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Nonparametric variational inference via score matching

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1 Introduction

Consider the posterior inference problem: we observe data $x_1, \dots, x_n \sim_{i.i.d.} \mathbb{P}_z$, a distribution with density $p(x|z)$. We place a prior $p(z)$ on $z \in \mathbb{R}^d$, and we wish to estimate the posterior density $p(z|x)$:

$$p(z|x) = \frac{p(x|z)p(z)}{p(x)}.$$

Typically $p(x)$ is intractable, so the posterior cannot be directly computed. Markov Chain Monte Carlo (MCMC) methods are a classical tool for this problem, but these methods can be infeasible for large datasets. *Variational inference* has emerged in recent decades as a powerful way to estimate a posterior in high-dimensional settings.

Variational inference posits a family $\mathcal{Q}$ for the posterior density and minimizes a measure of divergence between $q \in \mathcal{Q}$ and the true $p(z|x)$. It is common to choose q to maximize the evidence lower bound, $\mathcal{L}(q) := \mathbb{E}_q \log p(x, z) + H(q)$. This is equivalent to minimizing the KL divergence between $p(z|x)$ and q. A mean-field family, in which $q(z) = \prod_{i \leq d} q_i(z_i)$, is often posited for $\mathcal{Q}$. When the likelihood and prior are conjugate, this results in a simple coordinate ascent algorithm in which the updates are computable in closed form. In non-conjugate models, the Laplace method, which assumes a Gaussian family for $\mathcal{Q}$ and expands $\log p(x, z)$ to a quadratic term, is a popular approach; see Wang & Blei (2013) for more details.

In these and other standard methods, restrictive families are chosen for $\mathcal{Q}$ because of their computational convenience. But such methods have serious weaknesses. For instance, restricting $\mathcal{Q}$ to be a mean-field family means the posterior estimate will fail to capture dependence among the posterior coordinates and will underestimate the posterior variance; see Blei *et al.* (2017) for more discussion. The Gaussian form imposed on q in the Laplace method means the estimate will fail to capture multi-modality in the posterior.

We propose *nonparametric variational inference*, in which we assume that $\log q(z) \propto f(z)$ where $f(z) = \sum_{j=0}^{\infty} \gamma_j \phi_j(z)$, with ϕ_j being an orthogonal basis and γ_j being the terms we estimate. The method for estimating the basis coefficients γ is *score matching*, a technique from high-dimensional density estimation. Score matching seeks a density q to minimize a Fisher divergence, defined via

$$\mathcal{L}(q) = \mathbb{E}_p \|\nabla_z \log p(z) - \nabla_z \log q(z)\|_2^2. \tag{1}$$

In (1), ∇ denotes the gradient. This method is appealing for density estimation because it does not require estimation of a normalizing constant, which is typically intractable in high dimensions. By a simple argument using integration by parts, this objective simplifies to something that we can easily optimize in q; see Lemma 4.1. For exponential families, it further simplifies into a nice quadratic; see Lemma 4.2. It has been used in high dimensional density estimation where the normalizing constant is not computable, for example, in graphical models, c.f. Hyvarinen (2005); Janofsky (2015); Lin *et al.* (2016).

Review of recent literature Recent literature has developed methods to allow $\mathcal{Q}$ to be a richer family. For instance, the authors of Ranganath *et al.* (2016) use a dual representation of a divergence and a generative form of q to avoid the use of the density itself in the variational optimization. Their form of q is a multi-layer network; although it is still parametric, it is quite flexible. However, their algorithm requires optimization over both the parameters of q and the function in the dual representation. It would be ideal to have a method that does not require such a procedure. The authors of Gershman *et al.* (2012) propose "nonparametric variational inference," which uses a Gaussian-mixture form of q and the Delta method to approximate the model. The mixture of Gaussians for q resembles a kernel density estimator from nonparametric estimation. Moreover, this family for q, along with the Delta method, makes the optimization process fairly simple. The Gaussian-mixture family for q is also related to the "mixture of mean-field" family proposed by Bishop *et al.* (1998).

Notation For a real-valued function f, we write $f'(z)$ to mean the derivative of the function f with respect to the argument z. For a function $f : \mathbb{R}^d \to \mathbb{R}$, let $\triangle f = \sum_{i \le d} \partial^2 f(z)/\partial z_i^2$.

2 Score matching for posterior inference

Suppose we assume that $p(z|x) \propto e^{f(z|x)}$, i.e., the posterior has an exponential family form. Suppose further that $f(z|x) = f_x(z) = \gamma^\top \phi(z)$, where $\gamma \in \mathbb{R}^K$ and $\phi : \mathbb{R}^d \to \mathbb{R}^K$. Letting $A(z), k(z)$ be as defined in Lemma 4.2, the objective (1) simplifies to:

$$\int_z p(z|x) \left(\frac{1}{2} \gamma^\top A(z) \gamma + \gamma^\top k(z) \right) \, dz,$$

This has optimal solution

$$\begin{aligned} \hat{\gamma} &= \left(\int p(z|x) A(z) \, dz \right)^{-1} \int p(z|x) k(z) \, dz \\ &= \left(\int \frac{p(z,x)}{p(x)} A(z) \, dz \right)^{-1} \int \frac{p(z,x)}{p(x)} k(z) \, dz \\ &= \bar{A}^{-1} \bar{k}, \end{aligned} \tag{2}$$

where

$$\begin{aligned} \bar{A} &= \int p(z,x) A(z) \; dz \\ \bar{k} &= \int p(z,x) k(z) \; dz. \end{aligned}$$

That is, crucially, the solution (2) requires only integrals over $p(z,x)$, not over the uncomputable $p(z|x)$, since in the quadratic form, the $p(x)$ cancels out since the integrals are only over z. Now (2) is something we can calculate.

There is still an important difficulty: computing the integrals $\bar{A}, \bar{k}$ over the joint density. We propose importance sampling for this, and we note that one issue is that often $p(x|z)$ is extremely small if n is large, making importance sampling difficult, especially in high dimensional examples.

A more major issue is the following. Suppose that $\phi(z)$ is a polynomial; such an assumption is common in nonparametric density estimation. For instance, suppose $\phi(z) = 1 + z + z^2 + \ldots$. Then the first and second derivative functions, $A(z), k(z)$, will contain constant terms. This means that for example, $\bar{k}$ contains terms like $\int p(z,x) 1 \, dz$, which is precisely $p(x)$. In such an example, we would simply be estimating $p(x)$ via importance sampling. If we are going to do this, we might as well compute $p(z|x)$ directly. Such a form for ϕ is common, e.g., if the family is Gaussian; see Example 2.

However, we do implement this algorithm in some simple cases; see Nonparametric variational inference via score matching.

3 Alternative algorithms

We now propose an optimization that is related to the one proposed in (2) but circumvents some of the issues noted in Section 2. Our idea is related to the form of score matching used in Ranganath *et al.* (2016), and we now introduce some notation and background relevant to that paper. Let $\psi_p(z) = \frac{\partial \log p(z)}{\partial z}$. The authors of Ranganath *et al.* (2016) propose to optimimze following variational objective in q:

$$\sup_{f \in \mathcal{F}} |\mathbb{E}_{q(z)}(O^p_{LS} f)(z)| \tag{3}$$

where

$$O^p_{LS} f = \psi_p f + \nabla f. \tag{4}$$

As noted in Ranganath *et al.* (2016), the objective (3) is reasonable in the sense that it is zero when $q = p$, as we show in Lemma 3.1. Moreover, we can relate the objective (3) to a Stein discrepancy and then to a score matching objective resembling the one in (1), but now with the expectation taken over q instead of over the truth p. We state this in Lemma 3.2. It turns out that this objective has a close relationship to that in (1) and (3), as we state in Lemma 3.3. Proofs for these lemmas are provided in 5.1.

Lemma 3.1. *Suppose* $\lim_{z\to\infty} q(z) = \lim_{z\to-\infty} q(z) = 0$. *Then*

$$\mathbb{E}_{q(z)} \left(\psi_q f(z) + f'(z)\right) = 0$$

Lemma 3.2 (Equivalence of score-matching and Stein discrepancy)**.** *Let* $\mathcal{G}$ *be a class of functions of the form* $g(z) = \psi_p(z) f(z) + f'(z)$, *for* f *in some class of functions* $\mathcal{F}$. *Then*

$$\sup_{g \in \mathcal{G}} |\mathbb{E}_q g(z)| = \sup_{f \in \mathcal{F}} \mathbb{E}_{q(z)} (\psi_q(z) - \psi_p(z)) f(z) = \mathbb{E}_{q(z)} (\psi_q(z) - \psi_p(z))^2.$$

Lemma 3.2 motivates the use of the following, alternative score matching objective:

$$\mathcal{L}(q) = \mathbb{E}_q \|\nabla \log p - \nabla \log q\|_2^2. \tag{5}$$

Lemma 3.3. *Let* p, q *be densities that are positive everywhere. Let* $\mathcal{H}$ *be a class of functions, and let* $\mathcal{F}$ *be a class of functions of the form* $f(z) = \frac{p(z)}{q(z)} h(z)$ *for* $h \in \mathcal{H}$. *Then*

$$\sup_{f \in \mathcal{F}} |\mathbb{E}_q O^p_{LS} f| = \sup_{h \in \mathcal{H}} |\mathbb{E}_p O^q_{LS} h|$$

3.1 Kernel density estimation

Ranganath *et al.* (2016) optimize (3) directly, using an iterative, min-max style procedure. This optimization is nonconvex and is not guaranteed to reach some global optimum. We propose to instead directly optimize (5) via kernel density estimation and the reparametrization trick. We posit a sampling form for q; i.e., we generate Gaussian noise ξ, then feed it

through a (potentially complex) function f_ϕ to generate samples from z from q. That is, we draw

$$\begin{aligned} z_{0i} &\sim N(0, I_{d_0}) \\ z_i &= f_\phi(z_{0i}). \end{aligned} \tag{6}$$

We will let f_ϕ be a multilayer perceptron. Given this sampling form for q, we cannot write down an exact formula for $q(z)$; since this transformation of ξ is not invertible, we cannot use the change of variable density formula. Thus, it seems impossible to optimize (5) directly since it requires the form of q since we take $\nabla_z \log q(z)$. However, we propose to imitate the score matching method in Saremi *et al.* (2018) to get around this difficulty. This method is to approximate the form of q using an approximate kernel density estimator. For each data point z_i, we generate Gaussian samples $\xi_{i1}, \ldots, \xi_{im}$. Saremi *et al.* (2018) then use:

$$\nabla_\xi \log q(\xi) \approx \sum_{j=1}^{m} (z_i - \xi_{ij})$$

Note that a kernel density estimator using a Gaussian kernel would have the form:

$$q(z_i) \propto \sum_{j=1}^{m} e^{-\|z_i - \xi_{ij}\|_2^2 / 2\sigma^2}$$

So the gradient above is approximately the gradient of the log of this. We optimize the parameters of the likelihood using EM. So our full optimization is:

$$\max_\phi \sum_{i=1}^{n} \| \sum_{j=1}^{m} f_\phi(z_{0i}) - \xi_{ij} - \nabla_z \log p_\theta(x_i, f_\phi(z_{0i})) \| \leftarrow \text{ Posterior optimization}$$

$$\max_\theta \sum_{i=1}^{n} \log p_\theta(x_i, f(z_{0i})) \leftarrow \text{Likelihood optimization}$$

We carry this out in Tensorflow. Preliminary experiments on the MNIST data are available in the Github repository Variational autoencoder via score matching and ratio matching.

3.2 Ratio matching

We propose one other alternative. First, notice the following. For small h,

$$\nabla_z \log q(z) \approx \frac{\log q(z+h) - \log q(z)}{h} = \frac{1}{h} \log \frac{q(z+h)}{q(z)}$$

This is the basis of ratio-matching, which approximates score matching using the above representation of the derivative. Draw samples z_1, z_2 from a sampling form q, as in (6), and optimize

$$\mathbb{E}_q \| \log \frac{q(z_1)}{q(z_2)} - \log \frac{p(x, z_1)}{p(x, z_2)} \|_2^2. \tag{7}$$

This imitates the method of Hyvarinen (2007). To begin, we use a Gaussian form for q. Since we can sample from this, we use the reparametrization trick to estimate the integral in (7).

4 Basics of classical score matching

The objective (1) does not immediately appear to be something we can optimize in q, but it turns out that due to a simple argument using integration by parts, it actually is. We state this here and provide a one-dimensional proof; for the complete result, see Hyvarinen (2005).

Lemma 4.1 (The score matching objective can be optimized in q)**.** *Let* $\hat{q} = \operatorname{argmin}_q \mathcal{L}(q)$ *with* $\mathcal{L}(q)$ *as in* (1)*. Then*

$$\hat{q} = \operatorname*{argmin}_q \int_z p(z) \left(\frac{1}{2} \|\nabla \log q\|_2^2 + \triangle \log q \right) \, dz.$$

Proof. We provide the proof in one dimension only.

$$\mathcal{L}(q) \stackrel{c}{=} \int p(z) \left(\frac{\partial \log q(z)}{\partial z} \right)^2 - 2 \int p(z) \frac{\partial \log p(z)}{\partial z} \frac{\partial \log q(z)}{\partial z}.$$

Since $\frac{\partial \log p(z)}{\partial z} = p'(z)/p(z)$, the second term in the sum is $-2 \int p'(z) \frac{\partial \log q(z)}{\partial z}$. Using integration by parts,

$$\int p'(z) \frac{\partial \log q(z)}{\partial z} \stackrel{c}{=} - \int p(z) \frac{\partial^2 q(z)}{\partial z^2}.$$

□

Lemma 4.2 (Score matching for exponential families.)**.** *Let* $q(z) = \frac{e^{g(z)}}{\int e^{g(z)} dz}$*, and suppose* $g : \mathbb{R}^d \to \mathbb{R}$*, with* $g(z) = \gamma^\top \phi(z)$ *where* $\phi : \mathbb{R}^d \to \mathbb{R}^K$ *and* $\gamma \in \mathbb{R}^K$*. Let* $\mathcal{L}(q)$ *be as in* (1)*. Let* $\hat{\gamma} = \left(\mathbb{E}_{p(z)} A(z) \right)^{-1} \mathbb{E}_{p(z)} k(z)$*, where*

$$k(z) = \sum_{i \leq d} \frac{\partial^2 \phi(z)}{\partial z_i^2}$$

$$A(z) = \sum_{i \leq d} \frac{\partial \phi(z)}{\partial z_i} \frac{\partial \phi(z)}{\partial z_i}^\top.$$

Note $A \in \mathbb{R}^{K \times K}, k \in \mathbb{R}^K$*. Then*

$$\operatorname*{argmin}_q \mathcal{L}(q) \propto \exp\left(\hat{\gamma}^\top \phi(z) \right). \tag{8}$$

Proof. This follows directly from Lemma 4.1 and plugging in the form of the exponential family. We have

$$\frac{\partial \phi(z)}{\partial z_i} = \left(\frac{\partial \phi_1(z)}{\partial z_i}, \ldots, \frac{\partial \phi_K(z)}{\partial z_i} \right)^T$$

$$\frac{\partial^2 \phi(z)}{\partial z_i^2} = \left(\frac{\partial^2 \phi_1(z)}{\partial z_i^2}, \ldots, \frac{\partial^2 \phi_K(z)}{\partial z_i^2} \right)^T$$

Since $\log q(z) \propto g(z)$,

$$\begin{aligned}\frac{1}{2}\|\nabla \log q\|_2^2 + \triangle \log q &= \sum_{i\le d}\left(\frac{1}{2}\left(\frac{\partial g(z)}{\partial z_i}\right)^2 + \frac{\partial^2 g(z)}{\partial z_i^2}\right)\\ &= \sum_{i\le d}\left(\frac{1}{2}\left(\gamma^\top \frac{\partial \phi(z)}{\partial z_i}\right)^2 + \gamma^\top \frac{\partial^2 \phi(z)}{\partial z_i^2}\right)\\ &= \frac{1}{2}\gamma^\top\left(\sum_{i\le d}\frac{\partial \phi(z)}{\partial z_i}\frac{\partial \phi(z)}{\partial z_i}^\top\right)\gamma + \gamma^\top \sum_{i\le d}\frac{\partial^2 g(z)}{\partial z_i^2}\\ &= \frac{1}{2}\gamma^\top A(z)\gamma + \gamma^\top k(z).\end{aligned}$$

So $\mathcal{L}(q) \stackrel{c}{=} \frac{1}{2}\gamma^\top\left(\mathbb{E}_{p(z)}A(z)\right)\gamma + \gamma^\top\left(\mathbb{E}_{p(z)}k(z)\right)$, and the conclusion follows from optimizing this quadratic in γ. □

5 Appendix

5.1 Proofs

Proof of Lemma 3.1. First, by the product rule,

$$\mathbb{E}_{p(z)}\left(\psi_q(z)f(z) + f'(z)\right) = \int_z \frac{p(z)}{q(z)}\frac{\partial\left(q(z)f(z)\right)}{\partial z}\, dz$$

Now

$$\int \frac{q(z)}{q(z)}\frac{\partial(q(z)f(z))}{\partial z}\, dz = \int \frac{\partial}{\partial z}\left(q(z)f(z)\right)\, dz = q(\infty)f(\infty) - q(-\infty)f(-\infty) = 0.$$

□

Proof of Lemma 3.2. By Lemma 3.1, $\mathbb{E}_{p(z)}\psi_p(z)f(z) + f'(z) = 0$. So

$$\begin{aligned}\sup_{g\in\mathcal{G}}|\mathbb{E}_{p(z)}g(z)| &= \sup_{f\in\mathcal{F}}|\mathbb{E}_{p(z)}\left(\psi_q(z)f(z) + f'(z) - \psi_p(z)f(z) - f'(z)\right)|\\ &= \sup_{f\in\mathcal{F}}|\mathbb{E}_p(\psi_q - \psi_p)f|\end{aligned}$$

And this is maximized when $f(z) = \psi_q(z) - \psi_p(z)$. □

Proof of Lemma 3.3. This is clear if we use the representation in (**??**) and apply Lemma 3.2. That is,

$$\sup_{f\in\mathcal{F}}|\mathbb{E}_q O_{LS}^p f| = \sup_{f\in\mathcal{F}}\mathbb{E}_q(\psi_q - \psi_p)f = \sup_{h\in\mathcal{H}}\mathbb{E}_q\frac{p}{q}(\psi_q - \psi_p)h = \sup_{h\in\mathcal{H}}\mathbb{E}_p(\psi_q - \psi_p)h = \sup_{h\in\mathcal{H}}|\mathbb{E}_p O_{LS}^q h|$$

Alternatively (this is a sanity check):

$$\begin{aligned}
\sup_{f\in\mathcal{F}}|\mathbb{E}_q O^p_{LS} f| &= \sup_{f\in\mathcal{F}}|\mathbb{E}_q\left(\psi_p(z)f(z)+f'(z)\right)| \\
&= \sup_{h\in\mathcal{H}}\Big|\int q(z)\frac{p'(z)}{p(z)}\frac{p(z)}{q(z)}h(z)+\int q(z)\left(\frac{q(z)p'(z)-p(z)q'(z)}{q(z)^2}h(z)+\frac{p(z)}{q(z)}h'(z)\right)\Big| \\
&= \sup_{h\in\mathcal{H}}\Big|\int p'(z)h(z)+\int p'(z)h(z)-\int\frac{q'(z)}{q(z)}p(z)h(z)+\int p(z)h'(z)\Big| \\
&= \sup_{h\in\mathcal{H}}\Big|\int 2\left(p'(z)h(z)+p(z)h'(z)\right)-\int p(z)h'(z)-\int\frac{q'(z)}{q(z)}p(z)h(z)\Big| \\
&= \sup_{h\in\mathcal{H}}|\mathbb{E}_p\left(\psi_q(z)h(z)+h'(z)\right)|
\end{aligned}$$

since $p'(z)h(z)+p'(z)h(z)=\frac{\partial(p(z)h(z))}{\partial z}$, which has integral zero by Lemma 3.1. □

5.2 Exploring score matching with $\mathbb{E}_q$

The following lemma shows that the score-matching objective (5) decomposes into two components: a component matching q to p, and a component restricting q to be reasonably smooth. Thus the score-matching divergence decomposes in a similar manner as the KL divergence.

Lemma 5.1. *Suppose* $q(z)=\exp\left(f(z)-\Psi\right)$ *where* Ψ *is the normalizing constant. Let* $\mathcal{L}(q)=\mathbb{E}_q\|\nabla_z\log p-\nabla_z\log q\|_2^2$. *Then*

$$\mathcal{L}(q)=^c\frac{1}{2}\mathbb{E}_q\|\nabla_z\log p(z,x)\|_2^2+\mathbb{E}_q\Delta\log p(z,x)+\mathbb{E}_q\|\nabla_z f(z)\|_2^2$$

Proof. We provide the proof in one dimension only.

$$\mathcal{L}(q)=\int q(z)\left(\frac{\partial}{\partial z}\log p\right)^2-2\int q(z)\frac{q'(z)}{q(z)}\frac{p'(z)}{p(z)}+\int q(z)\left(\frac{\partial}{\partial z}\log q(z)\right)^2$$

The third term is $\mathbb{E}_q f'(z)^2$. And for the middle term, using integration by parts,

$$\int q(z)\frac{q'(z)}{q(z)}\frac{p'(z)}{p(z)}=\int q'(z)\frac{\partial}{\partial z}\log p(z)=^c-\int q(z)\frac{\partial^2}{\partial z^2}\log p(z)$$

□

The following lemma shows that when we assume $q(z)$ is a Gaussian density, the score matching objective as in (5) reduces to the Laplace method as in Wang & Blei (2013). In retrospect, this is obvious by Lemma 3.1; since we assume a Gaussian form for the model, as long as we are optimizing over $\mathcal{Q}$ that includes Gaussian densities, we should obtain "the right thing." But this is nice as a sanity check.

Lemma 5.2. *Let $z \in \mathbb{R}^d$. Let $f(z) := \log p(z)$ and suppose for any z_0,*

$$f(z) \approx f(z_0) + \nabla f(z_0)^T (z - z_0) + \frac{1}{2}(z - z_0)^T \nabla^2 f(z_0)(z - z_0)$$

. Let $z^* \in \operatorname{argmax} f(z)$. Let $\mathcal{Q}$ be $N(\lambda, V)$ densisties. Let $\hat{q} = \operatorname{argmin}_{q \in \mathcal{Q}} \mathbb{E}_q \|\nabla_z \log p - \nabla_z \log q\|_2^2$. Then $\hat{q}$ is the $N(\hat{\lambda}, \hat{V})$ density with

$$\hat{\lambda} = z^*$$
$$\hat{V} = -\nabla^2 f(z^*)$$

Proof. Let z^* be a mode of f, i.e., $\nabla_z f(z^*) = 0$. Then

$$f(z) \approx f(z_0) + \frac{1}{2}(z - z^*)^T \nabla^2 f(z^*)(z - z^*)$$

So

$$\nabla_z f(z) \approx \nabla^2 f(z^*)(z - z^*)$$

Let q be the $N(\lambda, V)$ density where $\lambda \in \mathbb{R}^d$ and $V \in \mathbb{R}^{d \times d}$; λ and V are the parameters to be optimized. Now $\nabla_z \log q(z) = -V^{-1}(z - \lambda)$. Now $z = V^{1/2} z_0 + \lambda$, where $z_0 \sim N(0, I_p)$. So

$$\begin{aligned}
\mathcal{L}(q) &= \mathbb{E}_q \|\nabla_z \log q(z) - \nabla_z \log p(z)\|_2^2 \\
&= \mathbb{E}_{z_0 \sim N(0, I_p)} \|-V^{-1/2} z_0 - \nabla^2 f(z^*)(V^{1/2} z_0 + \lambda - z^*)\|_2^2 \\
&= \mathbb{E}_{z_0} \|\left(-V^{-1/2} - \nabla^2 f(z^*) V^{1/2}\right) z_0 - \nabla^2 f(z^*)(\lambda - z^*)\|_2^2 \\
&= \mathbb{E}_{z_0} \|\left(-V^{-1/2} - \nabla^2 f(z^*) V^{1/2}\right) z_0\|_2^2 + \|\nabla^2 f(z^*)(\lambda - z^*)\|_2^2 \\
&= \|V^{-1/2} + \nabla^2 f(z^*) V^{1/2}\|_F^2 + \|\nabla^2 f(z^*)(\lambda - z^*)\|_2^2
\end{aligned}$$

Optimizing in λ yields:

$$\hat{\lambda} = z^*$$

Let $M = \nabla^2 f(z^*)$. Let's do one dimension to check:

$$v^{-1/2} + m v^{1/2} = \frac{1 + mv}{\sqrt{v}}$$

And

$$\left(\frac{1 + mv}{\sqrt{v}}\right)^2 = \frac{1 + 2mv + m^2 v^2}{v} = \frac{1}{v} + 2m + m^2 v$$

Now

$$\frac{\partial}{\partial v}\left(\frac{1}{v} + 2m + m^2 v\right) = -\frac{1}{v^2} + m^2$$

Setting this equal to zero yields:

$$V^2 = M^{-2} \Rightarrow V = \pm M^{-1}$$

which is exactly the Laplace method solution. □

Example 1 (Lemma 5.1 in the Gaussian case)**.** *Consider the objective* (5)*. In the case where q is Gaussian, as in, Lemma 5.2, we can see that only optimizing the first two terms of the score-matching objective would lead to a terribly sharp q (with zero variance). The final term (the penalty on the smoothness of q) forces more smoothness. Let the setting be as in Lemma 5.2: q is the $N(\lambda, V)$ and the Taylor expansion for $\log p(x, z)$ holds. Now,*

$$\begin{aligned}\frac{1}{2}\mathbb{E}_q\|\nabla_z \log p(z,x)\|_2^2+\mathbb{E}_q\Delta \log p(z,x) &= \frac{1}{2}\mathbb{E}_q(z-z^*)^T\left(\nabla^2 f(z^*)\right)^2(z-z^*) - \mathbb{E}_q\nabla^2 f(z^*) \\ &=^c \frac{1}{2}tr\left(V^T\left(\nabla^2 f(z^*)\right)^2 V\right) + (\lambda - z^*)^T\left(\nabla^2 f(z^*)\right)^2(\lambda - z^*)\end{aligned}$$

which would be optimized by setting $\hat{\lambda} = z^*$ and $\hat{V} = 0$. But we have the penalty:

$$\mathbb{E}_q\|\nabla \log q\|_2^2 = tr(V^{-1})$$

Due to this penalty, we end up with a reasonable q.

5.3 Examples of score matching for variational inference

In this section, we provide further discussion of the potential problems with using score matching as in (1) for posterior inference. We first show how the optimization would look if q is restricted to be Gaussian.

Example 2 (Score-matching with $\mathbb{E}_p$ for posterior inference when q has Gaussian form)**.** *Suppose q has form $N(\mu_x, \Sigma_x)$ where $\mu_x \in \mathbb{R}^d, \Sigma_x \in \mathbb{R}^{d\times d}$. Let our prior $p(z)$ be the $N(0, I_d)$ density. Note that we could have $d \gg n$. We have $q(z) \propto e^{g(z)}$ where*

$$g(z) = \gamma'\phi(z)$$

where $K = 2d$ and

$$\begin{aligned}\gamma &= \left(\Sigma^{-1}, \Sigma^{-1}\mu\right)^T \\ \phi(z) &= \left(-\frac{1}{2}zz', z\right)^T\end{aligned}$$

So (for $d = 1$, to keep it simple):

$$\begin{aligned}\frac{\partial\phi(z)}{\partial z} &= (-z, 1)^T \\ \frac{\partial^2\phi(z)}{\partial z^2} &= (1, 0)^T\end{aligned}$$

We have $A(z) \in \mathbb{R}^{2d\times 2d}$. Let e.g. z^2 indicate $(z_1^2, \ldots, z_d^2)$. We have

$$\begin{aligned}A(z) &= \begin{pmatrix} diag(z^2) & diag(-z) \\ diag(-z) & diag(1)\end{pmatrix} \text{ and} \\ k(z) &= (rep(-1, d), rep(0, d))^T\end{aligned}$$

Each submatrix is in $\mathbb{R}^{d\times d}$. We parameterize γ via B; it is some multi-layer non-linear function with many parameters B. Our objective, written as a sum, is

$$\mathbb{E}_{p(z|x)}\left(\sum_{j\le d}\gamma_{1j}^2 z_j^2 - \sum_{j\le d}\gamma_{2j}\gamma_{1j}z_j + \sum_{j\le d}\gamma_{2j}^2 - \sum_{j\le d}\gamma_{1j}\right)$$

Note that as noted in **?** *and Lin et al. (2016), there are closed-form solutions of μ, Σ. To see it, note that if $q(z)$ is $N(\mu, \Sigma)$,*

$$\log q(z) \propto \frac{-(z-\mu)'\Sigma^{-1}(z-\mu)}{2}$$

So the score-matching objective is

$$\frac{1}{2}\|\nabla_z \log q(z)\|_2^2 + \Delta_z \log q(z) = \frac{1}{2}\|\Sigma^{-1}(z-\mu)\|_2^2 + tr(\Sigma^{-1})$$

We can directly obtain:

$$\hat{\mu} = \mathbb{E}_{p(z|x)} z$$
$$\hat{\Sigma}_i = \mathbb{E}_{p(z|x)}(z-\hat{\mu})(z-\hat{\mu})'$$

While this is estimable for density estimation, it requires the posterior for us. Why does this happen when we can still not require $p(x)$ if we compute the exponential family parameter? Notice that e.g. in the simple $d = 1$ case, the quadratic we'd obtain for score-matching is:

$$\gamma'\mathbb{E}_{p(z|x)}\begin{pmatrix} z^2 & z \\ z & 1\end{pmatrix}\gamma - \gamma'\mathbb{E}_{p(z|x)}\begin{pmatrix}1\\0\end{pmatrix}$$

Optimizing this allows us to remove the $p(x)$, but notice that then, we optimize in γ $\gamma'\bar{A}\gamma' - \gamma'\bar{k}$, the usual thing, where

$$\bar{k} = \begin{pmatrix} p(x) \\ 0\end{pmatrix}$$

Now again we can approximate $p(x)$ via importance sampling, but we do have to approximate it either way.

5.4 Score matching for a bounded density

For a bounded density, score matching has a slightly different objective. See Janofsky (2015) for more details.

$$k_1(z) = \sum_{i\le d} 2(2z_i - 1)z_i(1-z_i)\frac{\partial\phi(z)}{\partial z_i}$$
$$k_2(z) = \sum_{i\le d} z_i^2(1-z_i)^2\frac{\partial^2\phi(z)}{\partial z_i^2}$$
$$k(z) = k_1(z) - k_2(z)$$
$$A(z) = \sum_{i\le d}\frac{\partial\phi(z)}{\partial z_i}\frac{\partial\phi(z)}{\partial z_i}' z_i^2(1-z_i)^2$$

For a bounded density (the second line is for an exponential family), the objective is:

$$\begin{aligned} h_\gamma(z) &= \sum_{i \le d} \frac{1}{2} \left(\frac{\partial g(z)}{\partial z_i} z_i(1-z_i) \right)^2 - 2(2z_i - 1) z_i (1-z_i) \frac{\partial g(z)}{\partial z_i} + z_i^2 (1-z_i)^2 \frac{\partial^2 g(z)}{\partial z_i^2} \\ &= \sum_{i \le d} \left(\gamma' \frac{\partial \phi(z)}{\partial z_i} z_i(1-z_i) \right)^2 - 2(2z_i - 1) z_i (1-z_i) \gamma' \frac{\partial \phi(z)}{\partial z_i} + z_i^2 (1-z_i)^2 \gamma' \frac{\partial^2 \phi(z)}{\partial z_i^2} \end{aligned}$$

In one dimension, and for $z \in [0,1]$, this simplifies to the following. Let $\phi : [0,1] \to \mathbb{R}^K$.

$$\begin{aligned} h_\gamma(z) &= \frac{1}{2} \left(\frac{\partial g(z)}{\partial z} z(1-z) \right)^2 - 2(2z-1) z(1-z) \frac{\partial g(z)}{\partial z} + z(1-z) \frac{\partial^2 g(z)}{\partial z^2} \\ &= \frac{1}{2} z^2 (1-z)^2 \gamma' A(z) \gamma - 2(2z-1) z(1-z) \gamma' k_1(z) + z^2 (1-z)^2 \gamma' k_2(z) \end{aligned}$$

where

$$\begin{aligned} k_1(z) &= \left(\frac{\partial \phi_1(z)}{\partial z}, \ldots, \frac{\partial \phi_K(z)}{\partial z} \right)' \\ k_2(z) &= \left(\frac{\partial^2 \phi_1(z)}{\partial z^2}, \ldots, \frac{\partial^2 \phi_K(z)}{\partial z^2} \right)' \\ k(z) &= k_1(z) - k_2(z) \\ A(z) &= k_1(z) k_1(z)' \end{aligned}$$

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