

# ON DOUBLE-NEGATION SHEAVES IN THE COPRESHEAF TOPOS ON A COFREE COMONOID

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This note fixes a polynomial functor  $p \in \mathbf{Poly}$  and studies the copresheaf topos  $\mathcal{C}_p := \mathcal{T}_p\text{-Set}$ ; we fix  $\Omega \in \mathcal{C}_p$  the subobject classifier (given by the copresheaf of sieves on  $\mathcal{T}_p^{\text{op}}$ ).

## 1. PRESHEAVES

1.1.  **$\mathcal{C}_p$  as a topos of dynamical systems.** A presheaf  $F \in \mathcal{T}_p$  consists of the following data (subject to no restrictions):

- (1) For each  $p$ -tree  $i \in \mathcal{T}_p$ , a set  $F(i)$ .
- (2) For each morphism  $f : i \rightarrow j$  in  $\mathcal{T}_p$  corresponding with an inclusion of a subtree at height one, a function  $F(f) : F(i) \rightarrow F(j)$ .

This corresponds with a “dynamical system” with “positions with future knowledge” corresponding with  $p$ -trees, states in each position corresponding with each set  $F(i)$ , and “transition functions” between the states in these positions where one moves to a possible “next state” according to the futures predicted by the  $p$ -tree structure.<sup>1</sup> I will henceforth refer to a presheaf  $F \in \mathcal{T}_p$  as a *p-dynamical system*.

1.2. **Subsystems.** Note that a morphism of  $p$ -dynamical systems  $F \rightarrow G$  is precisely a map  $F(i) \rightarrow G(i)$  from the  $i$ -states of  $F$  to the  $i$ -states of  $G$  for each  $i \in \mathcal{T}_p$ , compatible with the transition functions in  $F$  and  $G$ . A morphism is monic iff each of the constituent morphisms are monic; that is, a subobject corresponds with a subset of the states which is preserved under the transition functions.

As with any topos, the set of subobjects on a  $p$ -dynamical system  $\text{Sub}(F)$  comes equipped with a Heyting algebra structure; the join and meet are given by union and intersection, and the implication  $A \Rightarrow B$  is given by **FILL IN THE RELEVANT CHARACTERIZATION**. In particular, the *negation*  $\neg A = (A \Rightarrow 0)$  is given by the largest dynamical system contained in the set-theoretic complement of  $A$ , and hence  $\neg \neq A$  is given by the largest dynamical system whose complement is the same as  $A$ .

As with any topos,  $\neg\neg : \Omega \rightarrow \Omega$  is a Lawvere-Tierney topology on  $\mathcal{C}_p$ . We will seek to characterize the sheaves with respect to this topology, for which it will be useful to name the following dynamical (sub)systems.

### Example 1.1:

Let  $s \in F(i)$  be a state in a dynamical system, and let  $i = i_0 \rightarrow i_1 \rightarrow \dots$  be an  $\mathbb{N}$ -indexed sequence of composable morphisms. Define  $I := (i_n)_{n \in \mathbb{N}}$ .<sup>a</sup> Then, we may define the dynamical system  $U_{s,I}$ , called the *future of  $s$  along  $I$*  by

$$U_{s,I}(j) = \begin{cases} 1 & j \in I, \\ 0 & \text{otherwise.} \end{cases}$$

The transition functions are canonically defined, and there is a unique monic  $U_{s,I} \rightarrow F$  sending  $U_{s,I}(i)$  to  $S$ . We may combine these to yield a subsystem of *futures of  $S$* :

$$U_s(j) := \bigcup_{I \in (\mathcal{T}_p)^{\mathbb{N}} \text{ s.t. } I_0 = i} U_{s,I} = \begin{cases} 1 & \exists \text{ morphism } i \rightarrow j, \\ 0 & \text{otherwise.} \end{cases}$$

**Lemma 1.2.** *Any dynamical system  $F$  is generated by the associated subsystems  $U_s$ ; that is,*

$$F = \bigcup_{s \in \coprod_i F(i)} U_s.$$

<sup>1</sup>This sentence makes no sense.

Similarly, for a  $\mathbb{Z}$ -indexed sequence  $I$  of composable morphisms with  $I_0 = i$  and such that each morphism having codomain  $i$  has image containing  $s$ , there is a system  $V_{s,I}$  called the *eternity of  $s$  along  $I$* , defined by

$$V_s(j) = \begin{cases} 1 & j \in I \\ 0 & \text{otherwise.} \end{cases}$$

and we may combine these into the *eternities of  $s$* :

$$V_s(j) := \bigcup_I V_{s,I} = \begin{cases} 1 & \exists \text{ morphism } i \rightarrow j \text{ or } \exists \text{ morphism } f : j \rightarrow i \text{ s.t. } s \in \text{im } f, \\ 0 & \text{otherwise.} \end{cases}$$

There

<sup>a</sup>The notation here is confusing, and should be fixed.

It is perhaps troublesome that  $U_s$  is defined in reference to a particular state of a dynamical system, as the systems themselves depend only on the position that the state resides in. We can simply define  $U_i$  for position  $i$  by the above description; these are contained in the following example.

**Example 1.3:**

The *all-ones system*  $1_p$  has  $1_p(i) = \{i\}$  for all  $i \in \mathcal{F}_p$ , with transition functions given by the unique endomorphism of 1. Note that there are unique monics  $U_i \rightarrow V_i \rightarrow 1_p$ .

Consider mentioning that they generate all subobjects under union—they always do, but this time it's particularly simple.

## 2. SHEAVES

**2.1. Density.** The following lemma is well known:

**Lemma 2.1.** *In a presheaf topos, a subobject  $A \subset C$  is  $\neg\neg$ -dense iff all nonzero subobjects  $0 \subsetneq B \subset C$  intersect  $A$ .*

This powers the following (easy) proposition, which shows that dense subsystems correspond intuitively with *attainable win conditions*:

**Proposition 2.2.** *A subsystem  $F \subset G$  is dense iff there is no state  $s \in F(i)$  and sequence of morphisms  $i = i_0 \xrightarrow{f_0} i_1 \xrightarrow{f_1} i_2 \xrightarrow{f_2} \cdots$  such that  $f_n(s) \notin G$  for all  $n \in \mathbb{N}$ .*

*Proof.* Suppose there is such a state  $s$  and sequence  $I$ ; then, the subobject  $U_{s,I} \subset G$  is nonzero and does not intersect  $F$ , so it is not dense.

Now suppose that no such sequence exists, and suppose  $B \subset G$  is a nonzero subobject containing a state  $s \in B(i)$ . Then, picking some sequence  $I = i_0 \rightarrow i_1 \rightarrow \cdots$ , we have  $B \cap F \supset U_{s,I} \cap F \neq 0$ , so  $F$  is dense.  $\square$

The following dense monics will be useful.

**Example 2.3:**

Let  $F$  be a  $p$ -dynamical system. Let  $I$  be the sequence  $i_0 \xrightarrow{f_1} i_1 \xrightarrow{f_2} \cdots$ , and let  $I_{\geq n}$  be the suffix  $i_n \rightarrow i_{n+1} \rightarrow \cdots$ . Then, there is a factorization

$$U_{f_n(s), I_{\geq n}} \rightarrow U_{s,I} \rightarrow F.$$

It quickly follows from Proposition 2.2 that the monic  $U_{f_n(s), I_{\geq n}} \rightarrow U_{s,I}$  is dense.

Similarly, for  $I$  a  $\mathbb{Z}$ -diagram and  $I_{\geq 0}$  its truncation to  $\mathbb{N}$ , the monic  $U_{s, I_{\geq 0}} \rightarrow V_{s,I}$  is monic.<sup>a</sup>

<sup>a</sup>The latter subsumes the former.

One characterization of the closure of  $F \subset G$  is the largest closed subobject of  $G$  containing  $F$  as a dense subobject.<sup>2</sup> Using this and Proposition 2.2, we have the following lemma.

<sup>2</sup>Is this true?

**Lemma 2.4.** *Let  $F \subset G$  be a  $p$ -dynamical subsystem. Then, we may compute the closure of  $F$  as **CHARACTERIZATION GOES HERE**.*

$$\neg\neg F$$

**2.2. Sheaves as ancient systems which remember history.** We say that a  $p$ -dynamical system  $F$  is *ancient* if all transition functions  $F(i) \rightarrow F(j)$  are epic, and say that  $F$  *remembers history* if  $F(i) \rightarrow F(j)$  are monic.

**Proposition 2.5.** *A  $p$ -dynamical system  $F$  is a  $\neg\neg$ -separated presheaf iff it remembers history. A  $p$ -dynamical system  $F$  is a  $\neg\neg$ -sheaf iff it is ancient and remembers history.*

*Proof.* We first verify the statement for separated presheaves. We have to verify that,  $F$  remembers history iff for all dense monics  $A \rightarrowtail E$ , the induced map

$$\mathrm{Hom}_{\mathcal{C}_p}(E, F) \rightarrow \mathrm{Hom}_{\mathcal{C}_p}(A, F)$$

is monic.

First suppose that  $F$  does not remember history, and there are two distinct states  $s, t \in F(i)$  and a morphism  $f : i \rightarrow j$  such that  $f(s) = f(t)$ . Then, since  $U_s = U_t$  as (dense) subobjects of  $U_{f(s)} = U_{f(t)}$ , we have two distinct extensions

$$\begin{array}{ccc} U_s & \xrightarrow{\quad} & F \\ & \searrow & \uparrow \\ & U_{f(s)=f(t)} & \xrightarrow{\quad} F \\ & \nearrow & \uparrow \\ U_t & \xrightarrow{\quad} & F \end{array}$$

so that  $F$  is not separated.

Conversely, suppose that  $F$  does remember history, and suppose we have two morphisms  $\varphi, \varphi' : E \rightarrow F$  which each restrict to  $A$  identically. At position  $j$  possessing morphism  $f : j \rightarrow i$ , this is represented by commuting parallel morphisms

$$\begin{array}{ccc} E(i) & \longrightarrow & F(i) \\ \uparrow & & \uparrow \\ E(j) & \rightrightarrows & F(j) \end{array}$$

which must coincide since the morphism  $F(j) \rightarrowtail F(i)$  is monic.<sup>3</sup>

For  $\neg\neg$ -sheaves, it suffices to prove that the morphism  $\mathrm{Hom}_{\mathcal{C}_p}(E, F) \rightarrow \mathrm{Hom}_{\mathcal{C}_p}(A, F)$  is epic iff  $F$  is ancient. This will work by a similar argument; if  $F$  is not ancient, we may pick a state  $s \in \coprod_i F(i)$  and morphism  $f : j \rightarrow i$  such that  $F(j)$  is nonempty (say, containing  $t \in F(j)$ ) and such that  $s \notin \mathrm{im} f$ , and consider the embedding  $U_s \rightarrowtail F$ . Then,  $U_s$  is isomorphic as a  $p$ -dynamical system to  $U_{f(t)} \subset U_t$ , but there is no morphism  $U_t \rightarrow F$  extending the given morphism.

Conversely, if  $F$  is ancient, we probably have to assume AoC, and then just choose preimages to extend a morphism  $A \rightarrow F$  to  $E$ .

□

<sup>3</sup>This needs to be corrected later; it isn't necessarily the case that any  $E(i)$  is totally subsumed by  $A$ . Instead, we have to make some argument using colimits, which I don't particularly want to do..