


Eigen::QuaternionBase
::normalize



```
graph LR; A["Eigen::QuaternionBase::normalize"] --> B["Eigen::QuaternionBase::coeffs"]; B --> C["Eigen::RotationBase< Derived, 3 >::derived"]
```

Eigen::QuaternionBase
::coeffs

Eigen::RotationBase
< Derived, 3 >::derived