OT CAS AND TO
AI-512 MATHEMATICS FOR
MACHINE LEARNING
Or Noth William Control
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01 0
Q-1-a) To minimize $  z  ^2$ [z.'n-veiter of modifications]
modifications ]
0 = 2 + 10 . \ . \ . \ . \ . \ . \ . \ . \ . \ .
We minimize w.s.t D(2+z) = xs
la equality constraint
Assumption: D'has linearly independent nous.
adD(x+z) = xS
$Dx + Dx = \alpha S $
$O = O \times A + O \times A \times$
Lagrangian function L(Z, L)
The state of the s
$L(z,\lambda) = z^{T}z + \lambda^{T}(Dz - \alpha S + Dx)$
(**1 ->c) (Ja)s = x
DL (2, s) = 0 Vie[1, mi]
∂2;
(2 4 J) ( (ag) c) a + cc
DL (2, x) =0 Vie [1k]
1.00-3 M 7 ( 00) 0 - 0

$$\frac{\partial L}{\partial \lambda_i} (2, \hat{\lambda}) = D_i(x+z) - xS_i = 0$$

$$\frac{\partial L}{\partial z_i} \left( \vec{z}, \hat{\lambda} \right) = 2 \sum_{j=1}^{\infty} (1)(\vec{z}_j) + \sum_{j=1}^{k} \hat{\lambda}_j \left( D_j \right)_i = 0$$

Weiling in compact matein form

$$\nabla_{z}L = 2\hat{z} + D^{T}\hat{\lambda} = 0$$

$$z = -\frac{1}{\lambda}$$

$$\nabla_{\lambda}L = D(n+z) - \alpha S = 0$$

$$\frac{D(x-D^{T}\lambda)- \chi S=0}{2}$$

$$2(Dx - \alpha S) = DD^{T}\lambda$$

$$\lambda = 2(DD^T)^{-1}(Dx-\lambda S)$$

Substituting & in 02

$$2\hat{2} + D^{T}(2(DD^{T})^{-1})(D_{x}-xS) = 0$$

$$\hat{z} = D^{T}(DD^{T})^{-1}(\alpha S - D\alpha)$$