- 1. Consider the function  $f(x) = e^x xe^x$ 
  - (a) Find the root of f

We can find the root of f rather simply analytically in the following way:

$$f(x) = e^{x} - xe^{x}i$$
$$0 = e^{x} - xe^{x}$$
$$xe^{x} = e^{x}$$
$$x = 1$$

(b) Test Newton's method, the secant method, and bisection.

The points we wish to test for each method, the iteration count, and the approximation of the root is all given in the below table (along with the iteration count). It was done using the SciPy optimization library.

Bisection			
Points	Approximation	Iterations	
(0,2)	1.0	1	
(-5,5)	1.0000000000002274	43	
(-10,2)	0.99999999995453	43	
(-1,2)	0.999999999995453	41	
(0,1)	1.0	1	

Newton's Method			
Points	Approximation	Iterations	
0.5	1.0	7	
2	1.0	7	
10	1.0	17	
-0.5	Failed to converge	100	
-5	Failed to converge	100	

Secant Method			
Points	Approximation	Iterations	
(0,2)	1.0	13	
(0,10)	Result too large	-	
(-1,2)	Failed to converge	100	
(-5,5)	Failed to converge	100	
(-10,2)	Failed to converge	100	

There were two types of errors that came up when attempting this. 1) "Result too large" or 2) Failed to converge after X iterations. I have logged them accordingly, and listed their iteration number where possible. I used 100 as the maxiter value.

(c) How do inital parameters impact the success in finding the root of the three methods?

It would seem that the inital parameters have quite a large impact on the root finding success of each method. Bisection had 0 failures while the Secant method failed nearly every attempt at finding the root, despite not having particularly different inital parameters. In particular, the Newton/Secant method seems to be sensitive to negative numbers and large intervals for this function.

(d) Sketch a plot of f and eplain why negative initial parameters are not successful for some methods.

We can quickly plot this function using matplotlib to see the following plot.

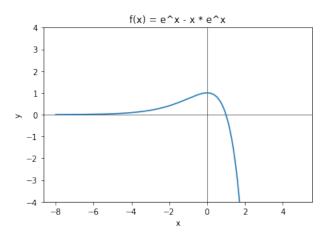


Figure 1: A plot of f(x)

We can immediately see why we were getting errors for negative numbers and larger ranges. as  $x \to -\infty$  we see  $f(x) \to 0$ , thus if the Newton or Secant method were given an inital value that was too far into the negative x, it would iterate too many times, and eventually get close enough to 0 as you go out towards infinity (after a very large number of iterations of course). This, however, would not be a root.

(e) What is a better terminating criteria than  $f(x_k) \approx 0$ 

We can see from (d) that the termination criteria for the methods should not be  $f(x_k) \approx 0$  as an asymptote would get arbitrarily close to 0 without ever reaching it. So we need a more reliable way of determining when we are nearing a root. We can consider the slope of our line (secant or otherwise) and can attempt to determine based on this. If the slope of our line is within some small percentage of difference from the last time, we know we are on a shallow slope, and therefore could be on an asymptote. If we know that the slope is somewhat steeper than the previous iteration, and that we are within an approximation of 0, then it is a safer bet that we have actually arrived at a root of the function.

This is not necessarily always going to work, though. One could imagine a line with vanishingly small slope, would eventually satisfy this dual condition, even if it wasn't actually at the intercept. I do think, though, that it would be a better condition than just  $f(x_k) \approx 0$ 

2. Consider the optimization problem, max f(x,y) = x + 2y subject to:

$$y \le 9$$

$$-y \le -1$$

$$2x + y \le 25$$

$$-2x - y \le -9$$

$$-2x + y \le 1$$

$$2x - y \le 15$$

(a) Draw the feasible region. Label the boundary curves and corner points.

Using matplotlib, we can create a rough graph of the feasible region (I could not figure out how to make the resolution of the imshow image higher, so I apologize for it's rather blocky and inaccurate nature.)

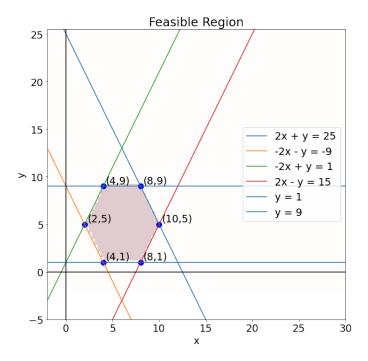


Figure 2: A plot of the feasible region of our constraing problem

(b) Find the maximum of f and where it occurs.

We can find the maximal value point by simply testing all the corner points in our objective function. Doing so, yields the following results.

Points	Values
(4,9)	22
(2,5)	12
(8,9)	26
(10,5)	20
(8,1)	10
(4,1)	6

So we can clearly see the maximal value is 26, and it occurs at point (8,9).

## (c) Verify your answer using SciPy.

We can quickly verify the above answer using SciPy. We can setup a serires of arrays that quantify our system. First is the A array which represents the coefficients of our constraint inequalities.

$$A = \begin{bmatrix} 0 & 1\\ 0 & -1\\ 2 & 1\\ -2 & -1\\ -2 & 1\\ 2 & -2 \end{bmatrix}, \quad b = \begin{bmatrix} 9\\ -1\\ 25\\ -9\\ 1\\ 15 \end{bmatrix}, \quad c = \begin{bmatrix} 1 & 2 \end{bmatrix}$$

Then we have the matrices b and c. The b matrix are the constraints themselves, while the c matrix is based on our objective function. We can then solve this using SciPy in the following way:

from scipy.optimize import linprog

Running the above code block gives us some output, the important parts being:

```
fun: -25.999999999969482
...
x: array([8., 9.])
```

Which align exactly with the maximal value and point we found in our table seen above (part b).

## 3. Some very type A bakers

A bakery wants to sell forty five Valentine's Day gift bags. They have decided to offer two types of bags: Bags of type A will contain four of cupcakes and two cookies, and bags of type B will contain two cupcakes and five cookies. Baskets of type A will be sold for \$12 and baskets of type B will be sold for \$16. The bakery has 90 cookies and 115 cupcakes in total.

(a) Solve for how many baskets of each type should be made to maximize the profits of the bakery. If it is fractional, round down to the nearest whole number solution.

We can start, by ordering our system in a table according to the types of baskets, and the quantity of each item within those baskets.

	Cupcakes (c)	Cookies (k)
Basket A	4	2
Basket B	2	5
Total	115	90

With this, we can quickly setup our optimization innequalities, but first, we should figure out our objective function. It should take the following form...

$$P(a,b) = 12a + 16b$$

Now we can list our constraints based on the table above...

$$4a + 2b \le 115$$
$$2a + 5b \le 90$$

We also know that (of course)  $c \ge 0$  and  $k \ge 0$ 

Given the following information, we can either draw the feasible region and solve, or we can construct arrays to use SciPy linprog again. I will do the latter method, to save time and space.

Then we have the following matrices...

$$A = \begin{bmatrix} 4 & 2 \\ 2 & 5 \end{bmatrix}, \quad b = \begin{bmatrix} 115 \\ 90 \end{bmatrix}, \quad c = \begin{bmatrix} 12 & 16 \end{bmatrix}$$

Which we can plug into SciPy in the exact same way as seen in 2.c to get the following result.

Thus, we have our maximal value at (24, 8) or 24 of type A baskets and 8 type B baskets, which, upon plugging into our objective function, returns the maximal profit or \$416.

One can double check this result, by quickly plotting the constraint function on an application like desmos, and can see that this is, in fact, the optimal value.

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