# Problem Set 4: DSGE

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### Exercise 1

$$\frac{1}{e^{z_t}K_t^{\alpha} - Ae^{z_t}K_t^{\alpha}} = \beta E_t \frac{\alpha e^{z_{t+1}} (Ae^{z_t}K_t^{\alpha})^{\alpha - 1}}{e^{z_{t+1}} (Ae^{z_t}K_t^{\alpha})^{\alpha} - Ae^{z_{t+1}} (Ae^{z_t}K_t^{\alpha})^{\alpha}}$$

$$= \beta E_t \frac{\alpha (Ae^{z_t}K_t^{\alpha})^{-1}}{1 - A}$$

$$\frac{1}{e^{z_t}K_t^{\alpha}(1 - A)} = \beta E_t \frac{\alpha (Ae^{z_t}K_t^{\alpha})^{-1}}{1 - A}$$

$$A = \beta \alpha$$

Therefore,  $K_{t+1} = \beta \alpha e^{z_t} K_t^{\alpha}$ 

#### Exercise 2

1. 
$$c_t = (1 - \tau)[w_t l_t (r_t - \delta) k_t] + k_t + T_t - k_{t+1}$$

2. 
$$\frac{1}{c_t} = \beta E_t \{ \frac{1}{c_{t+1}} [(r_{t+1} - \delta)(1 - \tau) + 1] \}$$

3. 
$$\frac{a}{1-l_t} = \frac{1}{c_t} w_t (1-\tau)$$

4. 
$$r_t = \alpha e^{z_t} K_t^{\alpha - 1} L_t^{1 - \alpha}$$

5. 
$$w_t = (1 - \alpha)e^{z_t}K_t^{\alpha}L_t^{-\alpha}$$

6. 
$$\tau[w_t l_t + (r_t - \delta)k_t] = T_t$$

7. 
$$z_t = (1 - \rho_z)\bar{z} + \rho_z z_{t-1} + \epsilon_t^z$$
;  $\epsilon_t^z \sim i.i.d.(0, \sigma_z^2)$ 

### Exercise 3

1. 
$$c_t = (1 - \tau)[w_t l_t (r_t - \delta) k_t] + k_t + T_t - k_{t+1}$$

2. 
$$c_t^{-\gamma} = \beta E_t \{ c_{t+1}^{-\gamma} [(r_{t+1} - \delta)(1 - \tau) + 1] \}$$

3. 
$$\frac{a}{1-l_t} = c_t^{-\gamma} w_t (1-\tau)$$

4. 
$$r_t = \alpha e^{z_t} K_t^{\alpha - 1} L_t^{1 - \alpha}$$

5. 
$$w_t = (1 - \alpha)e^{z_t}K_t^{\alpha}L_t^{-\alpha}$$

6. 
$$\tau[w_t l_t + (r_t - \delta)k_t] = T_t$$

7. 
$$z_t = (1 - \rho_z)\bar{z} + \rho_z z_{t-1} + \epsilon_t^z; \ \epsilon_t^z \sim i.i.d.(0, \sigma_z^2)$$

### Exercise 4

1. 
$$c_t = (1 - \tau)[w_t l_t (r_t - \delta) k_t] + k_t + T_t - k_{t+1}$$

2. 
$$c_t^{-\gamma} = \beta E_t \{ c_{t+1}^{-\gamma} [(r_{t+1} - \delta)(1 - \tau) + 1] \}$$

3. 
$$a(1-l_t)^{-\xi} = c_t^{-\gamma} w_t (1-\tau)$$

4. 
$$r_t = \alpha e^{z_t} K_t^{\eta - 1} [\alpha K_t^{\eta} + (1 - \alpha) L_t^{\eta}]^{\frac{1 - n}{n}}$$

5. 
$$w_t = (1 - \alpha)e^{z_t}L_t^{\eta - 1}[\alpha K_t^{\eta} + (1 - \alpha)L_t^{\eta}]^{\frac{1 - n}{n}}$$

6. 
$$\tau[w_t l_t + (r_t - \delta)k_t] = T_t$$

7. 
$$z_t = (1 - \rho_z)\bar{z} + \rho_z z_{t-1} + \epsilon_t^z$$
;  $\epsilon_t^z \sim i.i.d.(0, \sigma_z^2)$ 

## Exercise 5

1. 
$$c_t = (1 - \tau)[w_t(r_t - \delta)k_t] + k_t + T_t - k_{t+1}$$

2. 
$$c_t^{-\gamma} = \beta E_t \{ c_{t+1}^{-\gamma} [(r_{t+1} - \delta)(1 - \tau) + 1] \}$$

3. 
$$r_t = \alpha K_t^{\alpha - 1} (e^{z_t})^{(1 - \alpha)}$$

4. 
$$w_t = (1 - \alpha) K_t^{\alpha} (e^{z_t})^{-\alpha}$$

5. 
$$\tau[w_t + (r_t - \delta)k_t] = T_t$$

6. 
$$z_t = (1 - \rho_z)\bar{z} + \rho_z z_{t-1} + \epsilon_t^z$$
;  $\epsilon_t^z \sim i.i.d.(0, \sigma_z^2)$ 

Steady-state versions of these equations are given by

1. 
$$\bar{c} = (1 - \tau)[\bar{w}(\bar{r} - \delta)\bar{k}] + \bar{T}$$

2. 
$$\bar{c}^{-\gamma} = \beta E_t \{ \bar{c}^{-\gamma} [(\bar{r} - \delta)(1 - \tau) + 1] \}$$

3. 
$$\bar{r} = \alpha \bar{k}^{\alpha - 1} (e^{\bar{z}})^{(1 - \alpha)}$$

4. 
$$\bar{w} = (1 - \alpha)\bar{k}^{\alpha}(e^{\bar{z}})^{-\alpha}$$

5. 
$$\tau[\bar{w} + (\bar{r} - \delta)\bar{k}] = \bar{T}$$

6. 
$$0 = \epsilon_t^{\bar{z}}; \ \epsilon_t^z \sim i.i.d.(0, \sigma_z^2)$$

The algebraic solution of steady state capital as a function of  $\bar{z}$  is

$$\bar{k} = \left[ \frac{1}{(e^{\bar{z}})^{1-\alpha}} \left( \frac{1-\beta}{\alpha\beta(1-\tau)} + \frac{\delta}{\alpha} \right) \right]^{\frac{1}{\alpha-1}}$$

### Exercise 6

1. 
$$c_t = (1 - \tau)[w_t(r_t - \delta)k_t] + k_t + T_t - k_{t+1}$$

2. 
$$c_t^{-\gamma} = \beta E_t \{ c_{t+1}^{-\gamma} [(r_{t+1} - \delta)(1 - \tau) + 1] \}$$

3. 
$$a(1-l_t)^{-\xi} = c^{-\gamma}w_t(1-\tau)$$

4. 
$$r_t = \alpha K_t^{\alpha - 1} (L_t e^{z_t})^{(1 - \alpha)}$$

5. 
$$w_t = (1 - \alpha) K_t^{\alpha} (L_t e^{z_t})^{-\alpha}$$

6. 
$$\tau[w_t l_t + (r_t - \delta)k_t] = T_t$$

7. 
$$z_t = (1 - \rho_z)\bar{z} + \rho_z z_{t-1} + \epsilon_t^z; \ \epsilon_t^z \sim i.i.d.(0, \sigma_z^2)$$

Steady-state versions of these equations are given by

1. 
$$\bar{c} = (1 - \tau)[\bar{w}(\bar{r} - \delta)\bar{k}] + \bar{T}$$

2. 
$$\bar{c}^{-\gamma} = \beta E_t \{ \bar{c}^{-\gamma} [(\bar{r} - \delta)(1 - \tau) + 1] \}$$

3. 
$$a(1-\bar{l})^{-\xi} = c^{-\gamma}\bar{w}(1-\tau)$$

4. 
$$\bar{r} = \alpha \bar{k}^{\alpha - 1} (\bar{l}1 - e^{\bar{z}})^{(1 - \alpha)}$$

5. 
$$\bar{w} = (1 - \alpha)\bar{k}^{\alpha}(\bar{l}e^{\bar{z}})^{-\alpha}$$

6. 
$$\tau[\bar{w}\bar{l} + (\bar{r} - \delta)\bar{k}] = \bar{T}$$

7. 
$$0 = \epsilon_t^{\bar{z}}; \ \epsilon_t^z \sim i.i.d.(0, \sigma_z^2)$$