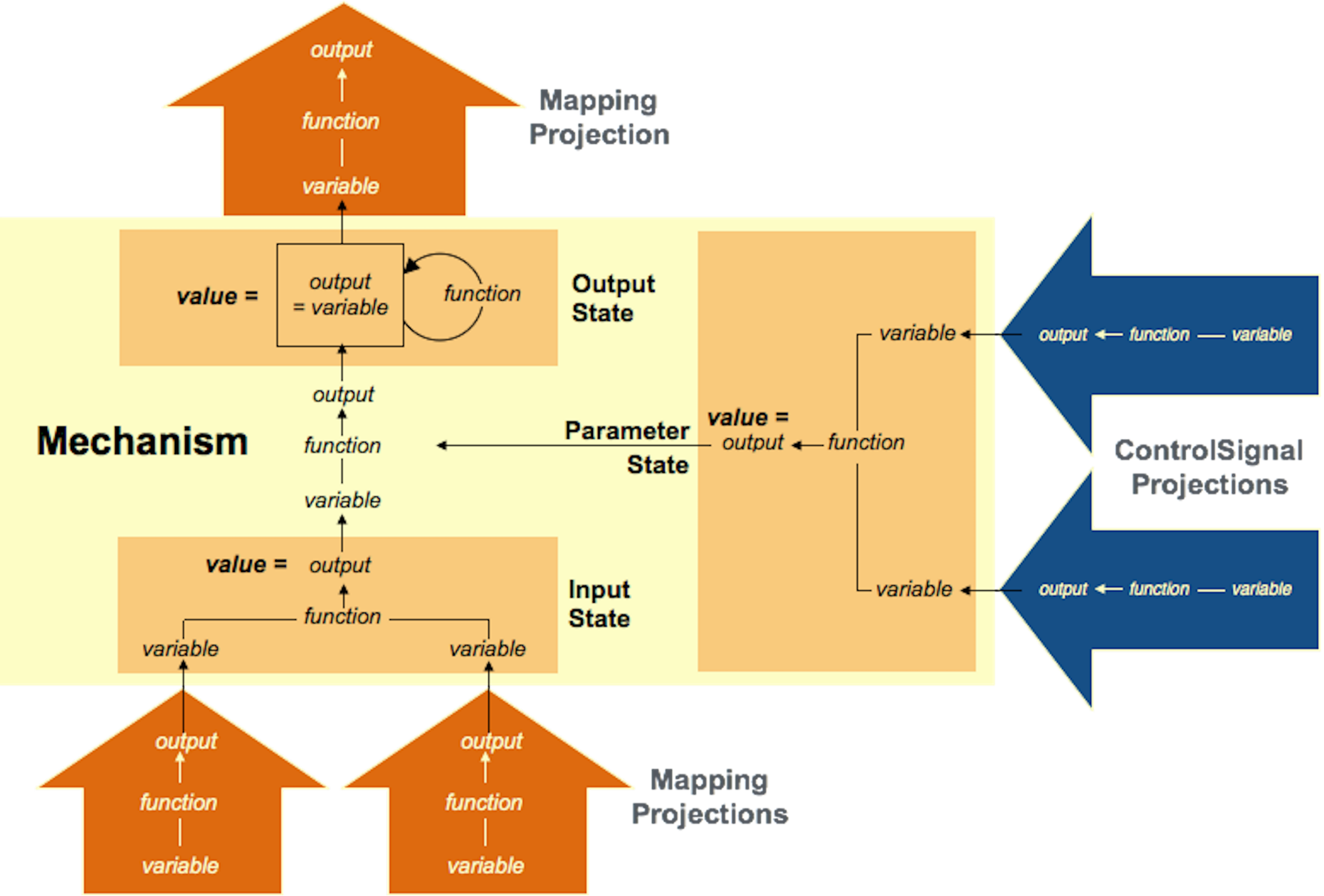
output
function
variable
Mapping Projection
value =
output = variable
function
Output State
output
function
variable
Mechanism
Parameter State
value =
output
function
variable
output
function
variable
ControlSignal Projections
value =
output
function
variable
variable
Input State
output
function
variable
output
function
variable
Mapping Projections