

## TTK4125 - Exercise 2

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## Problems

### Preliminary

Our Static Parameter Estimator (SPM) is given by:  $y = \theta^* \phi(t)$ , where  $\theta$  is an estimate of  $\theta^*$  which is an unknown constant. We define the parameter estimation error as:

$$\tilde{\theta}(t) = \theta(t) - \theta^*$$

We then have the estimation error as:

$$\varepsilon(t) = y(t) - \theta \phi = -\tilde{\theta} \phi(t)$$

The given Lyapunov function is:

$$V(t) = \frac{1}{2\gamma} \tilde{\theta}^2$$

Which is positive definite, and its derivative is:

$$\dot{V}(t) = \frac{1}{\gamma} \tilde{\theta} \dot{\tilde{\theta}} = -\frac{1}{\gamma} \tilde{\theta} \dot{\theta} = \frac{1}{\gamma} \tilde{\theta} (-\gamma \phi^2 \tilde{\theta}) = -\phi^2 \tilde{\theta}^2 = -\varepsilon^2 \leq 0$$

Which is negative semi-definite. The update law is given as:

$$\dot{\theta} = \gamma \phi \varepsilon = -\gamma \phi^2 \tilde{\theta}$$

#### 1. $\theta \in \mathcal{L}_\infty$

This claim is the same as the condition:  $\sup_{t \geq 0} |f(t)| < \infty \iff f \in \mathcal{L}_\infty$

We have a positive definite function  $V(t)$  with a semi-negative definite derivative  $\dot{V}(t)$ , given the update law. This means that since  $V$  is non-increasing and so is  $\tilde{\theta}$ , and since  $\theta^*$  is constant, then  $\theta(t)$  must be non-increasing as well, implying that it's bounded. implying that  $\theta \in \mathcal{L}_\infty$ .

#### 2. $\varepsilon \in \mathcal{L}_2$

Following the argumentation presented in lecture 2, we have:

$$\int_0^\infty |\varepsilon|^2 dt = \int_0^\infty -\dot{V} dt = V(0) - V(t)_\infty < \infty$$

Implying that  $\varepsilon \in \mathcal{L}_2$ .

#### 3. $\varepsilon \in \mathcal{L}_\infty$ given that $\phi \in \mathcal{L}_\infty$

Meaning we need  $\sup_{t \geq 0} |\varepsilon| < \infty$  which would imply  $\sup_{t \geq 0} |\tilde{\theta} \phi| < \infty$ .

We have already shown that  $\tilde{\theta} \in \mathcal{L}_\infty$ , and since  $\phi \in \mathcal{L}_\infty$  is given, then the product of the two must also be bounded, which implies that  $\varepsilon \in \mathcal{L}_\infty$ .

#### 4. $\varepsilon \leftrightarrow 0$ given $\phi, \dot{\phi} \in \mathcal{L}_\infty$

By Lemma A.4.7, if  $\varepsilon, \dot{\varepsilon} \in \mathcal{L}$ , and  $\varepsilon \in \mathcal{L}_p$  for some  $p \in [1, \infty)$ , then

$\varepsilon \rightarrow 0$  as  $t \rightarrow \infty$ .

We have already shown that  $\varepsilon \in \mathcal{L}_2$ , so we need to show that  $\varepsilon, \dot{\varepsilon} \in \mathcal{L}_\infty$ .

Given that  $\phi \in \mathcal{L}_\infty$  we have that  $\varepsilon \in \mathcal{L}_\infty$  already.

Now,  $\sup_{t \geq 0} |\dot{\varepsilon}| \Rightarrow \sup_{t \geq 0} |-\dot{\theta}\phi - \tilde{\theta}\dot{\phi}|$

Already,  $\theta \in \mathcal{L}_\infty$

And with  $\dot{\theta} = \gamma\varepsilon\phi$  and now if  $\phi \in \mathcal{L}_\infty$  is given, then  $\varepsilon \in \mathcal{L}_\infty$  giving  $\dot{\theta} \in \mathcal{L}_\infty$ .

Resulting in  $\dot{\theta}, \theta \in \mathcal{L}_\infty$  using  $\phi, \dot{\phi} \in \mathcal{L}_\infty$  and  $\varepsilon, \dot{\varepsilon} \in \mathcal{L}_\infty$  and  $\varepsilon \in \mathcal{L}_2$ .  
Now by using "Barbalat's Lemma", we can say that  $\varepsilon \rightarrow 0$  as  $t \rightarrow \infty$ .

From this we cannot conclude that  $\theta \rightarrow \theta^*$ .

From  $\varepsilon = y - \theta\phi$  we see that this only tends to zero if either  $\phi \rightarrow 0$  or  $\tilde{\theta} \rightarrow 0$ .

This shows that we can reach zero estimation error without zero parameter estimation error. In this case if  $\varepsilon = 0, \dot{\theta} = 0$ , our  $\theta$  is not updating, even though it might be wrong. We can see this relation from

$$\dot{\tilde{\theta}} = -\gamma\tilde{\theta}\phi^2$$

So we need  $\phi \neq 0$  for  $\dot{\tilde{\theta}}$  to be driving  $\tilde{\theta}$  to change.

This is known as persistent excitation.