## Open Sets

Analysis

Nathanael Seen

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**Definition.** Let  $\langle M, \rho \rangle$ , be a metric space. A set  $G \subseteq M$  is open (in M), if for every  $x \in G$  there exists r > 0 such that  $B[x, r] \subseteq G$ .

## Examples.

1. In any metric space;  $\langle M, \rho \rangle$ , an open ball; B[a,r], is an open set. Proof. Let  $x \in B[a,r]$ . Then,  $\rho(x,a) < r$ , and set  $s = r - \rho(x,a) > 0$ . (WTS:  $B[x,s] \subseteq B[a,r]$ ) Now, take any  $y \in B[x,s]$ . Then, by the triangle inequality;

$$\rho(y,a) \le \rho(y,x) + \rho(x,a) < s + (r-s) = r$$

Thus,  $y \in B[a, r]$ , and we are done.

2. In the discrete metric space;  $\langle M, d \rangle$ , any subset  $G \subseteq M$  is open. Proof. Take any  $x \in G$ . (WTS:  $B[x,1] \subseteq G$ ) Now, for any  $y \in B[x,1]$ ,  $\rho(x,y) < 1$ . Thus,  $y = x \in G$ , and we are done. **Theorem.** In any metric space;  $\langle M, \rho \rangle$ , the empty set;  $\emptyset$ , and M, are both open (in M).

*Proof.* There are no  $x \in \emptyset$  in the first place. Thus, by vacuity, every  $x \in \emptyset$  satisfies the open set requirement, and  $\emptyset$  is open.

Now, for M, we can always find an open ball; B[x,r], namely one that only contains x, by choosing a (small enough) r>0. But, by definition of open balls, all balls must be contained in M. Hence, M is open.

**Theorem.** Let  $\mathcal{F}$  be a nonempty family of open sets in M, then  $\bigcup_{G \in \mathcal{F}} G$  is also open in M.

*Proof.* Take any  $x \in H = \bigcup_{G \in \mathcal{F}}$ . Then,  $x \in G$ , for some  $G \in \mathcal{F}$ . Since, G is open, then there exists an r > 0 where  $B[x, r] \subseteq G \subseteq H$ . Thus, H is open.

**Theorem.** The intersection of  $\underline{\text{finitely}}$  many open sets in M;  $\bigcap_{i=1}^{m} G_i$  is also open in M.

*Proof.* Take any  $x \in H = \bigcap_{i=1}^m G_i$ . Then,  $x \in G_i$ , for all  $i \in [1, m]$ . Since, each  $G_i$  is open, there exists  $r_i > 0$  where  $B[x, r_i] \subseteq G_i$ . Let  $r = \min\{r_1, r_2, \ldots, r_m\}$ . Then,  $B[x, r] \subseteq B[x, r_i] \subseteq G_i$  (for all i) = H. Hence, H is open.

**Remark.** The intersection of <u>infinitely</u> many open sets however might not always be open. Consider  $\overline{\mathbb{R}}$  with the Euclidean metric and  $G_n = B[0, \frac{1}{n}] = \left(\frac{-1}{n}, \frac{1}{n}\right)$ , which is open for all  $n \in \mathbb{N}$ . However,  $\bigcap_{n=1}^{\infty} G_n = \{0\}$ , is clearly not open (as we can never find any open ball of positive radii around 0).

**Theorem.** Let  $\langle M_1, \rho_1 \rangle$ ,  $\langle M_2, \rho_2 \rangle$  be metric spaces, and  $f: M_1 \to M_2$  be a function. Then f is continuous (on  $M_1$ ) if and only if  $f^{-1}(G)$  is open in  $M_1$  whenever G is open in  $M_2$  (for any subset  $G \subseteq M_1$ ).

*Proof.* Suppose that f is continuous (on  $M_1$ ) and G is open (in  $M_2$ ). Then, take any  $x \in f^{-1}(G) \Longrightarrow y = f(x) \in G$ . Since, G is open, then there exists some r > 0, where  $B[y, r] \subseteq G$ . But, since f is continuous, then (by the open ball characterisation of continuity)  $f^{-1}(B[y, r]) = f^{-1}(B[f(x), r]) \supseteq B[x, s]$ , for some s > 0. Thus,  $B[x, s] \subseteq f^{-1}(G)$ , and  $f^{-1}(G)$  is open, as needed.

Conversely, suppose that  $f^{-1}(G)$  is open in  $M_1$  if G is open in  $M_2$ . (WTS: f is continuous  $\iff \forall x \in M_1$  and  $\varepsilon > 0$ , there exists a  $\delta > 0$  such that  $f^{-1}(B[f(x),\varepsilon]) \supseteq B[x,\delta]$ .) Now, let  $x \in M_1$  and  $\varepsilon > 0$  be given. Then,  $f(x) \in f(M_1) \subseteq M_2$ , and consider the open ball;  $B[f(x),\varepsilon] \subseteq M_2$ , which is open in  $M_2$ . Then, by our supposition,  $f^{-1}(B[f(x),\varepsilon]) \subseteq M_1$  is also open in  $M_1$ . But,  $x \in f^{-1}(B[f(x),\varepsilon])$ , and since  $B[f(x),\varepsilon]$  is open, then there exists a  $\delta > 0$  such that  $B[x,\delta] \subseteq f^{-1}(B[f(x),\varepsilon])$ . But, this is exactly what we wanted for f to be continuous, and we are done.

**Remark.** Both directions of the previous proof uses the open ball characterisation of continuity. The proof however, gives us yet another characterisation of continuity; this time more generally in terms of open sets!