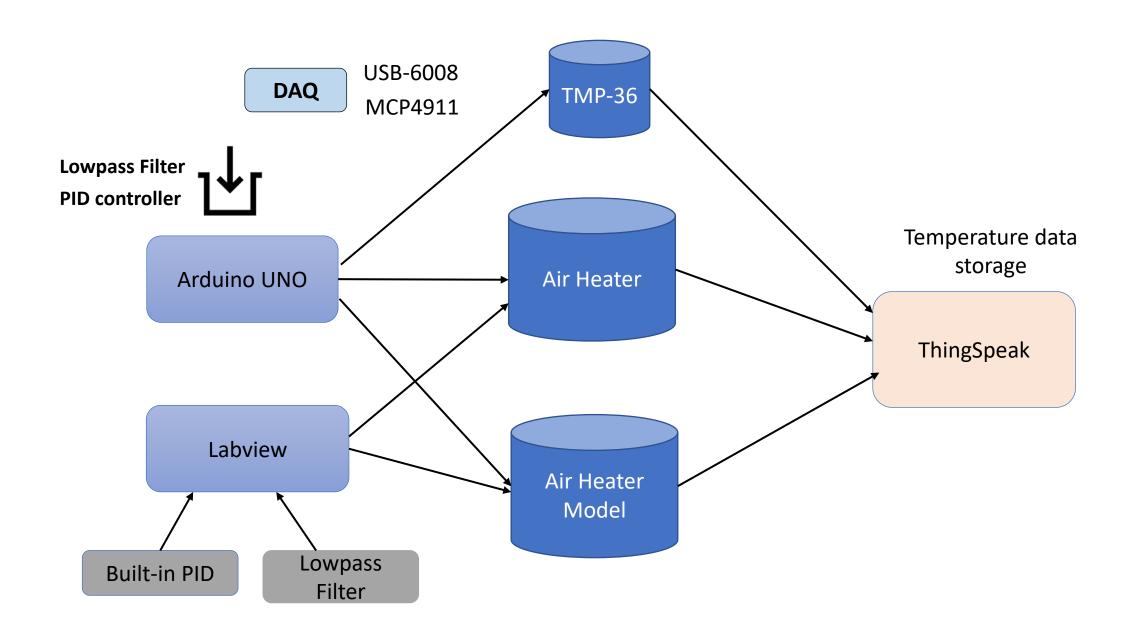
#### LAB 1

## Internet of Things and Arduino

Shamim Al Mamun

Industrial IT and Automation



# Create a PI controller using the Arduino Software (IDE)

#### Discrete PI controller Equation

$$u_k = u_{k-1} + K_p(e_k - e_{k-1}) + \frac{K_p}{T_i}T_Se_k$$
  
Where  $e_k = r_k - y_k$ 



Simulation\_AirHeater\_MatModel\_PiControl\_Filter

```
void loop()
{
    PiController();
    AirHeater();
    //LowPassFilter();
    SerialPlotter();
    k=k+1;
    delay(wait);
}
void PiController()
{
    u_prev = u;
    e = r - Tout;
    u = u_prev + Kp*(e - e_prev) + (Kp/Ti)*Ts*e;
    if (u < 0)
        u = 0;
    if (u > 5)
        u = 5;
    }
}
```

# Create Air Heater Model using the Arduino Software (IDE)

#### Discrete Air Heater Model Equation

$$T_{out}(k+1) = T_{out}(k) + \frac{T_s}{\theta_t} \{ -T_{out}(k) + [K_h u(k) + T_{env}] \}$$

Considering, Time delay =0

Simulation\_AirHeater\_MatModel\_PiControl\_Filter | Arduino 1.8.19

File Edit Sketch Tools Help



#### Simulation\_AirHeater\_MatModel\_PiControl\_Filter §

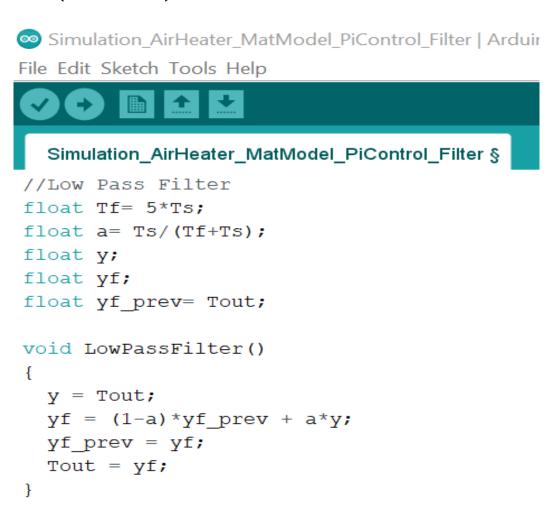
```
// Air Heater Model
float Kh = 3.5;
float Theta_t = 22;
float Theta_d = 2;
float Tenv = 21.5;
float Tout = Tenv;
float Tout_prev = Tenv;

void AirHeater()
{
    Tout_prev = Tout;
    Tout = Tout_prev + (Ts/Theta_t) * (-Tout_prev + Kh*u + Tenv);
}
```

# Create Lowpass Filter using the Arduino Software (IDE)

The discrete version of the Lowpass Filter:

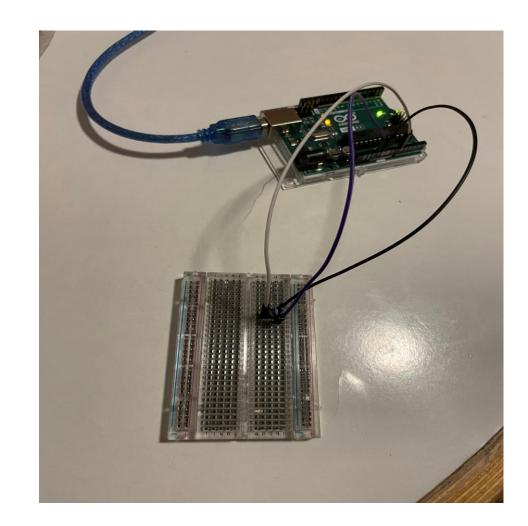
$$y_f(k) = (1 - a)y_f(k - 1) + ay$$



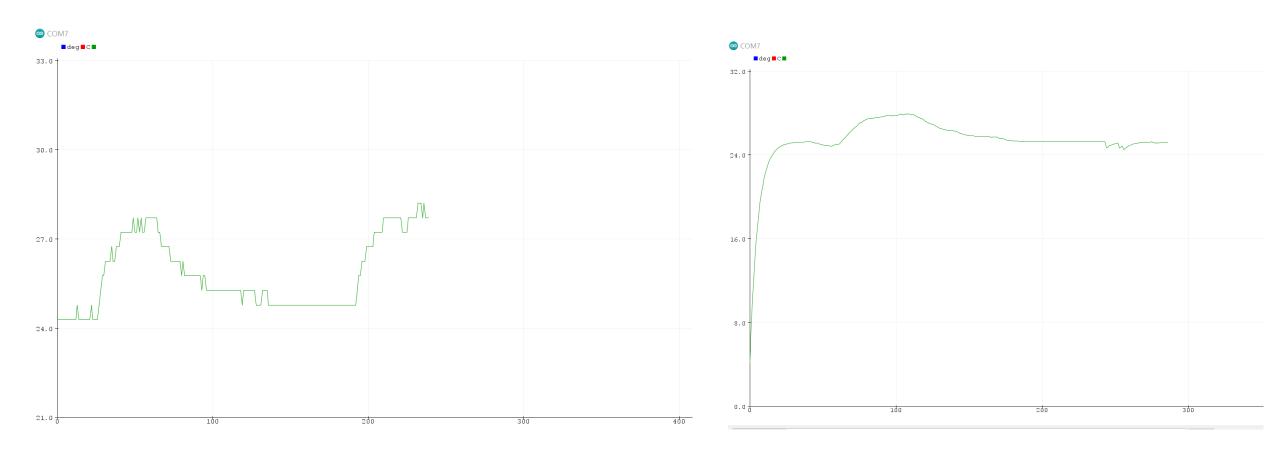
# Test Lowpass Filter using a TMP36 Temperature Sensor

Temperature\_data\_from\_TMP36\_sensor\_with\_filter | Arduino 1.8.19
File Edit Sketch Tools Help

```
Temperature_data_from_TMP36_sensor_with_filter §
Serial.begin (9600);
void loop()
Temperature TMP36();
LowPassFilter();
Serial.print(" deg C: ");
Serial.println(degreesC);
delay(1000);
void LowPassFilter()
  y = degreesC;
 yf = (1-a)*yf prev + a*y;
 yf prev = yf;
  degreesC = yf;
void Temperature TMP36()
adcValue = analogRead(temperaturePin);
voltage = (adcValue*5)/1023;
degreesC = 100*voltage - 50;
```



## Comparison of TMP36 sensor data



Temperature data without Lowpass filter

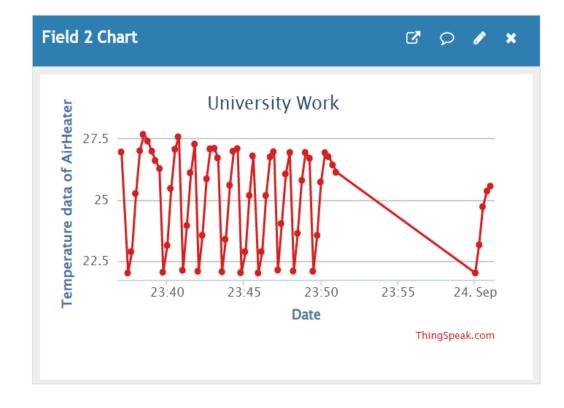
Temperature data with Lowpass filter

### Air Heater Model Data



## Air Heater Model Data stored in ThingSpeak

```
Thingspeak_write_tempData_Model
                                secrets.h
 Serial.print("t=:");
 Serial.print(Ts*k);
 Serial.print(", u=");
 Serial.print(u);
 Serial.print(", Tout=");
 Serial.print(Tout);
void ThingSpeakWrite()
 unsigned long myChannelNumber = SECRET CH ID;
 const char * myWriteAPIKey = SECRET WRITE APIKEY;
 int channelField = 2;
 int x = ThingSpeak.writeField(myChannelNumber, channelField,
 temperatureValue, myWriteAPIKey);
 if(x == 200){
  Serial.println("Channel update successful.");
 else{
   Serial.println("Problem updating channel. HTTP error code " + String(x));
```



### Real Air Heater Data

File Edit Sketch Tools Help ∞ COM8 16:17:42.825 -> t=:6.70, u=0.00, Temperature=32.2732.29 Read\_Temperature\_fromAirHeater 16:17:42.919 -> t=:6.80, u=0.00, Temperature=32.2932.31 16:17:43.012 -> t=:6.90, u=0.00, Temperature=32.3132.32 //simulation 16:17:43.153 -> t=:7.00, u=0.00, Temperature=32.3232.32 float Ts =0.1; 16:17:43.248 -> t=:7.10, u=0.00, Temperature=32.3232.32 int wait = 1000\*Ts; 16:17:43.340 -> t=:7.20, u=0.00, Temperature=32.3232.31 ∞ COM8 16:17:43.434 -> t=:7.30, u=0.00, Temperature=32.3132.30 int k=0; 16:17:43.527 -> t=:7.40, u=0.00, Temperature=32.3032.30 int TempPin= A0; 16:17:43.621 -> t=:7.50, u=0.00, Temperature=32.3032.29 40.0 float TempValue; 16:17:43.762 -> t=:7.60, u=0.00, Temperature=32.2932.29 float Voltage read; 16:17:43.856 -> t=:7.70, u=0.00, Temperature=32.2932.29 16:17:43.949 -> t=:7.80, u=0.00, Temperature=32.2932.26 float Deg read; 16:17:44.041 -> t=:7.90, u=0.00, Temperature=32.2632.23 int OutPin = 9; 16:17:44.135 -> t=:8.00, u=0.00, Temperature=32.2332.19 30.0 float u signal; 16:17:44.230 -> t=:8.10, u=0.00, Temperature=32.1932.17 16:17:44.370 -> t=:8.20, u=0.00, Temperature=32.1732.13 16:17:44.462 -> t=:8.30, u=0.00, Temperature=32.1332.11 // Air Heater 16:17:44.557 -> t=:8.40, u=0.00, Temperature=32.1132.10 float y1 = 20;20.0 16:17:44.652 -> t=:8.50, u=0.00, Temperature=32.1032.09 float y2 = 50; 16:17:44.744 -> t=:8.60, u=0.00, Temperature=32.0932.07 16:17:44.886 -> t=:8.70, u=0.00, Temperature=32.0732.03 float x1 = 1; 16:17:44.980 -> t=:8.80, u=0.00, Temperature=32.0331.98 float x2=5; 16:17:45.073 -> t=:8.90, u=0.00, Temperature=31.9831.95 10.0 16:17:45.166 -> t=:9.00, u=0.00, Temperature=31.9531.91 16:17:45.259 -> t=:9.10, u=0.00, Temperature=31.9131.88 16:17:45.352 -> t=:9.20, u=0.00, Temperature=31.8831.87 //PI controller 16:17:45.492 -> t=:9.30, u=0.00, Temperature=31.8731.85 float r = 30;16:17:45.586 -> t=:9.40, u=0.00, Temperature=31.8531.83 0.0 \ float Kp = 0.8; 300 200 400 16:17:45.680 -> t=:9.50, u=0.00, Temperature=31.8331.78 float Ti = 20; 16:17:45.774 -> t=:9.60, u=0.00, Temperature=31.7831.73 Send Newline 9600 baud 16:17:45.867 -> t=:9.70, u=0.00, Temperature=31.7331.68 float u = 0; 16:17:45.960 -> t=:9.80, u=0.00, Temperature=31.6831.64 float u prev= 0; 16:17:46.102 -> t=:9.90, u=0.00, Temperature=31.6431.61 float e = 0;

16:17:46.182 -> t=:10.00, u=0.00, Temperature=31.6131.58 16:17:46.274 -> t=:10.10, u=0.00, Temperature=31.58