# **Nathan Duncan**

**EDUCATION** 

**Bachelor of Applied Science** 

Kingston, ON | Expected Spring 2026

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Project Portfolio: nathanduncan.github.io

QUEEN'S UNIVERSITY

Specialization in Mechatronics and Robotics Engineering. Holding a 3.9/4.3 CGPA.

Coursework: Automatic Controls; Signals and Systems; Data Structures and Algorithms; Mechatronics Design I-III

**WORK EXPERIENCE** 

# **DEFENCE RESEARCH AND DEVELOPMENT CANADA** | CONTROL INTERN Ottawa, ON | May 2024 - Present

- Conducted a **literature review** of over **155** academic publications discussing teams of unmanned aerial systems, to create an internal reference document and provide background research for subsequent projects.
- Created a robust hierarchal event-triggered linear MPC controller for online management of multi-UAV missions.
- Assisted in the experiments of other defence scientists, operating RADAR and sensing equipment, collecting and analyzing wide-band radio signals, and preparing technical documents.

#### **ROBORA LAB** | Undergraduate Student Researcher

Kingston, ON | July 2023 - May 2024

- Coauthored *Distributed Model Predictive Control for Cooperative Multirotor Landing on Uncrewed Surface Vessel in Waves*, presenting a novel control solution to the rendezvous problem of two agents in an open-water environment.
- Programmed a **custom Python simulation tool** to display state outputs and enable inter-agent communication.
- Contributed to a project to create **spatiotemporal maps** of semi-static shoreline environments via **unmanned aerial vehicles (UAV)** and **unmanned surface vehicles (USV)** for safe ship-to-shore connections.
- Coordinated and performed large set data collections with a custom UAV sensor suite using **ROS** for task execution.

# **UTILITIES KINGSTON** | GEOGRAPHIC INFORMATION SYSTEMS STUDENT Kingston, ON | May 2023 – July 2023

- Developed, edited and maintained **GIS data** and other GIS output products to reflect the current state of assets.
- Conducted analysis of spatial information, generated data queries and summarized statistics within the City of Kingston's largest geographic database while supporting the Utilities Engineering Department and GIS Team.

#### PRO JECTS

#### MREN 303 COURSE PROJECT | QUEEN'S UNIVERSITY

Kingston, ON | Jan 2024 - Apr 2024

- Designed, created, and programmed a mobile platform to compete in a head-to-head robotics competition.
- Modeled the platforms chassis and four-wheel differential drive train in **SolidWorks** before being fabricated with **laser cut** medium-density fiberboard and **3D printed** ABS plastic components.
- Mapped Gamepad inputs to wheel and manipulator actions for manual operation and programmed an autonomous line following routine using a base mounted color sensor in Python regulated with a **PID controller**.

# **SAE AUTODRIVE CHALLENGE** | QUEEN'S UNIVERSITY

Kingston, ON | Oct 2022 - July 2023

- Worked as a member of the **Systems Integration** sub team and liaison to the Controls sub-team on a project to bring a Chevrolet Bolt to **Level 4 autonomy** (5 hr/week commitment).
- Tasked to program 5 publisher-subscriber nodes in C++ using ROS2, to manage the input and output data of the control team and allow programs to execute with optimized time complexity.
- Installed and maintained Chevorlet's Ushr map in **QGIS** using a **PostgreSQL** database to identify superficial road elements and supplement **navigation**.

#### MREN 203 COURSE PROJECT | QUEEN'S UNIVERSITY

Kingston, ON | Jan 2023 - Apr 2023

- Tasked with creating an **unmanned ground vehicle (UGV)**, designed for mobile **autonomous monitoring** of irritant air chemicals circulating indoor environments.
- Presented a minimum viable product which could navigate a small room using LiDAR, camera and proprioceptive sensors and create a live web-based heatmap of CO<sub>2</sub> levels that can be monitored remotely.

# SKILLS

**Languages:** C, C++, Python, NIOS II Assembly **Libraries:** ROS, ROS2, TensorFlow, OpenCV, Django

Technologies: Linux, QGIS, Git, SolidWorks, LATEX, MATLAB/Simulink

Licenses: G, sRPAS (Basic Operations)

# **ACHIEVEMENTS**

**DEAN'S SCHOLAR** | Obtained an Engineering Sessional GPA of 3.5 while taking at least 30 units. **GOVERNOR GENERAL'S ACADEMIC MEDAL** | Awarded to the top graduate of a secondary school.

2022-2024

2021