# KETAN VASUDEVA

# **Engineering Science Student**



# **EDUCATION**

# Engineering Science - Robotics Major - BASc University of Toronto

- September 2018 Present
- Minor in **Business**
- Dean's List

### **EXPERIENCE**

# Science Software Engineering Intern GHGSat

- May 2021 May 2022
- ♥ Montreal, Quebec
- Working in R&D to deliver industry-level greenhouse gas density maps by implementing scientific software to process raw satellite data.
- Created R&D solutions to speed up data processing by a factor of 4, reduce image artifacts by 50%, and calibrate optical instrument characterization data. Created and reported KPI to track company performance.
- Independently developed and maintained a command-line tool which allows team to visually analyze and plot satellite retrieval data.

#### Software Team Lead

### **UTDL** Robodog Design Team - University of Toronto

- 🛗 January 2022 August 2022
- ♥ Toronto, Ontario
- Leading software development of a team of over 10 students creating an autonomous robotic dog and manipulator, specifically leveraging **ROS**. Challenges include computer vision, path planning, and hardware control.

# Space Systems Team Member

#### University of Toronto Aerospace Team (UTAT)

- March 2019 June 2021
- ♥ Toronto, Ontario
- Worked towards deploying a satellite by 2023 to measure Anthropogenic CH4 levels across the GTA through hyperspectral imaging. Worked in the Firmware, Payload-Electronics, and Systems Engineering teams.
- Inclusion (Chair): created a space within UTAT to discuss and implement Equity, Diversity, and Inclusion goals.

#### Praxis 3 Research Assistant

### **University of Toronto**

- Researching with the faculty to build a fresh and innovative Engineering Science design course focusing on global community collaboration.
- Created literature review which was used as foundation for creation of course partnerships and materials.

# Full Stack Software Engineer

### Manulife - Canadian Architecture

- May 2020 August 2020
- ♥ Waterloo, Ontario
- Developed and deployed a web tool, using **Agile** methodology, to **automate** security threat analysis reports for Security Architecture. **Increased productivity by 30%** by decreasing average report creation time.

# PUBLICATIONS/RESEARCH

#### Thesis Research

 Investigating Markov Brain Techniques for Robotic Swarm Control in Space Exploration

#### **EUCASS Conference**

 A Concept of Operations for a Sustainable Human-Centred Lunar Settlement by Integration State-of-the-Art ISRU Technologies -DOI: 10.13009/EUCASS2022-6167

### Small Satellite Conference

- FINCH: A Blueprint for Accessible and Scientifically Valuable Remote Sensing Satellite Missions - Code: SSC22-WKVII-04
- Inspiring the Next Generation: Challenges and Strategies for Onboarding and Retention in an Undergraduate CubeSat Design Team - Code: SSC21-P2-37

### PERSONAL PROJECTS

# NASA SpaceApps 2020 Hackathon - Toronto and Canada CSA Winner

 Created an educational sandbox tool to simulate the challenges of communicating with people on Mars using NASA/CSA data sets, React.js, Node.js/Express.js, and Python.

#### The Sound of Space Podcast Host (UTAT)

 Co-host a podcast dedicated to creating, sharing, and explaining the wonders, dangers, and practical applications of space with space enthusiasts.

# Engineers Without Borders Canada (EWB) - Policy and Advocacy Team

 Met with Members of Parliament in order to advocate for the 2030 EWB's sustainable development goals.

#### **UTDL** Designathon

 Designed, prototyped, built, and tested a pinlocked fully-integrated safety box to prevent home delivery package thefts using Arduino, CAD, and various motors.

# **ACHIEVEMENTS**

- Paula Burke Bursary recipient University of Toronto
- University of Toronto Scholar and AIA Canada Scholarship recipient
- UofT Varsity Ultimate Team Rookie of the Year