TilePilot: A Lightweight Framework for Generating Optimized GPU Kernels

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TileLang: A GPU DSL for Structured, Composable Kernel Programming

- ★ Python-based DSL for GPU kernel development
- Separates dataflow from scheduling (e.g., memory layout, thread binding)
- Kernels are written using tiles as first-class objects
- Provides low-level primitives for:
- Memory allocation: T.alloc_shared(), T.alloc_fragment()
- Computation: T.gemm(), T.reduce(), T.copy()
- Scheduling: T.Pipelined, T.Parallel, T.annotate_layout()
- Compiler handles backend optimizations

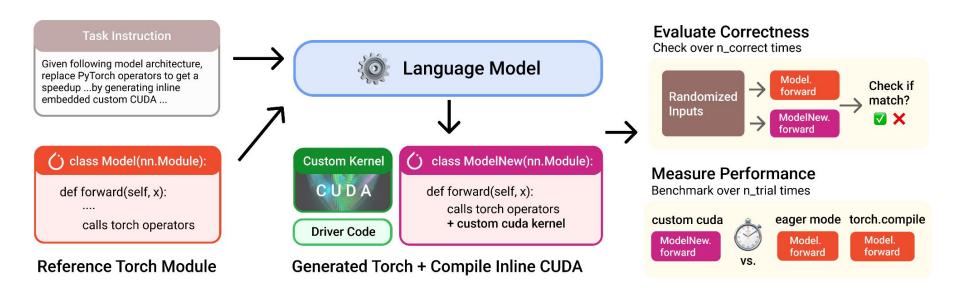
Goal: Automatically generate efficient GPU kernels in a new low-resource DSL

- **o** Input: PyTorch Models containing arbitrary operations
- Output: Fast, correct TileLang kernels to speed up the model

Must be:

- V Functionally correct
- Performance competitive
- Scheap and easy to generate

KernelBench: Our Benchmark for Functional + Performance Evaluation



Challenge: TileLang is new, under-documented, and performance-critical

```
import tilelang.language as T
def Matmul(A: T.Buffer, B: T.Buffer, C: T.Buffer):
                       Kernel Context Initialization
    with T. Kernel (
        ceildiv(N, block N), ceildiv(M, block M), threads=128
    ) as (bx, by):
                              Buffer Allocation
       A shared = T.alloc shared((block M, block K))
                                                                       Shared
        B shared = T.alloc shared((block K, block N))
                                                                      Memory
       C local = T.alloc fragment((block M, block N), accum dtype) Register
       T.clear(C local)
                                         Initialize Accumulate Buffer with Zero
                     Main Loop with Pipeline Annotation
        for k in T.Pipelined(ceildiv(K, block K), num stages=3):
                    Copy Data from Global to Shared Memory
            T.copy(A[by * block M, k * block K], A shared)
            T.copy(B[k * block K, bx * block N], B shared)
                                     GFMM
            T.gemm (A shared, B shared, C local)
                       Write Back to Global Memory
       T.copy (C local, C[by * block M, bx * block N])
```

Source: github.com/tile-ai/tilelang

Insight: Kernel generation is often pattern recombination

- - Coalesced Memory Access
 - Shared Memory Tiling
 - Thread Divergence Avoidance

Hypothesis: if we could retrieve relevant working examples and adapt them, we can teach a model a new language with very limited training data

TilePilot: Progressive Learning with RAG



Seed Stage

37 handwritten TileLang kernels



Bootstrapping Stage

Retrieve and adapt similar kernels



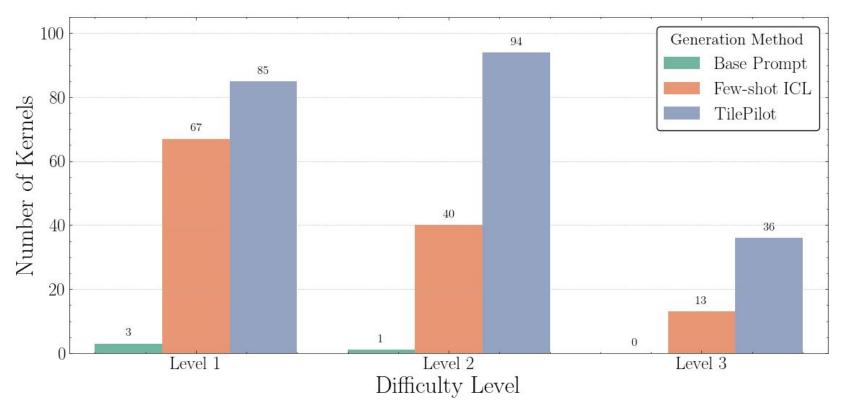
Optimization Stage

Fix slow or incorrect kernels

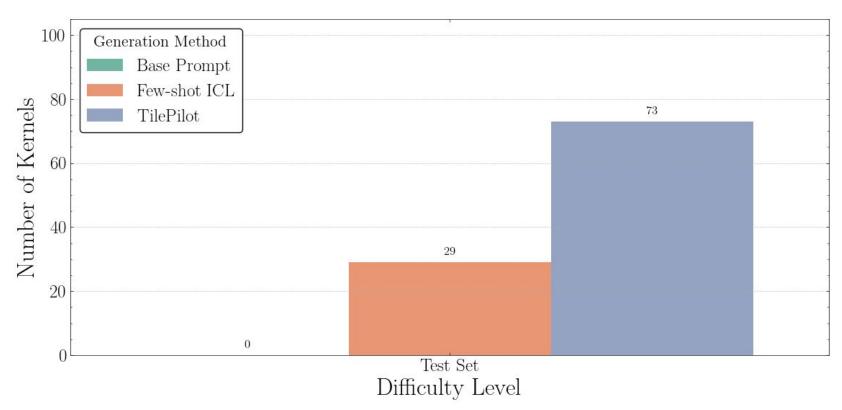


Results

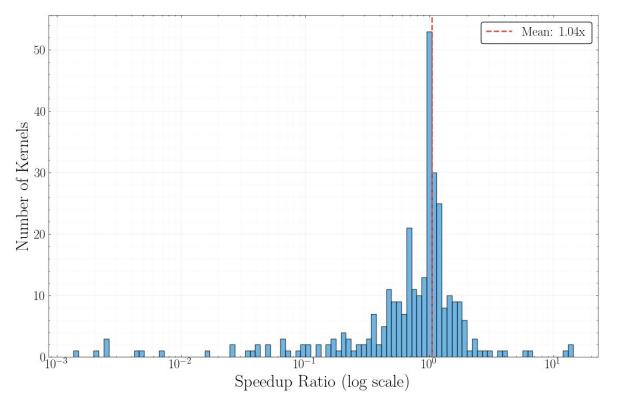
Correctness: TilePilot achieved 79% more successful generations vs. few-shot prompting



Correctness: TilePilot has greater zero-shot generalization on a held out test set

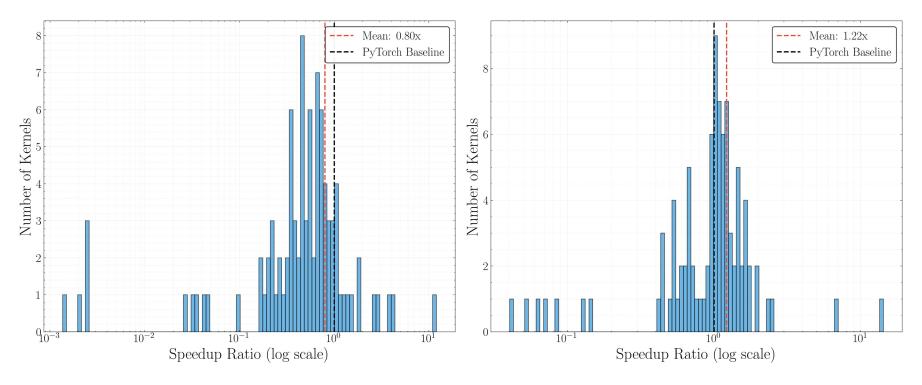


Performance: Many kernels outperform PyTorch baselines



Speedup Ratios across All Generated Kernels

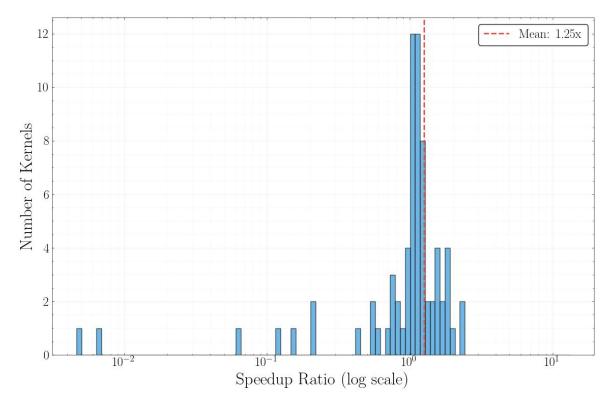
Performance: Many kernels outperform PyTorch baselines



Level 1 Speedup Ratios

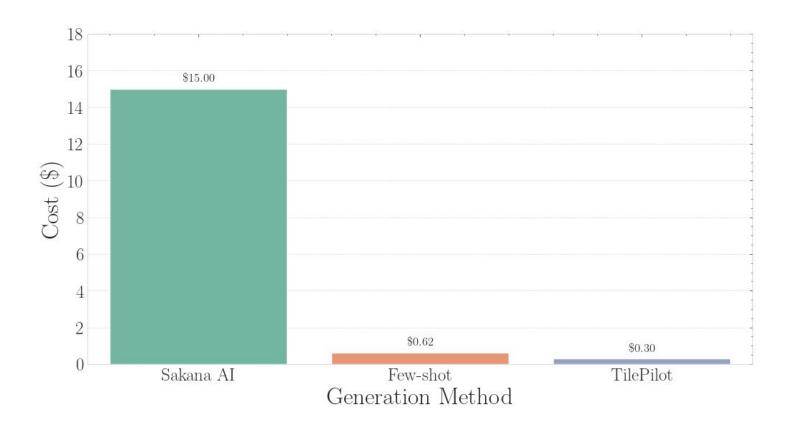
Level 2 Speedup Ratios

Performance: Many kernels outperform PyTorch baselines



Speedup Ratios on Held Out Test Set

Cost: TilePilot reduces kernel generation cost by 50x



TilePilot matches or beats CUDA baselines — despite no training data for TileLang

Comparison between TilePilot (TileLang) and KernelBench leaderboard (CUDA).

Level	TilePilot			Leaderboard		
	Total	Mean	Speedup > 1.0x	Total	Mean	Speedup > 1.0x
Level 1	83	0.80x	18%	65	0.88x	20%
Level 2	82	1.22x	62%	65	1.18x	52%
Level 3	29	0.85x	28%	26	0.82x	15%

Case Study: TilePilot can act like an LLM Compiler, discovering algorithmic simplifications

```
class Model(nn.Module):
    ...
    def forward(self, x):
        x = torch.matmul(x, self.weight.T) # Gemm
        x = torch.sum(x, dim=1, keepdim=True) # Sum
        x = x * self.scaling_factor # Scaling
        return x
```

$$sum(X \cdot W^T, dim = 1) = X \cdot sum(W, dim = 0)$$

Case Study: TilePilot can act like an LLM Compiler, discovering algorithmic simplifications

```
# Each thread processes one row of the input matrix X
with T.Kernel(T.ceildiv(batch_size, block_size), threads=block_size) as bx:
    tx = T.get_thread_binding(0)
    row = bx * block size + tx
    if row < batch size:
        # Initialize accumulator for this row
        acc = T.alloc_local((1,), accum_dtype)
       T.clear(acc)
       # This kernel computes X * sum(W, dim=0) efficiently by:
       # 1. Wsum is pre-computed as sum(W, dim=0) before kernel launch
       # 2. For each row i of X, compute dot product with Wsum
       # 3. This gives us sum(X[i,:] * sum(W, dim=0))
        # 4. Which is equivalent to sum(X[i,:] * W[:,:], dim=1)
        # 5. This avoids the full matrix multiplication X * W.T
        for k in T.serial(input size):
            acc[0] += X[row, k] * Wsum[k]
       # Apply scaling factor (which includes the division by 2)
        # Final computation: (sum(X[row,:] * Wsum[:]) * scale const)
        val = acc[0] * scale_const
        Out[row, 0] = T.Cast(dtype, val)
```

Where We Struggled, and Where We're Going Next

- Level 1 is deceptively hard
- TileLang's autotuner is too experimental for now
- Level 3 needs advanced patterns (multi-kernel fusion), need more examples
- ★ KernelBench can be unreliable → small input sizes crashes TMA

TilePilot enables fast, low-cost, compiler-like LLM kernel generation



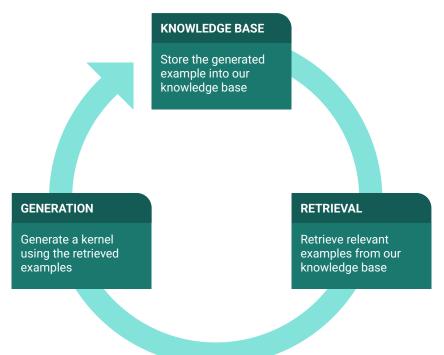


GPU kernels share

common structures, and

optimization patterns are

well defined



Training with TilePilot: Enabling Efficient Model Training 🚀



We use TilePilot to show that you don't need a massive model or dataset to get strong results for training models.

Start with 200 high-quality kernels

- For each kernel, TracePilot generates a step-by-step reasoning trace:
- Explains the "why" behind each optimization
- Total mapping, fusion, and performance choices
- Captures expert logic, not just code
- Result:

A dataset of expert reasoning traces paired with kernels

time Use for Training:

Train models to not just copy code, but to reason and optimize like an expert