

On the number of types in sparse graphs

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based on joint work with Sebastian Siebertz and Szymon Toruńczyk



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Part 1: Sparsity

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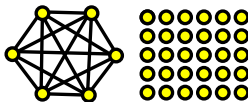
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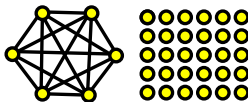
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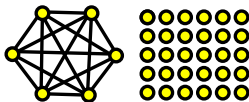
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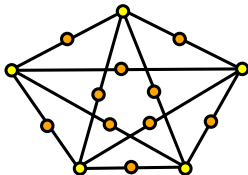
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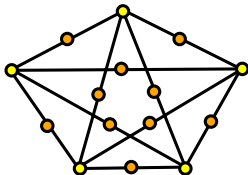
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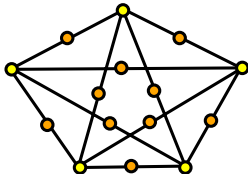
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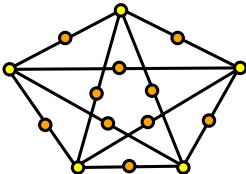
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 - If we are looking for a structurally robust notion of sparsity, morally this example should be dense.

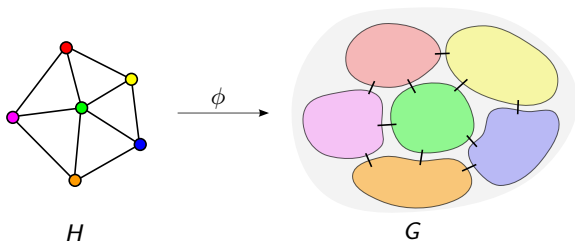


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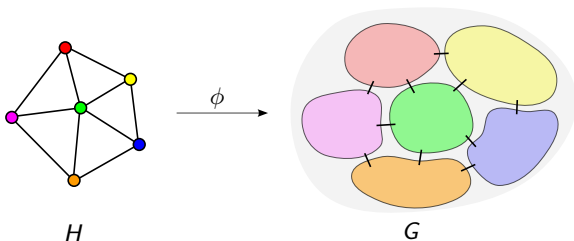
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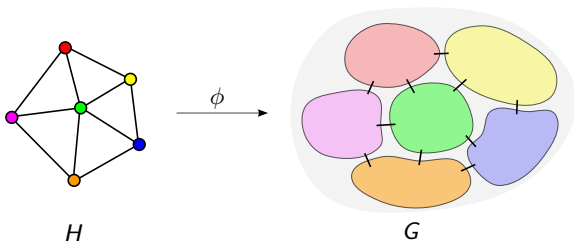
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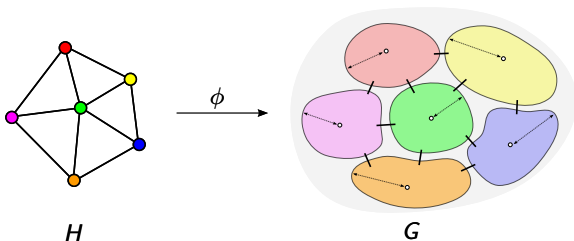
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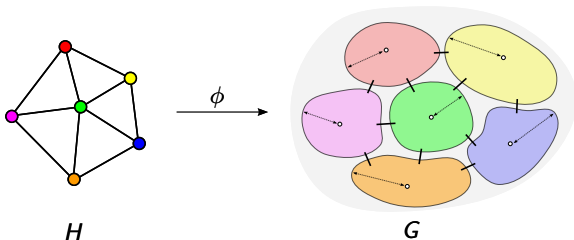
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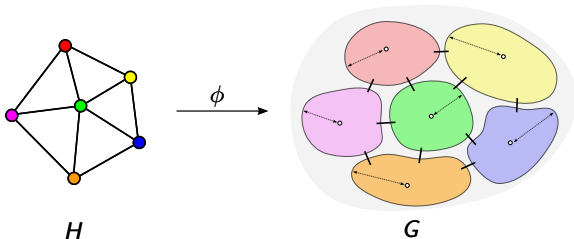
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- **Idea:** Replace **subgraphs** with **shallow minors** in the definition.



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 - If $H \in \mathcal{C} \nabla d$, then H has $\mathcal{O}_{\varepsilon,d}(|V(H)|^{1+\varepsilon})$ edges, for any $\varepsilon > 0$.

Hierarchy of sparsity

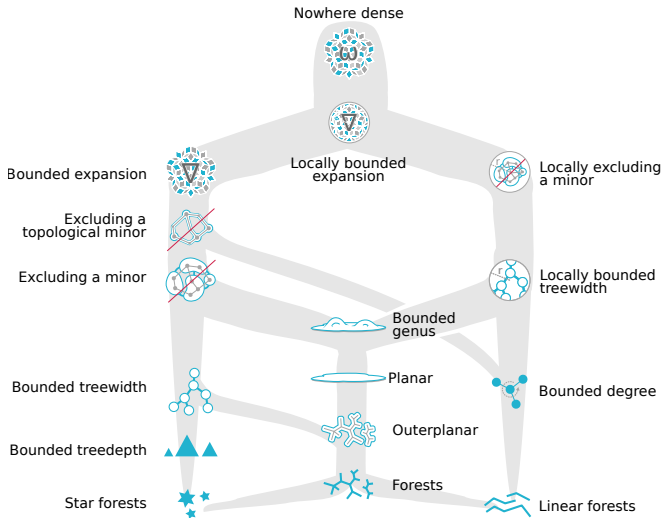


Figure by Felix Reidl

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 - **Nowhere denseness delimits tractability for many basic problems.**



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- FPT algorithms for structures whose Gaifman graphs have bounded degree, are planar, H -minor-free, ...

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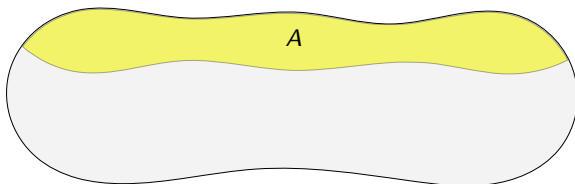
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 - Provides a natural barrier for locality-based methods.

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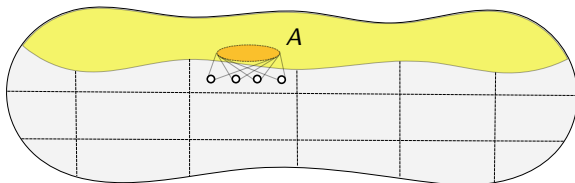


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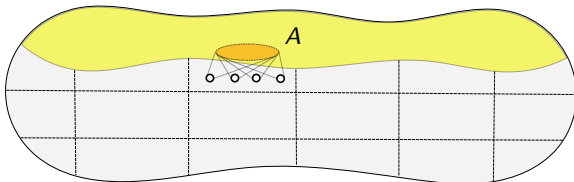
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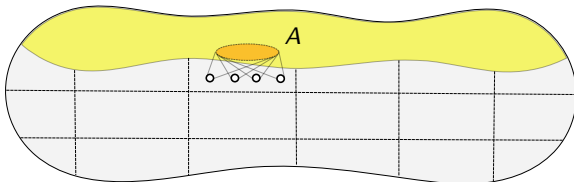
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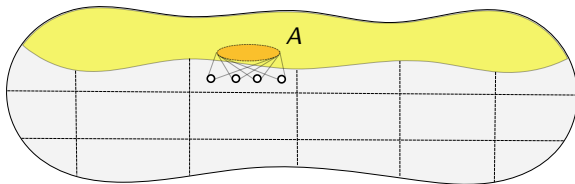


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Let \mathcal{C} be a class of graphs, $G \in \mathcal{C}$, $A \subseteq V(G)$, and $r \in \mathbb{N}$.

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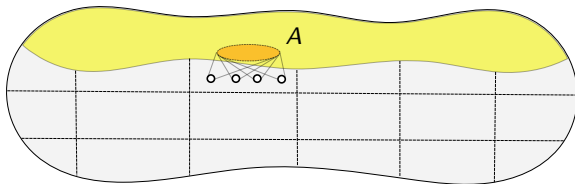


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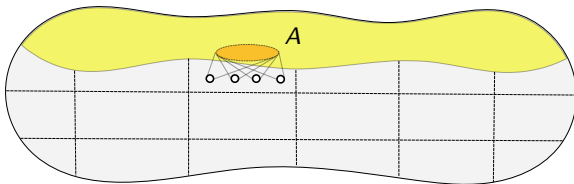


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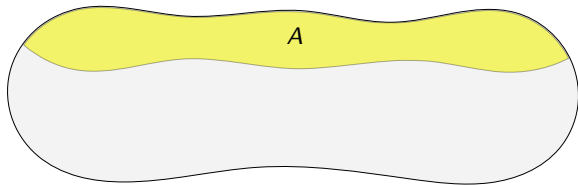
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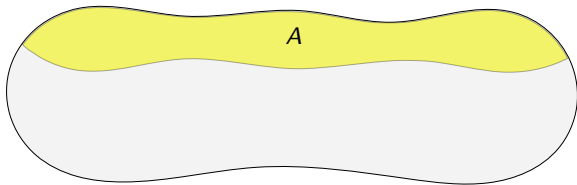
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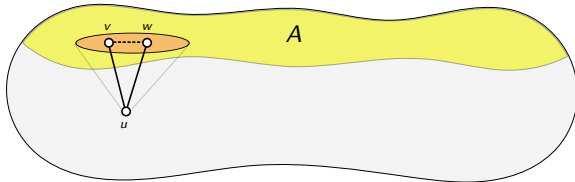
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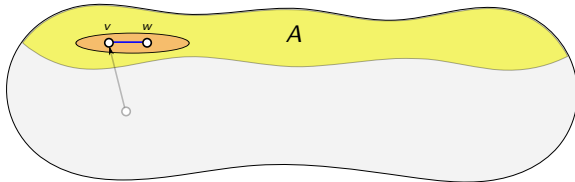
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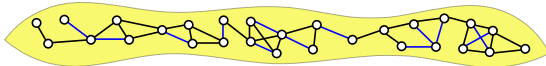
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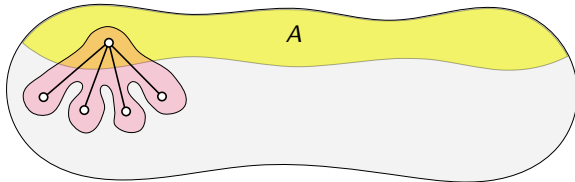


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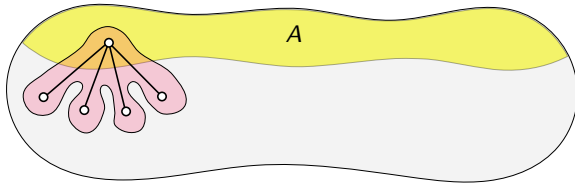
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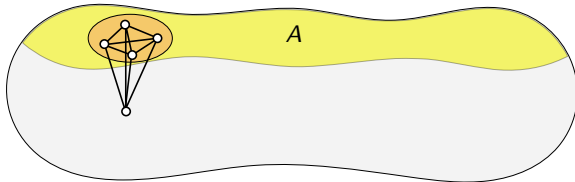
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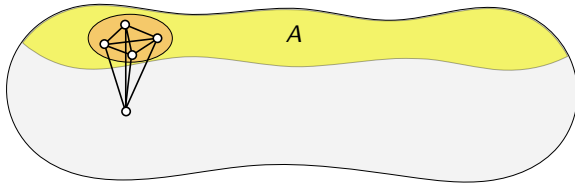
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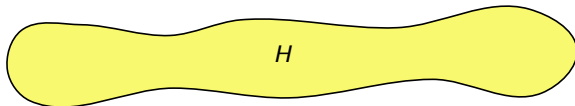
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- **Need:** The number of cliques in H is linear in $|A|$.



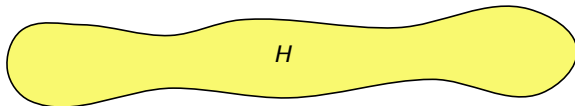
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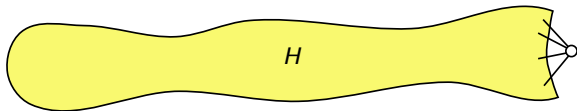
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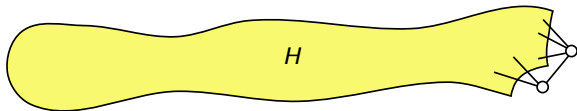
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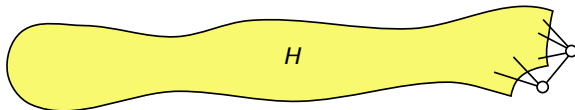
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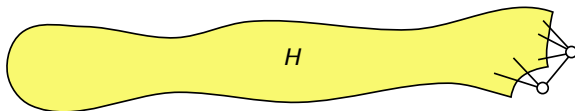
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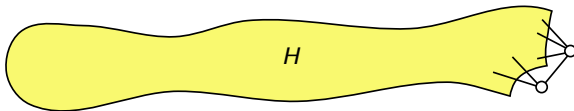
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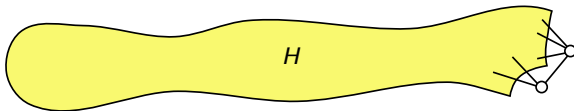
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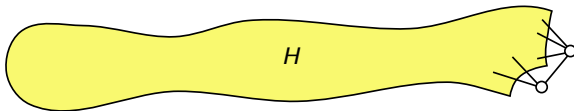
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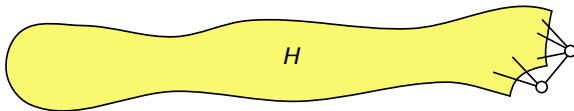
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Part 2: Stability and types

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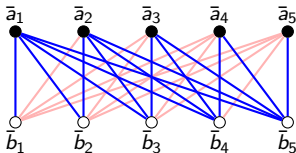
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such that for all $i, j \in \{1, \dots, k\}$ we have

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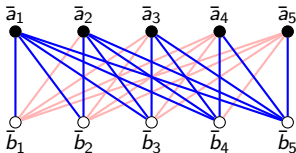
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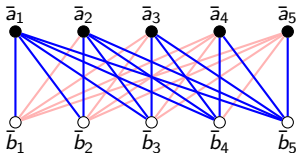
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A theory \mathbb{T} is stable if and only if for some infinite cardinal κ , for every model \mathbb{M} of \mathbb{T} and set $A \subseteq \mathbb{M}$ with $|A| \geq \kappa$, the number of types over A has the same cardinality as A .

Part 3: Sparsity and types

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Let \mathcal{C} be a monotone class of finite graphs.

Then \mathcal{C} is stable if and only if \mathcal{C} is nowhere dense.

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 - If \mathcal{C} is nowhere dense, then for any $\varepsilon > 0$ the number of δ -types over A is at most $c|A|^{|\bar{x}|+\varepsilon}$, where c depends on \mathcal{C} , δ , ε .
- We now sketch the proof for graph classes of bounded expansion and $|\bar{x}|, |\bar{y}| = 1$.

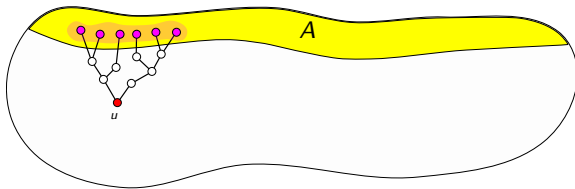
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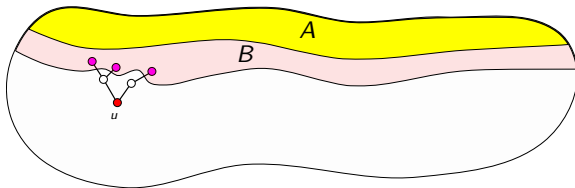
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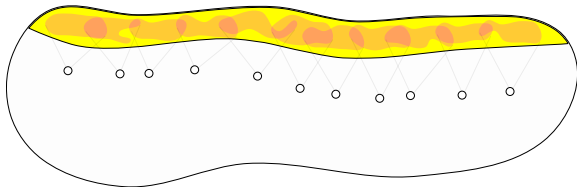
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vertices of A reachable from u by an A -avoiding paths of length $\leq r$.
- **Fact:** There exists $B \supseteq A$ such that
 - $|B| \leq c|A|$ and
 - every r -projection of $u \notin B$ onto B has size $\leq c$.



- **Cor:** We may assume that r -projections onto A are of constant size.

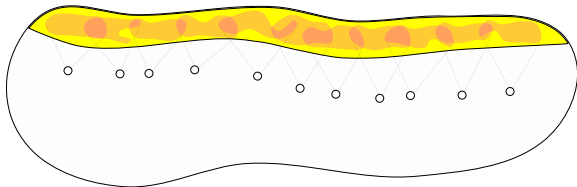
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- **Ergo:** It suffices to bound the number of types for each possible distance- r projection by a constant.



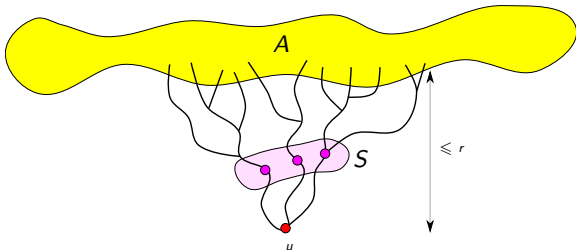
Locality

Feferman-Vaught Lemma

For every formula $\delta(x, y) \in \text{FO}(\Sigma)$ there exists $r \in \mathbb{N}$ and a finite set of formulas Δ such that the following holds.

Let G be a graph, u be a vertex, and A and S be subsets of vertices such that every path of length $\leq r$ from u to A passes through S . Then

$$\text{tp}_\delta(u/A) \quad \text{is determined by} \quad \text{tp}_\Delta(u/S).$$



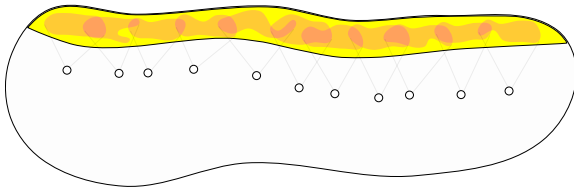
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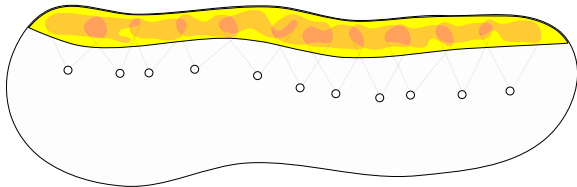
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- If S is the r -projection of u on A , then S r -separates u from A .
- The number of Δ -types on S of constant size is constant.



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- **Thank you for your attention!**