


```
Eigen::TensorBase<  
  TensorVolumePatchOp  
< Planes, Rows, Cols,  
  XprType >, ReadOnlyAccessors >
```

```
Eigen::TensorVolumePatch  
Op< Planes, Rows, Cols,  
  XprType >
```



```
graph RL; A[Eigen::TensorVolumePatchOp< Planes, Rows, Cols, XprType >] --> B[Eigen::TensorBase< TensorVolumePatchOp< Planes, Rows, Cols, XprType >, ReadOnlyAccessors >];
```

The diagram illustrates the relationship between two Eigen classes. A grey box on the right contains the definition of `Eigen::TensorVolumePatchOp< Planes, Rows, Cols, XprType >`. Two blue arrows point from this box to a white box on the left, which contains the definition of `Eigen::TensorBase< TensorVolumePatchOp< Planes, Rows, Cols, XprType >, ReadOnlyAccessors >`. This indicates that `TensorVolumePatchOp` is a base class for `TensorBase`.