# **Nathan Tsao**

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#### **EDUCATION**

#### University of Illinois at Urbana-Champaign

Aug 2019 – May 2022

• Bachelor of Science in Mechanical Engineering

Champaign, IL

- o Cumulative GPA: 3.85
- o Four-time Dean's List recipient
- Relevant Coursework: Robot Dynamics and Control, Solid Mechanics I (graduate),
  Intermediate Dynamics, Mechanical Design, Introduction to Robotics, Signal Processing,
  Heat Transfer, Engineering Materials, Fluid Dynamics, Dynamics of Mechanical Systems,
  Electrical and Electronic Circuits, Thermodynamics.

#### **EXPERIENCE**

### **UIUC RoboDesign Lab**

Jan 2022 – May 2022

Undergraduate Research Assistant

Champaign, IL

• Developing a force-sensing foot for humanoid robots.

#### **CLASS PROJECTS**

### **Instrumented Foot for Humanoid Robot**

Aug 2021 – Dec 2021

- Led team to prototype a force-sensing foot for use on a humanoid robot.
- Simulated foot deformation and sensor outputs with MATLAB.
- Manufactured foot prototype with 3D-printed parts.

## 3-Speed Transmission Design

*Jan 2021 – May 2021* 

- Utilized two planetary gear sets and dog clutches to design a three-speed transmission.
- Completed FEA with Fusion 360 to meet factor of safety requirements.
- Simulated transmission in Solidworks.

# **Snack-Disposing Walker Mechanism**

Aug 2020 – Dec 2020

- Designed lightweight, durable, easy-to-assemble quadruped walker.
- Analyzed reaction forces and gait speed of leg mechanism to reach a walking speed of 100 mm/s.
- Judged as best design project by peers.

#### **SKILLS**

- Solidworks, MATLAB, Creo, Fusion 360, Octave, Simulink, Gazebo, Kotlin, Java, Python.
- Fluent in English and Mandarin.