FinancialMathematics

Nick Syring

2023-02-01

Contents

1	Introduction					
2	Introduction					
3	The geometric Brownian motion model of asset value an Monte Carlo simulation					
	3.1	Asset values as random variables	9			
	3.2	Geometric Brownian motion model of asset prices over time $\ .$	10			
	3.3	Monte Carlo simulation of the gBm model	12			
	3.4	Off on a tangent: reducing MC variability	15			

4 CONTENTS

Chapter 1

Introduction

Chapter 2

Introduction

Chapter 3

The geometric Brownian motion model of asset value and Monte Carlo simulation

3.1 Asset values as random variables

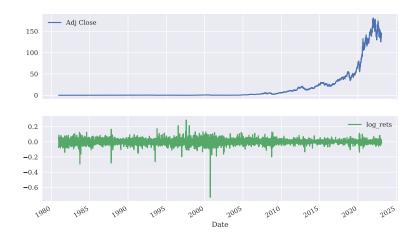
Let $\{S_t, t \geq 0\}$ denote the values of an asset at times t. Ideally, we think of time as a continuum, so that S_t is a *continuous process*. Practically, however, we will approximate the continuous process by a discrete one by performing computations associated with the process at a grid of t values in some interval [0,T] with mesh-size Δt .

We model the process S_t as a random or stochastic sequence; essentially, it is just a sequence of realizations of random variables.

Here is a plot of Apple's (AAPL) close-of-day stock price and logarithm of return $\log(S_t/S_{t-1})$ from its initial listing to the present day. Stock prices are available much more often than daily, so the data visualized below already represent a discretization of the underlying process (with mesh-size 1 day).

```
import numpy as np
import numpy.random as npr
import matplotlib as mpl
from matplotlib.pylab import plt
import math

plt.style.use('seaborn')
mpl.rcParams['font.family'] = 'serif'
```



3.2 Geometric Brownian motion model of asset prices over time

The mathematics of continuous stochastic processes is advanced. Rather than presenting a full account here we focus on an intermediate level of understanding

of one of the most common models used for asset prices. Later we will modify the model to account for several real-life phenomena.

It is folk-wisdom that the log returns of at asset $\log \frac{S_t}{S_{t-1}}$ are normally-distributed, or, rather, are modeled as such. This comes as a consequence of modeling the sequence of asset prices as a geometric Brownian motion.

A Brownian motion (which is also called a Wiener process) is essentially a sequence of normal random variables. Specifically, the process W_t satisfies - $W_0 = 0$ - W_t is continuous a.s. - W_t has independent increments - $W_t - W_s \sim N(0,t-s)$ for $0 \le s \le t$ Additionally, the sequence is measurable with respect to a filtration, an ordered family of sigma-fields (for details see, for example, Resnick's A Probability Path Chapter 10).

The geometric Brownian motion (gBm) model says changes in asset price from time t to time t + s are determined by a Brownian motion and a drift. This is typically written in the following fashion as a stochastic differential equation (SDE) with respect to instantaneous price change:

$$dS_t = rS_t dt + \sigma S_t dW_t$$

where r is a risk-free interest rate, dt is an instantaneous change in time, σ is a volatility (standard deviation) parameter, and W_t is a Brownian motion.

It is important to keep in mind the SDE doesn't really mean anything—rather, it is simply notation used to express a stochastic integral in a concise manner. A more meaningful expression of the geometric Brownian motion model is given by the difference equation

$$S_{t+s} = S_t = \int_t^{t+s} r S_u \, du + \int_t^{t+s} \sigma S_u \, dW_u.$$

The primary challenge to overcome is how to define integration with respect to the Brownian motion W_u . For various technical reasons, such an integration cannot behave exactly in the same way integration works for real-valued functions, i.e., Riemann integration. A new theory of integration, Ito integration, is needed.

Rather than giving a thorough treatment of Ito's calculus, we will simply provide an informal derivation of Ito's Lemma, which is enough to provide a "solution" to the geometric Brownian motion. Let $f(t, S_t)$ be a function of time and asset price at time t. Take a two term Taylor expansion of f and use the geometric Brownian motion SDE in the chain rule as follows:

$$\begin{split} df &= \frac{\partial f}{\partial t} dt + \frac{\partial f}{\partial S_t} dS_t + \frac{1}{2} \frac{\partial^2 f}{\partial S_t^2} dS_t^2 + \cdots \\ &= \frac{\partial f}{\partial t} dt + \frac{\partial f}{\partial S_t} (rS_t dt + \sigma S_t dW_t) + \frac{1}{2} \frac{\partial^2 f}{\partial S_t^2} (r^2 S_t^2 dt^2 + 2r\sigma S_t^2 dt dW_t + \sigma^2 S_t^2 dW_t^2) + \cdots. \end{split}$$

Then, Ito's Lemma says $dW_t^2 = O(dt)$ and the substitution $dW_t^2 = dt$ is justified, while the terms dt^2 and $dt dW_t$ are ignorable and may be substituted by zero. The Taylor expansion simplifies, according to Ito, to

$$df = \left(\frac{\partial f}{\partial t} + rS_t \frac{\partial f}{\partial S_t} + \frac{\sigma^2}{2} S_t^2 \frac{\partial^2 f}{\partial S_t^2}\right) dt + \sigma \frac{\partial f}{\partial S_t} S_t dW_t.$$

Now, let $f(t, S_t) := \log(S_t)$, the log asset price at time t. In that case, we have the following derivatives:

$$\partial f/\partial t = 0 \quad \partial f/\partial S_t = 1/S_t \quad \partial^2 f/\partial S_t^2 = -1/S_t^2.$$

Substituting these into the SDE above, we get

$$d\log S_t = r\,dt - \frac{\sigma^2}{2S_t^2}S_t^2\,dt + \frac{\sigma}{S_t}S_t\,dW_t.$$

Next integrate both sides:

$$\log S_t = \log(S_0) + \left(r - \frac{\sigma^2}{2}\right)t + \sigma\,W_t.$$

Exponentiate to obtain

$$S_t = S_0 \exp \left(rt - \frac{\sigma^2}{2} t + \sigma \, W_t \right). \label{eq:State}$$

Recall that $W_t - W_0 := W_t$ has variance t and see that S_t/S_0 is log-normally distributed with parameters $(r - \sigma^2/2)t$ and $\sigma t^{1/2}$, which means it is right-skewed with mean $\exp(rt)$ and variance $(\exp(\sigma^2 t) - 1) \cdot \exp(2rt)$.

Armed with Ito's Lemma, we have confirmed the folk-wisdom that log-returns from time t to t+s are (modeled as) normal random variables with mean $(r-\frac{\sigma^2}{2})s$ and variance σ^2s . One last minor point: if S_t/S_0 has a lognormal distribution with density f, then the density of S_t is simply

$$g(s) = S_0^{-1} f(s/S_0),$$

a scaled log-normal. This is helpful, e.g., for comparing the exact distribution of S_t to MC samples values of S_t , as we do below.

3.3 Monte Carlo simulation of the gBm model

As we showed above, there is an exact solution to the geometric Brownian motion SDE—namely, a continuous time random process characterized by independent, normal log-returns over disjoint time periods. Equivalently, given

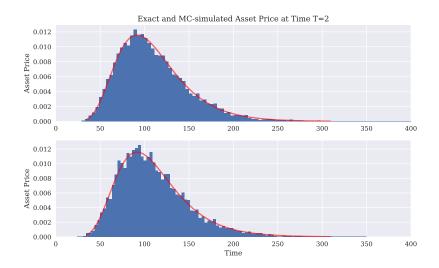
the asset value S_0 at time zero we know S_t/S_0 is log-normally distributed with the parameters given above.

Later, we will modify (complicate) the gBm model to take into account several real-life phenomena including, e.g., time-varying volatility. The augmented models do not necessarily have explicit solutions like the gBm model. Alternatively, we can simulate many times from the model to compute approximate solutions—this is called Monte Carlo. It's not needed for the gBm model, but we will illustrate it here in order to take advantage of the simplified setting of gBm before moving on to more complicated models.

Below we compare three methods for computing S_T at time T, given S_0 , σ , and r: the explicit solution due to Ito, a Monte Carlo (MC) simulation from the lognormal distribution, and a MC simulation of paths of asset values S_s for a discretization $s \in \{s_0 = 0, s_1, \dots, s_{M+1} = T\}$. All three provide the same answer (in a distributional sense) but the MC procedures contain some additional MC variability (noise) that decreases as the number of simulations increases.

```
import numpy as np
import numpy.random as npr
import matplotlib as mpl
from matplotlib.pylab import plt
import math
from scipy.stats import lognorm
plt.style.use('seaborn')
mpl.rcParams['font.family'] = 'serif'
S0 = 100
r = 0.05
sigma = 0.25
T = 2.0
# Exact density of ST based on qBm model
mu = np.exp((r - sigma**2/2)*T)
s = sigma * math.sqrt(T)
x = \text{np.linspace(lognorm.ppf}(0.001, s, scale = mu), lognorm.ppf(0.999, s, scale = mu), 1000)
# MC sampling of density of ST
I=10000
ST = S0 * np.exp((r-0.5*sigma**2)*T + sigma*math.sqrt(T)*npr.standard_normal(I))
# MC sampling of asset price path SO to ST at 50 equally-spaced timepoints
M = 50
dt = T / M
```

```
S = np.zeros((M+1, I))
S[0] = S0
for t in range(1,M+1):
    S[t]=S[t-1]*np.exp((r - 0.5*sigma**2)*dt + sigma*math.sqrt(dt)*npr.standard_normal
# Plots of asset Price distribution at T = 2
plt.figure(figsize = (10,6))
plt.subplot(211)
# histogram of MC samples from scaled log-normal
hist1 = plt.hist(ST,100,density = True)
# scaled log-normal density
dens = plt.plot(x*S0, (1/S0)*lognorm.pdf(x, s, scale = mu),
       'r-', lw=2, alpha=0.6)
plt.ylabel('Asset Price')
plt.title('Exact and MC-simulated Asset Price at Time T=2')
plt.xlim([0,400])
#plt.ylim([0,0.0014])
## (0.0, 400.0)
plt.subplot(212)
# histogram of path-wise MC samples from scaled log-normal over grid of 50 times
hist2 = plt.hist(S[-1],100,density = True)
dens = plt.plot(x*S0, (1/S0)*lognorm.pdf(x, s, scale = mu),
       'r-', lw=2, alpha=0.6)
plt.ylabel('Asset Price')
plt.xlabel('Time')
plt.xlim([0,400])
#plt.ylim([0,0.0014])
## (0.0, 400.0)
plt.show()
```



3.4 Off on a tangent: reducing MC variability

The difference between the theoretic (exact) values for the mean and standard deviation of S_T and the corresponding MC approximations (shown below) is due to MC error. The Law of Large Numbers (LLN) implies MC error declines to zero as the number of MC samples increases to infinity. In practice, using many more MC samples in order to reduce MC error has the trade-off of increasing computation time (and memory usage if storing those random variates in a vector). On the other hand, there are a few ways to reduce MC error by making more clever choices of MC samples.

```
import scipy.stats as scs

def print_stats(a2,a3):
    stat2 = scs.describe(a2)
    stat3 = scs.describe(a3)
    print('%14s %14s %14s %14s' % ('statistic', 'data set 1', 'data set 2', 'data set 3'))
    print(45 * '-')
    print('%14s %14s %14.3f %14.3f' % ('size', 'NA', stat2[0], stat3[0]))
    print('%14s %14s %14.3f %14.3f' % ('min', 'NA', stat2[1][0], stat3[1][0]))
    print('%14s %14s %14.3f %14.3f' % ('max', 'NA', stat2[1][1], stat3[1][1]))
    print('%14s %14.3f %14.3f %14.3f' % ('mean', S0*math.exp(r*T), stat2[2], stat3[2]))
    print('%14s %14.3f %14.3f %14.3f' % ('stdev', S0*math.sqrt((math.exp(sigma**2 * T)-1)*math.exp

print_stats(ST, S[-1])
```

##	statistic	data set 1	data set 2	data set 3
##				
##	size	NA	10000.000	10000.000
##	min	NA	29.258	24.067
##	max	NA	419.303	349.919
##	mean	110.517	109.880	109.751
##	stdev	40.327	40.134	39.021

The simplest way to reduce MC variability (besides increasing the number of samples) is to use anti-thetical variates. When sampling standard normal random variates this amounts to sampling z and using both (z,-z) as samples. To get 2I samples one only needs to actually compute I samples, the remaining I are the same in magnitude but with the opposite signs. This accomplishes exact mean-matching, i.e., $(2I)^{-1}\sum_{i=1}^{2I}z_i=0$, exactly the standard normal distribution mean.

Another method for reducing MC variability is second-moment matching. Suppose we generate antithetical samples $z=(z_1,\ldots,z_I)$. Let $z_i^\star:=z_i/s_z$ for $i=1,\ldots,I$ where s_z is the sample standard deviation of z. Now, z^\star has sample mean exactly zero and sample standard deviation exactly 1.

Further, a Box-Cox transformation may be used if the samples z have positive skew. (If they have negative skew, then the samples may be reflected about the maximum value to produce a set of positively-skewed values starting from zero.) After applying the Box-cox transformation, the resulting values y should be close to symmetric (closer to a normal distribution than the original variates) and a further standardization $z_i^{\star} = (y_i - \overline{y})/s_y$ may be used to transform the values to approximately standard normal.

The following simulation supports the use of standardized antithetic variates. By design, these had exactly zero mean and unit variance, but were slightly more likely to be skewed compared to vanilly MC samples. Box-Cox transformed variates did not perform better, and were more likely to display excess kurtosis than even vanilla MC variates. It is worth pointing out that antithetic variates may be produced sequentially while standardized variates requires storing all variates in memory, which may be a problem in some applications.

```
import scipy.stats as scs
import numpy as np
import numpy.random as npr

def bc_standardize(z):
    M = np.max(z)
    zM = M-z+0.0000001
    y = scs.boxcox(zM)
    m = np.mean(y[0])
    s = np.std(y[0], ddof=1)
```

```
z_{star} = (y[0]-m)/s
 return z_star
def at_standardize(z):
 s = np.std(z, ddof=1)
 z_star = z/s
 return z_star
kurtosis_vals = np.zeros((1000,8))
skew_vals = np.zeros_like(kurtosis_vals)
mean_vals = np.zeros_like(kurtosis_vals)
std_vals = np.zeros_like(kurtosis_vals)
def print_stats2():
 for i in range(1,1001):
   X = npr.standard_normal(10000)
   Z1 = npr.standard_normal(5000)
   Z2 = npr.standard_normal(5000)
   Z3 = -Z1
   Z4 = -Z2
   Z = np.concatenate((Z1,Z2))
   Y = np.concatenate((Z1,Z3))
   W = np.concatenate((Z2,Z4))
   Ystar = bc_standardize(Y)
   Wstar = bc_standardize(W)
   Yst = at_standardize(Y)
   Wst = at_standardize(W)
   stat1 = scs.describe(X, ddof = 1)
   stat2 = scs.describe(Z, ddof = 1)
   stat3 = scs.describe(Y, ddof = 1)
   stat4 = scs.describe(W, ddof = 1)
   stat5 = scs.describe(Ystar, ddof = 1)
   stat6 = scs.describe(Wstar, ddof = 1)
   stat7 = scs.describe(Yst, ddof = 1)
   stat8 = scs.describe(Wst, ddof = 1)
   mean_vals[i-1,:] = np.array([stat1[2], stat2[2], stat3[2], stat4[2], stat5[2], stat6[2], stat
   std_vals[i-1,:] = np.array([stat1[3], stat2[3], stat3[3], stat4[3], stat5[3], stat6[3], stat6
   kurtosis_vals[i-1,:] = np.array([stat1[4], stat2[4], stat3[4], stat4[4], stat5[4], stat6[4],
   skew_vals[i-1,:] = np.array([stat1[5], stat2[5], stat3[5], stat4[5], stat5[5], stat6[5], stat
 print('%14s %14.3f %14.3f %14.3f %14.3f %14.3f %14.3f %14.3f %14.3f \( '\mathbf{w}' \) ('mean mean', np.mean(mean')
 print('%14s %14.3f %14.3f
 print('%14s %14.3f %14.3f %14.3f %14.3f %14.3f %14.3f %14.3f %14.3f' % ('mean std', np.mean(std
 print('%14s %14.3f %14.3f %14.3f %14.3f %14.3f %14.3f %14.3f %14.3f' % ('std std', np.std(std_t
```

18CHAPTER 3. THE GEOMETRIC BROWNIAN MOTION MODEL OF ASSET VALUE AND MON

```
print('%14s %14.3f %14.3f %14.3f %14.3f %14.3f %14.3f %14.3f %14.3f' % ('mean kurtos print('%14s %14.3f %14
```

print_stats2()

##	statistic	data set 1	data set 2	data set 3	data set 4	data
##	mean mean	0.000	0.000	0.000	-0.000	
##	std mean	0.010	0.010	0.000	0.000	
##	mean std	0.999	1.000	1.001	1.000	
##	std std	0.014	0.015	0.021	0.020	
##	mean kurtosis	-0.001	-0.001	0.000	-0.000	-
##	std kurtosis	0.024	0.024	0.000	0.000	
##	mean skew	0.002	0.002	0.003	-0.001	
##	std skew	0.049	0.049	0.068	0.070	