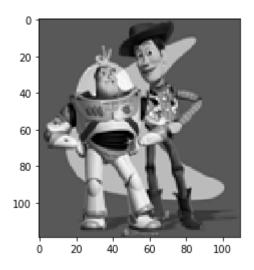
```
In [1]: import cv2
import time
import numpy as np
from scipy.sparse import csr_matrix
from scipy.sparse import lil_matrix
from scipy.sparse.linalg import lsqr
%matplotlib inline
import matplotlib.pyplot as plt
from utils import *
import os
```

```
In [2]: toy_img = cv2.cvtColor(cv2.imread('samples/toy_problem.png'), cv2.COLOR_
toy_img = cv2.cvtColor(toy_img, cv2.COLOR_BGR2GRAY).astype('double') / 2
plt.imshow(toy_img, cmap="gray")
```

Out[2]: <matplotlib.image.AxesImage at 0x7f26d022e790>



Part 1 Toy Problem (20 pts)

```
In [78]: def toy_reconstruct(toy_img):
             The implementation for gradient domain processing is not complicated
             1. minimize (v(x+1,y)-v(x,y) - (s(x+1,y)-s(x,y)))^2
             2. minimize (v(x,y+1)-v(x,y) - (s(x,y+1)-s(x,y)))^2
             Note that these could be solved while adding any constant value to
             3. minimize (v(1,1)-s(1,1))^2
             :param toy img: numpy.ndarray
             im=toy img
             im_h, im_w = toy_img.shape
             im2var = np.arange(im_h * im_w).reshape(im_w, im_h).T
             num v = (im h)*(im w)
             num e = im h*(im w-1) + im w*(im h-1) + 1
             \#A = np.zeros((num e, num v))
             A = lil matrix((num e,num v))
             b = np.zeros((num_e,))
             e=0
             for x in range(im w):
                 for y in range(im_h):
                     if x < im w-1:
                         A[e,im2var[y][x+1]] = 1
                         A[e,im2var[y][x]] = -1
                         b[e] = im[y][x+1] - im[y][x]
                         e+=1
                     if y < im h-1:
                         A[e,im2var[y+1][x]] = 1
                         A[e,im2var[y][x]] = -1
                         b[e] = im[y+1][x] - im[y][x]
                         e+=1
             A[e,im2var[0][0]] = 1
             b[e] = im[0][0]
             A=A.tocsr()
             v = lsqr(A, b)
             return v[0].reshape((im_w, im_h)).T
```

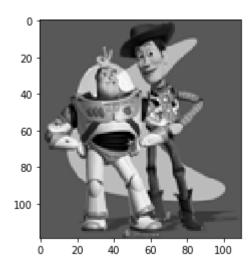
```
In [79]: im_out = toy_reconstruct(toy_img)

if im_out.any():
    print("Error is: ", np.sqrt(((im_out - toy_img)**2).sum()))

plt.close()
plt.imshow(im_out, cmap="gray")
```

Error is: 0.00031701850068623744

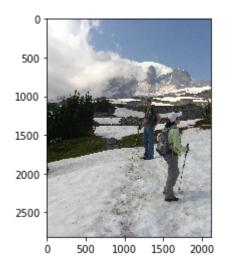
Out[79]: <matplotlib.image.AxesImage at 0x7f26c40e7590>



### **Preparation**

# In [5]: # Feel free to change image background\_img = cv2.cvtColor(cv2.imread('samples/im2.JPG'), cv2.COLOR\_E plt.figure() plt.imshow(background\_img)

#### Out[5]: <matplotlib.image.AxesImage at 0x7f26cfd072d0>



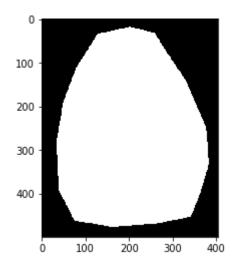
# In [7]: # Feel free to change image object\_img = cv2.cvtColor(cv2.imread('samples/penguin-chick.jpeg'), cv2. import matplotlib.pyplot as plt %matplotlib notebook mask\_coords = specify\_mask(object\_img)

If it doesn't get you to the drawing mode, then rerun this function ag ain.



```
In [8]: xs = mask_coords[0]
    ys = mask_coords[1]
    %matplotlib inline
    import matplotlib.pyplot as plt
    plt.figure()
    mask = get_mask(ys, xs, object_img)
```

<Figure size 432x288 with 0 Axes>

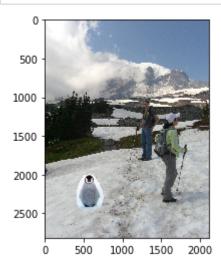


# In [9]: %matplotlib notebook import matplotlib.pyplot as plt bottom\_center = specify\_bottom\_center(background\_img)

If it doesn't get you to the drawing mode, then rerun this function ag ain. Also, make sure the object fill fit into the background image. Ot herwise it will crash



In [10]: %matplotlib inline
 import matplotlib.pyplot as plt
 cropped\_object, object\_mask = align\_source(object\_img, mask, background)



**Part 2 Poisson Blending (50 pts)** 

```
In [2]: def hms(secs):
    hours = int(secs/3600.)
    remain = secs - hours*3600
    mins = int(remain/60.)
    remain = int(remain - mins*60)
    return (hours, mins, remain)
```

```
In [3]: def poisson blend(cropped object, object_mask, background_img):
            :param cropped object: numpy.ndarray One you get from align source
            :param object mask: numpy.ndarray One you get from align source
             :param background img: numpy.ndarray
            #T0 D0
            \#idx is the list of x, y coordinates that are in the mask
            idx = np.where(object mask==1)
            idx = np.concatenate((idx[0].reshape(-1,1),idx[1].reshape(-1,1)),axi
            s=cropped object
            t=background img
            im h, im w, = t.shape
            im2var = np.arange(im_h * im_w).reshape(im_w, im_h).T
            num v = im h*im w
            num e = np.where(object mask==1)[0].shape[0] * 5
            return v = np.zeros(t.shape)
            for c in range(3):
                #A = csr_matrix((num_e,num_v))
                A = lil matrix((num e,num v))
                b = np.zeros((num e,))
                e=0
                tick = time.time()
                for x in range(im w):
                    for y in range(im_h):
                         if object mask[y][x]==1:
                             if \times < im w-1:
                                 A[e,im2var[y][x+1]] = -1
                                 A[e,im2var[y][x]] = 1
                                 b[e] = s[y][x][c] - s[y][x+1][c]
                                 e+=1
                             if y < im h-1:
                                 A[e,im2var[y+1][x]] = -1
                                 A[e,im2var[y][x]] = 1
                                 b[e] = s[y][x][c] - s[y+1][x][c]
                                 e+=1
                             if x > 0:
                                 A[e,im2var[y][x-1]] = -1
                                 A[e,im2var[y][x]] = 1
                                 b[e] = s[y][x][c] - s[y][x-1][c]
                                 e+=1
                             if y > 0:
                                 A[e,im2var[y-1][x]] = -1
                                 A[e,im2var[y][x]] = 1
                                 b[e] = s[y][x][c] - s[y-1][x][c]
                                 e+=1
                             if object mask[y][x+1]==0:
                                 A[e,im2var[y][x]] = 1
                                 b[e] = t[y][x+1][c] + s[y][x][c] - s[y][x+1][c]
                             if object_mask[y][x-1]==0:
                                 A[e,im2var[v][x]] = 1
                                 b[e] = t[y][x-1][c] + s[y][x][c] - s[y][x-1][c]
```

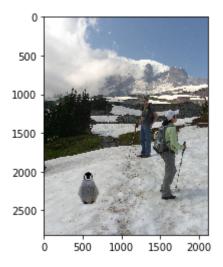
```
e+=1
                if object mask[y+1][x]==0:
                    A[e,im2var[y][x]] = 1
                    b[e] = t[y+1][x][c] + s[y][x][c] - s[y+1][x][c]
                    e+=1
                if object_mask[y-1][x]==0:
                    A[e,im2var[y][x]] = 1
                    b[e] = t[y-1][x][c] + s[y][x][c] - s[y-1][x][c]
    tock = time.time()
    hr, mn, sc = hms(tock-tick)
    print(f'Equations for channel {c} took {hr} hours, {mn} minutes,
    tick = time.time()
    A=A.tocsr()
    A=csr matrix(A)
    A=A[:e,:]
    b=b[:e]
    tock = time.time()
    hr, mn, sc = hms(tock-tick)
    print(f'Segmenting for channel {c} took {hr} hours, {mn} minutes
    tick = time.time()
    v = lsqr(A, b)
    tock = time.time()
    hr, mn, sc = hms(tock-tick)
    print(f'LSQR for channel {c} took {hr} hours, {mn} minutes, and
    return v[:,:,c] = v[0].reshape((im w, im h)).T
d3 mask = np.stack((object mask,object mask),axis=2)
return_v = background_img*(1-d3_mask) + return_v*d3_mask
return v[return v > 1] = 1.
return v[return v < 0] = 0.
return return_v
```

```
In [13]: tickt = time.time()
   im_blend = poisson_blend(cropped_object, object_mask, background_img)
   if im_blend.any():
        %matplotlib inline
        import matplotlib.pyplot as plt
        plt.imshow(im_blend)
        tockt = time.time()

   h, m, s = hms(tockt-tickt)

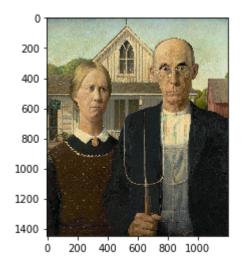
   print(f'Total time took {h} hours, {m} minutes, and {s} seconds')
```

```
Equations for channel 0 took 0 hours, 0 minutes, and 10 seconds
Segmenting for channel 0 took 0 hours, 0 minutes, and 0 seconds
(505756, 5947392)
(505756,)
5947392
505756
LSQR for channel 0 took 0 hours, 1 minutes, and 43 seconds
Equations for channel 1 took 0 hours, 0 minutes, and 10 seconds
Segmenting for channel 1 took 0 hours, 0 minutes, and 0 seconds
(505756, 5947392)
(505756,)
5947392
505756
LSQR for channel 1 took 0 hours, 1 minutes, and 42 seconds
Equations for channel 2 took 0 hours, 0 minutes, and 10 seconds
Segmenting for channel 2 took 0 hours, 0 minutes, and 0 seconds
(505756, 5947392)
(505756,)
5947392
505756
LSQR for channel 2 took 0 hours, 1 minutes, and 43 seconds
Total time took 0 hours, 5 minutes, and 43 seconds
```



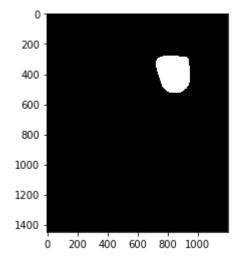
```
In [3]: background_img = cv2.cvtColor(cv2.imread('samples/farmer.jpg'), cv2.COL(
    plt.close()
    plt.imshow(background_img)
```

Out[3]: <matplotlib.image.AxesImage at 0x7f40d80a6350>



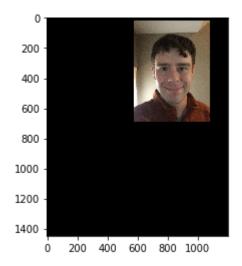
```
In [4]: object_mask = cv2.cvtColor(cv2.imread('samples/face_mask.jpg'), cv2.COL(
   object_mask = np.mean(object_mask,axis=2)
   object_mask[object_mask >= 0.5] = 1.
   object_mask[object_mask < 0.5] = 0.
   plt.close()
   plt.imshow(object_mask,cmap='gray')</pre>
```

Out[4]: <matplotlib.image.AxesImage at 0x7f40d7bbd810>



```
In [5]: foreground_img = cv2.cvtColor(cv2.imread('samples/smile_cropped.jpg'), or plt.close()
    plt.imshow(foreground_img)
```

Out[5]: <matplotlib.image.AxesImage at 0x7f40d7b37390>

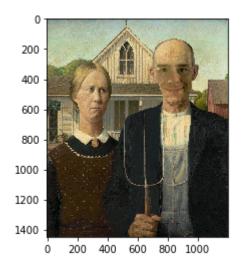


```
In [9]: tickt = time.time()
    im_blend = poisson_blend(foreground_img, object_mask, background_img)
    if im_blend.any():
        %matplotlib inline
        import matplotlib.pyplot as plt
        plt.imshow(im_blend)
    tockt = time.time()

h, m, s = hms(tockt-tickt)

print(f'Total time took {h} hours, {m} minutes, and {s} seconds')
```

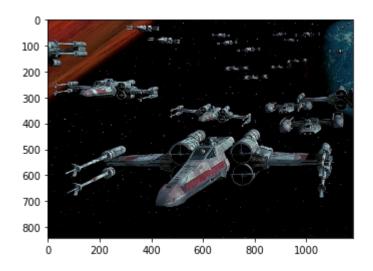
Equations for channel 0 took 0 hours, 0 minutes, and 1 seconds Segmenting for channel 0 took 0 hours, 0 minutes, and 0 seconds LSQR for channel 0 took 0 hours, 0 minutes, and 16 seconds Equations for channel 1 took 0 hours, 0 minutes, and 1 seconds Segmenting for channel 1 took 0 hours, 0 minutes, and 0 seconds LSQR for channel 1 took 0 hours, 0 minutes, and 16 seconds Equations for channel 2 took 0 hours, 0 minutes, and 2 seconds Segmenting for channel 2 took 0 hours, 0 minutes, and 0 seconds LSQR for channel 2 took 0 hours, 0 minutes, and 16 seconds Total time took 0 hours, 0 minutes, and 57 seconds



In [10]: plt.imsave('smile\_farmer.jpg',im\_blend)

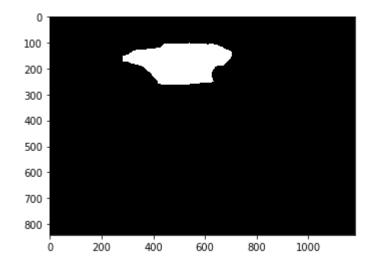
```
In [11]: background_img = cv2.cvtColor(cv2.imread('samples/xwings.jpg'), cv2.COL(
    plt.close()
    plt.imshow(background_img)
```

Out[11]: <matplotlib.image.AxesImage at 0x7f408d423290>



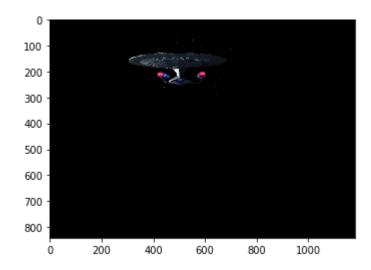
```
In [12]: object_mask = cv2.cvtColor(cv2.imread('samples/enterprise_mask.jpg'), cv
   object_mask = np.mean(object_mask,axis=2)
   object_mask[object_mask >= 0.5] = 1.
   object_mask[object_mask < 0.5] = 0.
   plt.close()
   plt.imshow(object_mask,cmap='gray')</pre>
```

Out[12]: <matplotlib.image.AxesImage at 0x7f408f6f5d90>



```
In [13]: foreground_img = cv2.cvtColor(cv2.imread('samples/enterprise_cropped.jpq
    plt.close()
    plt.imshow(foreground_img)
```

#### Out[13]: <matplotlib.image.AxesImage at 0x7f408fd1a990>

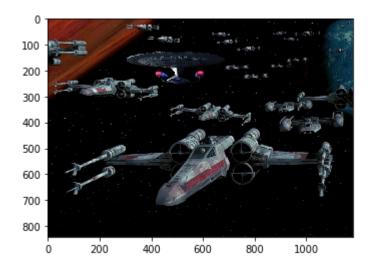


```
In [14]:
    tickt = time.time()
    im_blend = poisson_blend(foreground_img, object_mask, background_img)
    if im_blend.any():
        %matplotlib inline
        import matplotlib.pyplot as plt
        plt.imshow(im_blend)
    tockt = time.time()

    h, m, s = hms(tockt-tickt)

    print(f'Total time took {h} hours, {m} minutes, and {s} seconds')
```

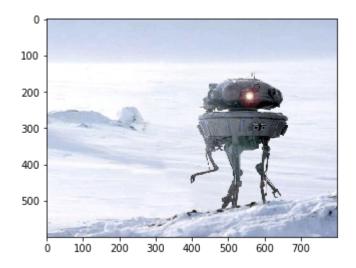
Equations for channel 0 took 0 hours, 0 minutes, and 1 seconds Segmenting for channel 0 took 0 hours, 0 minutes, and 0 seconds LSQR for channel 0 took 0 hours, 0 minutes, and 8 seconds Equations for channel 1 took 0 hours, 0 minutes, and 1 seconds Segmenting for channel 1 took 0 hours, 0 minutes, and 0 seconds LSQR for channel 1 took 0 hours, 0 minutes, and 8 seconds Equations for channel 2 took 0 hours, 0 minutes, and 1 seconds Segmenting for channel 2 took 0 hours, 0 minutes, and 0 seconds LSQR for channel 2 took 0 hours, 0 minutes, and 8 seconds Total time took 0 hours, 0 minutes, and 32 seconds



In [15]: plt.imsave('enterprise\_xwings.jpg',im\_blend)

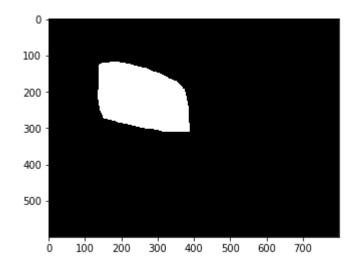
```
In [4]: background_img = cv2.cvtColor(cv2.imread('samples/probe.jpg'), cv2.C0LOF
    plt.close()
    plt.imshow(background_img)
```

Out[4]: <matplotlib.image.AxesImage at 0x7f80063d1410>



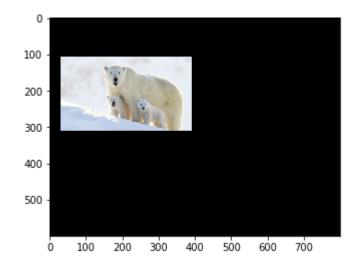
```
In [5]: object_mask = cv2.cvtColor(cv2.imread('samples/polar_bear_mask_fail.jpg'
    object_mask = np.mean(object_mask,axis=2)
    object_mask[object_mask >= 0.5] = 1.
    object_mask[object_mask < 0.5] = 0.
    plt.close()
    plt.imshow(object_mask,cmap='gray')</pre>
```

Out[5]: <matplotlib.image.AxesImage at 0x7f7ff4420810>



In [6]: foreground\_img = cv2.cvtColor(cv2.imread('samples/polar\_bear\_cropped.jpg
plt.close()
plt.imshow(foreground\_img)

Out[6]: <matplotlib.image.AxesImage at 0x7f7ff4415390>

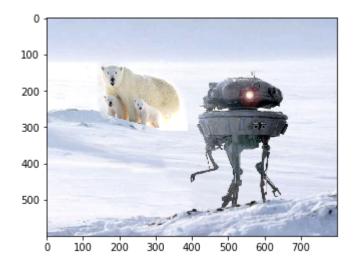


```
In [7]: tickt = time.time()
    im_blend = poisson_blend(foreground_img, object_mask, background_img)
    if im_blend.any():
        %matplotlib inline
        import matplotlib.pyplot as plt
        plt.imshow(im_blend)
        tockt = time.time()

    h, m, s = hms(tockt-tickt)

    print(f'Total time took {h} hours, {m} minutes, and {s} seconds')
```

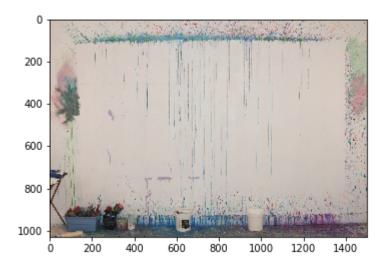
Equations for channel 0 took 0 hours, 0 minutes, and 1 seconds Segmenting for channel 0 took 0 hours, 0 minutes, and 0 seconds LSQR for channel 0 took 0 hours, 0 minutes, and 3 seconds Equations for channel 1 took 0 hours, 0 minutes, and 1 seconds Segmenting for channel 1 took 0 hours, 0 minutes, and 0 seconds LSQR for channel 1 took 0 hours, 0 minutes, and 3 seconds Equations for channel 2 took 0 hours, 0 minutes, and 1 seconds Segmenting for channel 2 took 0 hours, 0 minutes, and 0 seconds LSQR for channel 2 took 0 hours, 0 minutes, and 3 seconds Total time took 0 hours, 0 minutes, and 16 seconds



```
In [8]: plt.imsave('polar_droid_fail.jpg',im_blend)
In []:
In []:
In []:
```

## Part 3 Mixed Gradients (20 pts)

In [16]: background\_img = cv2.cvtColor(cv2.imread('samples/street.jpg'), cv2.COL(
 plt.figure()
 plt.imshow(background\_img)



#### Out[16]: <matplotlib.image.AxesImage at 0x7f7ff414f410>

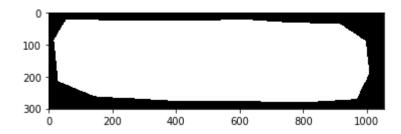
In [13]: object\_img = cv2.cvtColor(cv2.imread('samples/we\_the\_people2.jpg'), cv2.
import matplotlib.pyplot as plt
%matplotlib notebook
mask\_coords = specify\_mask(object\_img)

If it doesn't get you to the drawing mode, then rerun this function ag ain.



```
In [14]: xs = mask_coords[0]
    ys = mask_coords[1]
    %matplotlib inline
    import matplotlib.pyplot as plt
    plt.figure()
    mask = get_mask(ys, xs, object_img)
```

<Figure size 432x288 with 0 Axes>

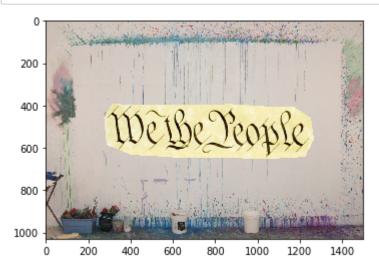


# In [17]: %matplotlib notebook import matplotlib.pyplot as plt bottom\_center = specify\_bottom\_center(background\_img)

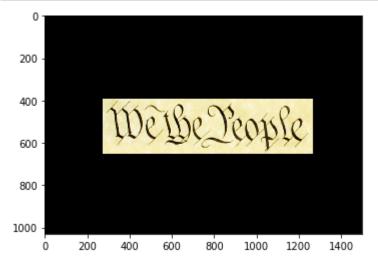
If it doesn't get you to the drawing mode, then rerun this function ag ain. Also, make sure the object fill fit into the background image. Ot herwise it will crash



In [18]: %matplotlib inline
 import matplotlib.pyplot as plt
 cropped\_object, object\_mask = align\_source(object\_img, mask, background\_



In [19]: plt.close()
 plt.imshow(cropped\_object)
 plt.imsave('samples/we\_the\_people\_cropped.jpg',cropped\_object)



```
In [20]: def mix blend(cropped object, object mask, background img):
             :param cropped object: numpy.ndarray One you get from align source
             :param object mask: numpy.ndarray One you get from align source
              :param background img: numpy.ndarray
             idx = np.where(object mask==1)
             idx = np.concatenate((idx[0].reshape(-1,1),idx[1].reshape(-1,1)),axi
             s=cropped_object
             t=background img
             im_h, im_w, _ = t.shape
             im2var = np.arange(im_h * im_w).reshape(im_w, im_h).T
             num v = im h*im w
             num_e = np.where(object_mask==1)[0].shape[0] * 5
             return v = np.zeros(t.shape)
             for c in range(3):
                 \#A = csr \ matrix((num \ e, num \ v))
                 A = lil matrix((num e,num v))
                 b = np.zeros((num e,))
                 e=0
                 tick = time.time()
                 for x in range(im w):
                      for y in range(im_h):
                          if object mask[y][x]==1:
                              if x < im w-1:
                                  si = s[y][x][c] - s[y][x+1][c]
                                  ti = t[y][x][c] - t[y][x+1][c]
                                  if np.absolute(si) > np.absolute(ti):
                                      d = si
                                  else:
                                      d = ti
                                  A[e,im2var[y][x+1]] = -1
                                  A[e,im2var[y][x]] = 1
                                  b[e] = d
                                  e+=1
                              if y < im_h-1:
                                  si = s[y][x][c] - s[y+1][x][c]
                                  ti = t[y][x][c] - t[y+1][x][c]
                                  if np.absolute(si) > np.absolute(ti):
                                      d = si
                                  else:
                                      d = ti
                                  A[e,im2var[y+1][x]] = -1
                                  A[e,im2var[y][x]] = 1
                                  b[e] = d
                                  e+=1
                              if x > 0:
                                  si = s[y][x][c] - s[y][x-1][c]
                                  ti = t[y][x][c] - t[y][x-1][c]
                                  if np.absolute(si) > np.absolute(ti):
                                      d = si
```

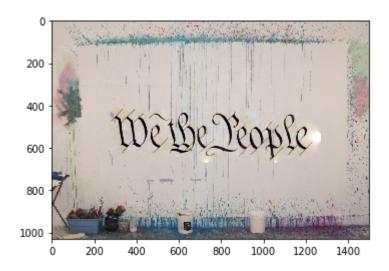
```
else:
        d = ti
    A[e,im2var[y][x-1]] = -1
    A[e,im2var[y][x]] = 1
    b[e] = d
    e+=1
if y > 0:
    si = s[y][x][c] - s[y-1][x][c]
    ti = t[y][x][c] - t[y-1][x][c]
    if np.absolute(si) > np.absolute(ti):
        d = si
    else:
        d = ti
    A[e,im2var[y-1][x]] = -1
    A[e,im2var[y][x]] = 1
    b[e] = d
    e+=1
if object mask[y][x+1]==0:
    si = s[y][x][c] - s[y][x+1][c]
    ti = t[y][x][c] - t[y][x+1][c]
    if np.absolute(si) > np.absolute(ti):
        d = si
    else:
        d = ti
    A[e,im2var[y][x]] = 1
    b[e] = t[y][x+1][c] + d
    e+=1
if object_mask[y][x-1]==0:
    si = s[y][x][c] - s[y][x-1][c]
    ti = t[y][x][c] - t[y][x-1][c]
    if np.absolute(si) > np.absolute(ti):
        d = si
    else:
        d = ti
    A[e,im2var[v][x]] = 1
    b[e] = t[y][x-1][c] + d
    e+=1
if object mask[y+1][x]==0:
    si = s[y][x][c] - s[y+1][x][c]
    ti = t[y][x][c] - t[y+1][x][c]
    if np.absolute(si) > np.absolute(ti):
        d = si
    else:
        d = ti
    A[e,im2var[y][x]] = 1
    b[e] = t[y+1][x][c] + d
    e+=1
if object_mask[y-1][x]==0:
    si = s[y][x][c] - s[y-1][x][c]
    ti = t[y][x][c] - t[y-1][x][c]
    if np.absolute(si) > np.absolute(ti):
        d = si
```

```
else:
                        d = ti
                    A[e,im2var[y][x]] = 1
                    b[e] = t[y-1][x][c] + s[y][x][c] - s[y-1][x][c]
                    e+=1
    tock = time.time()
    hr, mn, sc = hms(tock-tick)
    print(f'Equations for channel {c} took {hr} hours, {mn} minutes,
    tick = time.time()
    A=A.tocsr()
    A=A[:e,:]
    b=b[:e]
    tock = time.time()
    hr, mn, sc = hms(tock-tick)
    print(f'Segmenting for channel {c} took {hr} hours, {mn} minutes
    tick = time.time()
    v = lsqr(A, b)
    tock = time.time()
    hr, mn, sc = hms(tock-tick)
    print(f'LSQR for channel {c} took {hr} hours, {mn} minutes, and
    return v[:,:,c] = v[0].reshape((im w, im h)).T
d3_mask = np.stack((object_mask,object_mask,object_mask),axis=2)
return v = background img*(1-d3 mask) + return v*d3 mask
return v[return v > 1] = 1.
return_v[return_v < 0] = 0.
return return v
```

#### In [ ]:

```
In [40]: im_mix = mix_blend(cropped_object, object_mask, background_img)
if im_mix.any():
    %matplotlib inline
    import matplotlib.pyplot as plt
    plt.imshow(im_mix)
```

Equations for channel 0 took 0 hours, 0 minutes, and 12 seconds Segmenting for channel 0 took 0 hours, 0 minutes, and 0 seconds LSQR for channel 0 took 0 hours, 0 minutes, and 38 seconds Equations for channel 1 took 0 hours, 0 minutes, and 12 seconds Segmenting for channel 1 took 0 hours, 0 minutes, and 0 seconds LSQR for channel 1 took 0 hours, 0 minutes, and 38 seconds Equations for channel 2 took 0 hours, 0 minutes, and 12 seconds Segmenting for channel 2 took 0 hours, 0 minutes, and 0 seconds LSQR for channel 2 took 0 hours, 0 minutes, and 37 seconds



```
In [41]: plt.imsave('we_the_people1.jpg',im_mix)
```

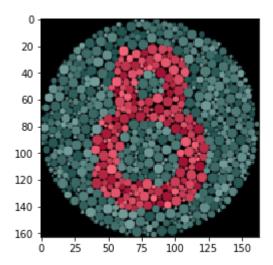
### **Bells & Whistles (Extra Points)**

Color2Gray (20 pts)

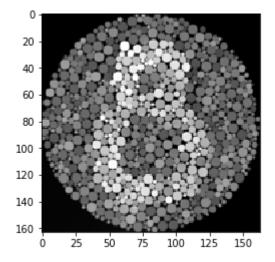
```
In [141]: | def color2gray(clr_img):
              The implementation for gradient domain processing is not complicated
              1. minimize (v(x+1,y)-v(x,y) - (s(x+1,y)-s(x,y)))^2
              2. minimize (v(x,y+1)-v(x,y) - (s(x,y+1)-s(x,y)))^2
              Note that these could be solved while adding any constant value to
              3. minimize (v(1,1)-s(1,1))^2
               :param toy img: numpy.ndarray
               im=clr img
              im h, \overline{im}_w, im_c = im.shape
              im2var = np.arange(im_h * im_w).reshape(im_w, im_h).T
              num v = (im h)*(im w)
              num e = im h*(im w-1) + im w*(im h-1) + 1
              \#A = np.zeros((num e, num v))
              A = lil matrix((num e,num v))
              b = np.zeros((num_e,))
              e=0
              for x in range(im w):
                   for y in range(im_h):
                       if x < im w-1:
                           d = im[y,x+1,:] - im[y,x,:]
                           d = max(d.min(), d.max(), key=abs)
                           A[e,im2var[y][x+1]] = 1
                           A[e,im2var[y][x]] = -1
                           b[e] = d
                           e+=1
                       if y < im h-1:
                           d = im[y+1,x,:] - im[y,x,:]
                           d = max(d.min(), d.max(), key=abs)
                           A[e,im2var[y+1][x]] = 1
                           A[e,im2var[y][x]] = -1
                           b[e] = d
                           e+=1
              A[e,im2var[0][0]] = 1
              b[e] = np.mean(im[0,0,:])
              A=A.tocsr()
              v = lsqr(A, b)
              v[0][v[0] > 1] = 1.
              v[0][v[0] < 0] = 0.
               return v[0].reshape((im w, im h)).T
```

```
In [143]: clr_img = cv2.cvtColor(cv2.imread('samples/colorBlind8.png'), cv2.C0LOR_
plt.imshow(clr_img)
```

Out[143]: <matplotlib.image.AxesImage at 0x7f26a8ddf790>

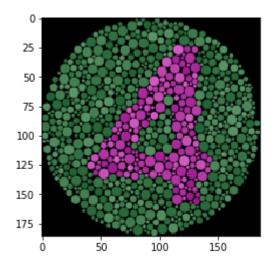


```
In [144]: gray_img = color2gray(clr_img)
    plt.close()
    plt.imshow(gray_img,cmap='gray')
    im_save = np.stack((gray_img,gray_img,gray_img),axis=2)
    plt.imsave('gray_colorblind8.jpg',im_save)
```

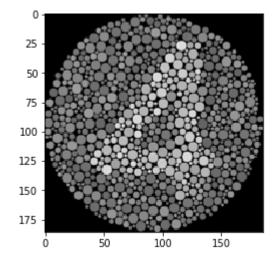


```
In [127]: clr_img = cv2.cvtColor(cv2.imread('samples/colorBlind4.png'), cv2.COLOR_
    plt.close()
    plt.imshow(clr_img)
```

Out[127]: <matplotlib.image.AxesImage at 0x7f26c425cd90>



```
In [142]: gray_img = color2gray(clr_img)
    plt.close()
    plt.imshow(gray_img,cmap='gray')
    im_save = np.stack((gray_img,gray_img,gray_img),axis=2)
    plt.imsave('gray_colorblind4.jpg',im_save)
```



### **Laplacian pyramid blending (20 pts)**

```
In [29]:

def blur_img(img,kernel_size=None):
    #sigma_low = 1./(2*np.pi*cutoff_low)
    kernel = cv2.getGaussianKernel(kernel_size,-1)
    kernel = np.dot(kernel,kernel.T)
    blur_img = cv2.filter2D(img, -1, kernel)

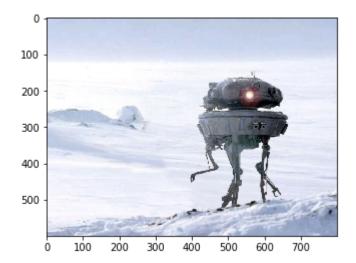
#if kernel_size is None:
    # kernel_size = int(min(img.shape[0],img.shape[1])/15)
    #if kernel_size % 2 == 0:
    # kernel_size += 1
    #blur_img = cv2.GaussianBlur(img,(kernel_size,kernel_size),cv2.BORDE

return blur_img
```

```
In [55]: def laplacian_blend(img1, img2, mask):
    L10 = img1 - blur_img(img1,kernel_size=25)
    L20 = img2 - blur_img(img2,kernel_size=25)
    mask_L0 = blur_img(mask,kernel_size=5)
    mask_L0 = np.stack((mask_L0,mask_L0,mask_L0),axis=2)
    L0 = L20 * mask_L0 + L10 * (1-mask_L0)
    L11 = blur_img(img1,kernel_size=25)
    L21 = blur_img(img2,kernel_size=25)
    mask_L1 = blur_img(mask,kernel_size=25)
    mask_L1 = np.stack((mask_L1,mask_L1,mask_L1),axis=2)
    L1 = L21 * mask_L1 + L11 * (1-mask_L1)
    lap_blend = L1 + L0
    lap_blend[lap_blend > 1] = 1.
    lap_blend[lap_blend < 0] = 0.
    return lap_blend</pre>
```

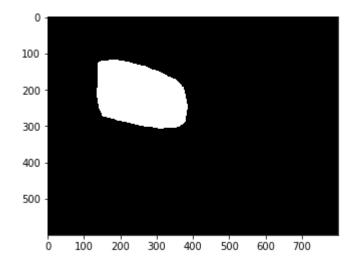
```
In [41]: background_img = cv2.cvtColor(cv2.imread('samples/probe.jpg'), cv2.C0LOF
    plt.close()
    plt.imshow(background_img)
```

Out[41]: <matplotlib.image.AxesImage at 0x7fe734316690>



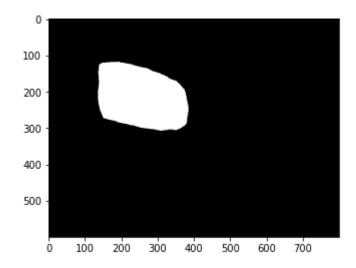
```
In [2]: object_mask = cv2.cvtColor(cv2.imread('samples/polar_bear_mask.jpg'), cv
   object_mask = np.mean(object_mask,axis=2)
   object_mask[object_mask >= 0.5] = 1.
   object_mask[object_mask < 0.5] = 0.
   plt.close()
   plt.imshow(object_mask,cmap='gray')</pre>
```

Out[2]: <matplotlib.image.AxesImage at 0x7fe75d929e10>



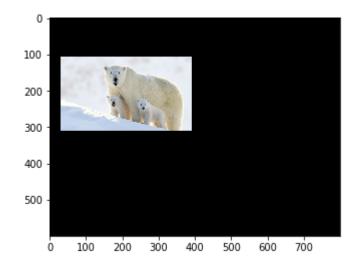
```
In [39]: mask_l1 = blur_img(object_mask,kernel_size=5)
   plt.close()
   plt.imshow(mask_l1,cmap='gray')
```

Out[39]: <matplotlib.image.AxesImage at 0x7fe7343c8ed0>

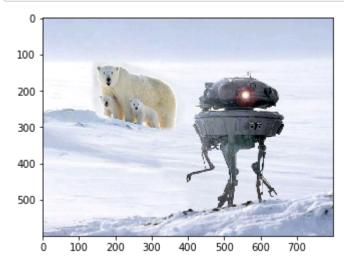


```
In [43]: foreground_img = cv2.cvtColor(cv2.imread('samples/polar_bear_cropped.jp@
plt.close()
plt.imshow(foreground_img)
```

Out[43]: <matplotlib.image.AxesImage at 0x7fe734273d90>



```
In [57]: lap_blend = laplacian_blend(background_img, foreground_img, object_mask)
    plt.close()
    plt.imshow(lap_blend)
    plt.imsave('laplacian_blend.jpg',lap_blend)
```



In	[ ]:	
In	[ ]:	
In	[ ]:	
In	[ ]:	

# More gradient domain processing (up to 20 pts)

```
In [ ]:
```