

Eigen::HybridNonLinearSolver  
::solveNumericalDiffOneStep

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::solveOneStep

Eigen::internal::dogleg

```
graph LR; A[Eigen::HybridNonLinearSolver::solveNumericalDiffOneStep] --> C[Eigen::internal::dogleg]; B[Eigen::HybridNonLinearSolver::solveOneStep] --> C;
```

The diagram illustrates the relationship between two public methods of the Eigen::HybridNonLinearSolver class and a common internal function. Two white rectangular boxes on the left represent the public methods: 'Eigen::HybridNonLinearSolver::solveNumericalDiffOneStep' (top) and 'Eigen::HybridNonLinearSolver::solveOneStep' (bottom). Two blue arrows originate from the right side of these boxes and point towards a single gray rectangular box on the right labeled 'Eigen::internal::dogleg'. This indicates that both public methods delegate the actual solving work to the internal 'dogleg' function.