

Contents

- [PREAMBLE](#)
- [QUESTION 1: COMMENTING](#)
- [QUESTION 2: PLOTTING](#)
- [2\(a\) PLOT RESULT](#)
- [2\(b\) PLOT RESULT](#)
- [2\(c\) PLOT RESULT](#)
- [QUESTION 3: COMPLEX ROOTS](#)
- [3\(a\) WRITE FUNCTION IN SEPARATE FILE \(TEMPLATE PROVIDED\)](#)
- [3\(b\) ANSWER QUESTION](#)
- [3\(c\) OUTPUT RESULTS](#)

PREAMBLE

DO NOT REMOVE THE LINE BELOW

```
clear;
```

QUESTION 1: COMMENTING

=====

```
% Copy and comment every line of the following MATLAB script. Say what
% each line is doing in your comment. Explain each MATLAB line by using
% no more than one comment line, as done in the first line below. Run and
% publish the script:

a=zeros(1,10) % Generate and print a 1x10 row vector of zeros
b=ones(4,2) % Generate and print a 4x2 matrix of ones
c= size(b); % Gets size of matrix b and returns the dimensions in a vector
abs([-2.2 , 3]) % Calculates the absolute value of each element in the array [-2.2, 3]
floor(1.6) % Rounds down the value of 1.6 to the nearest integer
d=[1:-2.5:-9]; % Creates a row vector starting at 1, with steps of 2.5, until 9
f=d(2); g=sin(pi/2); % Extracts the second element of d and computes sine of pi/2 (sine(pi/2) = 1)
K=[1.4, 2.3; 5.1, 7.8]; % Creates a 2x2 matrix with specified values
m=K(1,2); % Extracts first row of K matrix
n=K(:,2); % Extracts second column of K matrix
p=K(1,2); % Extracts element in first row and second column of K
comp = 10+40i; % Creates a complex number with real part 10 and imaginary part 40
real(comp) % Extracts the real part of the complex number comp
imag(comp) % Extracts the imaginary part of the complex number comp
abs(comp) % Calculates the absolute value (magnitude) of the complex number comp
angle(comp) % Calculates the phase angel (in radians) of the complex number comp
disp('haha, MATLAB is fun'); % Displays the string "haha, MATLAB is fun" in th ecommand window
3^2 % Calculates 3 raised to the power of 2
4==4 % Checks if 4 is equal to 4
[2==8 3~=5] % Checks if 2 is equal to 8, and if 3 is not equal to 5, returns [false true]
x=[1:3:10]; % Creates a row vector starting at 1, with steps of 3, until 10
y=[5 9 6 8]; % Creates a row vector with the specified values
tic; pause(0.2); toc % Measures the elapsed time for a pause of 0.2 seconds
q = zeros(10,1); % Creates a 10 x 1 column vector filled with zeros
for ii = 1:10 % Starts a loop from ii = 1 to 10
    q(ii) = ii^2; % Assigns the square of ii to the ii-th element of q
end % Ends the loop
figure(129); % Creates a figure window with the ID 129
stem(x,y) % Creates a stem plot of x versus y
hold on; % Holds the current plot so that the new plots can be added
plot(x,y, 'k', 'linewidth', 2) % Plot x versus y with a black line of width 2
plot(x,y, '+r', 'markersize', 20); % Plot x versus y with red plus markers of size 20
hold off; % Releases the hold on the current plot
xlabel('Horizontal Axis') % Labels the x-axis as "Horizontal Axis"
ylabel('Vertical Axis') % Labels the y-axis as "Vertical Axis"
```

```
a =
     0     0     0     0     0     0     0     0     0     0
```

b =

```
1    1
1    1
1    1
1    1
```

ans =

```
2.2000    3.0000
```

ans =

```
1
```

ans =

```
10
```

ans =

```
40
```

ans =

```
41.2311
```

ans =

```
1.3258
```

haha, MATLAB is fun

ans =

```
9
```

ans =

```
logical
```

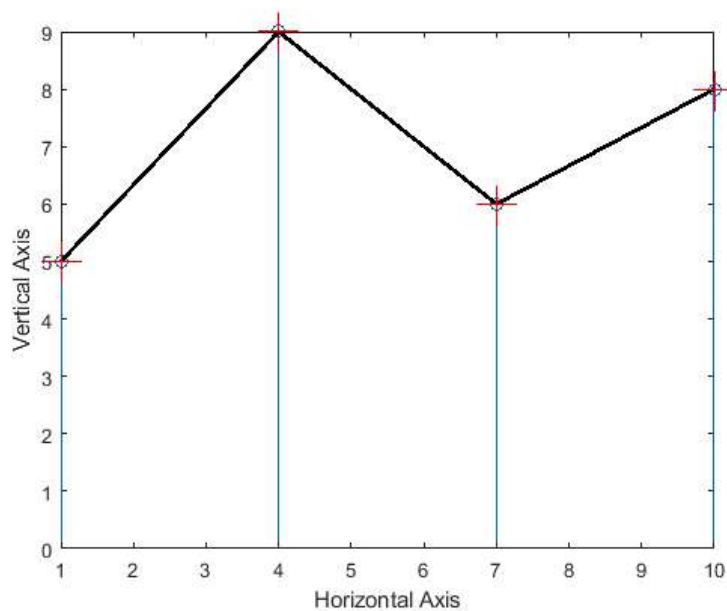
```
1
```

ans =

```
1×2 logical array
```

```
0    1
```

Elapsed time is 0.211086 seconds.



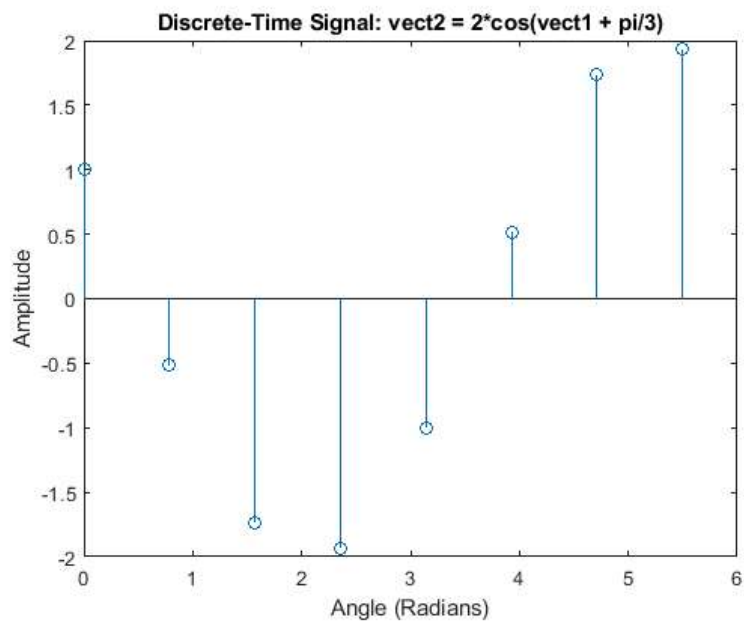
QUESTION 2: PLOTTING

=====

2(a) PLOT RESULT

```
% Given
vect1 = [0 pi/4 2*pi/4 3*pi/4 4*pi/4 5*pi/4 6*pi/4 7*pi/4]; % Angle values
vect2 = 2*cos(vect1 + pi/3); % Discrete-time signal

% plot using stem
stem(vect1, vect2) % Plot vect2 as discrete-time signal
xlabel('Angle (Radians)') % Label x-axis
ylabel('Amplitude') % Label y-axis
title('Discrete-Time Signal: vect2 = 2*cos(vect1 + pi/3)') % Title of the plot
```



2(b) PLOT RESULT

```
% Given
theta = 0 : pi/20 : 3*pi; % Angle ranges 0 to 3*pi with step size pi/20
y = cos(theta.^2); % Discrete-time signal

% plot using stem
```

```

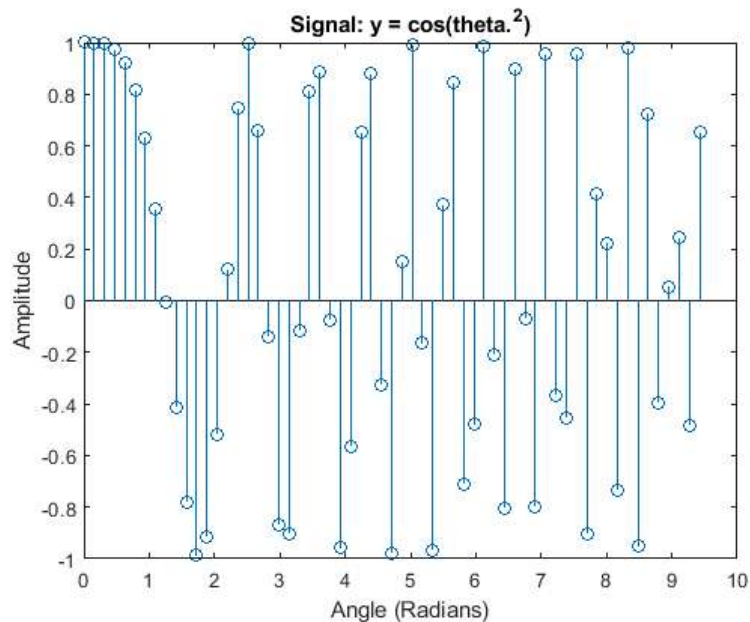
stem(theta, y)
xlabel('Angle (Radians)')
ylabel('Amplitude')
title('Signal: y = cos(theta.^2)')

```

```

% Plot y versus theta
% Label x-axis
% Label y-axis
% Title of the plot

```



2(c) PLOT RESULT

```

% Given
t = -4 : 0.01 : 4;
y = 2*cos((pi/2)*t) + 3*cos(2*pi*t);

```

```

% Time ranges between -4 <= t <= 4, with step size 0.01
% Signal equation

```

```

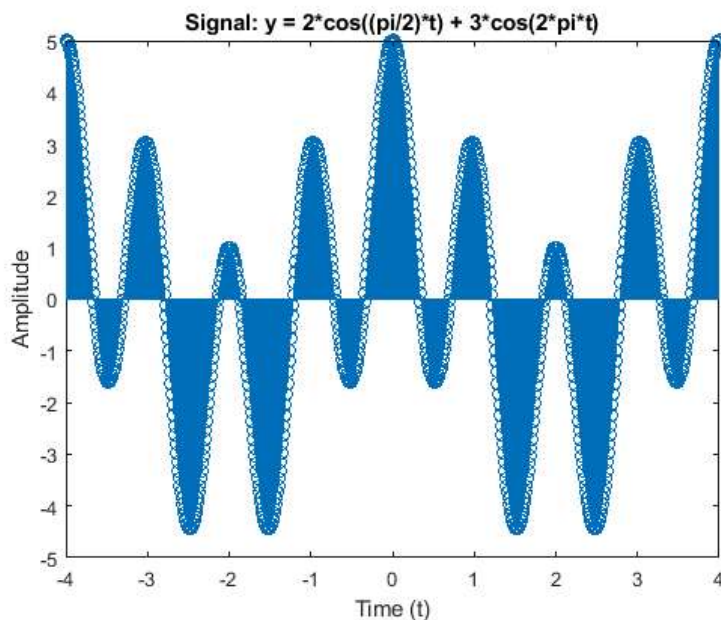
% plot using stem
stem(t, y)
xlabel('Time (t)')
ylabel('Amplitude')
title('Signal: y = 2*cos((pi/2)*t) + 3*cos(2*pi*t)')

```

```

% Plot y versus t
% Label x-axis
% Label y-axis
% Title of the plot

```



QUESTION 3: COMPLEX ROOTS

=====

3(a) WRITE FUNCTION IN SEPARATE FILE (TEMPLATE PROVIDED)

```
type('myroots.m')
```

```
function r = myroots(n, a)
% myroots: Find all the nth roots of the complex number a
%
% Input Args:
%   n: a positive integer specifying the nth roots
%   a: a complex number whose nth roots are to be returned
%
% Output:
%   r: 1xn vector containing all the nth roots of a

% Converting to polar
A = abs(a); % Magnitude of coomplex number
phi = angle(a); % Argument (phase) of a

% nth root
roots = zeros(1,n); % Initializes vector to stores the roots
for k = 0 : n-1; % loops through n times

    % Formula for nth root
    r(k+1) = (A^(1/n)) * exp(1i * (phi + 2*pi*k)/n); % r(k+1) is nth root (MATLAB starts from 1)
end

end
```

3(b) ANSWER QUESTION

```
% The command "help myroots" gives an explanation of what the root does,
% what inputs are needed, and what the outputs are. Essentially, it has the
% same description as the comments at the top in the myroots.m file. The
% purpose of this command would help to define a function does, what the
% proper inputs for the function are, and how the function outputs the
% information. This would be useful for debugging in otder to figure out if
% there is a problem with the way prior code is inputing information, and
% how it is handling the output after the function use.
```

3(c) OUTPUT RESULTS

```
% Calculate 5th root of -1
a1 = -1; % Defines a = -1, or defines what we are finding the root of
root1 = 5; % Defines the root number
root_a1 = myroots(root1,a1); % Creates the function to calculate the root
disp(root_a1); % Displays the root

% Calculates the 11th root of 2048j
a2 = 2048 * 1i; % Defines a = 2048j, since i is imaginary
root2 = 11; % Defines the root number
root_a2 = myroots(root2,a2); % Calls the function to calcluate the root
disp(root_a2); % Displays the root
```

Columns 1 through 4

```
0.8090 + 0.5878i -0.3090 + 0.9511i -1.0000 + 0.0000i -0.3090 - 0.9511i
```

Column 5

```
0.8090 - 0.5878i
```

Columns 1 through 4

```
1.9796 + 0.2846i 1.5115 + 1.3097i 0.5635 + 1.9190i -0.5635 + 1.9190i
```

Columns 5 through 8

```
-1.5115 + 1.3097i -1.9796 + 0.2846i -1.8193 - 0.8308i -1.0813 - 1.6825i
```

Columns 9 through 11

```
-0.0000 - 2.0000i 1.0813 - 1.6825i 1.8193 - 0.8308i
```