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# Building a Simple Command-Line Interface (CLI)

**Nathan** Jones

# AGENDA

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Why and What is it?

2

Plan of Attack

3

Step 1: Read from UART

4

Step 2: Simple commands

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Step 3: Commands + values

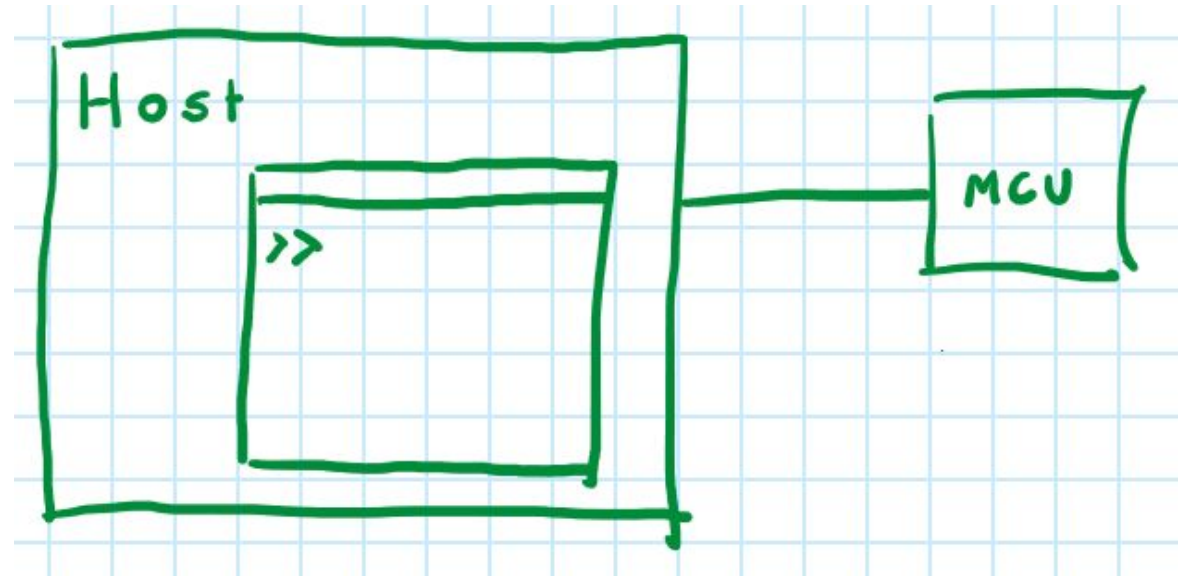
6

Going Further

<https://github.com/nathancharlesjones/simple-cli>

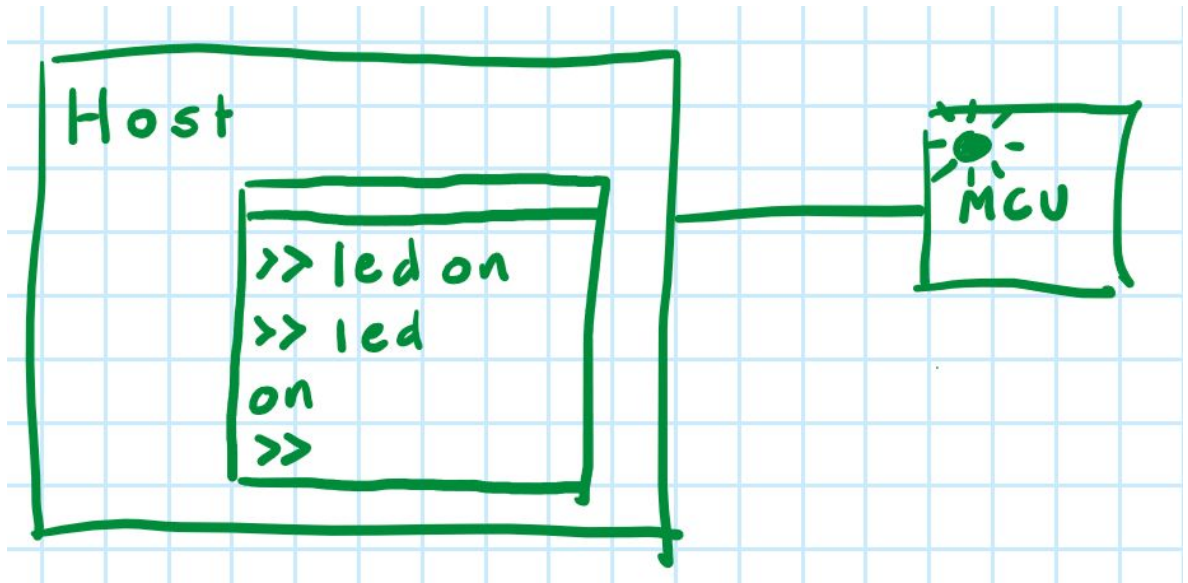
# Why and What is it?

- Control tasks
- Query state
- REPL
- Load data/firmware
- On-chip debugging
- Monitor/small OS



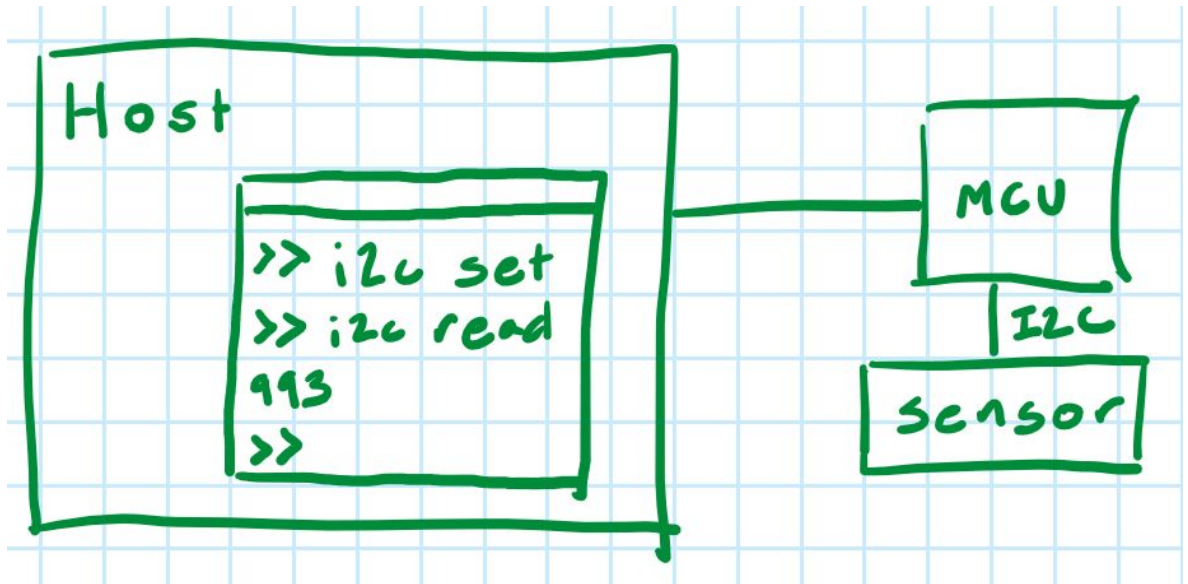
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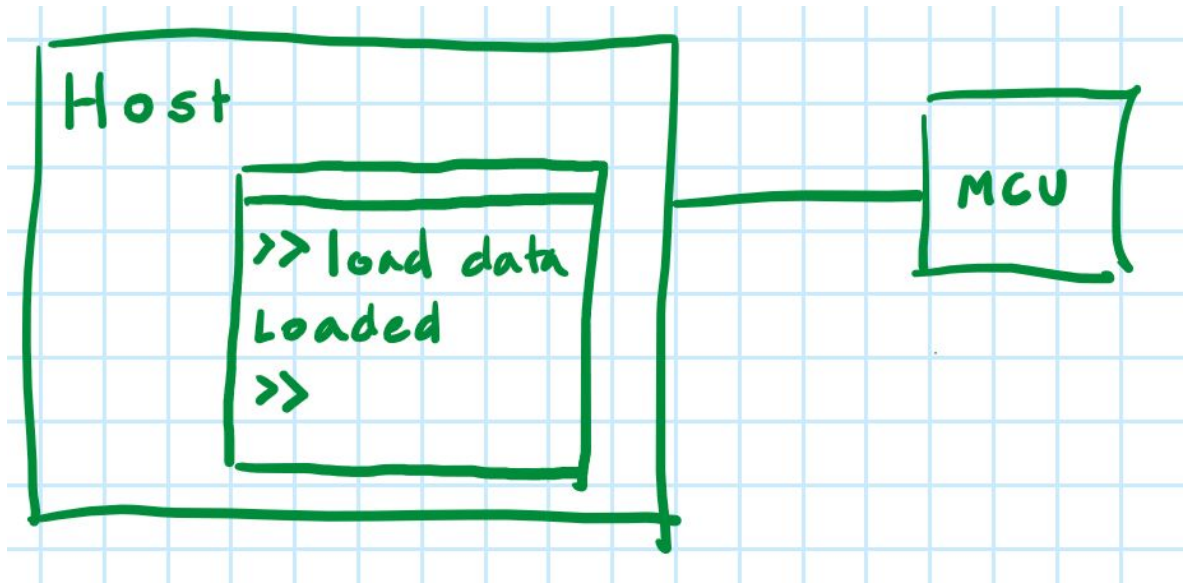
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- Control tasks
- Query state
- **REPL**
- Load data/firmware
- On-chip debugging
- Monitor/small OS



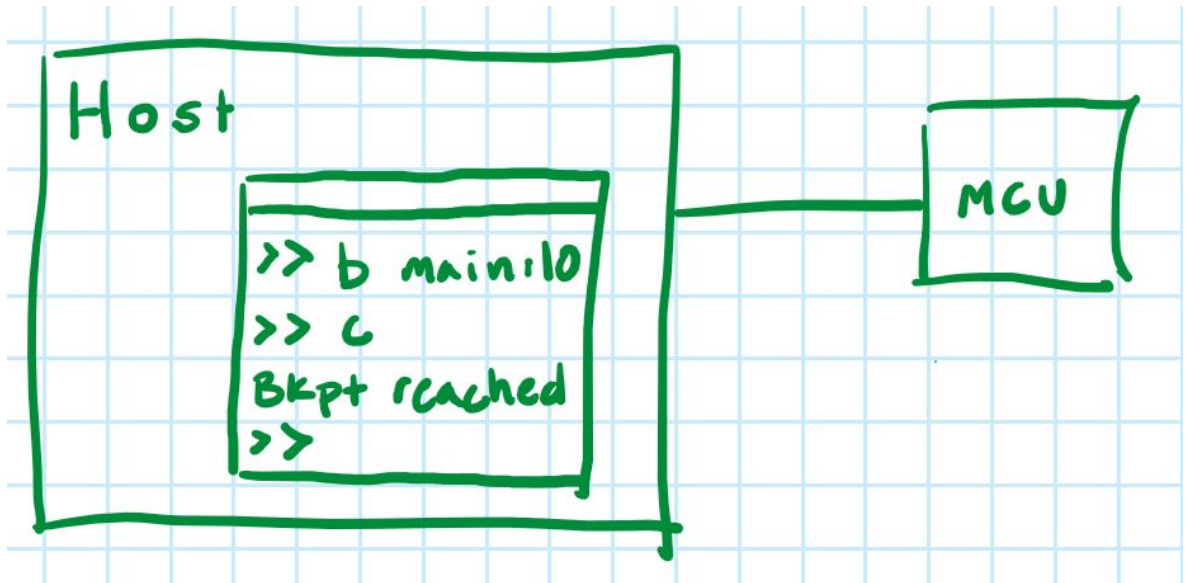
# Why and What is it?

- Control tasks
- Query state
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- **Load data/firmware**
- On-chip debugging
- Monitor/small OS



# Why and What is it?

- Control tasks
- Query state
- REPL
- Load data/firmware
- **On-chip debugging (Cortex-M)**
- Monitor/small OS



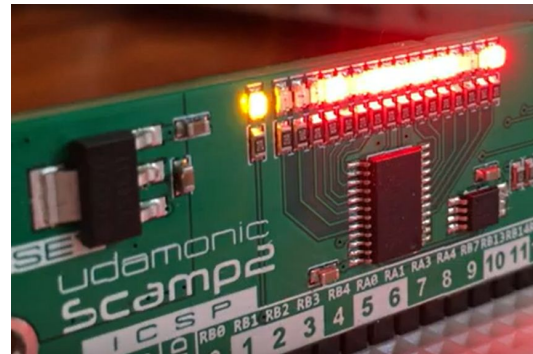
# Why and What is it?

- Control tasks
- Query state
- REPL
- Load data/firmware
- On-chip debugging
- **Monitor/small OS**

```
: blinken
begin
    random leds
    blink
    key? until
    0 leds
;

ok

blinken|
```



```
uShell 0.1.0
[host /]$ ls
d---- .
d---- bin/
d---- dev/
d---- etc/
-r--- readme.txt
[host /]$ cat readme.txt
Welcome to MicroShell DEMO implementation!
You will see how most common features work.
Enjoy!
[host /]$
```





The first thing I do in a new project is blink an LED. The next thing is to bring up a command-line shell. It's a great way to get stuff running quickly.

- andyturk (on the [EEVBlog forum](#))

# 1

## Command-Line Blinky

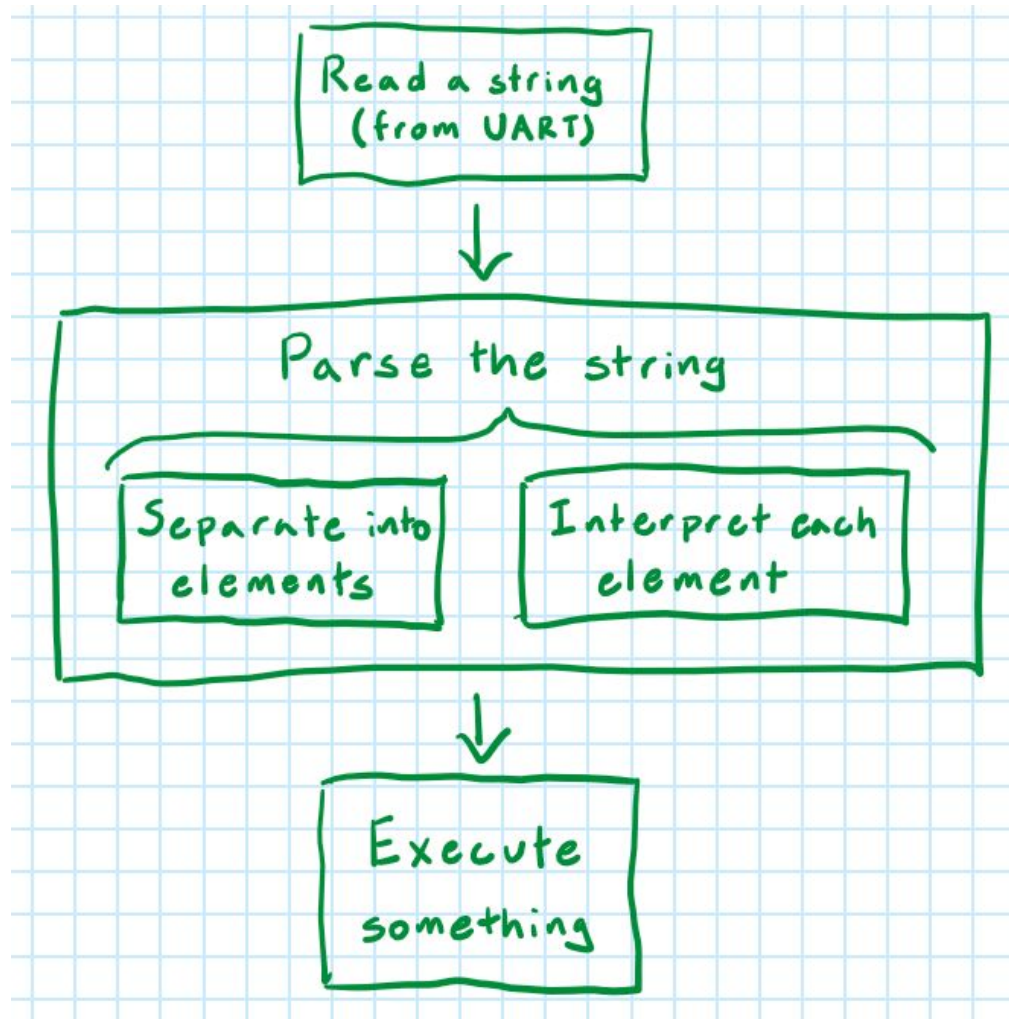
Message Dictionary	
on	Turns the LED on (at the last stored duty cycle & frequency)
off	Turns the LED off
dc <val>	Sets the duty cycle. Val is an integer percent value. Returns the current duty cycle if <val> is omitted.
freq <val>	Sets the blink frequency. Val is a float value in Hertz. Returns the current frequency if <val> is omitted.



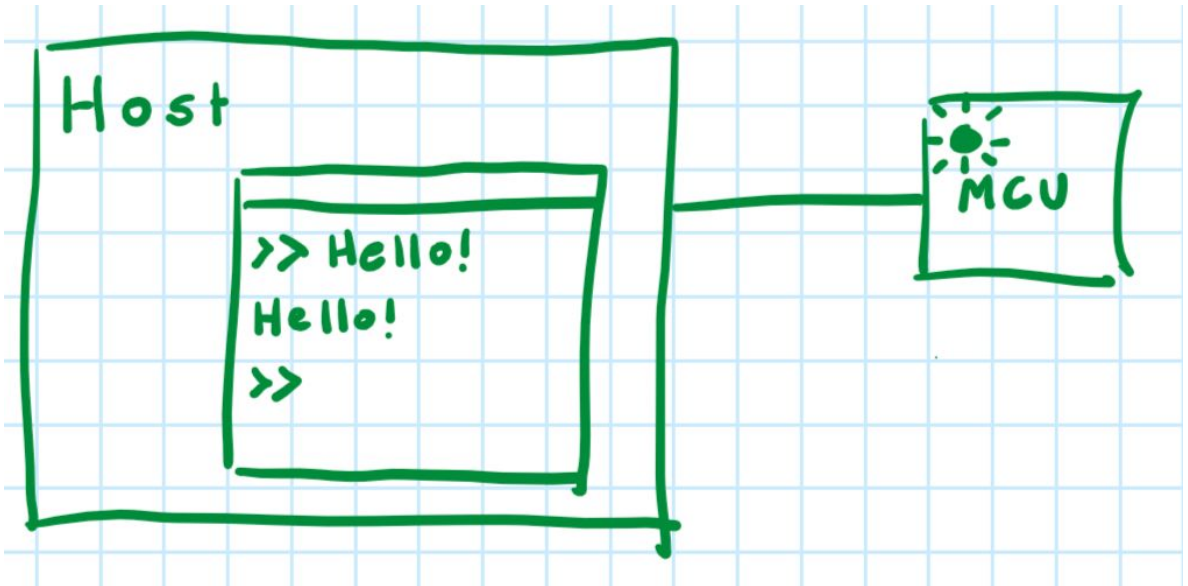
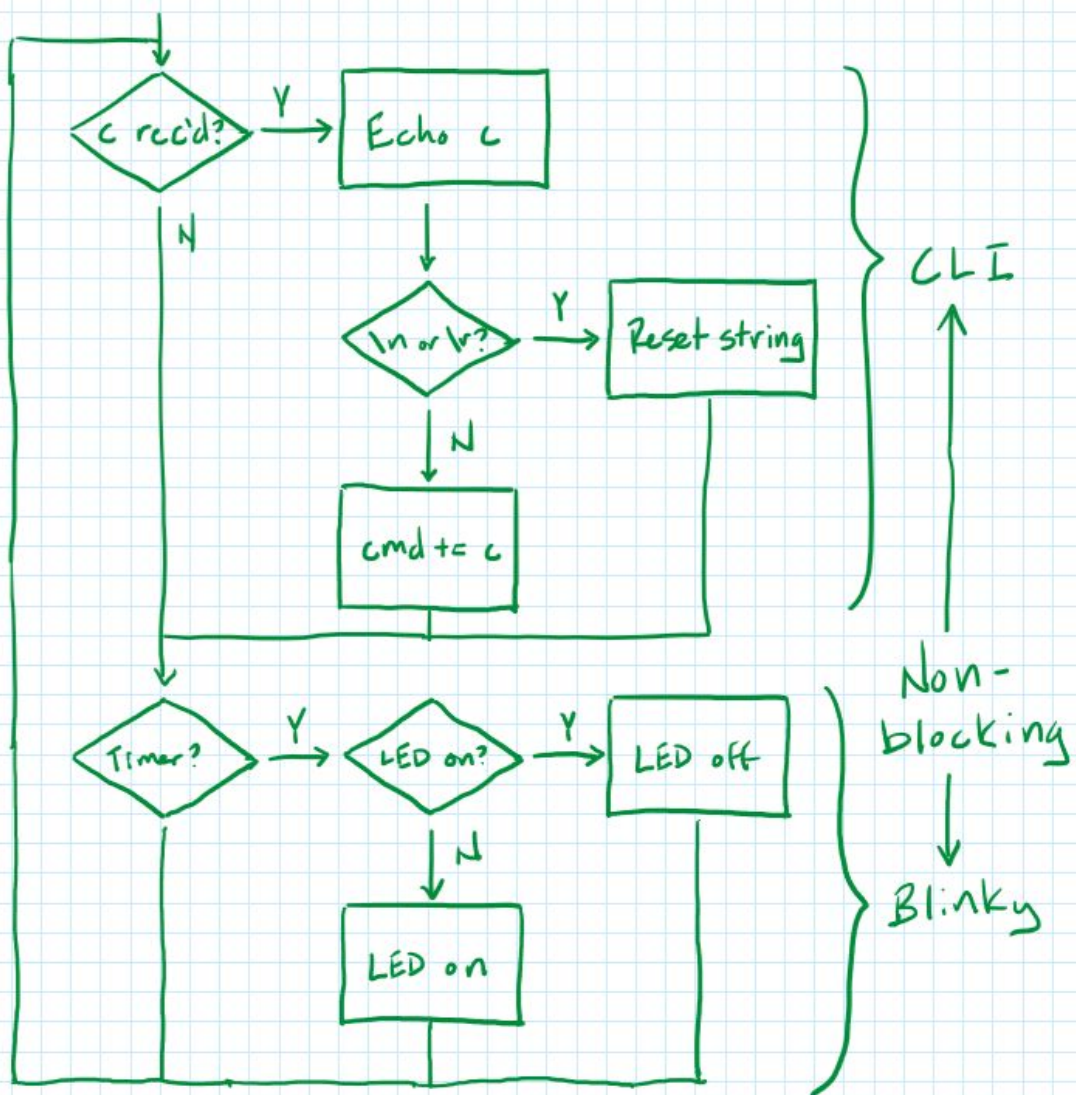
# Live Display of ADC Values with PyQt

Message Dictionary		
To	r	Requests an ADC value
From	<val>	4-digit ADC value in ASCII

# Plan of Attack



# Step 1: Read from UART



# Step 1: Read from UART

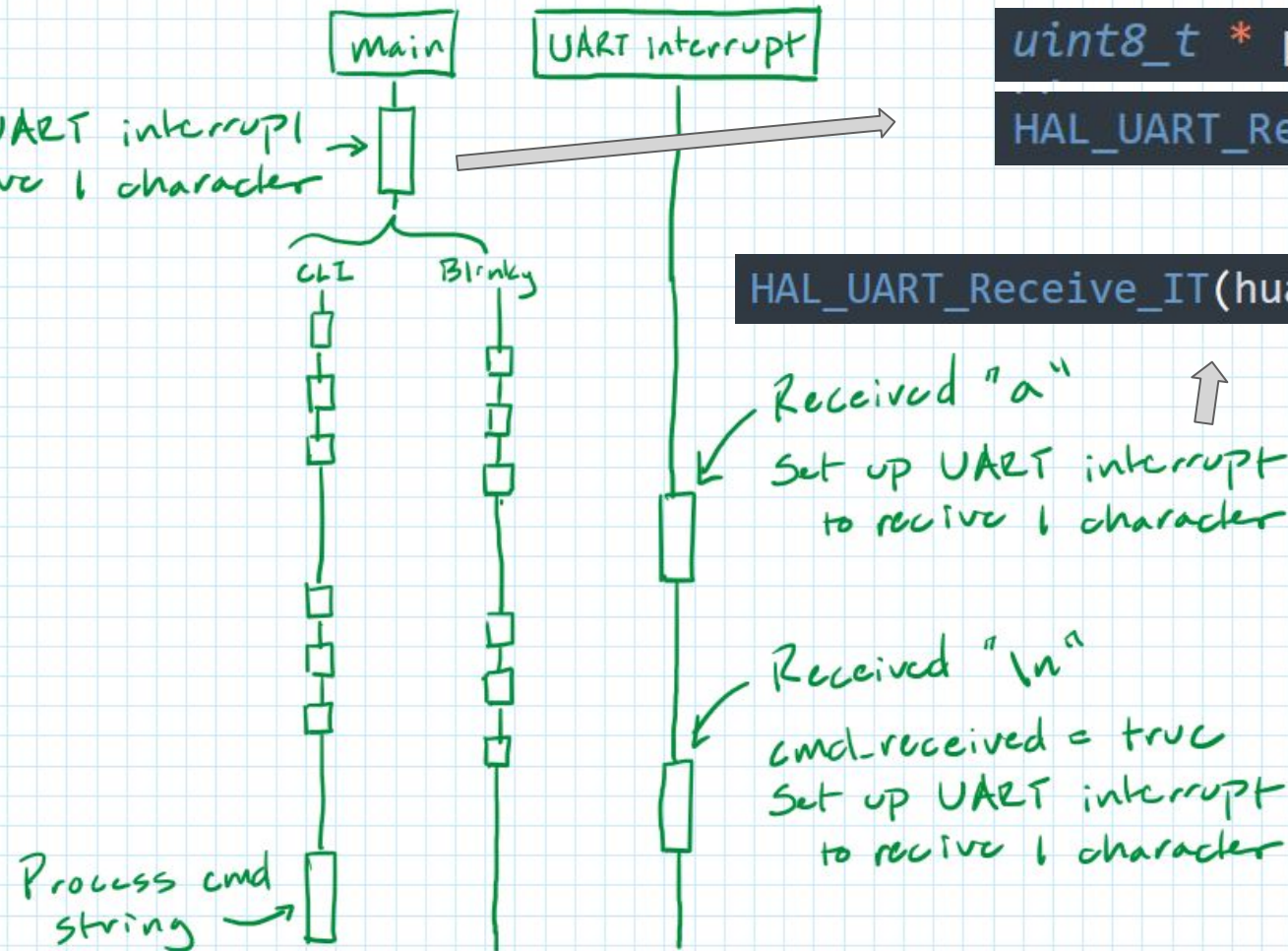
~~Serial.available()~~

```
uint8_t cmd[MAX_CMD_LEN] = {0};
```

```
uint8_t * p_current_char = cmd;
```

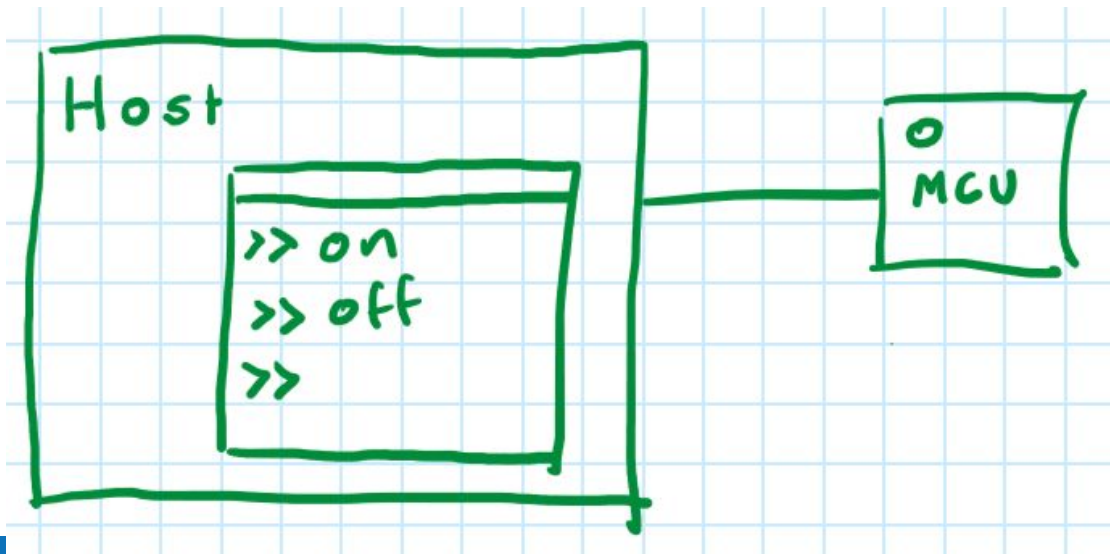
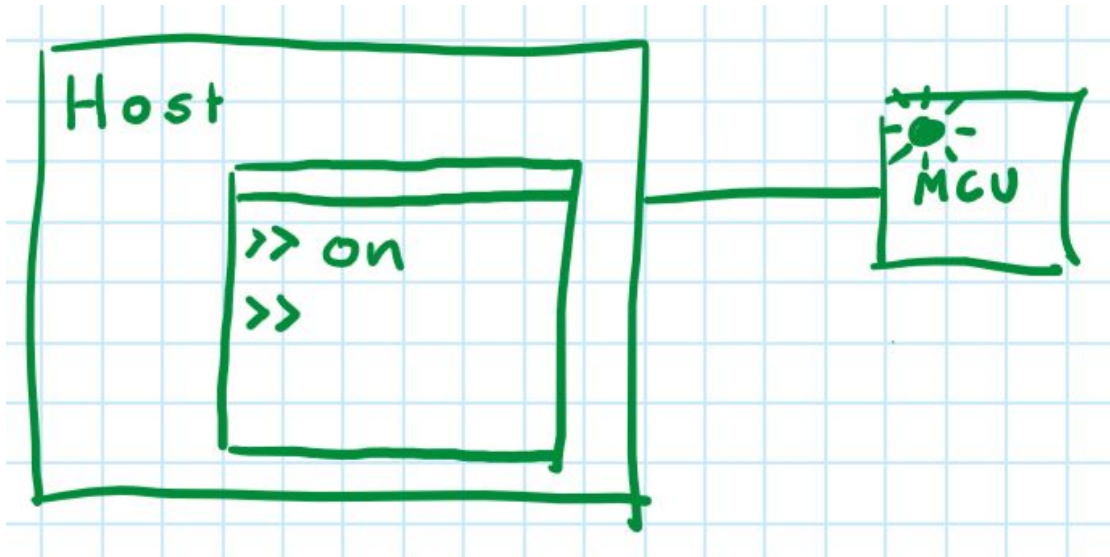
```
HAL_UART_Receive_IT(&huart2, cmd, (size_t)1);
```

```
HAL_UART_Receive_IT(huart, ++p_current_char, (size_t)1);
```





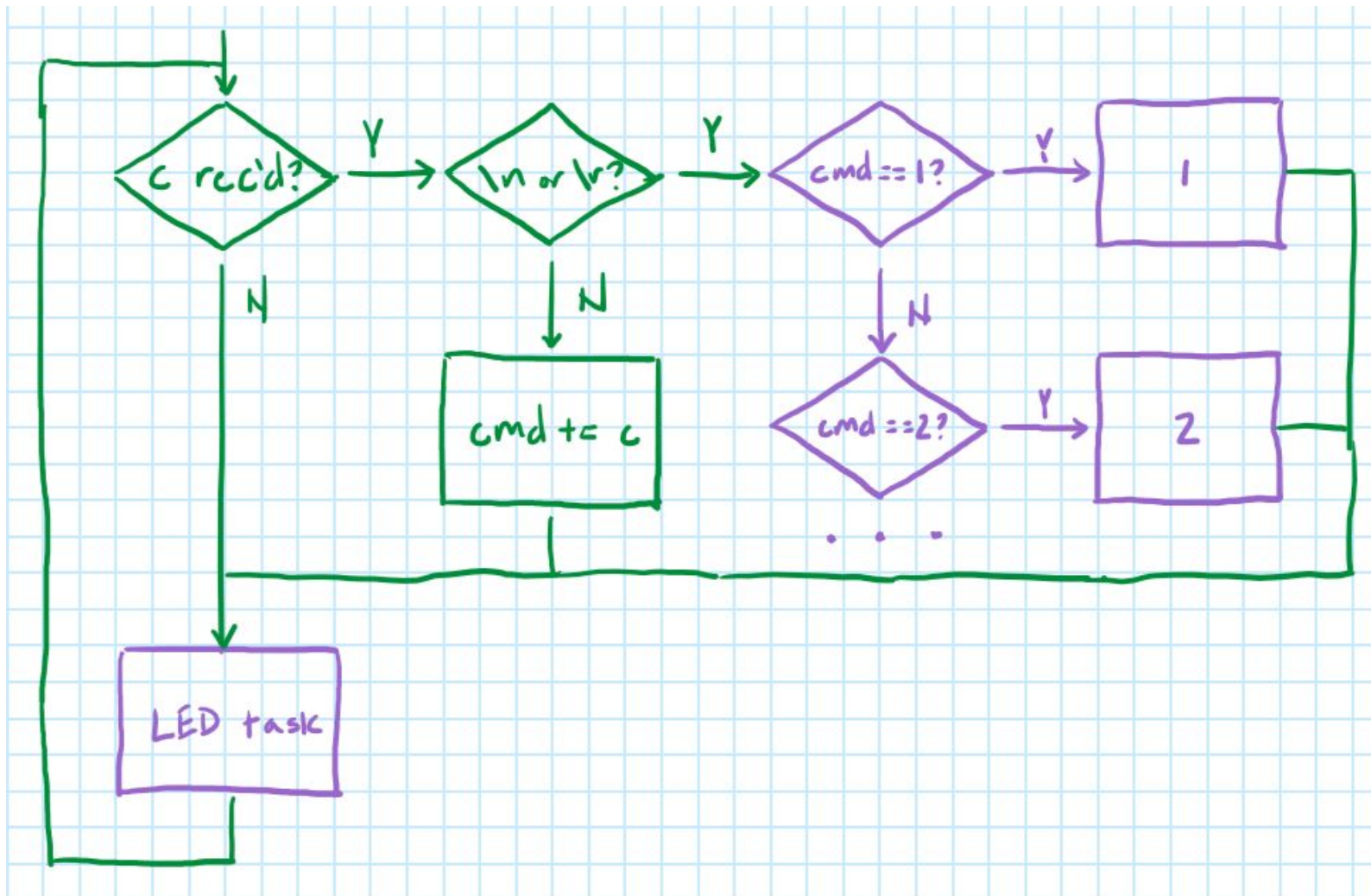
## Step 2: Simple Commands



### Message Dictionary

on	Turns on the on-board LED
off	Turns off the on-board LED

## Step 2: Simple Commands

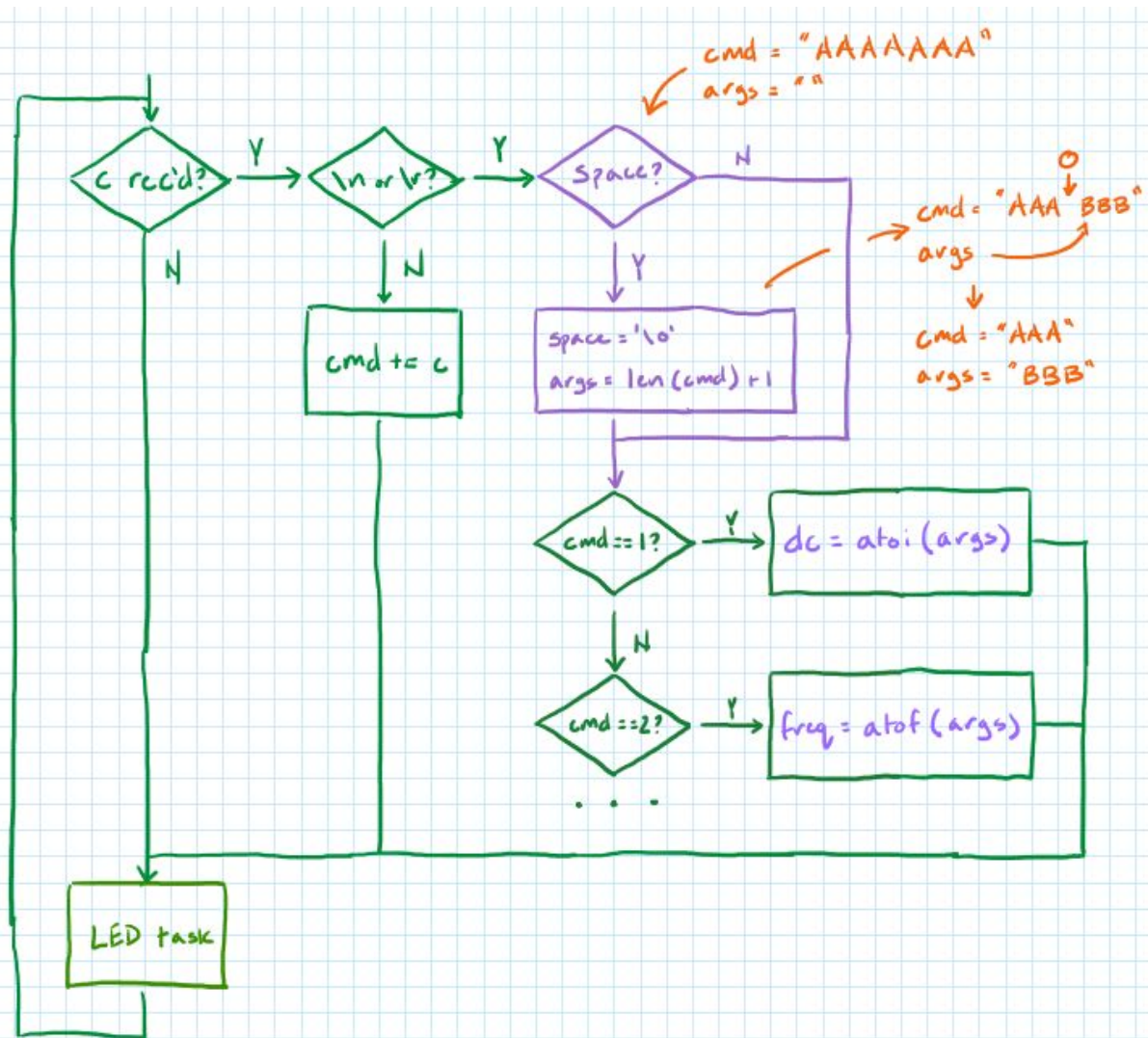


### Message Dictionary

on	Turns on the on-board LED
off	Turns off the on-board LED



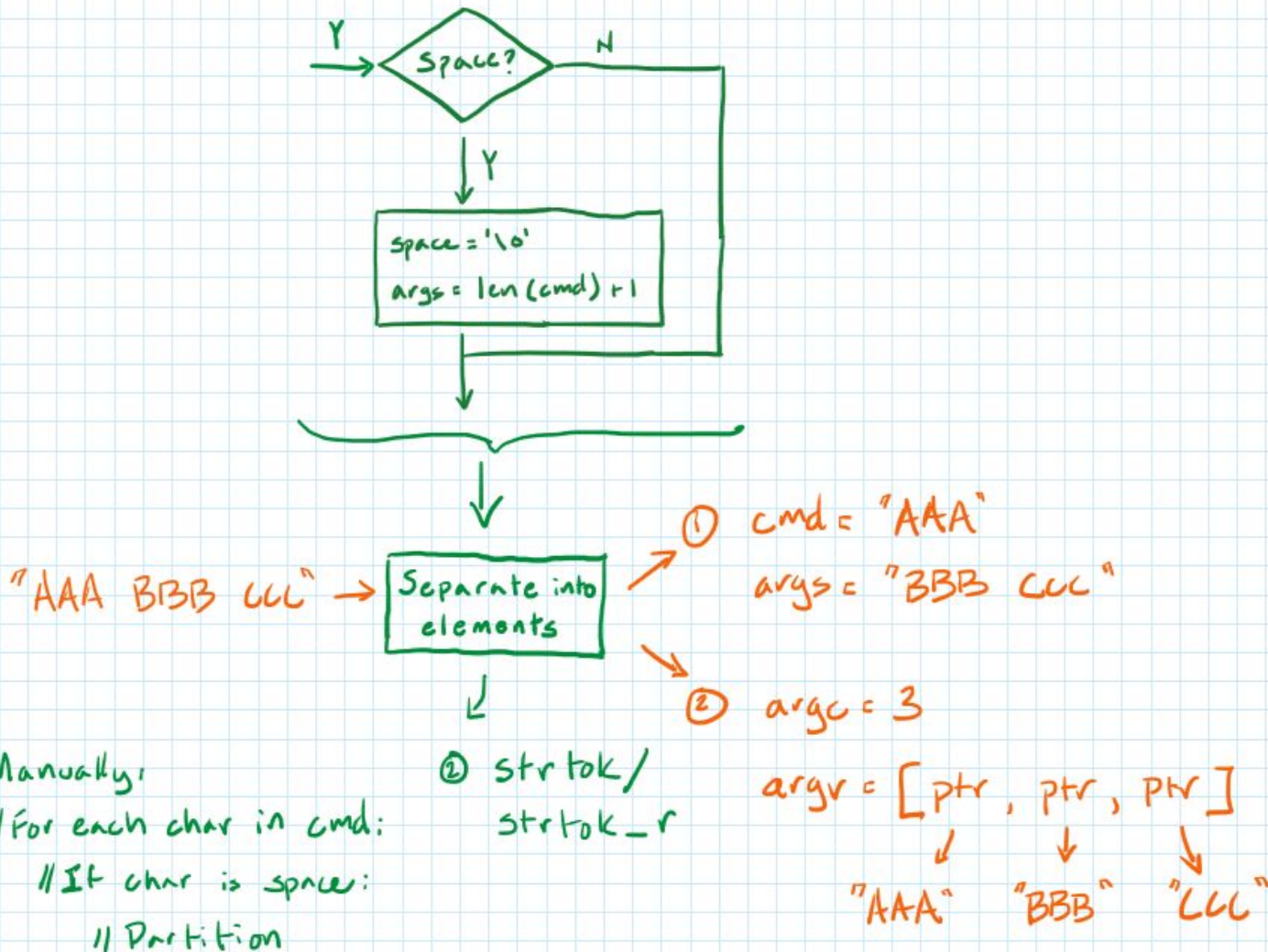
## Step 3: Commands + Values



### Message Dictionary

on	Turns the LED on (at the last stored duty cycle & frequency)
off	Turns the LED off
dc <val>	Sets the duty cycle. Val is an integer percent value. Returns the current duty cycle if <val> is omitted.
freq <val>	Sets the blink frequency. Val is a float value in Hertz. Returns the current frequency if <val> is omitted.

## Step 3: Commands + Values



# Going Further

## CLI Libraries

- [Anchor](#)
- [Memfault](#)
- [Args](#)
- [getopt](#) / [Gengetopt](#)

## Architectural Improvements

- Wireless communication
- Modules/Message passing
- RTOS
- Double-buffering
- Security
- Framing
- Error checking

## 6

# Wireless CLI

Message Dictionary	
on	Turns the LED on (at the last stored duty cycle & frequency)
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freq <val>	Sets the blink frequency. Val is a float value in Hertz. Returns the current frequency if <val> is omitted.

# Going Further

## Improving line reading

- [getline](#)
- [linenoise](#)

## Interpreters/Monitors/OSes

- [FlashForth](#)
- [uBASIC](#)
- [microshell](#)
- [RIDE Shell and C.impl interpreter](#) (ELLO computer)

## [On-chip Debugging](#)

# THANK YOU

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