

# Comments on the Quadratic Form

Nathan Marianovsky

**Definition 1** (Quadratic Form). Formally a quadratic form is defined as:

$$f(\vec{x}) = \frac{1}{2} \vec{x}^T A \vec{x} - \vec{b}^T x + c$$

where:

$$c \in \mathbb{R}, \quad \vec{x}, \vec{b} \in \mathbb{R}^n, \quad \text{and} \quad A \in \mathbb{R}^{n^2}$$

**Definition 2** (Del Operator). The *del operator* is formally defined as:

$$\nabla = \begin{pmatrix} \frac{\partial}{\partial x_1} \\ \frac{\partial}{\partial x_2} \\ \frac{\partial}{\partial x_3} \\ \vdots \\ \frac{\partial}{\partial x_n} \end{pmatrix}$$

where it is known to be a linear operator:

$$\begin{aligned} \nabla(\alpha f(\vec{x}) + \beta g(\vec{x})) &= \begin{pmatrix} \frac{\partial}{\partial x_1} \\ \frac{\partial}{\partial x_2} \\ \frac{\partial}{\partial x_3} \\ \vdots \\ \frac{\partial}{\partial x_n} \end{pmatrix} (\alpha f(\vec{x}) + \beta g(\vec{x})) \\ &= \begin{pmatrix} \frac{\partial}{\partial x_1}(\alpha f(\vec{x}) + \beta g(\vec{x})) \\ \frac{\partial}{\partial x_2}(\alpha f(\vec{x}) + \beta g(\vec{x})) \\ \frac{\partial}{\partial x_3}(\alpha f(\vec{x}) + \beta g(\vec{x})) \\ \vdots \\ \frac{\partial}{\partial x_n}(\alpha f(\vec{x}) + \beta g(\vec{x})) \end{pmatrix} \\ &= \begin{pmatrix} \alpha \frac{\partial}{\partial x_1} f(\vec{x}) \\ \alpha \frac{\partial}{\partial x_2} f(\vec{x}) \\ \alpha \frac{\partial}{\partial x_3} f(\vec{x}) \\ \vdots \\ \alpha \frac{\partial}{\partial x_n} f(\vec{x}) \end{pmatrix} + \begin{pmatrix} \beta \frac{\partial}{\partial x_1} g(\vec{x}) \\ \beta \frac{\partial}{\partial x_2} g(\vec{x}) \\ \beta \frac{\partial}{\partial x_3} g(\vec{x}) \\ \vdots \\ \beta \frac{\partial}{\partial x_n} g(\vec{x}) \end{pmatrix} \\ &= \alpha \nabla f(\vec{x}) + \beta \nabla g(\vec{x}) \end{aligned}$$

**Definition 3** (Gradient). Given a scalar function that has  $n$  parameters such as  $f(\vec{x})$  above, then the *derivative* or *gradient* is formally defined as:

$$f'(\vec{x}) = \nabla f(\vec{x}) = \begin{pmatrix} \frac{\partial}{\partial x_1} \\ \frac{\partial}{\partial x_2} \\ \frac{\partial}{\partial x_3} \\ \vdots \\ \frac{\partial}{\partial x_n} \end{pmatrix} f(\vec{x}) = \begin{pmatrix} \frac{\partial f}{\partial x_1} \\ \frac{\partial f}{\partial x_2} \\ \frac{\partial f}{\partial x_3} \\ \vdots \\ \frac{\partial f}{\partial x_n} \end{pmatrix}$$

**Proposition 1.** The gradient of the quadratic form is given as:

$$f'(\vec{x}) = \frac{1}{2}A^T\vec{x} + \frac{1}{2}A\vec{x} - \vec{b}$$

and if  $A$  is symmetric:

$$f'(\vec{x}) = A\vec{x} - \vec{b}$$

*Proof.* To prove the proposition we begin by defining:

$$A = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{pmatrix}$$

$$\vec{x} = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} \quad \vec{b} = \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{pmatrix}$$

Now using this we have:

$$A\vec{x} = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} = \begin{pmatrix} \sum a_{1i}x_i \\ \sum a_{2i}x_i \\ \vdots \\ \sum a_{ni}x_i \end{pmatrix}$$

$$A^T\vec{x} = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} = \begin{pmatrix} \sum a_{i1}x_i \\ \sum a_{i2}x_i \\ \vdots \\ \sum a_{in}x_i \end{pmatrix}$$

where the sums are iterated from  $i = 1$  to  $n$  to account for all the components. Now the next step is:

$$\vec{x}^T A \vec{x} = \begin{pmatrix} x_1 & x_2 & \dots & x_n \end{pmatrix} \begin{pmatrix} \sum a_{1i}x_i \\ \sum a_{2i}x_i \\ \vdots \\ \sum a_{ni}x_i \end{pmatrix}$$

$$= x_1 \sum a_{1i}x_i + x_2 \sum a_{2i}x_i + \dots + x_n \sum a_{ni}x_i$$

$$= \sum x_j \sum a_{ji}x_i$$

$$= \sum \sum a_{ji}x_i x_j$$

With this we have a nice consolidated form for that annoying matrix multiplication. Now we want to find the partial derivatives. To begin we consider the partial derivative with respect to  $x_1$ :

$$\frac{\partial(\vec{x}^T A \vec{x})}{\partial x_1} = \frac{\partial}{\partial x_1} \left[ x_1 \sum a_{1i}x_i + x_2 \sum a_{2i}x_i + \dots + x_n \sum a_{ni}x_i \right]$$

$$= (2a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n) + (a_{21}x_2 + a_{31}x_3 + \dots + a_{n1}x_n)$$

$$= \sum a_{1i}x_i + \sum a_{i1}x_i$$

Since  $k = 1$  is a specific case, in general we have:

$$\frac{\partial(\vec{x}^T A \vec{x})}{\partial x_k} = \sum a_{ki}x_i + \sum a_{ik}x_i$$

Now all of the hard work is done. Phew! All that is left is to simplify our expression. We begin by writing down the gradient:

$$\begin{aligned}\nabla(\vec{x}^T A \vec{x}) &= \begin{pmatrix} \sum a_{1i}x_i + \sum a_{i1}x_i \\ \sum a_{2i}x_i + \sum a_{i2}x_i \\ \vdots \\ \sum a_{ni}x_i + \sum a_{in}x_i \end{pmatrix} \\ &= \begin{pmatrix} \sum a_{1i}x_i \\ \sum a_{2i}x_i \\ \vdots \\ \sum a_{ni}x_i \end{pmatrix} + \begin{pmatrix} \sum a_{i1}x_i \\ \sum a_{i2}x_i \\ \vdots \\ \sum a_{in}x_i \end{pmatrix} \\ &= A\vec{x} + A^T\vec{x}\end{aligned}$$

Lastly before jumping into the quadratic form we define:

$$\begin{aligned}\vec{b}^T \vec{x} &= \begin{pmatrix} b_1 & b_2 & \dots & b_n \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} \\ &= \sum b_i x_i\end{aligned}$$

where the gradient is going to be:

$$\begin{aligned}\nabla(\vec{b}^T \vec{x}) &= \nabla\left(\sum b_i x_i\right) \\ &= \begin{pmatrix} \frac{\partial}{\partial x_1} \sum b_i x_i \\ \frac{\partial}{\partial x_2} \sum b_i x_i \\ \vdots \\ \frac{\partial}{\partial x_n} \sum b_i x_i \end{pmatrix} \\ &= \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{pmatrix} \\ &= \vec{b}\end{aligned}$$

Now using our results, the gradient of the quadratic form is going to be:

$$\begin{aligned}f'(\vec{x}) &= \nabla f(\vec{x}) \\ &= \frac{1}{2} \nabla(\vec{x}^T A \vec{x}) - \nabla(\vec{b}^T \vec{x}) + \nabla(c) \\ &= \frac{1}{2} (A\vec{x} + A^T\vec{x}) - (\vec{b}) + (\vec{0}) \\ &= \frac{1}{2} A\vec{x} + \frac{1}{2} A^T\vec{x} - \vec{b}\end{aligned}$$

Lastly if  $A$  is symmetric that means  $A = A^T$  which will give:

$$f'(\vec{x}) = A\vec{x} - \vec{b}$$

