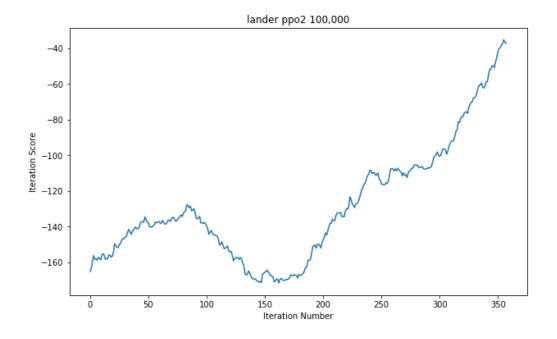
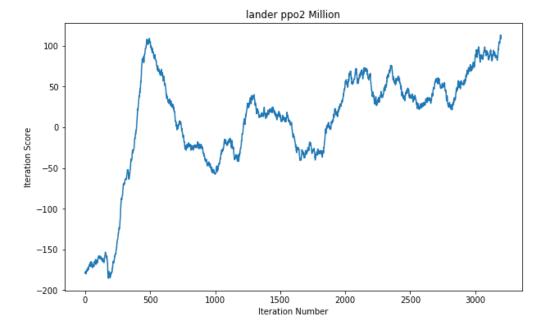
```
In [2]:
        import pandas as pd
        import matplotlib.pyplot as plt
        import numpy as np
In [3]:
        # Nearest Episodes for Moving average
        k = 100
In [4]:
        # lander ppo2 100,000
        # Read in File as pandas dataframe
        file_data = pd.read_csv("lander/lander_ppo2_100000.csv", index_col=False)
        lander_ppo2_100000_df = pd.DataFrame(columns= file_data.iloc[0,:], data=file_da
        ta.iloc[1:,].as matrix())
        #PLOTTING
        fig, ax = plt.subplots(1,1, figsize=(10,6))
        x_h = pd.to_numeric(lander_ppo2_100000_df.index.values)
        ppo2_hy = pd.to_numeric(lander_ppo2_100000_df.r.values)
        ax.set_title("lander ppo2 100,000")
        ax.set_xlabel("Iteration Number")
        ax.set_ylabel("Iteration Score")
        #ax.plot(x_h , ppo2_hy);
        ppo2 hy2 = []
        for i in range(len(ppo2_hy) - k):
            num = 0
            for j in range(k):
                num += ppo2_hy[i+j]
            ppo2_hy2.append(num/k)
        ax.plot(x_h[:-k], ppo2_hy2);
```



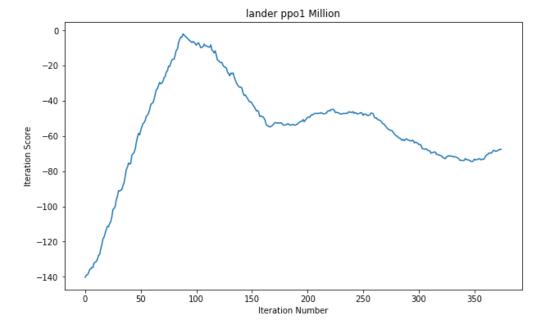
```
In [5]: | # lander ppo2 MILLION
        # Read in File as pandas dataframe
        file_data = pd.read_csv("lander/lander_ppo2_million.csv", index_col =False)
        lander_ppo2_million_df = pd.DataFrame(columns= file_data.iloc[0,:], data=file_d
        ata.iloc[1:,].as_matrix())
        #PLOTTING
        fig, ax = plt.subplots(1,1, figsize=(10,6))
        x_m = pd.to_numeric(lander_ppo2_million_df.index.values)
        ppo2_my = pd.to_numeric(lander_ppo2_million_df.r.values)
        ax.set title("lander ppo2 Million")
        ax.set xlabel("Iteration Number")
        ax.set_ylabel("Iteration Score")
        #ax.plot(x m , ppo2 my);
        ppo2 my2 = []
        for i in range(len(ppo2 my) - k):
            num = 0
            for j in range(k):
                num += ppo2_my[i+j]
            ppo2_my2.append(num/k)
        ax.plot(x_m[:-k], ppo2_my2);
```

after removing the cwd from sys.path.



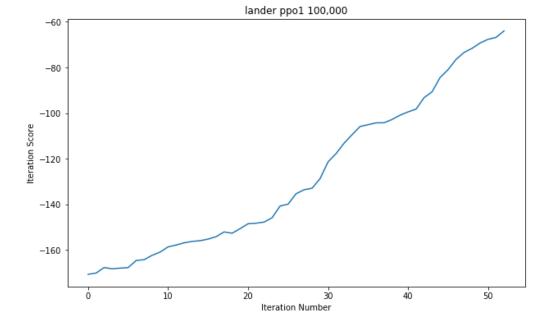
```
In [6]: | # lander ppo1 MILLION
        # Read in File as pandas dataframe
        file_data = pd.read_csv("lander/lander_ppo1_million.csv", index_col=False)
        lander_ppo1_million_df = pd.DataFrame(columns= file_data.iloc[0,:], data=file_d
        ata.iloc[1:,].as_matrix())
        #PLOTTING
        fig, ax = plt.subplots(1,1, figsize=(10,6))
        x = pd.to_numeric(lander_ppo1_million_df.index.values)
        ppo1_my = pd.to_numeric(lander_ppo1_million_df.r.values)
        ax.set title("lander ppo1 Million")
        ax.set_xlabel("Iteration Number")
        ax.set_ylabel("Iteration Score")
        #ax.plot(x , ppo1 my);
        ppo1 my2 = []
        for i in range(len(ppo1 my) - k):
            num = 0
            for j in range(k):
                num += ppo1_my[i+j]
            ppo1_my2.append(num/k)
        ax.plot(x[:-k], ppo1_my2);
```

after removing the cwd from sys.path.



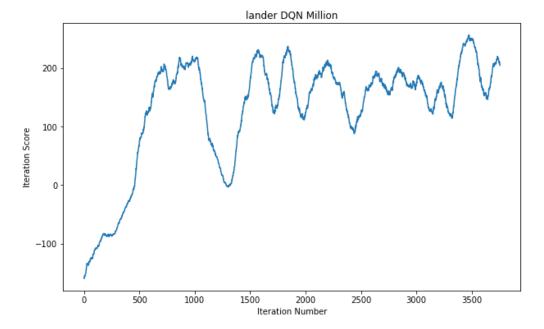
```
In [7]: | # lander ppol 100,000
        # Read in File as pandas dataframe
        file_data = pd.read_csv("lander/lander_ppo1_100000.csv", index_col=False)
        lander_ppo1_100000_df = pd.DataFrame(columns= file_data.iloc[0,:], data=file_da
        ta.iloc[1:,].as_matrix())
        #PLOTTING
        fig, ax = plt.subplots(1,1, figsize=(10,6))
        x = pd.to_numeric(lander_ppo1_100000_df.index.values)
        ppo1 hy = pd.to numeric(lander ppo1 100000 df.r.values)
        ax.set title("lander ppo1 100,000")
        ax.set_xlabel("Iteration Number")
        ax.set_ylabel("Iteration Score")
        #ax.plot(x , ppo1 hy);
        ppo1 hy2 = []
        for i in range(len(ppo1 hy) - k):
            num = 0
            for j in range(k):
                num += ppo1_hy[i+j]
            ppo1_hy2.append(num/k)
        ax.plot(x[:-k], ppo1_hy2);
```

after removing the cwd from sys.path.



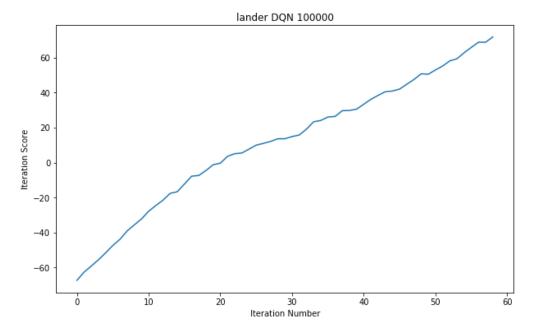
```
In [8]: # lander DQN Million
        # Read in File as pandas dataframe
        file_data = pd.read_csv("lander_lander_dqn_million.csv", index_col=False)
        lander_dqn_million_df = pd.DataFrame(columns= file_data.iloc[0,:], data=file_da
        ta.iloc[1:,].as_matrix())
        #PLOTTING
        fig, ax = plt.subplots(1,1, figsize=(10,6))
        x = pd.to numeric(lander dgn million df.index.values)
        dgn my = pd.to numeric(lander dgn million df.r.values)
        ax.set title("lander DQN Million")
        ax.set_xlabel("Iteration Number")
        ax.set_ylabel("Iteration Score")
        #ax.plot(x , dqn my);
        dqn my2 = []
        for i in range(len(dqn my) - k):
            num = 0
            for j in range(k):
                num += dqn_my[i+j]
            dqn_my2.append(num/k)
        ax.plot(x[:-k], dqn_my2);
```

after removing the cwd from sys.path.



```
In [9]: # lander DQN 100000
        # Read in File as pandas dataframe
        file_data = pd.read_csv("lander/lander_dqn_100000.csv", index_col=False)
        lander_dqn_million_df = pd.DataFrame(columns= file_data.iloc[0,:], data=file_da
        ta.iloc[1:,].as_matrix())
        #PLOTTING
        fig, ax = plt.subplots(1,1, figsize=(10,6))
        x = pd.to numeric(lander dgn million df.index.values)
        dgn my = pd.to numeric(lander dgn million df.r.values)
        ax.set title("lander DQN 100000")
        ax.set_xlabel("Iteration Number")
        ax.set_ylabel("Iteration Score")
        #ax.plot(x , dqn my);
        dqn hy2 = []
        for i in range(len(dqn my) - k):
            num = 0
            for j in range(k):
                num += dqn_my[i+j]
            dqn_hy2.append(num/k)
        ax.plot(x[:-k], dqn_hy2);
```

after removing the cwd from sys.path.



```
In [10]: # lander DDPG Million
    # Read in File as pandas dataframe
    file_data = pd.read_csv("lander_ddpg_million.csv")
    lander_ddpg_million_df = pd.DataFrame(columns= file_data.iloc[0,:], data=file_d
    ata.iloc[1:,].as_matrix())

#PLOTTING
fig, ax = plt.subplots(1,1, figsize=(10,6))
x = pd.to_numeric(lander_ddpg_million_df.index.values)
y = pd.to_numeric(lander_ddpg_million_df.l.values)
ax.set_title("lander DDPG Million")
ax.set_xlabel("Iteration Number")
ax.set_ylabel("Iteration Score")
ax.plot(x, y);

# Moving average dangerous, maybe like k-nearest neigbors type of thing
```

```
FileNotFoundError
                                          Traceback (most recent call last)
<ipython-input-10-38b38ce083dc> in <module>
      1 # lander DDPG Million
      2 # Read in File as pandas dataframe
----> 3 file_data = pd.read_csv("lander/lander_ddpg_million.csv")
      4 lander_ddpg_million_df = pd.DataFrame(columns= file_data.iloc[0,:], dat
a=file_data.iloc[1:,].as_matrix())
~/jupyter nb directory/jupyter nb env/lib/python3.6/site-packages/pandas/io/par
sers.py in parser_f(filepath_or_buffer, sep, delimiter, header, names, index_co
l, usecols, squeeze, prefix, mangle_dupe_cols, dtype, engine, converters, true_
values, false_values, skipinitialspace, skiprows, nrows, na_values, keep_defaul
t_na, na_filter, verbose, skip_blank_lines, parse_dates, infer_datetime_format,
keep_date_col, date_parser, dayfirst, iterator, chunksize, compression, thousan
ds, decimal, lineterminator, quotechar, quoting, escapechar, comment, encoding,
dialect, tupleize cols, error bad lines, warn bad lines, skipfooter, doublequot
e, delim whitespace, low memory, memory map, float precision)
                            skip blank lines=skip blank lines)
    677
--> 678
                return read(filepath or buffer, kwds)
    679
    680
            parser_f.__name__ = name
~/jupyter_nb_directory/jupyter_nb_env/lib/python3.6/site-packages/pandas/io/par
sers.py in _read(filepath_or_buffer, kwds)
    438
    439
            # Create the parser.
--> 440
            parser = TextFileReader(filepath or buffer, **kwds)
    441
    442
            if chunksize or iterator:
~/jupyter nb directory/jupyter nb env/lib/python3.6/site-packages/pandas/io/par
sers.py in __init__(self, f, engine, **kwds)
    785
                    self.options['has_index_names'] = kwds['has_index_names']
    786
--> 787
                self. make engine(self.engine)
    788
    789
            def close(self):
~/jupyter nb directory/jupyter nb env/lib/python3.6/site-packages/pandas/io/par
sers.py in _make_engine(self, engine)
   1012
            def _make_engine(self, engine='c'):
   1013
                if engine == 'c':
-> 1014
                    self. engine = CParserWrapper(self.f, **self.options)
   1015
                    if engine == 'python':
   1016
~/jupyter_nb_directory/jupyter_nb_env/lib/python3.6/site-packages/pandas/io/par
sers.py in __init__(self, src, **kwds)
                kwds['usecols'] = self.usecols
   1706
   1707
-> 1708
                self._reader = parsers.TextReader(src, **kwds)
   1709
   1710
                passed_names = self.names is None
pandas/_libs/parsers.pyx in pandas._libs.parsers.TextReader.__cinit__()
pandas/ libs/parsers.pyx in pandas. libs.parsers.TextReader. setup parser sourc
e()
FileNotFoundError: File b'lander/lander_ddpg_million.csv' does not exist
```

```
In [11]: # lander DDPG 100000
# Read in File as pandas dataframe
file_data = pd.read_csv("lander/lander_ddpg_100000.csv")
lander_ddpg_100000_df = pd.DataFrame(columns= file_data.iloc[0,:], data=file_data.iloc[1:,].as_matrix())

#PLOTTING
fig, ax = plt.subplots(1,1, figsize=(10,6))
x = pd.to_numeric(lander_ddpg_100000_df.index.values)
y = pd.to_numeric(lander_ddpg_100000_df.l.values)
ax.set_title("lander DDPG 100000")
ax.set_xlabel("Iteration Number")
ax.set_ylabel("Iteration Score")
ax.plot(x, y);
```

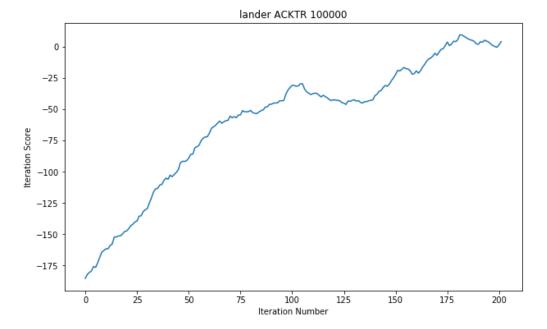
```
FileNotFoundError
                                          Traceback (most recent call last)
<ipython-input-11-9a17b11f981a> in <module>
      1 # lander DDPG 100000
      2 # Read in File as pandas dataframe
----> 3 file_data = pd.read_csv("lander/lander_ddpg_100000.csv")
      4 lander_ddpg_100000_df = pd.DataFrame(columns= file_data.iloc[0,:], data
=file_data.iloc[1:,].as_matrix())
~/jupyter nb directory/jupyter nb env/lib/python3.6/site-packages/pandas/io/par
sers.py in parser_f(filepath_or_buffer, sep, delimiter, header, names, index_co
l, usecols, squeeze, prefix, mangle_dupe_cols, dtype, engine, converters, true_
values, false_values, skipinitialspace, skiprows, nrows, na_values, keep_defaul
t_na, na_filter, verbose, skip_blank_lines, parse_dates, infer_datetime_format,
keep_date_col, date_parser, dayfirst, iterator, chunksize, compression, thousan
ds, decimal, lineterminator, quotechar, quoting, escapechar, comment, encoding,
dialect, tupleize_cols, error_bad_lines, warn_bad_lines, skipfooter, doublequot
e, delim whitespace, low memory, memory map, float precision)
                            skip blank lines=skip blank lines)
    677
--> 678
                return read(filepath or buffer, kwds)
    679
    680
            parser_f.__name__ = name
~/jupyter_nb_directory/jupyter_nb_env/lib/python3.6/site-packages/pandas/io/par
sers.py in _read(filepath_or_buffer, kwds)
    438
    439
            # Create the parser.
--> 440
            parser = TextFileReader(filepath or buffer, **kwds)
    441
            if chunksize or iterator:
    442
~/jupyter_nb_directory/jupyter_nb_env/lib/python3.6/site-packages/pandas/io/par
sers.py in __init__(self, f, engine, **kwds)
    785
                    self.options['has_index_names'] = kwds['has_index_names']
    786
--> 787
                self. make engine(self.engine)
    788
    789
            def close(self):
~/jupyter nb directory/jupyter nb env/lib/python3.6/site-packages/pandas/io/par
sers.py in _make_engine(self, engine)
   1012
            def _make_engine(self, engine='c'):
   1013
                if engine == 'c':
-> 1014
                    self. engine = CParserWrapper(self.f, **self.options)
   1015
                    if engine == 'python':
   1016
~/jupyter_nb_directory/jupyter_nb_env/lib/python3.6/site-packages/pandas/io/par
sers.py in __init__(self, src, **kwds)
                kwds['usecols'] = self.usecols
   1706
   1707
-> 1708
                self._reader = parsers.TextReader(src, **kwds)
   1709
   1710
                passed_names = self.names is None
pandas/_libs/parsers.pyx in pandas._libs.parsers.TextReader.__cinit__()
pandas/ libs/parsers.pyx in pandas. libs.parsers.TextReader. setup parser sourc
e()
FileNotFoundError: File b'lander/lander_ddpg_100000.csv' does not exist
```

```
In [12]: k = 100
         y2 = []
         for i in range(len(y) - k):
             num = 0
             for j in range(k):
                 num += y[i+j]
             y2.append(num/k)
         # lander DDPG 100000
         # Read in File as pandas dataframe
         file data = pd.read csv("lander/lander ddpg 100000.csv")
         lander_ddpg_100000_df = pd.DataFrame(columns= file_data.iloc[0,:], data=file_da
         ta.iloc[1:,].as matrix())
         #PLOTTING
         fig, ax = plt.subplots(1,1, figsize=(10,6))
         x2 = pd.to_numeric(lander_ddpg_100000_df.iloc[:-k].index.values)
         #y = pd.to_numeric(lander_ddpg_100000_df.l.values)
         ax.set_title("lander DDPG 100000")
         ax.set_xlabel("Iteration Number")
         ax.set_ylabel("Iteration Score")
         ax.plot(x2, y2);
```

NameError: name 'y' is not defined

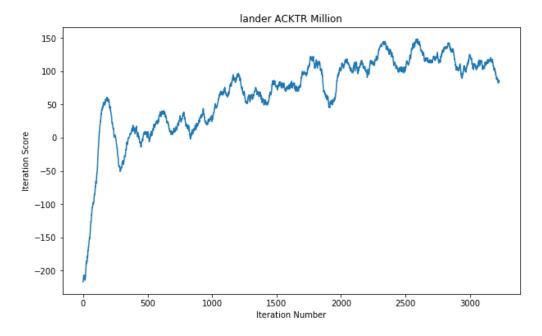
```
In [13]: # lander ACKTR 100,000
         # Read in File as pandas dataframe
         file_data = pd.read_csv("lander/lander_acktr_100000.csv", index_col = False)
         lander_acktr_100000_df = pd.DataFrame(columns= file_data.iloc[0,:], data=file_d
         ata.iloc[1:,].as_matrix())
         #PLOTTING
         fig, ax = plt.subplots(1,1, figsize=(10,6))
         x = pd.to numeric(lander acktr 100000 df.index.values)
         y = pd.to numeric(lander acktr 100000 df.r.values)
         ax.set title("lander ACKTR 100000")
         ax.set_xlabel("Iteration Number")
         ax.set_ylabel("Iteration Score")
         #ax.plot(x, y);
         acktr hy2 = []
         for i in range(len(y) - k):
             num = 0
             for j in range(k):
                 num += y[i+j]
             acktr_hy2.append(num/k)
         ax.plot(x[:-k], acktr_hy2);
```

after removing the cwd from sys.path.



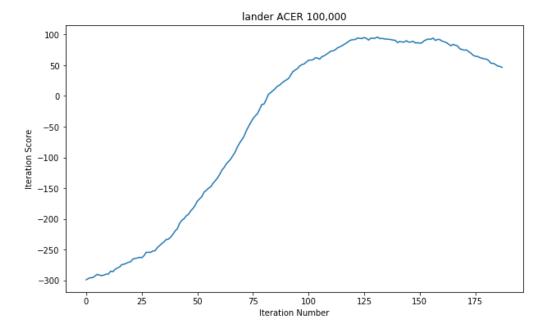
```
In [14]: # lander ACKTR MILLION
         # Read in File as pandas dataframe
         file_data = pd.read_csv("lander/lander_acktr_million.csv",index_col=False)
         lander_acktr_million_df = pd.DataFrame(columns= file_data.iloc[0,:], data=file_
         data.iloc[1:,].as_matrix())
         #PLOTTING
         fig, ax = plt.subplots(1,1, figsize=(10,6))
         x = pd.to numeric(lander acktr million df.index.values)
         y = pd.to numeric(lander acktr million df.r.values)
         ax.set title("lander ACKTR Million")
         ax.set_xlabel("Iteration Number")
         ax.set_ylabel("Iteration Score")
         #ax.plot(x, y);
         k = 100
         acktr_my2 = []
         for i in range(len(y) - k):
             num = 0
             for j in range(k):
                 num += y[i+j]
             acktr_my2.append(num/k)
         ax.plot(x[:-k], acktr_my2);
         #file_data.iloc[0,:].values
```

after removing the cwd from sys.path.

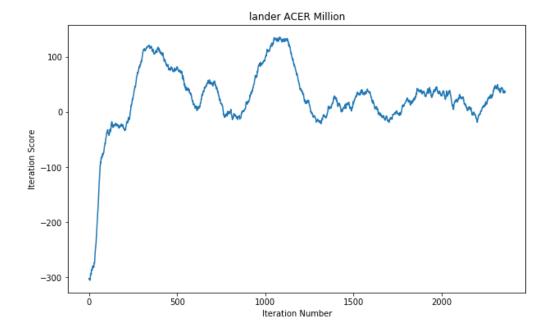


```
In [15]: # lander ACER 100000
         # Read in File as pandas dataframe
         file_data = pd.read_csv("lander/lander_acer_100000.csv", index_col=False)
         lander_acer_100000_df = pd.DataFrame(columns= file_data.iloc[0,:], data=file_da
         ta.iloc[1:,].as_matrix())
         #PLOTTING
         fig, ax = plt.subplots(1,1, figsize=(10,6))
         x = pd.to numeric(lander acer 100000 df.index.values)
         y = pd.to numeric(lander acer 100000 df.r.values)
         ax.set title("lander ACER 100,000")
         ax.set_xlabel("Iteration Number")
         ax.set ylabel("Iteration Score")
         k = 100
         acer hy2 = []
         for \bar{i} in range(len(y) - k):
             num = 0
             for j in range(k):
                 num += y[i+j]
             acer_hy2.append(num/k)
         ax.plot(x[:-k], acer_hy2);
```

after removing the cwd from sys.path.

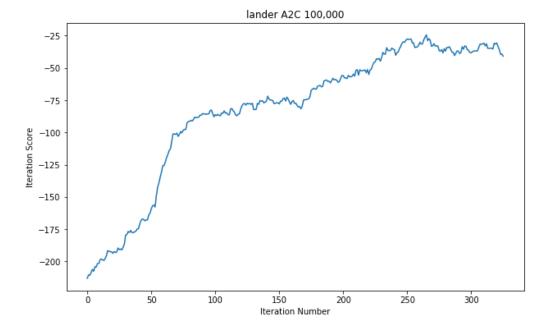


```
In [16]: # lander ACER MILLION
         # Read in File as pandas dataframe
         file_data = pd.read_csv("lander/lander_acer_million.csv", index_col=False)
         lander_acer_million_df = pd.DataFrame(columns= file_data.iloc[0,:], data=file_d
         ata.iloc[1:,].as_matrix())
         #PLOTTING
         fig, ax = plt.subplots(1,1, figsize=(10,6))
         x = pd.to_numeric(lander_acer_million_df.index.values)
         y = pd.to_numeric(lander_acer_million_df.r.values)
         ax.set title("lander ACER Million")
         ax.set_xlabel("Iteration Number")
         ax.set_ylabel("Iteration Score")
         #ax.plot(x, y);
         acer my2 = []
         for i in range(len(y) - k):
             num = 0
             for j in range(k):
                 num += y[i+j]
             acer_my2.append(num/k)
         ax.plot(x[:-k], acer_my2);
```



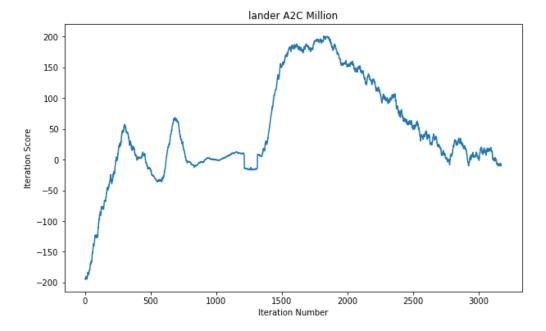
```
In [17]: # lander A2C 100,000
         # Read in File as pandas dataframe
         file_data = pd.read_csv("lander/lander_a2c_100000.csv", index_col=False)
         lander_a2c_100000_df = pd.DataFrame(columns= file_data.iloc[0,:], data=file_dat
         a.iloc[1:,].as_matrix())
         #PLOTTING
         fig, ax = plt.subplots(1,1, figsize=(10,6))
         x = pd.to numeric(lander a2c 100000 df.index.values)
         y = pd.to numeric(lander a2c 100000 df.r.values)
         ax.set title("lander A2C 100,000")
         ax.set_xlabel("Iteration Number")
         ax.set_ylabel("Iteration Score")
         #ax.plot(x, y);
         a2c hy2 = []
         for i in range(len(y) - k):
             num = 0
             for j in range(k):
                 num += y[i+j]
             a2c_hy2.append(num/k)
         ax.plot(x[:-k], a2c_hy2);
```

after removing the cwd from sys.path.



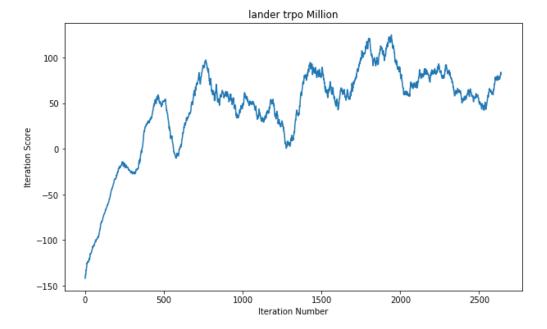
```
In [18]: # lander A2C MILLION
         # Read in File as pandas dataframe
         file_data = pd.read_csv("lander/lander_a2c_million.csv", index_col=False)
         lander_a2c_million_df = pd.DataFrame(columns= file_data.iloc[0,:], data=file_da
         ta.iloc[1:,].as_matrix())
         #PLOTTING
         fig, ax = plt.subplots(1,1, figsize=(10,6))
         x = pd.to numeric(lander a2c million df.index.values)
         y = pd.to numeric(lander a2c million df.r.values)
         ax.set title("lander A2C Million")
         ax.set_xlabel("Iteration Number")
         ax.set_ylabel("Iteration Score")
         #ax.plot(x, y);
         a2c my2 = []
         for i in range(len(y) - k):
             num = 0
             for j in range(k):
                 num += y[i+j]
             a2c_my2.append(num/k)
         ax.plot(x[:-k], a2c_my2);
```

after removing the cwd from sys.path.



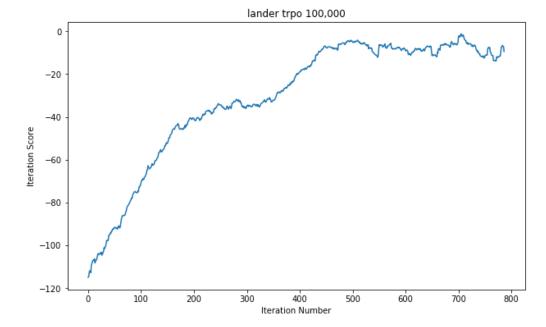
```
In [19]: # lander trpo MILLION
         # Read in File as pandas dataframe
         file_data = pd.read_csv("lander/lander_trpo_million.csv", index_col=False)
         lander_trpo_million_df = pd.DataFrame(columns= file_data.iloc[0,:], data=file_d
         ata.iloc[1:,].as_matrix())
         #PLOTTING
         fig, ax = plt.subplots(1,1, figsize=(10,6))
         x = pd.to_numeric(lander_trpo_million_df.index.values)
         y = pd.to numeric(lander trpo million df.r.values)
         ax.set title("lander trpo Million")
         ax.set_xlabel("Iteration Number")
         ax.set_ylabel("Iteration Score")
         #ax.plot(x, y);
         trpo my2 = []
         for i in range(len(y) - k):
             num = 0
             for j in range(k):
                 num += y[i+j]
             trpo_my2.append(num/k)
         ax.plot(x[:-k], trpo_my2);
```

after removing the cwd from sys.path.



```
In [20]: | # lander trpo 100,000
         # Read in File as pandas dataframe
         file_data = pd.read_csv("lander/lander_trpo_100000.csv", index_col=False)
         lander_trpo_100000_df = pd.DataFrame(columns= file_data.iloc[0,:], data=file_da
         ta.iloc[1:,].as_matrix())
         #PLOTTING
         fig, ax = plt.subplots(1,1, figsize=(10,6))
         x = pd.to numeric(lander trpo 100000 df.index.values)
         y = pd.to_numeric(lander_trpo_100000_df.r.values)
         ax.set title("lander trpo 100,000")
         ax.set_xlabel("Iteration Number")
         ax.set_ylabel("Iteration Score")
         #ax.plot(x, y);
         trpo hy2 = []
         for i in range(len(y) - k):
             num = 0
             for j in range(k):
                 num += y[i+j]
             trpo_hy2.append(num/k)
         ax.plot(x[:-k], trpo_hy2);
```

after removing the cwd from sys.path.



```
In [25]: | fig_t, ax_t = plt.subplots(1,2,figsize=(20,12))
         # MAYBE CHANGE K FOR 100,000
         # A2C
         ax_t[0].plot(x_m[:1000], a2c_my2[:1000], label="A2C");
         ax_t[1].plot(x_h[:100], a2c_hy2[:100], label="A2C");
         # ACER
         ax t[0].plot(x m[:1000], acer my2[:1000], label="ACER");
         ax_t[1].plot(x_h[:100], acer_hy2[:100], label="ACER");
         # ACKTR
         ax t[0].plot(x m[:1000], acktr my2[:1000], label="ACKTR");
         ax_t[1].plot(x_h[:100], acktr_hy2[:100], label="ACKTR");
         # DON
         ax_t[0].plot(x_m[:1000], dqn_my2[:1000], label="DQN");
         ax_t[1].plot(x_h[:59], dqn_hy2[:59], label="DQN");
         # PP01
         ax_t[0].plot(x_m[:375], ppo1_my2[:375], label="PP01");
         ax_t[1].plot(x_h[:53], ppol_hy2[:53], label="PPO1");
         ax_t[0].plot(x_m[:1000], ppo2_my2[:1000], label="PP02");
         ax_t[1].plot(x_h[:100], ppo2_hy2[:100], label="PP02");
         # TRPO
         ax_t[0].plot(x_m[:1000], trpo_my2[:1000], label="TRPO");
         ax_t[1].plot(x_h[:100], trpo_hy2[:100], label="TRPO");
         # MAYBE CHANGE K FOR 100,000
         ax t[0].legend();
         ax t[1].legend();
         fig t.suptitle("Performance of Deep Learning Algorithms on Lunar Lander", fonts
         ize=30);
         ax_t[0].set_title("First 10,000 Episodes",fontsize=15)
         ax_t[1].set_title("First 1,000 Episodes", fontsize=15);
```

Performance of Deep Learning Algorithms on Lunar Lander

