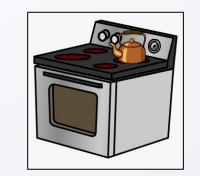
#### **CSE 417 Autumn 2025**

#### Lecture 16: Dynamic Programming - Sequences

Nathan Brunelle

## Oven Allocation (aka subset sum)



Suppose we had an oven and a set of n items to bake

Each item  $b_i = (t_i, p_i)$  takes  $t_i$  minutes to bake, and can be sold for a profit of  $p_i$  dollars

We have M total minutes available to bake

What should we bake to maximize our profit?

$$M = 30$$

Best solution:  $b_1$ ,  $b_2$ ,  $b_3$ 

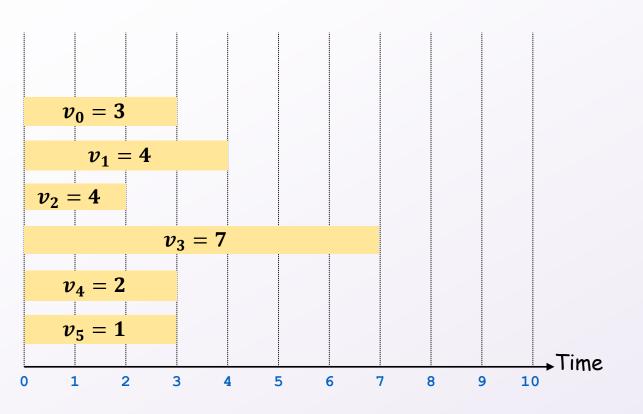
Uses 27 minutes

Earns \$41

$$b_0 = (23,20), b_1 = (10,15), b_2 = (12,18), b_3 = (5,8)$$

#### Oven Allocation - Full Recursive Structure

$$oven(i,m) = \begin{cases} \max(oven(i-1,m), oven(i-1,m-t_i) + p_i) & \text{if } t_i \leq m \\ oven(i-1,m) & \text{otherwise} \end{cases}$$



#### **Choices:**

Include/exclude the last item Including only allowable if  $t_i \leq m$ 

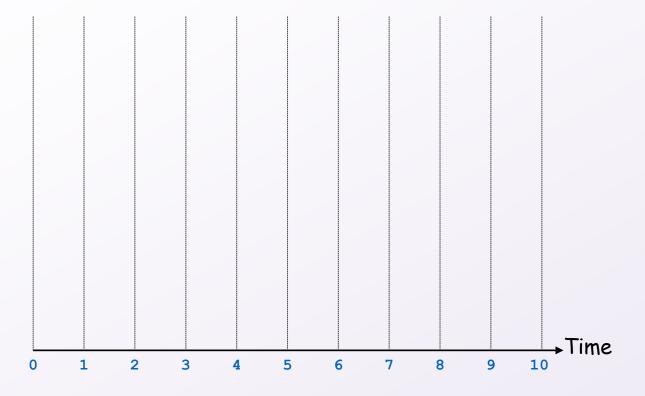
#### If we exclude:

subproblem is defined by item i-1 AND by m

If  $t_i \le m$  and we include: subproblem is defined by item i-1AND by  $m-t_i$ 

#### Oven Allocation - Base Case

$$oven(i,m) = \begin{cases} \max(oven(i-1,m), oven(i-1,m-t_i) + p_i) & \text{if } t_i \leq m \\ oven(i-1,m) & \text{otherwise} \end{cases}$$



Base case: no items left oven(-1, m) = 0

## Oven Allocation - Memory Structure

$$oven(i,m) = \begin{cases} \max(oven(i-1,m), oven(i-1,m-t_i) + p_i) & \text{if } t_i \leq m \\ oven(i-1,m) & \text{otherwise} \end{cases}$$

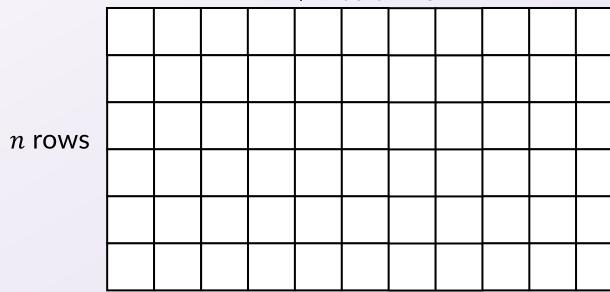
Two parameters necessary to identify each subproblem:

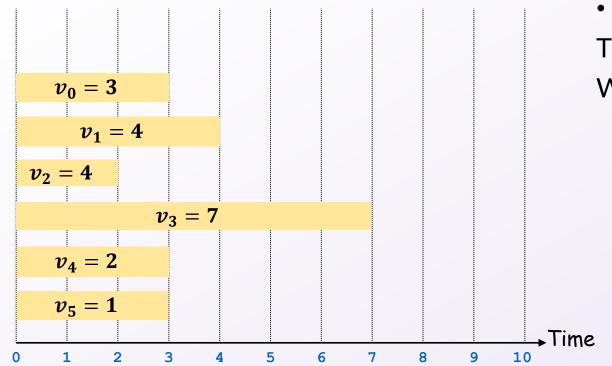
- The current item *i*
- The amount of time available m

There are n values of i and M + 1 values of m (0 to M)

We will use a 2-dimensional array that is  $n \times M$ 

$$M + 1$$
 columns





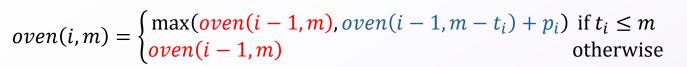
#### **Oven Allocation Top-Down**

```
mem = an array of n rows and M + 1 columns full of -1s
def oven(i, m):
      if mem[i][m] > -1:
             return mem[i][m]
      if i == -1:
             return 0
      solution = oven(i-1,m)
      if(t_i \leq m):
              solution = max(solution, oven(i-1,m-t_i)+p_i)
       mem[i][m] = solution
      return solution
```

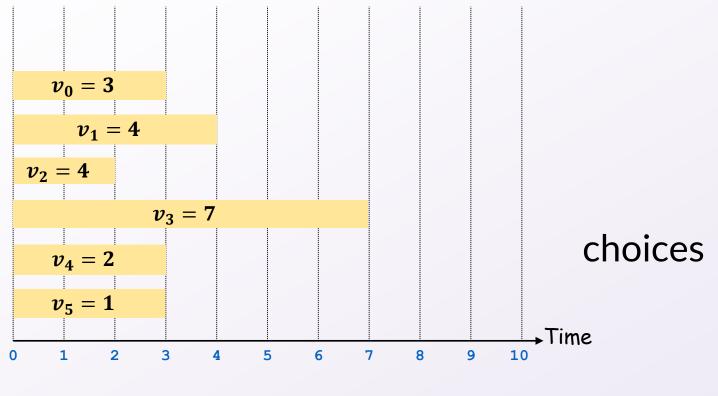
### Oven Allocation Top-Down with choices

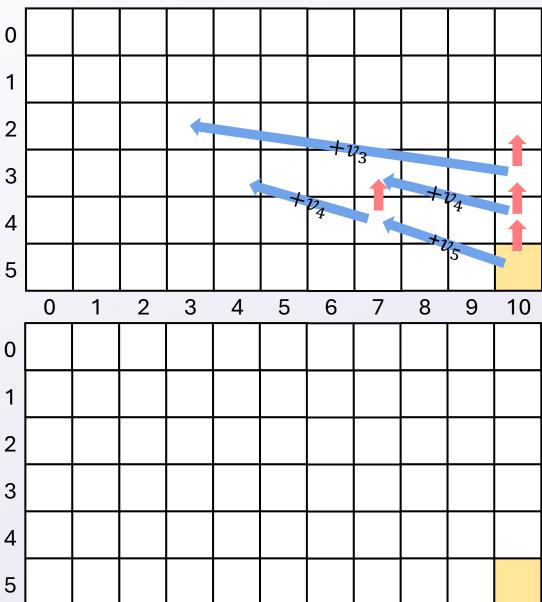
```
mem = an array of n rows and M + 1 columns full of -1s
choices = an array of n rows and M + 1 columns full of booleans
def oven(i, m):
        if mem[i][m] > -1:
                return mem[i][m]
        if i == -1:
                 return 0
        solution = oven(i-1,m)
        choices[i][m] = False
        if(t_i \le m and solution< oven(i-1,m-t_i)+p_i):
                 solution = oven(i-1,m-t_i)+p_i
                 choices[i][m] = True
        mem[i][m] = solution
        return solution
```

## **Oven Allocation Example**

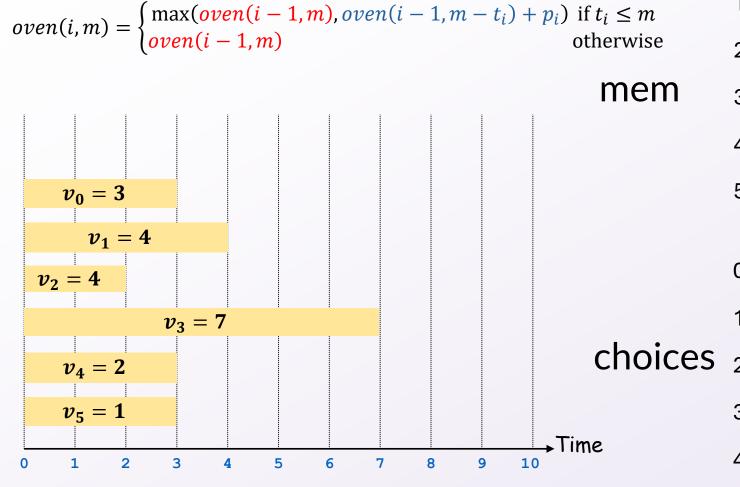








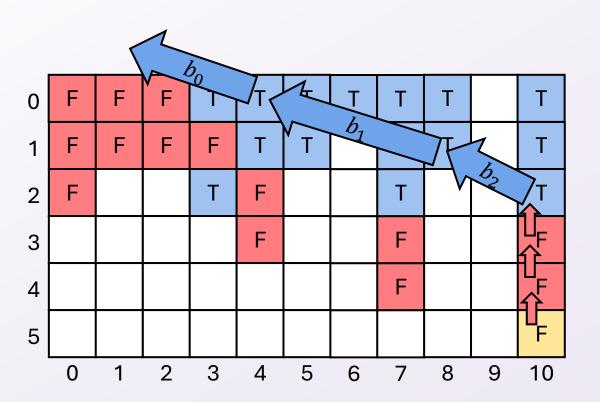
Oven Allocation Example - complete



	Compiete											
0	0	0	0	3	3	3	3	3	3		3	
1	0	0	0	3	4	4		7	7		7	
2	0			4	1			8			11	
3					4		_+ı	38	4		11	
4						+	$v_4$	8	*	4	11	
5										5	11	
	0	1	2	3	4	5	6	7	8	9	10	
0	П	F	H	Т	Τ	Т	Т	Т	Т		Т	
1	F	F	F	F	Т	Т		Т	Т		Т	
2	F			T	F			Т			T	
3					F			F			F	
4								ш			ш	
5											F	

# **Using Choices**

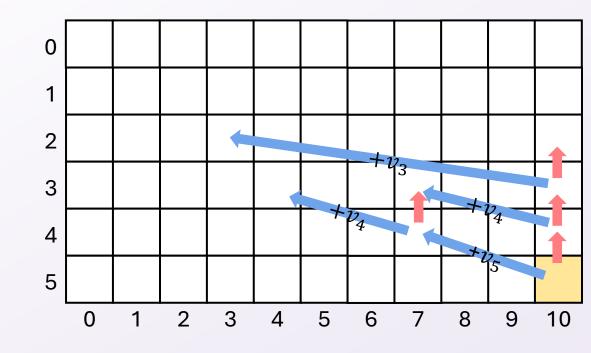
```
Def findChoices(choices, n, m):
  items = \{\}
  time = m
  for(item = n; item >= 0; item--):
    if (choices[item][time]):
       items.add(item)
       time -= t_{\text{item}}
  return items
```



## Selecting an order

$$oven(i,m) = \begin{cases} \max(oven(i-1,m), oven(i-1,m-t_i) + p_i) & \text{if } t_i \leq m \\ oven(i-1,m) & \text{otherwise} \end{cases}$$

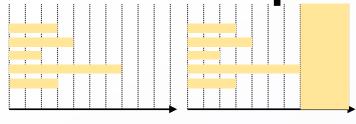
mem



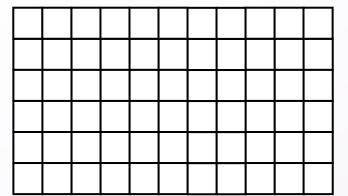
Each subproblem needs only cells in the row above it, and to its left.

Sufficient to fill in top to bottom, left to right

# Four Steps - Oven Allocation Step 4



1. Formulate the answer with a recursive structure What are the options for the last choice? For each such option, what does the subproblem look like? How do we use it?



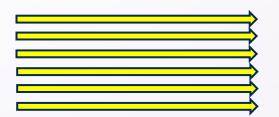
2. Choose a memory structure.

Figure out the possible values of all parameters in the recursive calls.

How many subproblems (options for last choice) are there?

What are the parameters needed to identify each?

How many different values could there be per parameter?



3. Specify an order of evaluation. (Optional)

Want to guarantee that the necessary subproblem solutions are in memory when you need them.

With this step: a "Bottom-up" (iterative) algorithm

Without this step: a "Top-down" (recursive) algorithm

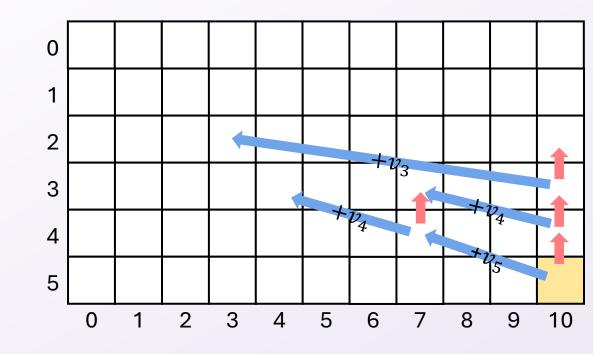
4. See if there's a way to save space (Optional)

Is it possible to reuse some memory locations?

## Can we save space?

$$oven(i,m) = \begin{cases} \max(oven(i-1,m), oven(i-1,m-t_i) + p_i) & \text{if } t_i \leq m \\ oven(i-1,m) & \text{otherwise} \end{cases}$$

mem



Each subproblem needs only cells in the row above it

Two rows are enough: the current one, and the one with subproblem solutions

# **String Similarity**

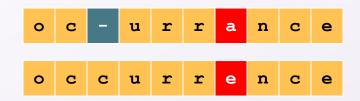
#### How similar are two strings?

6 mismatches, 1 gap

ocurrance

occurrence

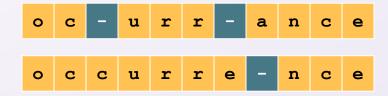
Clearly a better matching



1 mismatch, 1 gap

Maybe a better matching

depends on cost of gaps vs mismatches



0 mismatches, 3 gaps

#### **Edit Distance**

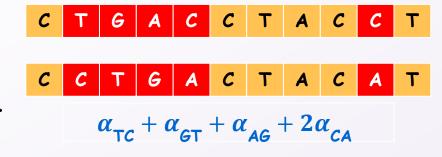
#### **Applications:**

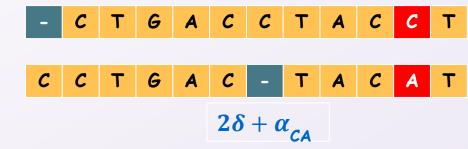
Basis for Unix diff.

Speech recognition.

Computational biology.

autocorrect





Edit distance: [Levenshtein 1966, Needleman-Wunsch 1970]

Gap penalty  $\delta$ ; mismatch penalty  $\alpha_{pq}$  if symbol p is replaced by symbol q.

**Cost** = gap penalties + mismatch penalties.

## Sequence Alignment

#### **Sequence Alignment:**

Given: Two strings  $X = x_1 x_2 \dots x_m$  and  $Y = y_1 y_2 \dots y_n$ 

**Find:** "Alignment" of **X** and **Y** of minimum edit cost.

**Defn:** An alignment M of X and Y is a set of ordered pairs  $x_i - y_j$  s.t. each symbol of X and Y occurs in at most one pair with no "crossing pairs".

$$cost(M) = \sum_{(x_i, y_j) \in M} \alpha_{x_i y_j} + \sum_{i: x_i \text{ unmatched}} \delta + \sum_{j: y_j \text{ unmatched}} \delta$$
mismatch
gap

Note: if 
$$x_i = y_j$$
 then  $\alpha_{x_i y_i} = 0$ 

# Example: CTACCG vs TACATG

$$M = \{x_2 - y_1, x_3 - y_2, x_4 - y_3, x_5 - y_4, x_6 - y_6\}$$

#### **Edit Distance - Four Steps, Step 1**

1. Formulate the answer with a recursive structure What are the options for the last choice? For each such option, what does the subproblem look like? How do we use it?

2. Choose a memory structure.

Figure out the possible values of all parameters in the recursive calls.

How many subproblems (options for last choice) are there?

What are the parameters needed to identify each?

How many different values could there be per parameter?

3. Specify an order of evaluation. (Optional)

Want to guarantee that the necessary subproblem solutions are in memory when you need them.

With this step: a "Bottom-up" (iterative) algorithm

Without this step: a "Top-down" (recursive) algorithm

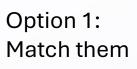
4. See if there's a way to save space (Optional) Is it possible to reuse some memory locations?

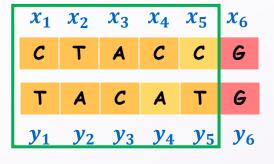
## **Step 1: Identify Recursive Structure**

 $x_1$   $x_2$   $x_3$   $x_4$   $x_5$   $x_6$  $y_2$   $y_3$   $y_4$   $y_5$   $y_6$ 

 $j \cdot \delta$  if i = 0

Consider the last two indices  $x_i$  and  $y_i$ Options for what to do with them:





We use up one index from x and y

$$OPT(i-1, j-1) + \alpha_{x_i y_j}$$

 $i \cdot \delta$  if j = 0 $\min \begin{cases} OPT(i-1,j-1) + \alpha_{x_iy_j} \\ OPT(i-1,j) + \delta \\ OPT(i,j-1) + \delta \end{cases}$  $OPT(i,j) = \left\{ \right.$ 

We use up one index from x only

 $x_4$   $x_5$   $x_6$ 

 $\chi_3$ 

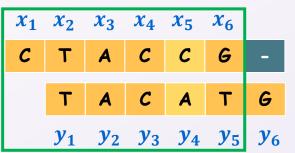
Accrue a gap penalty

$$OPT(i-1,j) + \delta$$

Option 2: Don't match  $x_i$ 

$$y_1$$
  $y_2$   $y_3$   $y_4$   $y_5$   $y_6$ 

Don't match  $y_i$ 

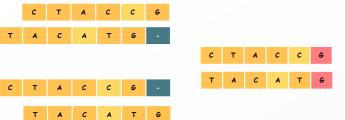


We use up one index from y only

Accrue a gap penalty

$$OPT(i, j-1) + \delta$$

## **Edit Distance – Four Steps, Step 2**



1. Formulate the answer with a recursive structure What are the options for the last choice? For each such option, what does the subproblem look like? How do we use it?

2. Choose a memory structure.

Figure out the possible values of all parameters in the recursive calls. How many subproblems (options for last choice) are there? What are the parameters needed to identify each? How many different values could there be per parameter?

3. Specify an order of evaluation. (Optional) Want to guarantee that the necessary subproblem solutions are in memory when you need them.

With this step: a "Bottom-up" (iterative) algorithm Without this step: a "Top-down" (recursive) algorithm

4. See if there's a way to save space (Optional) Is it possible to reuse some memory locations?

### **Step 2: Identify Memory Structure**

$$OPT(i,j) = \begin{cases} j \cdot \delta & \text{if } i = 0\\ i \cdot \delta & \text{if } j = 0 \end{cases}$$

$$OPT(i-1,j-1) + \alpha_{x_i y_j}$$

$$OPT(i-1,j) + \delta$$

$$OPT(i,j-1) + \delta$$

How many parameters?

2

What does each represent?

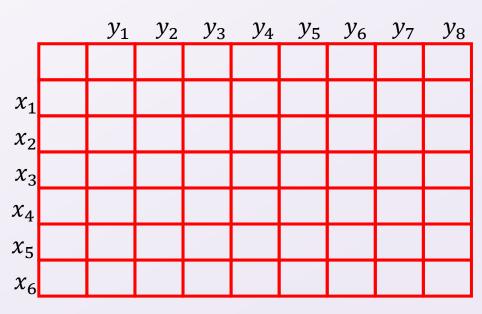
The number of items in each sequence

How many different values?

Length of sequence *x* for *i* 

Length of sequence y for j

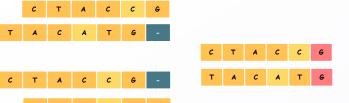
 $n \cdot m$  overall

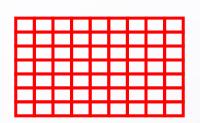


## **Top-Down Sequence Alignment**

```
align(i, j):
           if OPT[i][j] not blank: // Check if we've solved this already
                       return OPT[i][j]
           if i \cdot j == 0: // Check if this is a base case
                       solution = (i + j) \cdot \delta
                       OPT[i][j] = solution // Always save your solution before returning
                       return solution
           match = align(i - 1, j - 1) // solve each subproblem
           gapx = align(i - 1,j) // solve each subproblem
           gapy = align(j, i - 1) // solve each subproblem
           solution = min(match + \alpha_{x_iy_i}, gapx + \delta, gapy+ \delta) // Pick the subproblem to use
            OPT[i][j] = solution // Always save your solution before returning
           return solution
```

### **Edit Distance – Four Steps, Step 3**





1. Formulate the answer with a recursive structure What are the options for the last choice?

For each such option, what does the subproblem look like? How do we use it?

Choose a memory structure.

Figure out the possible values of all parameters in the recursive calls.

How many subproblems (options for last choice) are there?

What are the parameters needed to identify each?

How many different values could there be per parameter?

3. Specify an order of evaluation. (Optional)

Want to guarantee that the necessary subproblem solutions are in memory when you need them.

With this step: a "Bottom-up" (iterative) algorithm

Without this step: a "Top-down" (recursive) algorithm

4. See if there's a way to save space (Optional)

Is it possible to reuse some memory locations?

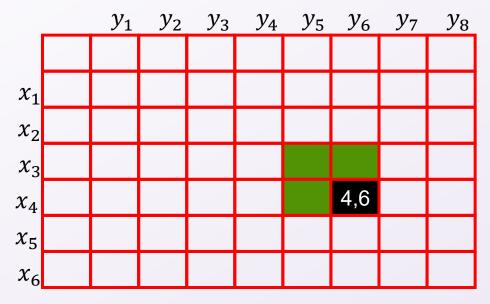
## **Step 3: Identify Order of Evaluation**

$$OPT(i,j) = \begin{cases} j \cdot \delta & \text{if } i = 0\\ i \cdot \delta & \text{if } j = 0 \end{cases}$$

$$OPT(i-1,j-1) + \alpha_{x_iy_j}$$

$$OPT(i-1,j) + \delta$$

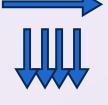
$$OPT(i,j-1) + \delta$$



Any of these orders will work:

- Each index depends on 3 others:
- 1. The one above it: (i 1, j)
- 2. The one to its left: (i, j 1)
- 3. The one to it's upper left: (i-1, j-1)

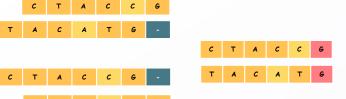
- Top-to-bottom, then left-to-right
- Left-to-right, then top-to-bottom
- Diagonally

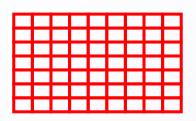


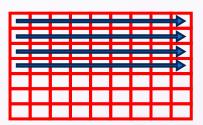
## **Bottom-Up Sequence Alignment**

```
align(x, y):
       for i = 0 up to n:
              OPT[i][0] = 0 // Solve and save base cases
       for j = 0 up to m:
              OPT[0][j] = 0 // Solve and save base cases
       for i = 1 up to n:
              for j = 1 up to m:
                     match = OPT[i-1][j-1] // solve each subproblem
                     gapx = OPT[i][j-1] // solve each subproblem
                     gapy = OPT[i - 1][j] // solve each subproblem
                     solution = min(match + \alpha_{x_iy_i}, gapx + \delta, gapy+ \delta) // pick solution
                     OPT[i][j] = solution // save solution
       return OPT[n][m]
```

## **Edit Distance – Four Steps, Step 4**







- 1. Formulate the answer with a recursive structure What are the options for the last choice?

  For each such option, what does the subproblem look like? How do we use it?
- 2. Choose a memory structure.

  Figure out the possible values of all parameters in the recursive calls.

  How many subproblems (options for last choice) are there?

  What are the parameters needed to identify each?

  How many different values could there be per parameter?
- 3. Specify an order of evaluation. (Optional) Want to guarantee that the necessary subproblem solutions are in memory when you need them.

With this step: a "Bottom-up" (iterative) algorithm Without this step: a "Top-down" (recursive) algorithm

4. See if there's a way to save space (Optional) Is it possible to reuse some memory locations?

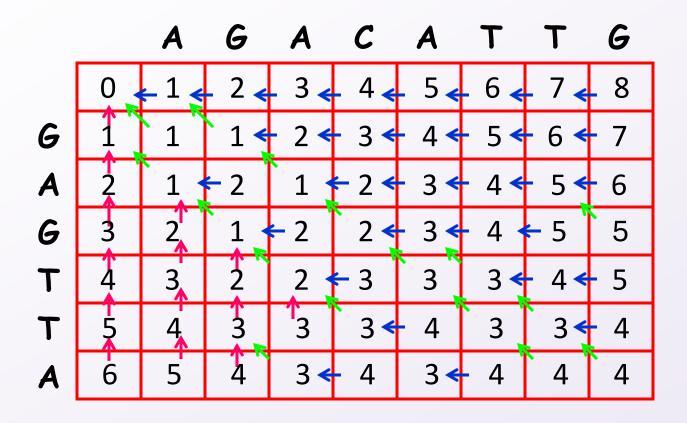
		A	G	A	C	A	T	T	G
	0	1	2	3	4	5	6	7	8
G	1								
A	2								
G	3								
T	4								
T	5								
A	6								

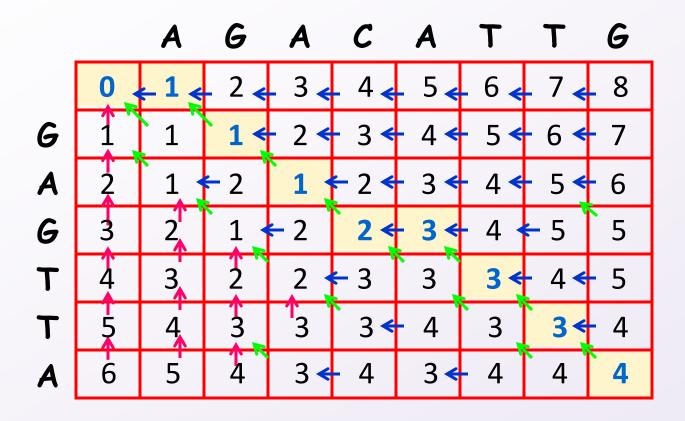
		A	G	A	C	A	T	T	G
	0	1	2	3	4	5	6	7	8
G	1	1	1	2	3	4	5	6	7
A	2								
G	3								
T	4								
T	5								
A	6								

		A	G	A	C	A	T	T	G
	0	1	2	3	4	5	6	7	8
G	1	1	1	2	3	4	5	6	7
A	2	1	2	1					
G	3								
T	4								
T	5								
A	6								

		A	G	A	C	A	T	T	G
	0	1	2	3	4	5	6	7	8
G	1	1	1	2	3	4	5	6	7
A	2	1	2	1	2	3	4	5	6
G	3	2	1	2	2	3	4	5	5
T	4								
T	5								
A	6								

		A	G	A	C	A	T	T	G
	0	1	2	3	4	5	6	7	8
G	1	1	1	2	3	4	5	6	7
A	2	1	2	1	2	3	4	5	6
G	3	2	1	2	2	3	4	5	5
T	4	3	2	2	3	3	3	4	5
T	5	4	3	3	3	4	3	3	4
A	6	5	4	3	4	3	4	4	4





**Optimal Alignment** 

#### Final reminders

HW5 released today @ 11:30am.

I have OH now-12:30pm:

- Meet at front of classroom, we'll walk over together
- CSE (Allen) 434 if you're coming later

Glenn has online OH 12-1pm