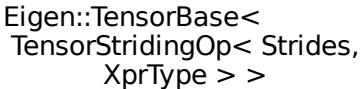


```
Eigen::TensorBase<  
  TensorStridingOp< Strides,  
    XprType > >
```



The diagram illustrates the relationship between two Eigen classes. A light gray box at the top contains the code for `Eigen::TensorBase`, which is a template class that takes `TensorStridingOp` as a template argument. A darker gray box at the bottom contains the code for `Eigen::TensorStridingOp`. Two blue arrows point from the `TensorStridingOp` box up to the `TensorBase` box, indicating that `TensorStridingOp` inherits from or is a base class for `TensorBase`.

```
Eigen::TensorStridingOp  
< Strides, XprType >
```