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Lab: Graphs (Part A)

Updated 1:15pm Sun March 4
   * fixed the traversal algo

Updated: 4:30pm Sat March 3
   * removed the requirement to return a tree
   * added path function

Due: in your lab session; week of March 4
Language: Python

A. G=(V,E)
   Let V be the set v0,v1,v2,...
   (i.e., with ascending non-negative indices)
   and E be the set e0,e1,e2,...
   (i.e., with ascending non-negative indices)

Create a class "graph", with the following methods:
* __init__(self)
  create an empty store for the graph, which will be an adjacency list

* addVertex(self,n)
  this will add "n" vertices to the graph, and return the value of the
  final number of vertices in the graph; the function may be called
  multiple times to add more nodes to the graph.

  The first time this is called (arg=1), it should return 1 and expand
  the store for the adjacency list to have one slot (the index 0 slot);
  The second time this is called (arg=1), it will return 2, and expand the store
  for the adj list to have two slots. Etc.
  It can also be called with any non-zero positive integer arg.

  If there is an error return -1.

* addEdge(self,from_idx,to_idx,directed,weight)
  where from_idx and to_idx are nonnegative integers
  and directed is either True or False
  and weight is any integer other than 0

  This adds an edge (a directed edge if directed==True, otherwise
  an undirected edge) from vertex<from_idx> to vertex<to_idx>
  with non-zero integer weight, weight.

  If there is an error return False, else True

* traverse(self,start,typeBreadth)
  These functions will return a list obtained from a breadth or depth
  traversal of the graph (based on typeBreadthFirst).

  If there is an error: return an empty list.

  start is either None or a non-negative integer:
  * if start==None: then the traversal must traverse the entire graph
    (i.e., including all of the subgraphs that may be disconnected from
    one another)
  * if start is an integer up to the maximum index of graph vertices
    then the traversal is just to whatever vertices that are connected
    to it (i.e., for which a path exists from the vertex with an index of
    start).
    If an invalid start index is entered, this is an error (v.s.).

  typeBreadth: True for Breadth; False for Depth
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   The basic algo for graph traversal is as follows, with
   breadth traversal accomplished via C being a Queue, and
   depth   traversal accomplished via C being a Stack

   traverse(G=(V,E)):
      initialize C to empty
      initialize Discovered to have as many slots as there are v in V
      initialize Processed to have as many slots as there are v in V
      set all slots of Discovered to be False
      set all slots of Processed to be False
      for v in V:
         if Discovered[v] == False:
            store v into C
            Discovered[v]=True
         while C is not empty:
            retrieve w from C
            if Processed[w]==False:
               process(w)
               Processed[w]=True
            for x = all vertices adjacent to w
               if Discovered[x] == False:
                   store x into C
                   Discovered[x]=True

   This algo will have to be slightly modified to handle the "start"
   index. Which line of code needs to be adjusted?

   Return value:
   a list consisting of all nodes visited via the traversal
   * if start is set (i.e., is a valid integer) then this will be
     ONE list
   * if start is not set, then this will be a list of lists
     (each sublist corresponding to a different connected subset of the
     graph)
     e.g., [ [sublistA], [sublistB], [sublistC], ..., [sublistN] ]
     if there are connected subgraphs A through N
     e.g., [ [sublistA] ]
     if the entire graph is connected

 * connectivity(self,vx,vy)
   This returns a 2-list.

   Element[0] is True if there's a path from vx to vy, else False
   Element[1] is True if there's a path from vy to vx, else False

 * path(self,vx,vy)
   This returns a 2-list.

   Element[0] is a list of vertices from vx to vy, if there is a path,
              otherwise []
   Element[1] is a list of vertices from vy to vx, if there is a path,
              otherwise []

   Include endpoints

 Submit this with the standard submit command and an arg of 5
 The file should be called graph.py. NO additional helper files should
 be used.
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