


Eigen::QuaternionBase  
::setIdentity



```
graph LR; A["Eigen::QuaternionBase  
::setIdentity"] --> B["Eigen::QuaternionBase  
::coeffs"]; B --> C["Eigen::RotationBase  
< Derived, 3 >::derived"]
```

The diagram consists of three rectangular boxes arranged horizontally, connected by blue arrows pointing from left to right. The first box on the left is shaded gray and contains the text 'Eigen::QuaternionBase' followed by '::setIdentity' on a new line. The second box in the middle is white and contains 'Eigen::QuaternionBase' followed by '::coeffs' on a new line. The third box on the right is also white and contains 'Eigen::RotationBase' followed by '< Derived, 3 >::derived' on a new line. All boxes have a thin black border.

Eigen::QuaternionBase  
::coeffs

Eigen::RotationBase  
< Derived, 3 >::derived