Лабораторная работа №5

Transfer Learning

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Для решения задачи был выбран датасет с рентгеновскими снимками.

```
Ввод [1]: # License: BSD
          # Author: Sasank Chilamkurthy
          import torch
          import torch.nn as nn
          import torch.optim as optim
          from torch.optim import lr scheduler
          import torch.backends.cudnn as cudnn
          import numpy as np
          import torchvision
          from torchvision import datasets, models, transforms
          import matplotlib.pyplot as plt
          import time
          import os
          from PIL import Image
          from tempfile import TemporaryDirectory
          cudnn.benchmark = True
          plt.ion()
```

WARNING:tensorflow:From C:\Users\nprud\anaconda3\Lib\site-packages\keras \src\losses.py:2976: The name tf.losses.sparse_softmax_cross_entropy is d eprecated. Please use tf.compat.v1.losses.sparse_softmax_cross_entropy in stead.

WARNING:tensorflow:From C:\Users\nprud\anaconda3\Lib\site-packages\keras\src\backend.py:873: The name tf.get_default_graph is deprecated. Please use tf.compat.v1.get default graph instead.

Out[1]: <contextlib.ExitStack at 0x1ac1eb6db50>

```
Ввод [2]: data_transforms = {
              'train': transforms.Compose([
                  transforms.RandomResizedCrop(224),
                  transforms.RandomHorizontalFlip(),
                  transforms.ToTensor(),
                  transforms.Normalize([0.485, 0.456, 0.406], [0.229, 0.224, 0.225])
              ]),
              'val': transforms.Compose([
                  transforms.Resize(256),
                  transforms.CenterCrop(224),
                  transforms.ToTensor(),
                  transforms.Normalize([0.485, 0.456, 0.406], [0.229, 0.224, 0.225])
              ]),
          }
          data_dir = 'dataset/archive/images'
          image_datasets = {x: datasets.ImageFolder(os.path.join(data_dir, x),
                                                     data transforms[x])
                            for x in ['train', 'val']}
          dataloaders = {x: torch.utils.data.DataLoader(image_datasets[x], batch_size
                                                        shuffle=True, num_workers=4)
                        for x in ['train', 'val']}
          dataset sizes = {x: len(image datasets[x]) for x in ['train', 'val']}
          class_names = image_datasets['train'].classes
          device = torch.device("cuda:0" if torch.cuda.is_available() else "cpu")
Ввод [3]: dataset_sizes
 Out[3]: {'train': 1022, 'val': 1139}
Ввод [4]: class_names
```

Out[4]: ['non_xray', 'xray']

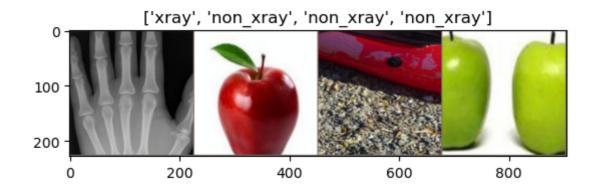
```
BBOД [5]:

def imshow(inp, title=None):
    """Display image for Tensor."""
    inp = inp.numpy().transpose((1, 2, 0))
    mean = np.array([0.485, 0.456, 0.406])
    std = np.array([0.229, 0.224, 0.225])
    inp = std * inp + mean
    inp = np.clip(inp, 0, 1)
    plt.imshow(inp)
    if title is not None:
        plt.title(title)
    plt.pause(0.001)

inputs, classes = next(iter(dataloaders['train']))

out = torchvision.utils.make_grid(inputs)

imshow(out, title=[class_names[x] for x in classes])
```



```
Ввод [6]: def train model(model, criterion, optimizer, scheduler, num epochs=25):
              since = time.time()
              with TemporaryDirectory() as tempdir:
                  best_model_params_path = os.path.join(tempdir, 'best_model_params.g
                  torch.save(model.state_dict(), best_model_params_path)
                  best acc = 0.0
                  for epoch in range(num_epochs):
                      print(f'Epoch {epoch}/{num_epochs - 1}')
                      print('-' * 10)
                      for phase in ['train', 'val']:
                          if phase == 'train':
                              model.train()
                          else:
                              model.eval()
                          running loss = 0.0
                          running_corrects = 0
                          for inputs, labels in dataloaders[phase]:
                              inputs = inputs.to(device)
                              labels = labels.to(device)
                              optimizer.zero_grad()
                              with torch.set_grad_enabled(phase == 'train'):
                                  outputs = model(inputs)
                                   , preds = torch.max(outputs, 1)
                                  loss = criterion(outputs, labels)
                                   if phase == 'train':
                                       loss.backward()
                                       optimizer.step()
                              running_loss += loss.item() * inputs.size(0)
                              running corrects += torch.sum(preds == labels.data)
                          if phase == 'train':
                              scheduler.step()
                          epoch loss = running loss / dataset sizes[phase]
                          epoch_acc = running_corrects.double() / dataset_sizes[phase]
                          print(f'{phase} Loss: {epoch_loss:.4f} Acc: {epoch_acc:.4f}
                          if phase == 'val' and epoch_acc > best_acc:
                              best_acc = epoch_acc
                              torch.save(model.state dict(), best model params path)
                      print()
                  time_elapsed = time.time() - since
                  print(f'Training complete in {time_elapsed // 60:.0f}m {time_elapse
                  print(f'Best val Acc: {best_acc:4f}')
                  model.load_state_dict(torch.load(best_model_params_path))
```

```
Ввод [7]: def visualize model(model, num images=6):
              was_training = model.training
              model.eval()
              images_so_far = 0
              fig = plt.figure()
              with torch.no grad():
                  for i, (inputs, labels) in enumerate(dataloaders['val']):
                      inputs = inputs.to(device)
                      labels = labels.to(device)
                      outputs = model(inputs)
                      _, preds = torch.max(outputs, 1)
                      for j in range(inputs.size()[0]):
                          images_so_far += 1
                          ax = plt.subplot(num_images//2, 2, images_so_far)
                          ax.axis('off')
                          ax.set_title(f'predicted: {class_names[preds[j]]}')
                          imshow(inputs.cpu().data[j])
                          if images_so_far == num_images:
                              model.train(mode=was_training)
                               return
                  model.train(mode=was training)
```

```
BBOД [8]: model_ft = models.resnet18(weights='IMAGENET1K_V1')
num_ftrs = model_ft.fc.in_features
model_ft.fc = nn.Linear(num_ftrs, 2)

model_ft = model_ft.to(device)

criterion = nn.CrossEntropyLoss()

optimizer_ft = optim.SGD(model_ft.parameters(), lr=0.001, momentum=0.9)

exp_lr_scheduler = lr_scheduler.StepLR(optimizer_ft, step_size=7, gamma=0.1)
```

```
Ввод [9]: model_ft = train_model(model_ft, criterion, optimizer_ft, exp_lr_scheduler,
                                  num_epochs=4)
           Epoch 0/3
           -----
           train Loss: 0.2315 Acc: 0.9119
           val Loss: 0.0041 Acc: 0.9991
           Epoch 1/3
           -----
           train Loss: 0.2475 Acc: 0.9100
           val Loss: 0.0018 Acc: 1.0000
           Epoch 2/3
           _____
           train Loss: 0.2435 Acc: 0.9149
           val Loss: 0.0012 Acc: 0.9991
           Epoch 3/3
           -----
           train Loss: 0.2333 Acc: 0.9315
           val Loss: 0.0303 Acc: 0.9939
           Training complete in 24m 0s
           Best val Acc: 1.000000
Ввод [10]: model_conv = torchvision.models.resnet18(weights='IMAGENET1K_V1')
           for param in model_conv.parameters():
               param.requires_grad = False
           num_ftrs = model_conv.fc.in_features
           model_conv.fc = nn.Linear(num_ftrs, 2)
           model_conv = model_conv.to(device)
           criterion = nn.CrossEntropyLoss()
           optimizer_conv = optim.SGD(model_conv.fc.parameters(), lr=0.001, momentum={
```

exp_lr_scheduler = lr_scheduler.StepLR(optimizer_conv, step_size=7, gamma={

Ввод [11]: model_conv = train_model(model_conv, criterion, optimizer_conv, exp_lr_scheduler, num_epochs=4)

Epoch 0/3

train Loss: 0.2885 Acc: 0.8669 val Loss: 0.0228 Acc: 0.9956

Epoch 1/3

train Loss: 0.2719 Acc: 0.8914 val Loss: 0.0182 Acc: 0.9947

Epoch 2/3

train Loss: 0.2981 Acc: 0.8992 val Loss: 0.0008 Acc: 1.0000

Epoch 3/3

train Loss: 0.3531 Acc: 0.8816 val Loss: 0.0032 Acc: 1.0000

Training complete in 14m 40s

Best val Acc: 1.000000

BBOД [12]: visualize_model(model_conv) plt.ioff() plt.show()

predicted: non_xray



predicted: non xray



predicted: non_xray



predicted: non_xray



predicted: xray



predicted: xray



```
BBOД [13]:

def visualize_model_predictions(model,img_path):
    was_training = model.training
    model.eval()

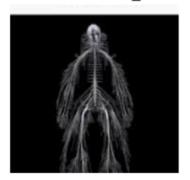
img = Image.open(img_path)
    img = data_transforms['val'](img)
    img = img.unsqueeze(0)
    img = img.to(device)

with torch.no_grad():
    outputs = model(img)
    __, preds = torch.max(outputs, 1)

ax = plt.subplot(2,2,1)
    ax.axis('off')
    ax.set_title(f'Predicted: {class_names[preds[0]]}')
    imshow(img.cpu().data[0])

model.train(mode=was_training)
```

Predicted: non_xray



Predicted: xray



Как видно по картинкам, несмотря на попытки запутать нейросеть, изображения были распознаны с поражающей точностью.

Вывод

В ходе выполнения лабораторной работы я произвела тонкую настройку (fine-tuning) предварительно обученной нейронной сети с целью развить способность распознавать, представляет ли анализируемое изображение рентгеновский снимок или нет. Данная задача относится к области передачи обучения (transfer learning) в машинном обучении.

Ввод []:		