

OUTLINE

- The Thread Model
- Thread Usage
- Thread Implementations
- POSIX Threads
- Concurrency Problems
- Race Condition
- Mutual Exclusion



LEARNING OUTCOMES

- Upon the completion of Week 7, you should be able to:
 - Understand the distinction between process and thread
 - Describe the basic thread models
 - Explain the difference between user-level threads and kernel-level threads
 - Discuss thread management in Unix/Linux
 - □ Discuss the problems related to concurrency
 - ☐ Understand the concept of a race condition
 - ☐ Understand the concept of critical regions
 - □ Describe the mutual exclusion requirements



THREADS

THE CONCEPT OF PROCESSES (REVISIT)

- The unit of resource allocation and a unit of protection.
- A (virtual) address space that holds the process image.
- Protected access to:
 - Processor(s)
 - Other processes
 - Files
 - I/O resources



THREADS

WHAT IS A THREAD?

- The unit of dispatching for execution is referred to as:
 - Thread or
 - Lightweight process
- The unit of resource ownership is referred to as:
 - Process or task
- Multi-threading:
 - The ability of an OS to support multiple concurrent paths of execution within a single process
 - 1 process : multiple threads of execution.



THREADS

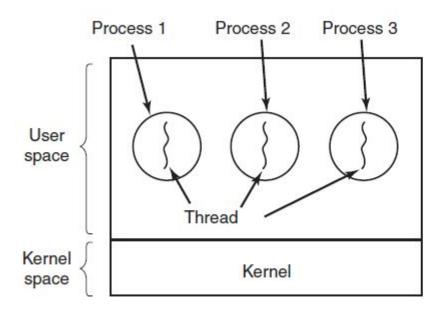
THREADS WITHIN A PROCESS

- □ Different part of a program may do different things and they can be executed concurrently to improve response time (or completion time).
 - Example: one thread may do a processor-bound task like rendering an image, while another thread responds to user interaction in the same program.
- ☐ If there is an interaction between different parts of the programs concurrency control need to be applied.
- Example: accessing and modifying a common variable mutual exclusion need to be satisfied.



SINGLE-THREADED APPROACH

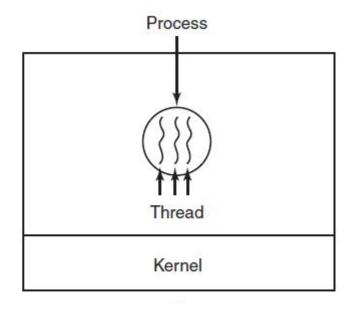
- □ A single thread of execution per process.
- ☐ The concept of a thread is not recognised referred as a single-threaded approach.
- ☐ Example: MS-DOS, Windows 3.1





MULTI-THREADED APPROACH

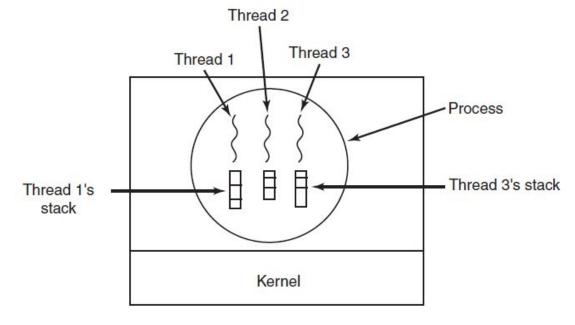
- One process with multiple threads.
- ☐ Example: Windows, Linux.





PER-PROCESS vs PER-THREAD ITEMS

Per process items	Per thread items	
Address space	Program counter	
Global variables	Registers	
Open files	Stack	
Child processes	State	
Pending alarms	0.000	
Signals and signal handlers		
Accounting information		

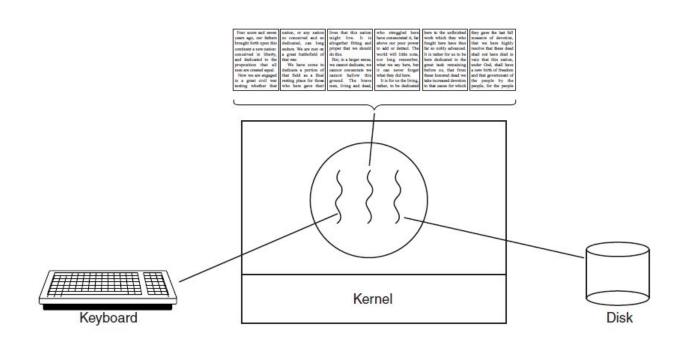


- The first column lists some items shared by all threads in a process.
- The second one lists some items private to each thread.

Each thread has its own stack.



EXAMPLES OF MULTI-THREADED APPLICATIONS



Dispatcher thread

Worker thread

Web page cache

Kernel

Network
connection

Web server process

Worker thread

Web page cache

A word processor with three threads.

A multithreaded Web server.



MULTI-THREADED WEB SERVER IMPLEMENTATION

```
while (TRUE) {
    get_next_request(&buf);
    handoff_work(&buf);
}

while (TRUE) {
    wait_for_work(&buf)
    look_for_page_in_cache(&buf, &page);
    if (page_not_in_cache(&page))
        read_page_from_disk(&buf, &page);
    return_page(&page);
}

(a)

(b)
```

A rough outline of the code for a multi-threaded web server (a) Dispatcher thread. (b) Worker thread.



BENEFITS OF USING THREADS

Speed: Takes less time to create a new thread than a process.
Speed: Takes less time to terminate a thread than a process.
Speed: Switching between two threads takes less time than switching between processes.
Speed: Communication between threads within the same process is faster than communication
between different processes.

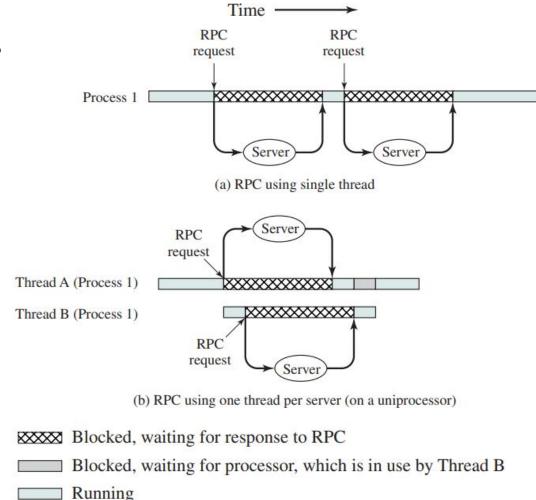
DRAWBACKS OF USING THREADS

- Reliability: A bug in one thread can disable multiple threads, or all threads.
 Security: If one thread is compromised, usually all threads are compromised.
 Consistency: Concurrency problems may arise with shared data structures
- Portability: Support for multithreading depends on CPU type, and performance gains may not be portable across different CPUs even of the same nominal architecture



BENEFITS OF USING THREADS: REMOTE PROCEDURE CALL (RPC) EXAMPLE

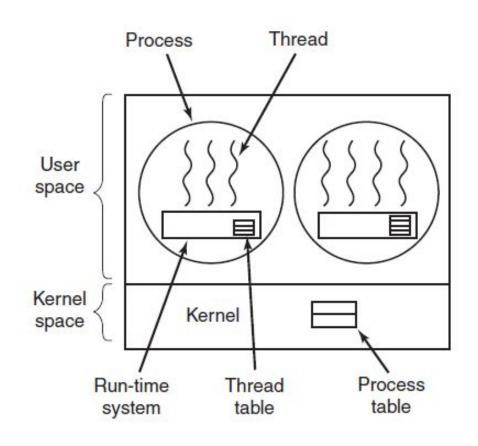
- □ For a single-threaded approach, 2 RPC requests are made one after another by Process 1 (Fig. a).
- → Process 1 is completely blocked while waiting for a response to arrive from the server (Fig. a).
- ☐ For a multi-threaded approach, Thread A sends the first RPC request and gets blocked (Fig. b).
- □ Thread B gets some CPU time and sends the second RPC request (Fig. b).
- ☐ The process completes quickly as the second RPC response arrives shortly after the first RPC response. (Fig. b).
- □ Assumption: Server is also multi-threaded. OR Different servers handled the RPC requests.





THREAD IMPLEMENTATIONS USER LEVEL THREADS (ULTs)

- □ All thread management is done by the application.
- The kernel is not aware of the existence of threads.
- Any application can be programmed to be multi-threaded by using a threads library.
 - Even if OS does not support threads.





USER LEVEL THREADS (ULTs)

Advantages:

- Thread switching does not require kernel mode privileges.
- Scheduling can be application specific.
- ULTs can run on any Operating Systems.

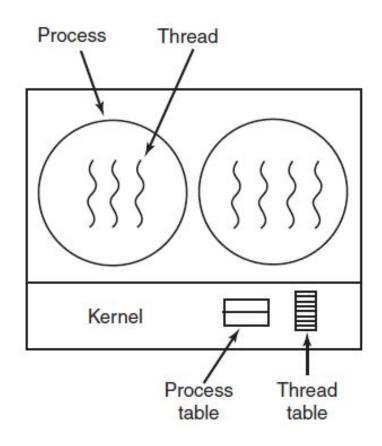
• Disadvantages:

- In a typical OS, many system calls are blocking.
- When a ULT executes a system call, not only is that thread gets blocked, but all of the threads within the process are also blocked.
- In a pure ULT strategy, a multi-threaded application cannot take the full advantage of multiprocessing.



THREAD IMPLEMENTATIONS KERNEL LEVEL THREADS (KLTs)

- ☐ Thread management is done by the kernel.
- No thread management is done by the application through API to the kernel thread facility.
- ☐ Example: Windows, Linux





KERNEL LEVEL THREADS (KLTs)

Advantages:

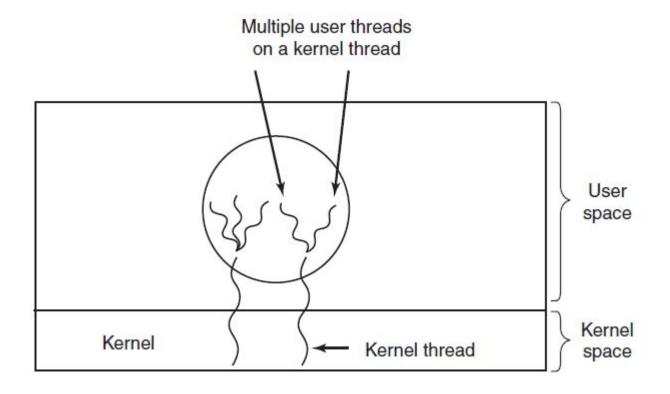
- The kernel can simultaneously schedule multiple threads from the same process on multiple processors.
- □ If one thread in a process is blocked, the kernel can schedule another thread of the same process.
- The kernel routines can also be multi-threaded.

• Disadvantages:

- ☐ The transfer of control from one thread to another thread within the same process requires a mode switch to the kernel.
 - Some overhead here.



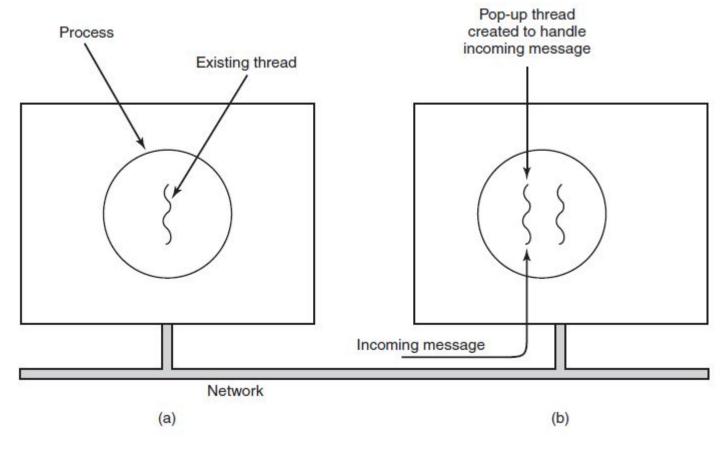
HYBRID IMPLEMENTATIONS



Multiplexing user-level threads onto kernel-level threads.



POP UP THREADS



Creation of a new thread when a message arrives:

(a) Before the message arrives. (b) After the message arrives.



POSIX THREADS (PTHREADS)

POSIX THREADS

PTHREADS LIBRARY

- ☐ Threads in Linux are known as **pthreads**. Managed through a separate API.
- ☐ The pthread library must be included and linked into the program in order to use threads.
 - #include <pthread.h>
 - Add -lpthread to the end of the gcc command to link the program against the pthread library
- □ pthread_create() spawn a new thread
- □ pthread_join() wait for another thread to terminate



POSIX THREADS

PTHREADS EXAMPLE PROGRAM

```
#include <pthread.h>
 #include <stdio.h>
 #include <stdlib.h>
 #define NUMBER OF THREADS
 void *print_hello_world(void *tid)
      /* This function prints the thread's identifier and then exits. */
       printf("Hello World. Greetings from thread %d\n", tid);
       pthread_exit(NULL);
 int main(int argc, char *argv[])
      /* The main program creates 10 threads and then exits. */
       pthread_t threads[NUMBER_OF_THREADS];
       int status, i;
      for(i=0; i < NUMBER_OF_THREADS; i++) {
            printf("Main here. Creating thread %d\n", i);
status = pthread_create(&threads[i], NULL, print_hello_world_(yoid *)i);
```



POSIX THREADS PTHREADS EXAMPLE PROGRAM

```
for(i=0; i < NUMBER_OF_THREADS; i++) {
    printf("Main here. Creating thread %d\n", i);
    status = pthread_create(&threads[i], NULL, print_hello_world, (void *)i);

    if (status != 0) {
        printf("Oops. pthread_create returned error code %d\n", status);
        exit(-1);
    }
}
exit(NULL);
```



CONCURRENCY PROBLEMS

CONCURRENCY PROBLEMS

WHY CONCURRENCY PROBLEMS OCCUR

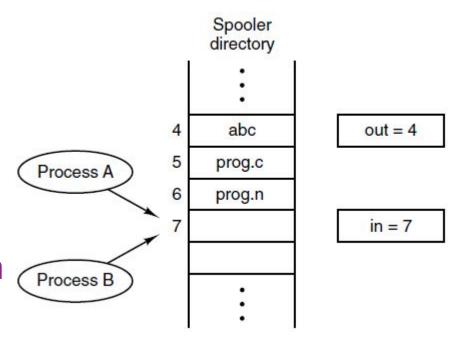
execution of cooperating processes.

- Processes that are working together may share some common storage or memory that each one can read and write to communicate between themselves.
 Processes need to access a shared resource in the system.
 Concurrent access to shared data may result in data inconsistency.
 Maintaining data consistency requires mechanisms to ensure the orderly
- □ Difficult to locate programming errors results are non-deterministic and not reproducible.
- ☐ The problem exists in both multiprogramming on uni-processor and multi-processors.



WHAT IS RACE CONDITION

- A Race Condition is a situation where two or more processes are reading or writing some shared data and the final result depends on who runs when.
- Occurs when multiple processes or threads read and write data items.
- ☐ Final result depends on the order of execution
 - "Loser" of the race is the process that updates last and will determine the final value of the variable
- ☐ To prevent race conditions, concurrent processes or threads must be synchronised.



Two processes want to access shared memory at the same time.



A RACE CONDITION IN UNIPROCESSOR MULTIPROGRAMMING

Consider the following procedure:

```
void echo()
{
    char_in = getchar();
    char_out = char_in;
    putchar(char_out);
}
```

- Read a character from the keyboard and store in char in.
- Transfer to char_out before being sent for display.
- Consider two different applications

 Process A and Process B —
 make a call to this procedure.



RACE CONDITION IN UNIPROCESSOR MULTIPROGRAMMING

Consider the following procedure:

```
void echo()
{
    char_in = getchar();
    char_out = char_in;
    putchar(char_out);
}
```

- Process A invokes echo() and is interrupted immediately after getchar returns its value and stores it in char_in (e.g. x).
- Process B is activated and invokes
 echo() and read a char (e.g. y) and runs to completion of the procedure.
- When process A resumes the value of x has been overwritten in char_in by process B and therefore its value x is lost.



RACE CONDITION IN UNIPROCESSOR MULTIPROGRAMMING

```
Process A:
                                     Process B:
 char in = getchar();
                                    char in = getchar();
                                    char out = char in;
                                    putchar(char out);
 char out = char in;
 putchar(char out);
```

TIME



MUTUAL EXCLUSION (MUTEX)

- Suppose n processes all competing to use some shared data.
- Each process has a code segment critical region where the shared data is accessed or manipulated.
- Mutual exclusion refers to the requirement of ensuring that no two concurrent processes are in their critical region at the same time.
- Mutual Exclusion is a basic requirement in concurrency control, to prevent race conditions.
- Ensure that when one process is executing in its critical region, no other process is allowed in its critical region.



MUTUAL EXCLUSION REQUIREMENTS TO AVOID RACE CONDITIONS

- No two processes may be simultaneously inside their critical regions.
- No assumptions may be made about speeds or the number of CPUs.
- No process running outside its critical region may block other processes.
- No process should have to wait forever to enter its critical region.



PREVENTING A RACE CONDITION BY USING MUTUAL EXCLUSION

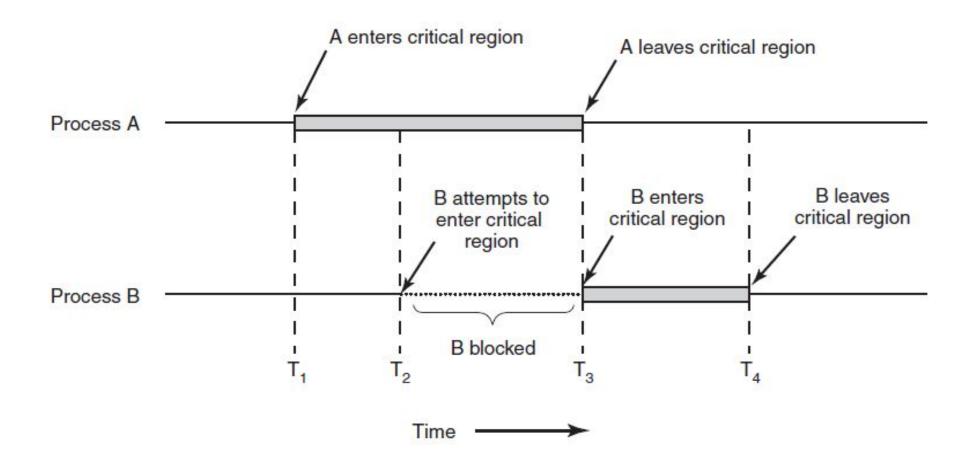
Consider the following procedure:

```
void echo()
{
    char_in = getchar();
    char_out = char_in;
    putchar(char-out);
}
```

- Assume only one process at a time to invoke and be in the echo procedure (the whole echo procedure is the critical region)
- Process A invokes the echo procedure and is interrupted immediately after getchar returns its value and stores it in char_in (e.g. x).
- Process B is activated and invokes echo procedure and since the echo procedure is used by process A, process B is blocked from further execution.
- At some later time, process A is resumed and completes the execution of **echo** and the proper input character will be displayed.
- When process A exits echo, this removes the block on process B.
- When process B is later resumed, the echo procedure is successfully invoked.



PREVENTING A RACE CONDITION BY USING MUTUAL EXCLUSION





RACE CONDITION IN MULTIPROCESSOR MULTIPROGRAMMING

- □ Same problem arises even when the processes A and B runs on different processors accessing unprotected shared variables.
- The solution outlined in the previous slides can work here.
- Protecting and controlling access to shared resources are critical.



EXAMPLE

```
/* PROCESS 1 */
                                   /* PROCESS 2 */
                                                                         /* PROCESS n */
                            void P2
                                                                   void Pn
void P1
 while (true) {
                              while (true) {
                                                                    while (true) {
  /* preceding code */;
                               /* preceding code */;
                                                                      /* preceding code */;
  entercritical (Ra);
                               entercritical (Ra);
                                                                      entercritical (Ra);
  /* critical section */;
                               /* critical section */;
                                                                      /* critical section */;
  exitcritical (Ra);
                               exitcritical (Ra);
                                                                      exitcritical (Ra);
  /* following code */;
                                /* following code */;
                                                                      /* following code */;
```

To enforce mutual exclusion, two function are provided: entercritical and exitcritical with the resource as the argument.



RACE CONDITIONS WITH MULTIPLE SHARED DATA RESOURCES

- □ The same problem exists even when processes access more than one shared resource.
- Processes must cooperate to ensure the shared data are properly managed.
- Control mechanisms are needed to ensure the integrity of the shared data.



RACE CONDITION EXAMPLE WITH MULTIPLE SHARED DATA RESOURCES

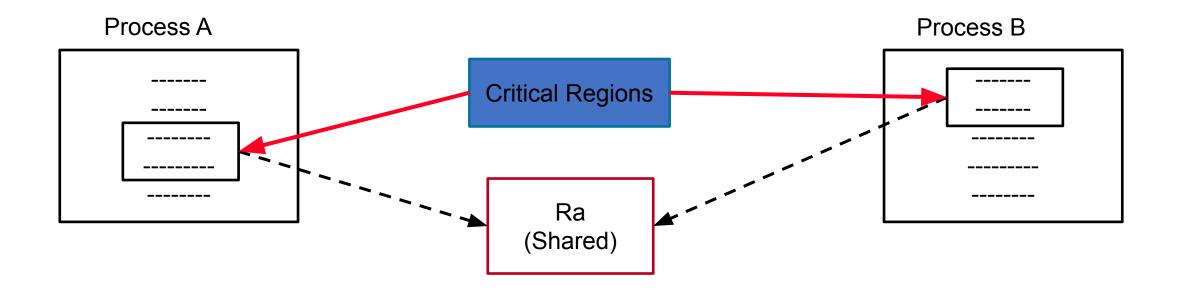
 Assuming that a = b at the beginning, and consider the following concurrent execution sequence:

```
a = a + 1; /* {PA} */
b = 2 * b; /* {PB} */
b = b + 1; /* {PA} */
a = 2 * a; /* {PB} */
```

- At the end of this execution, the condition a = b no longer holds!
- Solution: access to both a and b should be enclosed in the same critical region.

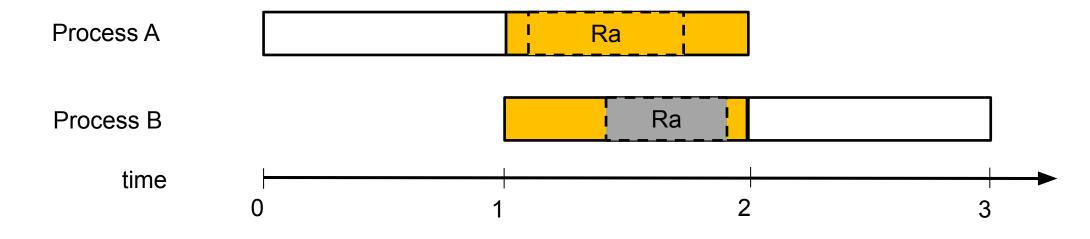


RACE CONDITION REVISIT





REVISIT



Process States

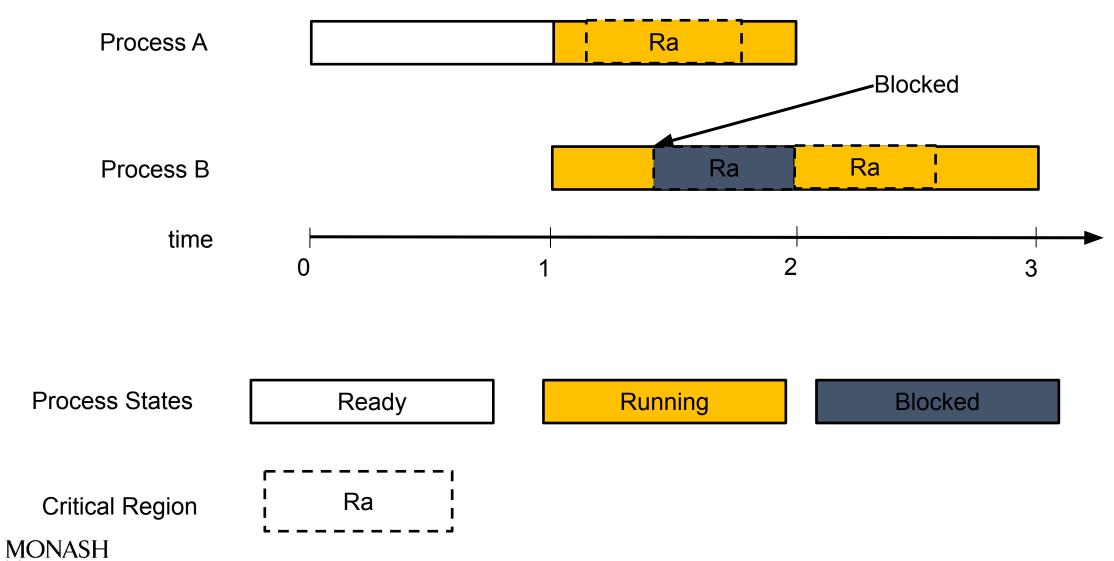
Ready

Running

Blocked



RACE CONDITION PREVENTION WITH MUTUAL EXCLUSION



CONCURRENCY PROBLEMS

MORE CONCURRENCY PROBLEMS

- Mutual Exclusion causes additional concurrency problems!!!
- Deadlock: two or more processes are waiting indefinitely for the other processes to release the system resources.
- Starvation: indefinite blocking of a process.



Summary

- ☐ So far we have discussed.
 - Introduction to threads
 - Thead Model
 - Thread implementations
 - Concurrency Problems
- ☐ Next week
 - Advanced Concurrency
- Reading
 - Tanenbaum, Chapter 2 (4th Edition)
 - Stallings, Chapter 7 (7th Edition)