ Output parameters: __
! *
! *
                         ) -- VLBI time delay. Units: seconds.
       DELAY ( REAL*8
                         ) -- VLBI delay rate. Units: dimensionless.
! *
        RATE ( REAL*8
!
    DER_DEL ( REAL*8
                         ) -- Vector of partial derivatives of group
! *
                              delay with respect to parameters of the
! *
                              model or some important intermediate
!
                              quantities. Dimension: DER__NDER.
               Symbolic names of the indexes of the partial derivatives
1
               in the array DER_DEL are defined in vtd.i .
1
 *
1
               Their meaning:
1
 *
               VTD DER E1
                              -- Earth rotation Euler angle 1
! *
                              -- Earth rotation Euler angle 2
               VTD__DER_E2
               VTD__DER_E3
                              -- Earth rotation Euler angle 3
! *
               VTD__DER_ST1X -- Station 1, X coordinate
! *
               VTD__DER_ST1Y -- Station 1, Y coordinate
! *
               VTD__DER_ST1Z -- Station 1, Z coordinate
```

```
VTD__DER_ST2X -- Station 2, X coordinate
               VTD__DER_ST2Y -- Station 2, Y coordinate
               VTD__DER_ST2Z -- Station 2, Z coordinate
! *
               VTD__DER_RA
                            -- Right ascension of the far-zone source
! *
                             -- Declination of the far-zone source
               VTD__DER_DL
               VTD__DER_AT1
                             -- Station 1, atmospheric path delay
               VTD__DER_AT2
                             -- Station 2, atmospheric path delay
               VTD__DER_ATN1 -- Station 1, atmospheric north tilt
               VTD__DER_ATE1
                             -- Station 1, atmospheric east tilt
1
               VTD__DER_ATN2
                             -- Station 2, atmospheric north tilt
               VTD__DER_ATE2
                             -- Station 2, atmospheric east tilt
! *
               VTD__DER_POS1
                             -- Position of near zone object, X coord.
               VTD__DER_POS2
                             -- Position of near zone object, Y coord.
!
               VTD__DER_POS3
                             -- Position of near zone object, Z coord.
                             -- Velocity of near zone object, X coord.
               VTD__DER_VEL1
               VTD__DER_VEL2 -- Velocity of near zone object, Y coord.
! *
               VTD__DER_VEL3 -- Velocity of near zone object, Z coord.
! *
               VTD__DER_AXF1 -- Antenna axis offset length 1st antenna. *
! *
               VTD__DER_AXF2 -- Antenna axis offset length 2nd antenna. *
! *
1
               VTD__ELEV1
                              -- Elevation angle of the 1st antenna
               VTD__ELEV2
                              -- Elevation angle of the 2nd antenna
               VTD__AZIM1
                              -- Aximuth angle of the 1st antenna
1
               VTD__AZIM2
                              -- Aximuth angle of the 2nd antenna
1
               VTD__TROP1
                              -- Slanted troposphere path at the
                                 1st antenna.
               VTD__TROP2
                              -- Slanted troposphere path at the
                                 2nd antenna.
               VTD__ION01
                              -- Slanted ionosphere path at the
                                 1st antenna.
               VTD__IONO2
                              -- Slanted ionosphere path at the
                                 2nd antenna.
               VTD__TRP_HZD1 -- Hydrostatic troposphere path delay in
! *
                                 zentith at the 1st antenna.
1
               VTD__TRP_HZD2 -- Hydrostatic troposphere path delay in
1
                                 zentith at the 2nd antenna.
               VTD__TRP_WZD1 -- Non-hydrostatic troposphere path delay
                                 in zentith at the 1st antenna.
! *
               VTD__TRP_WZD2 -- Non-hydrostatic troposphere path delay
1
                                 in zentith at the 1nd antenna.
               VTD__PARAL1
                              -- Parallactic agle at the 1st antenna
               VTD__PARAL2
                              -- Parallactic agle at the 2nd antenna
1
                              -- Contribution of the source structure
               VTD__STRUC
1
! *
                                 to time delay.
     DER_RAT ( REAL*8
                         ) -- Vector of partial derivatives of phase
! *
                              delay rate with respect to parameters of
! *
                              the model. Dimension: DER__NDER.
! *
1
                              Modified parameters: __
!
                        ) -- Object which keeps configuration and data
        VTD ( RECORD
!
                             related to VLBI Theoretical Delay (VTD)
! *
                             package.
       IUER ( INTEGER*4, OPT ) -- Universal error handler.
1
! *
                         Input: IUER=0 -- no error message will be
! *
                                          printed even in the case
 *
                                          of error.
! *
                                IUER=-1,-2,-3 -- in the case of error
                                          the message will be put on
! *
! *
                                IUER=-3 -- in the case of error after
! *
                                           printing the error message
```

```
the program will terminate.
                          Output:
                                if input value of IUER =-2,-3 -- IUER
                                           is not modified.
                                otherwise, the output value of IUER is 0 *
                                in the case of successful and
                                positive non-zero in the vase of errors.
extern void vtd_delay (
                             * sou_nam,
               char
                             * sta_nam1,
               char
                             * sta_nam2,
               char
                             * mjd_obs,
               int
                             * tai_obs,
               double
               vtd__obs_type * obs_typ,
               char
                             * vtd,
                             * tau,
               double
               double
                             * rate_ph,
               double
                             * der_del,
               double
                             * der_rat,
               int
                             * iuer,
               int
                               sizeof_sou_nam,
               int
                               sizeof_sta_nam1,
               int
                               sizeof_sta_nam2
              ) ;
```

3.6 VTD_DOPPLER

```
! *
! *
      Routine VTD_DOPPLER is the main routine of the package VTD for
! *
     computation of the Doppler frequency shift parameter. It computes
! *
     also partial derivatives of the Doppler frequency shift parameter
! *
     with respect to parameters of the model at the specified moment of *
! *
     time, for the specified stations and for the specified near zone
! *
     source using the model specified from the control file previously
     loaded into the data structure VTD. It is assumed that routines
     VTD_INIT, VTD_CONF and VTD_LOAD were called before the call
! *
     of VTD_DO.
! *
! *
     The Doppler frequency shift parameter is defined as a ratio of
! *
      the observed frequency to the emitted frequency minus 1.
! *
! *
     Precision of computation of VLBI time delay is deemed to be no
! *
     worse than 1.D-11 .
! *
! *
     CAVEAT: as of 2007.01.11, computation of partial derivatives is
! *
              not implemented.
! *
! *
! *
                            __ Input parameters: _
    SOU_NAM ( CHARACTER ) -- Name of the source. The source should
! *
                             be in the input catalogue defined in the
! *
                              control file.
! *
    STA_NAM ( CHARACTER ) -- Name of the station. The station name
! *
                              should be in the input catalogue defined
! *
                              in the control file.
        MJD ( INTEGER*4 ) -- Modified Julian date of the midnight of
```

! **********************

```
the observation.
! *
         TAI ( INTEGER*4 ) -- Time of the observations in seconds at
! *
                              time scale TAI elapsed from the midnight.
! *
! *
                              Output parameters: _
!
1
       D_FRQ ( REAL*8
                         ) -- The Doppler frequency shift parameter
                              defined as a ratio of the observed
! *
                              frequency to the emitted frequency minus 1.
!
    DER_DEL ( REAL*8
                         ) -- Vector of partial derivatives of the
                              Doppler frequency ratio with respect
! *
                              to parameters of the model. Dimension:
                              DER__NDER.
!
               Symbolic names of the indexes of the partial derivatives
               in the array DER_DEL are defined in vtd.i .
               Their meaning:
               VTD__DER_E1
                              -- Earth rotation Euler angle 1
! *
                              -- Earth rotation Euler angle 2
               VTD__DER_E2
! *
               VTD__DER_E3
                              -- Earth rotation Euler angle 3
               VTD__DER_ST1X -- Station, X coordinate
               VTD__DER_ST1Y -- Station, Y coordinate
               VTD__DER_ST1Z -- Station, Z coordinate
                              -- Right ascension of the far-zone source
               VTD__DER_RA
               VTD__DER_DL
                              -- Declination of the far-zone source
               VTD__DER_POS1 -- Position of near zone object, X coord.
               VTD__DER_POS2 -- Position of near zone object, Y coord.
               VTD__DER_POS3 -- Position of near zone object, Z coord.
               VTD__DER_VEL1 -- Velocity of near zone object, X coord.
               VTD__DER_VEL2 -- Velocity of near zone object, Y coord.
               VTD__DER_VEL3 -- Velocity of near zone object, Z coord.
    DER_FRQ ( REAL*8
                         ) -- Vector of partial derivatives of phase
! *
                              delay rate with respect to parameters of
!
                              the model. Dimension: DER__NDER.
!
                              Modified parameters: _
! *
        VTD ( RECORD
                        ) -- Object which keeps configuration and data
! *
                             related to VLBI Theoretical Delay (VTD)
! *
                             package.
! *
       IUER ( INTEGER*4, OPT ) -- Universal error handler.
                         Input: IUER=0 -- no error message will be
! *
                                          printed even in the case
                                          of error.
                                IUER=-1,-2,-3 -- in the case of error
                                          the message will be put on
                                          stdout.
1
                                IUER=-3 -- in the case of error after
1
                                           printing the error message
                                           the program will terminate.
                          Output:
                                if input value of IUER =-2,-3 -- IUER
                                           is not modified.
                                otherwise, the output value of IUER is 0
                                in the case of successful and
                                positive non-zero in the vase of errors. *
```

```
Routine VTD_READ_NZO reads the input file FILNZO with
                   coordinates of the near zone object, parses it and return arrays
                  of coordinates of the near zone object and time tags associated % \left( 1\right) =\left( 1\right) \left( 
! *
                  with these coordinates.
! *
! *
                                                                                     _ Input parameters: _
! *
                  FILNZO ( CHARACTER ) -- Name of the file with coordinates of the
                                                                                              the near zone objects. The file should
                                                                                              comply specifications of the
į *
                                                                                               "Apriori positions of a near zone object".
! * NZO_NAME ( CHARACTER ) -- Name of the near zone object.
! * OBJ_TYPE ( CHARACTER ) -- Type of the near zone object.
                                                                                               Support types:
                                                                                               VTD__MG -- Extra-galactic object
                                                                                              VTD__GAL -- Galactic object
! *
                                                                                              VTD__ES -- Near zone object near Earth
                     \mbox{M\_ARR} ( \mbox{INTEGER*4} ) -- The maximal points in the output arrays
! *
                                                                                              of near zone objects.
! *
1
                                                                                    __ Output parameters: __
                      L_ARR ( INTEGER*4 ) -- The number of points in the array of
                                                                                              the near zone object positions.
              MJD_ARR ( INTEGER*4 ) -- Array of MJD dates of position arrays of
                                                                                              near zone objects. Dimension: L_ARR.
               TAI\_ARR ( INTEGER*4 ) -- Array of TAU time tags of dates of
                                                                                              position arrays of near zone objects.
                                                                                              Dimension: L_ARR.
               POS_ARR ( INTEGER*4 ) -- Array of positions of the near zone
                                                                                              object. Units: meters. Dimension: 3,L_ARR.
              VEL_ARR ( INTEGER*4 ) -- Array of velocities of the near zone
                                                                                              object. Units: m/s. Dimension: 3,L_ARR.
! * CENTER_NAME ( CHARACTER ) -- Name of the center of the coordinate
! *
                                                                                                        system. Supported names:
                                                                                                         "EARTH BARYCENTER"
                                                                                                         "SOLAR SYSTEM BARICENTER"
                      REF_NAME ( CHARACTER ) -- Reference system name. Supported names:
                                                                                                        "EME2000"
! * TIM_CODE ( INTEGER*4 ) -- Time code of time tags. One of
                                                                                              VTD__TDB, VTD__TDT .
! * COO_CODE ( INTEGER*4 ) -- Code of the metric of the coordinate
                                                                                               system. Supported codes:
                                                                                               VTD__BRS, VTD__IERS1992, VTD__GRS .
                                                                                     __ Modified parameters: __
              IUER ( INTEGER*4, OPT ) -- Universal error handler.
                                                                                               Input: switch IUER=0 -- no error messages
! *
                                                                                                                     will be generated even in the case
                                                                                                                     of error. IUER=-1 -- in the case of
                                                                                                                     error the message will be put on
                                                                                                                     stdout.
                                                                                              Output: 0 in the case of successful
                                                                                                                        completion and non-zero in the
! *
                                                                                                                        case of error.
! * ### 02-JAN-2006 VTD_READ_NZO v2.0 (c) L. Petrov 11-JUN-2012 ###
```

```
Routine VTD_LOAD_NZO computes coefficients of the B-spline
      expansion of coordinates of the near zone object and loads them
      in the appropriate fields of the VTD object. Coordinates of the
! *
     near-zone objects are supposed to be read by VTD_READ_NZO. These
! *
      coordinates and time tags are passed to VTD_LOAD_NZO.
! *
! *
     The coefficients of the expansion will be used by other routines
      of the VTD library for computation of position, velocity and
! *
      acceleration of the near zone object for calculation of VLBI
! *
     path delay and/or Doppler frequency shift.
! *
! *
                           __ Input parameters: __
!
! * NZO_NAME ( CHARACTER ) -- Name of the near zone object.
 * OBJ_TYPE ( CHARACTER ) -- Type of the near zone object.
                              Support types:
! *
                              VTD__MG -- Extra-galactic object.
1
                              VTD__GAL -- Galactic object.
! *
                              VTD__SS -- Solar system object.
! *
                              VTD__ES -- Near Earth object.
 * OBJ_USED ( CHARACTER ) -- Type of the near zone object.
                              VTD__EM -- Observed emitter.
                              VTD__OR -- Observing orbiting antenna.
!
 * TIM_CODE ( INTEGER*4 ) -- Time code of time tags. One of
! *
                              VTD__TDB, VTD__TDT, VTD__UTC, VTD__TAI.
! *
       L_ARR ( INTEGER*4 ) -- The number of points in the array of
1
                              the near zone object positions.
!
    MJD_ARR ( INTEGER*4 ) -- Array of MJD dates of position arrays of
                              near zone objects. Dimension: L_ARR.
     TAI_ARR ( INTEGER*4 ) -- Array of TAU time tags of dates of
! *
                              position arrays of near zone objects.
! *
                              Dimension: L_ARR.
! *
    POS_ARR ( INTEGER*4 ) -- Array of positions of the near zone
! *
                              object. Units: meters. Dimension: 3,L_ARR.
! *
       L_NOD ( INTEGER*4 ) -- The number of nodes for the B-spline basis
1
                              of the expansion.
       L_DEG ( INTEGER*4 ) -- The degree of the B-spline basis.
!
! *
                           __ Modified parameters: ___
1
          VTD ( RECORD
                          ) -- Object which keeps configuration and data
1
! *
                               related to VLBI Theoretical Delay (VTD)
1
                               package.
     IUER ( INTEGER*4, OPT ) -- Universal error handler.
                              Input: switch IUER=0 -- no error messages
! *
                                     will be generated even in the case
! *
                                     of error. IUER=-1 -- in the case of
! *
                                     error the message will be put on
! *
                                     stdout.
1
                              Output: 0 in the case of successful
                                      completion and non-zero in the
! *
                                      case of error.
    ### 01-JAN-2006 VTD_LOAD_NZO v2.0 (c) L. Petrov 13-JUN-2012 ###
```

3.9 VTD_LT_ORB

	catal	ogı	ue of gro	und	sta	ations has already been loaded.
-						_ Input parameters:
	VTD	(RECORD)		Object which keeps configuration and data related to VLBI Theoretical Delay (VTD)
	_	-		-		package. Name of the ground station. Name of the orbiting station.
						The station should be in the input catalogue defined in the control file.
	MJD	(INTEGER*	4)		Modified Julian date of the midnight of the observation.
	TAI	(INTEGER*	4)		Time of the observations in seconds at time scale TAI elapsed from the midnight.
						Output parameters:
	LT	(REAL*8)		from the ground station to the orbiting
						station.
						Modified parameters:
	IUER	(INTEGER*) Universal error handler.
				_	rnbı	ut: IUER=0 no error message will be printed even in the case
						of error.
						IUER=-1,-2,-3 in the case of error
						the message will be put on stdout.
						IUER=-3 in the case of error after
						printing the error message
						the program will terminate.
					0u1	tput:
						if input value of IUER =-2,-3 IUER is not modified.
						otherwise, the output value of IUER is
						<pre>in the case of successful and positive non-zero in the vase of errors</pre>
	### 11	11	IN 2012	\/T!	٠	ODP v1 0 (c) Dotroy 14 OCT 2012 444
	### 14) ر -	אר- אור	VIL	∟	Γ_ORB v1.0 (c) L. Petrov 14-0CT-2012 ###

3.10 VTD_REL_ORB

```
Routine VTD_REL_ORB computes the time dilation for a VLBI station *
     which is on the orbit. The dilation is computed for interval
     of geocentric time coordinates MJD_BEG/TCG_BEG, MJD_END/TCG_END.
     It does this computation by evaluating the integral using
! *
     coefficients of spline interpolation which were computed by
! *
     routine VTD_LOAD_NZO.
! *
! *
                          __ Input parameters: __
        VTD ( VTD__TYPE ) -- Object which keeps configuration and data
                             related to VLBI Theoretical Delay (VTD)
                             package.
! * STA_ORB ( CHARACTER ) -- Name of the orbiting station.
! *
                             The station should be in the input
! *
                             catalogue defined in the control file.
! * MJD_BEG ( INTEGER*4 ) -- Modified Julian date of the midnight of
```

```
the beginning of the interval.
! * TCG_BEG ( REAL*8
                        ) -- Geocentric time coordinate for beginning of *
                             the interval.
! * MJD_END ( INTEGER*4 ) -- Modified Julian date of the midnight of
                             the end of the interval.
! *
! * TCG_END ( REAL*8
                        ) -- Geocentric time coordinate for end of
                             the interval.
! *
! *
! *
                              Modified parameters: ___
! *
! *
       IUER ( INTEGER*4, OPT ) -- Universal error handler.
! *
                         Input: IUER=0 -- no error message will be
! *
                                          printed even in the case
                                          of error.
                                IUER=-1,-2,-3 -- in the case of error
                                          the message will be put on
                                          stdout.
                                IUER=-3 -- in the case of error after
                                            printing the error message
                                           the program will terminate.
                          Output:
                                if input value of IUER =-2,-3 -- IUER
                                            is not modified.
                                otherwise, the output value of IUER is 0 *
                                in the case of successful and
                                positive non-zero in the vase of errors. *
                                                3.11 VTD_QUIT
! *
      Routine VTD_QUIT releases memory allocated by internal data
      structures of package VLBI Time Delay (VTD).
! *
! *
                           __ Modified parameters: ___
! *
!
          VTD ( RECORD
                          ) -- Object which keeps configuration and data *
! *
                               related to VLBI Theoretical Delay (VTD)
                               package.
     IUER ( INTEGER*4, OPT ) -- Universal error handler.
                              Input: switch IUER=0 -- no error messages
                                     will be generated even in the case
                                     of error. IUER=-1 -- in the case of ^{\star}
                                     error the message will be put on
                                     stdout.
                              Output: 0 in the case of successful
                                      completion and non-zero in the
                                      case of error.
```

3.12 VTD_GET_VERSION

VTD_QUIT v1.6 (c) L. Petrov 29-APR-2008 ### *

```
! * Returns the VTD label with version.
```

char * vtd,
int * iuer

14-APR-2006

) ;

extern void vtd_quit (

Questions and comments about this guide should be directed to:

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