## AI 512 - Mathematics for Machine Learning Assignment # 1

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Network tomography. A network consists of n links, labeled  $1, \ldots, n$ . A path through the Q1. network is a subset of the links. (The order of the links on a path does not matter here.) Each link has a (positive) delay, which is the time it takes to traverse it. We let d denote the n-vector that gives the link delays. The total travel time of a path is the sum of the delays of the links on the path. Our goal is to estimate the link delays (i.e., the vector d), from a large number of (noisy) measurements of the travel times along different paths. This data is given to you as an  $N \times n$  matrix P, where

 $P_{ij} = \begin{cases} 1 & \text{link } j \text{ is on path } i \\ 0 & \text{otherwise,} \end{cases}$ 

and an N-vector t whose entries are the (noisy) travel times along the N paths. You can assume that N > n. You will choose your estimate d by minimizing the RMS deviation between the measured travel times (t) and the travel times predicted by the sum of the link delays. Explain how to do this, and give a matrix expression for d. If your expression requires assumptions about the data P or t, state them explicitly.

Remark. This problem arises in several contexts. The network could be a computer network, and a path gives the sequence of communication links data packets traverse. The network could be a transportation system, with the links representing road segments.

3 Marks

Som.

Matein P is a tall matein

C: N > n assumption

To estimate: d

lase I

tNx1 E C(PNxm)

Ving RMS deviation we get exact value of dn×2

Lare II tn×2 \$ C(PN×m)

We get approximate solution

## Row interpretation

$$\left\| \left( \overrightarrow{P}_{d} - t \right) \right\|^{2} = \left( \widetilde{P}_{1} d - t_{2} \right)^{2} + \dots \left( \widetilde{P}_{n} d - t_{n} \right)^{2}$$

$$\frac{\partial}{\partial d} \left( (Pd-t)^{T} (Pd-t) \right) = 0$$

$$(P^TP)d = P^Tt$$

Assuming PTP is invertible,

$$\hat{d} = (P^T P)^{-1} P^T t \longrightarrow \text{but value}$$

if vare I, exact value of Pd=t if vare I, Least squares value of Pd=t.